

Embedded Control and Mechatronics (ECE-456)

Instructor:

Dr. Farzad Pourboghrat

Professor, Emeritus

Department of Electrical and Computer Engineering (ECE)

(618) 536-2364

pour@siu.edu

<http://heera.engr.siu.edu/staff1/pour/myweb/>

Course URL: <http://heera.engr.siu.edu/staff1/pour/courses/ece456/>

Syllabus:

The course syllabus is available on balckboard (ECE-456)

Textbook:

Dingyu Xue, YangQuan Chen and Derek P. Atherton, **Linear Feedback Control – Analysis and Design with MATLAB**, SIAM, 2007.

Course Materials

- Model-based design (MBD) approach:
 - Textbook materials (Xue, et al. 2007): modeling, analysis, and control (MAD) techniques,
 - Handouts: state-space techniques, selected tutorials,
 - Webinars: Matlab/Simulink & other toolboxes,
 - Microcontroller programming: Microchip, Arduino,
 - Laboratory experiments: motor control, etc.

Course Requirements

- Pre-requisite:
 - Courses: Math Methods in Engineering (315), Systems and Control (356),
 - Subject materials: classical undergraduate control, signals and systems,
 - Minimum knowledge of Matlab/Simulink programming
- See course syllabus on **blackboard**.

Course Expectations

- Class attendance will be observed.
- Homework:
 - Homework problems must be simulated and verified using Matlab/Simulink and other toolboxes.
 - Late submissions may lose up to 20% per day.
- Lab projects (groups of two)
 - Lab reports must be concise, include measured data, schematic of the set-up, Matlab analysis, control design, Simulink simulation and verification, implementation results and plots, conclusion, and signature of the TA verifying the completion of the lab project.
- Final project (groups of two or three)
 - An extension of the lab project (submit a brief proposal for project approval)
 - Implement, verify, and submit a final report
 - Must involve MAD process (**modeling, analysis, and control design**), using **Matlab and other Mathworks toolboxes**, for Arduino implementation.
 - Each student will be given a microcontroller kit (Aduino board, etc.).
 - The complete Arduino kit must be returned back at the end of the semester.

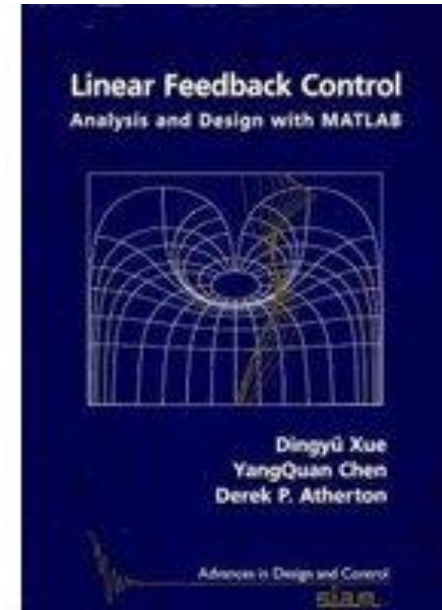
Chapter 1 – Introduction

- Embedded control design is a multidisciplinary subject, involving
 - Dynamic systems analysis
 - Modeling, estimation, and control
 - Simulation and signal processing
 - Microcontrollers and programming
 - Power electronics and drives
- An industry approach to this problem is “Model Based Design”
 - Based on modeling, analysis, and design (MAD) approach

Book Materials To Be Covered

- **Chapter 1** – Introduction to Feedback Control:
Historical background and basic guide to Matlab
- **Chapter 2** – Mathematical Models of Feedback Control Systems:
Physical modeling and corresponding Matlab commands
- **Chapter 3** – Analysis of Linear Control Systems:
Algorithms for analysis of linear systems with Matlab
- **Chapter 4** – Simulation Analysis of Nonlinear Systems:
Simulation and analysis of nonlinear systems with Simulink
- **Chapter 5** – Model-Based Controller Design:
Control designs based on known or estimated models of systems using Matlab
- **Chapter 6** – PID Controller Design:
Matlab-based PID control design
- **Chapter 7** – Robust Control Systems Design:
Advanced control design techniques with Matlab
- **Chapter 8** – Fractional-Order Controller - An Introduction:

Optional materials (if time allowed)



Getting Started with Matlab

- MATLAB (R20010a) is installed in labs E136, E237, and E230
- The installed toolboxes can be browsed via MATLAB start menu
- Stations in E230 have extra toolboxes used for this course
- A student version is available for \$100 plus \$30 per added toolbox
<http://www.mathworks.com/store/default.do>
- Online tutorial for MATLAB is available at
http://www.mathworks.com/academia/student_center/tutorials/

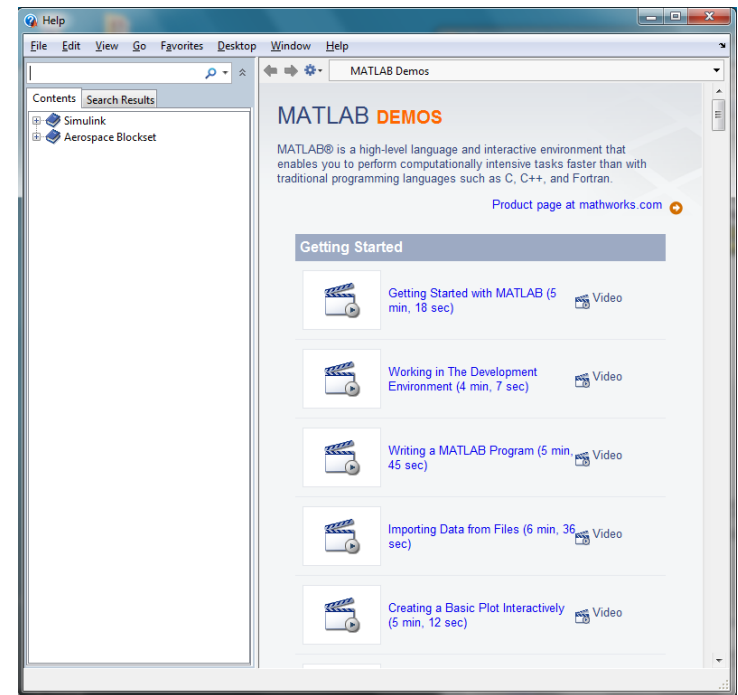
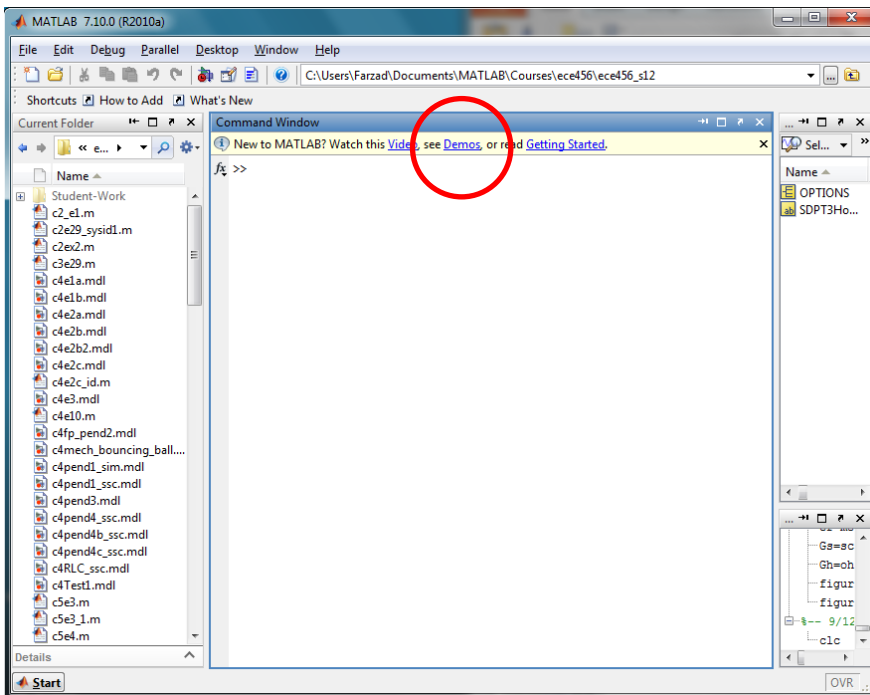
Learning Matlab

- Matlab stands for matrix lab, which is a product of Mathworks. Mathworks products include Matlab, Simulink, and many other toolboxes (control systems, system identification, ...).
- Introductory tutorials are available from links at the top of the workspace console when MATLAB is launched
- Media and help are also available from the Mathworks website:
<http://www.mathworks.com/index.html>
- Documentation and help are available at:
http://www.mathworks.com/help/?s_cid=HP_FF_S_Doc
- Webinar archives can be browsed at:
http://www.mathworks.com/company/events/webinars/upcoming.html?s_cid=HP_FF_E_Webinars

Matlab Demos

To launch the Matlab demos

- Click on “Demo” at the top of Matlab working window
- Click on any of the “Getting Started” demo videos
 - They each are only a few minutes long



Finding and Exploring Matlab Commands and Functions

- Typing **help** displays a list of help topics.
- Typing **help help** describes the syntax for help command with examples.
- Help is available via the help menu, or by typing **help** followed by the command / function-name:

```
>> help [command]
```

- To find a command based on functionality, the **lookfor** command can be used

```
>> lookfor [string]
```

- This returns a list of commands/functions whose name/description contain the specified string
- **Note**: when typing commands, if paused, a small window will pop over the command to suggest the command syntax

Standard Matlab Commands

- The basic element in Matlab is a complex valued matrix.

- To enter a matrix $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 0 \end{bmatrix}$, type:

`>> A=[1,2,3;4,5,6;7,8,0];` where `>>` is the Matlab prompt.

- The syntax of a typical function is:

`[list_of_return_values]=func_name(input_list)`

- For example, the function `bode()` can be called with the syntax:

`[mag,pjase]=bode(G,ω)`

- Other syntaxes could also be used:

`bode(G,ω)` ; draw Bode diagram over frequency range ω

`bode(G)` ; draw Bode diagram over default frequency range

`bode(G1,G2,G3)` ; draw Bode diagrams for several systems together

Graphics Facilities in Matlab

- Two-dimensional curves can be drawn using the function **plot()**
 - The syntax is:
`plot(x1,y1,x2,y2,x3,y3,...)`
where (x1,y1) is a pair of vectors (or matrices) holding the x- and y-axis data for the plots, (x2,y2) is another pair, and so on.
 - Other functions can be used to enhance the plot, such as:
 - `grid` to add or remove grids on the plot
 - `Xlable()` and `ylable()` to add label for the axes
 - `Title()` to add a title to the plot
 - `legend`, `text()` and `gtext()` to add one or more legends to plots
- Three-dimensional plots can be made using **mesh()** and **surf()** functions
- Other enhancements can be made using the graphics processor in CtrlLAB software, which is developed for the textbook
- CtrlLAB can be downloaded from: www.siam.org/books/dc14
 - Or from: www.mathworks.com/matlabcentral/fileexchange/18-ctrlab

Mathworks Academia Resources

Learn:

- [Student Competitions](#)
- [Simulink Student Challenge](#)
- [Interactive Tutorials](#)
- [MATLAB Fundamentals Self-Paced Training](#) new
- [Books for Getting Started](#)
- [MATLAB and Simulink Student Version](#)
- [MathWorks Certification Program](#)

Teach:

- [Classroom Resources](#)
- [Hardware for Project-Based Learning](#)
- [Physical Modeling in Academia](#)
- [1400+ Books](#)
- Books by Cleve Moler
- [Webinars](#)
- [Examples Published with MATLAB](#)
- [Free Student Version Evaluation for Instructors](#)
- [Software for High Schools](#)
- [MATLAB and Simulink Interactive Kit](#)

Research:

- [Application Areas](#)
- [Newsletters](#)
- [Technical Articles](#)
- [User Stories](#)
- [Book Program for Authors](#)

URL: <http://www.mathworks.com/academia/>

