

Automated Generation Of Code From Simulink To An Event-Based Simulation Framework

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Simulation Environments Used By MEI

- Simulink
 - Dynamic System Modeling/Simulations
 - Graphical Block-Diagramming Tool
 - -Tightly Integrated With Matlab Command Library
 - -Means To Generate Time-Driven Code
- Event-based Framework (EBF)
 - Discrete Event Messaging
 - Models created with compiled code
 - -Componentized Simulation Layers
 - Middleware, Controller Layers
 - User Components; Simulation Engine & Model Layers

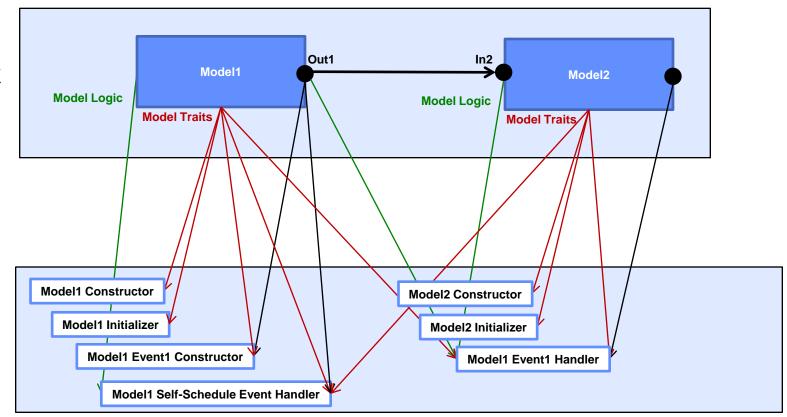
Benefit Derived From Porting Simulink-Developed Models
Into EBF Simulations



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Required Information Flow From Simulink To EBF During Code Generation

Simulink



EBF Code Elements



Time-consuming Manual Approach Initially Used

- •Functional model code generated from Simulink
- Other components hand-written

Functional Model

(Code Generated from Simulink or other sources) Implements Methods in the Model API

Input
Output
Graphic
File
XML
Database

Model API

Inline Functionality API

Interface Code

Process Events, Call Functional Model Publish and Subscribe to Attributes, Output Streams Implements Methods in the Inline Functionality API

Model Base Class

Simulation Engine

Controller

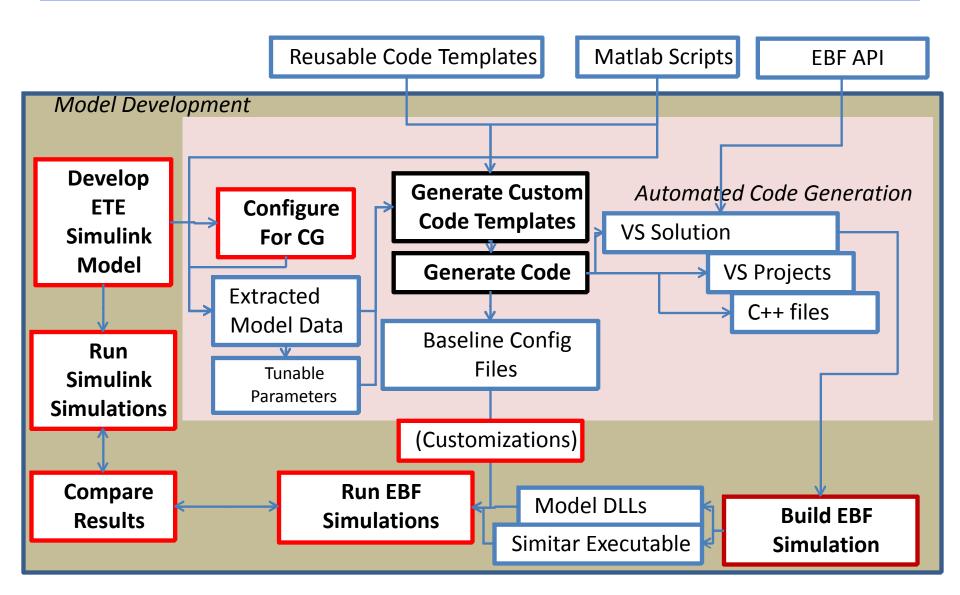


Tasks For Automation

- Extract Information About Targeted Models And Their I/O
- Store Information In A .MAT file
- Generate Functional Model Code From Simulink Using Standard Templates
- Generate Additional Interface Code Using Custom Code Templates
 - Model classes, including Event Handling Methods
 - Attribute classes
 - Event classes
- Generate Makefile Or Visual Studio Projects/Solution
- Compile & Build EBF code
- Generate Prototype Run-Time Configuration Files
 - Incorporate Simulink Tunable Parameters



Automated EBF Code Generation Implemented



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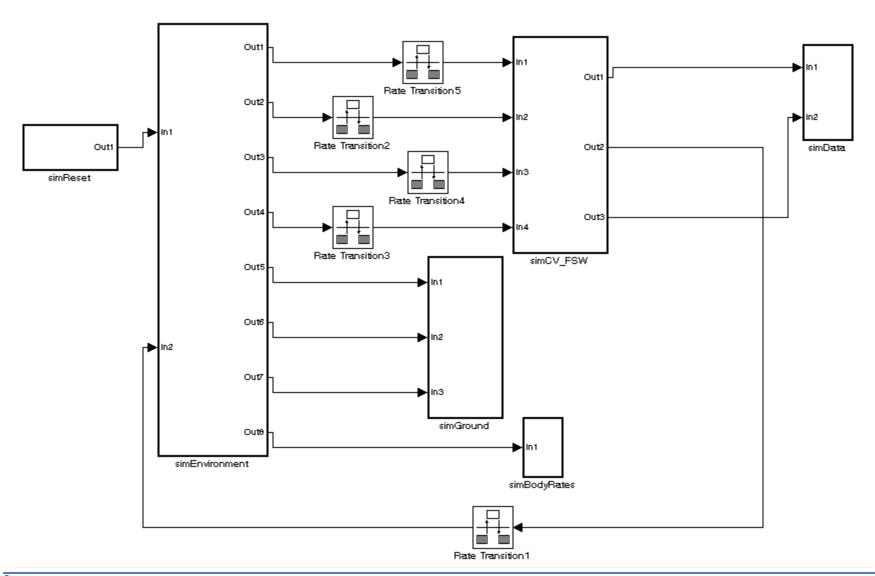


Testing Performed To Verify Fidelity Of Generated Code

- 4 Synthetic Test Cases
 - varied I/O schemes
 - varied feedback schemes
 - multiple rates
- 4 Simulink Models Developed In-House or By MEI Partners
 - Representation of Sensors, Association, State Estimation, Control, Actuators, and Flight Dynamics
- Output data from Simulink & EBF Simulations Compared

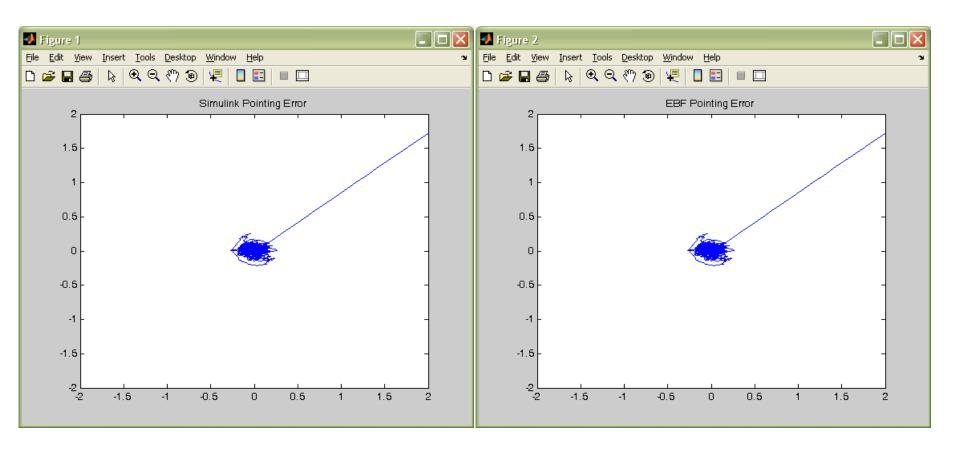


Example Scenario Targeted For Code Generation



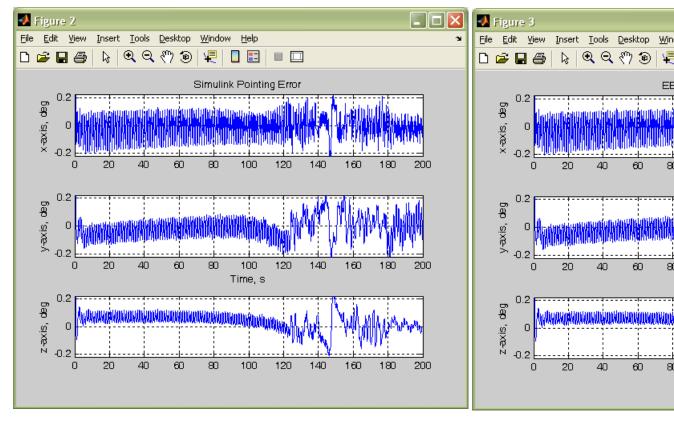


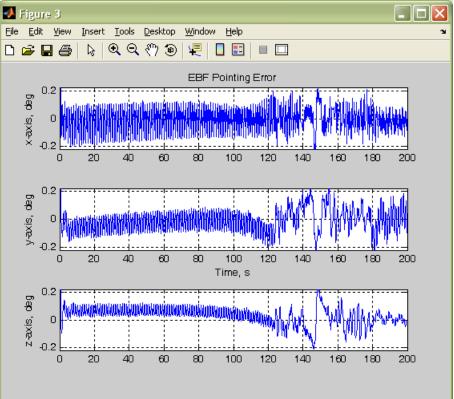
Example Parameter Compared: Pointing Error





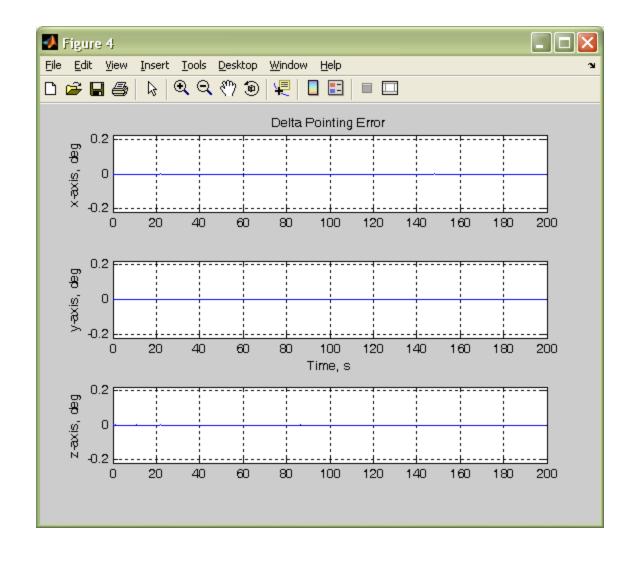
Pointing Error Time Plots Compared







Pointing Errors Compare Well





Summary

- Customized scripts and templates used to generate EBF scenario
 - Inputs/Outputs Characterized and Adapted
 - Model Traits Captured And Incorporated
- Templates Structured With EBF-Specific Code
 - Model, Event, Attribute Classes
 - Model Initialization and Event Handling Methods
 - Communication, Event Scheduling, Data Handling
- Code Generation Interface Tested and Validated With Several Scenarios