Polyspace Hands-on Workshop

Case Study

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目标

- Understanding Polyspace workflow
- Learn how to use Polyspace
  - Checking MISRA C rules violations
  - Checking defects and runtime errors
内容

- **Polyspace Overview**
  - Category of Static analysis
  - Use case of Polyspace products

- **Polyspace Hands-on workshop**
  - Description of the logic
  - Exercise 1 / 2 / 3 / 4 (Review MISRA, Defect, Code Metrics, Runtime Error)
  - Conclusion

- Q&A
内容

- Polyspace Overview
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- Q&A
静态分析功能分类

- Compiler Warnings
- Coding Rules, Code Metrics
- Formal Methods

Error Prevention

Error Detection

Bug Findings
(False negative)

Formal Methods
(No False negative)
Polyspace产品对应

- Error Prevention
  - Coding Rules, Code Metrics
  - Compiler Warnings
  - Polyspace Bug Finder
  - Polyspace Code Prover

- Error Detection
  - Bug Findings
    - (False negative)
  - Formal Methods
    - (No False negative)
  - Polyspace Bug Finder
  - Polyspace Code Prover
理解差异

- **All Bugs**
  - e.g., if(x=y) vs. if(x==y), memory leaks, partial array access

- **Statically Detectable**
  - e.g., divide by zero, overflow, illegal pointer dereferences

- **Provable**

Polyspace Bug Finder

Polyspace Code Prover
功能对比

Bug Finder

- Nothing Found
- Probable Bug

VS.

Code Prover

- Orange - Vulnerability
- Green - Reliable
- Grey – Unreachable / Dead
- Red - Faulty

- Purple - coding rule violations
Use Verification tools early in the lifecycle:

- Developers and testers
  - Prior to functional tests
- Project managers
  - Check progress of a project
- External quality assessor
  - Audit supplier’s code
- Model-Based Design
  - On generated code
Use Verification tools early in the lifecycle:

- Developers and testers – Prior to functional tests
- Project managers – Check progress of a project
- External quality assessor – Audit supplier’s code
- Model-Based Design – On generated code
Use cases

Software Engineers and/or Quality Engineers

Implementation

Software Engineers

Exercise 1/2/3/4

Design

Specification

SW Acceptance tests

Quality Assurance Engineers

SW Integration tests

Software Architects/Engineers and/or Quality Engineers

SW Unit Tests

Software Engineers and/or Quality engineers

Legend

BF Bug Finder

CP Code Prover

Your job of today
参考流程

- Find integration bugs
- Declaration mismatches
- Data race on shared variables
- Global variables usage

- Find local bugs
- Find MISRA violations
- Find “untestable” functions
- Perform Code Reviews

- Find runtime errors / unused code
- Prove absence of runtime errors on modules
- Justify MISRA violations

- Measure SW quality
- Quality report generation

Legend

- Bug Finder
- Code Prover
内容

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案例 - 安全带提示功能

Seatbelt Reminder
### 安全带提示逻辑 – 软件架构

**Inputs description**
- First parameter is input to represent Key and SeatBeltFasten. It incorporates Key and SeatBeltFasten status.
- Second parameter is input to represent current Speed. This should be processed by low-pass filter to prevent the signal from splashing in a sudden period.

**Outputs description**
- Third parameter is output to represent Seatbelt reminder icon.
- Return value of the function means error status. If there is error, it returns non-zero.

```c
signed int reminder_control (signed short inputs, float *input Curr speed, unsigned char * output)
```

- **Input (First parameter)**
  - **KEY**
    - **SeatBeltFasten** OFF: 0 (00000000 00000000)
    - **SeatBeltFasten** ON: 256 (00000001 00000000)
    - **SeatBeltFasten** CRANK: 512 (00000010 00000000)
  - **SeatBeltFasten** OFF: 0 (00000000 00000001)
    - **SeatBeltFasten** ON: 257 (00000001 00000001)
    - **SeatBeltFasten** CRANK: 513 (00000010 00000001)

- **Return value of the function**
  - means error status. If there is error, it returns non-zero.
suite int reminder_control (signed short inputs, float *input Curr speed, unsigned char * output)

**Inputs description**
- **First parameter** is input to represent Key and SeatBeltFasten. It incorporates Key and SeatBeltFasten status.
- **Second parameter** is input to represent current Speed. This should be processed by low-pass filter to prevent the signal from splashing in a sudden period.
- **First parameter** has information for KEY and SeatBeltFasten status.

<table>
<thead>
<tr>
<th>Input (First parameter)</th>
<th>KEY</th>
<th>SeatBeltFasten</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 (00000000 00000000)</td>
<td>OFF</td>
<td>Unfastened</td>
</tr>
<tr>
<td>256 (00000001 00000000)</td>
<td>ON</td>
<td>Unfastened</td>
</tr>
<tr>
<td>512 (00000010 00000000)</td>
<td>CRANK</td>
<td>Unfastened</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Input (First parameter)</th>
<th>KEY</th>
<th>SeatBeltFasten</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 (00000000 00000001)</td>
<td>OFF</td>
<td>Fastened</td>
</tr>
<tr>
<td>257 (00000001 00000001)</td>
<td>ON</td>
<td>Fastened</td>
</tr>
<tr>
<td>513 (00000010 00000001)</td>
<td>CRANK</td>
<td>Fastened</td>
</tr>
</tbody>
</table>

**Outputs description**
- **Third parameter** is output to represent Seatbelt reminder icon.
- Return value of the function means error status. If there is error, it returns non-zero.
安全带提示逻辑 – 功能描述

- Functional description
  - Sample time: 0.001 s (1000 Hz)
  - It should have low-pass filter to remove noise for the Speed value.
  - At Key Off, the Seatbelt reminder icon which is showed in the car dashboard must be switched off.
  - At Key On, the Seatbelt reminder icon status is related to the two inputs Speed and SeatBeltFasten. If the seat belt is fastened, SeatBeltIcon is always off. If the seat belt is unfastened, we consider two different cases (Low speed and High speed).
  - At Key Crank, the Seatbelt reminder icon must be switched on.

<table>
<thead>
<tr>
<th>Speed</th>
<th>KEY</th>
<th>SeatBeltFasten</th>
<th>Seatbelt Reminder icon</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt; 15 km/h (Low speed)</td>
<td>ON</td>
<td>Unfastened</td>
<td>Always ON</td>
</tr>
<tr>
<td>&gt;= 15 km/h (High speed)</td>
<td>ON</td>
<td>Unfastened</td>
<td>Flickering every 2 sec.</td>
</tr>
<tr>
<td></td>
<td>OFF</td>
<td>Fastened</td>
<td>Always OFF</td>
</tr>
<tr>
<td></td>
<td>CRANK</td>
<td>Unfastened / Fastened</td>
<td>Always ON</td>
</tr>
<tr>
<td></td>
<td>OFF</td>
<td>Unfastened / Fastened</td>
<td>Always OFF</td>
</tr>
</tbody>
</table>
内容

- Polyspace Overview
  - Category of Static analysis
  - Use case of Polyspace products

- Polyspace Hands-on workshop
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  - Exercise 1 / 2 / 3 / 4 (Review MISRA, Defect, Code Metrics, Runtime Error)
  - Conclusion

- Q&A
Exercises

- **Exercise 1: Create Polyspace project and Run it**
  1. Simulate the logic of the code and understand problems of it
  2. Create Bug Finder project first and Run it

- **Exercise 2: Review MISRA violations and defects**
  1. Enable all rules of MISRA C:2012 and most of defects
  2. Review all of them and try to remove most of violations and defects
  3. Run analysis for the modified code repeatedly
Exercise概览

- **Exercise 3 : Review Code Metrics**
  1. Enable option to calculate Code Metrics
  2. Review the result and modify source code to comply with HIS
  3. Run analysis for the modified code repeatedly

- **Exercise 4 : Review Code Prover result**
  1. Import Bug Finder project into Code Prover and Run it
  2. Run verification with Code Prover
  3. Review all MISRA violations and RTEs
  4. Do anything to make ALL GREEN!  (Please don’t remove all source code.)
系统需求理解 – 期望行为

<table>
<thead>
<tr>
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<th>Seatbelt Reminder icon</th>
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<tbody>
<tr>
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<td>ON</td>
<td>Unfastened</td>
<td>Always ON</td>
</tr>
<tr>
<td>(Low speed)</td>
<td></td>
<td></td>
<td></td>
</tr>
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<td>ON</td>
<td>Unfastened</td>
<td>Flickering every 2 sec.</td>
</tr>
<tr>
<td>(High speed)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>-</td>
<td>ON</td>
<td>Fastened</td>
<td>Always OFF</td>
</tr>
<tr>
<td>-</td>
<td>CRA</td>
<td>Unfastened / Fastened</td>
<td>Always ON</td>
</tr>
<tr>
<td>-</td>
<td>OFF</td>
<td>Unfastened / Fastened</td>
<td>Always OFF</td>
</tr>
</tbody>
</table>
系统需求理解 – 问题发现

<table>
<thead>
<tr>
<th>Speed</th>
<th>KEY</th>
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<th>Seatbelt Reminder icon</th>
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<tbody>
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<td>ON</td>
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</tr>
<tr>
<td>(Low speed)</td>
<td></td>
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</tr>
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<td></td>
<td></td>
</tr>
<tr>
<td>-</td>
<td>ON</td>
<td>Fastened</td>
<td>Always OFF</td>
</tr>
<tr>
<td>-</td>
<td>CRA NK</td>
<td>Unfastened /</td>
<td>Always ON</td>
</tr>
<tr>
<td>-</td>
<td>OFF</td>
<td>Fastened</td>
<td>Always OFF</td>
</tr>
<tr>
<td>-</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- Errnumber when low speed
- Rapid flash when high speed
- …
代码审查...

```c
signed int reminder_control (signed short inputs, float *input_Curr_speed, unsigned char * output)
{
    int errnumber;
    unsigned char input_SeatBeltFasten, input_KEY;
    static int timer_cnt;
    static unsigned char output_SeatBeltIcon = SB_ICON_OFF;
    signed int gFiltered_speed = 0;

    if (((unsigned short)inputs>>8) == 1) {
        input_SeatBeltFasten = 1;
    } else {
        input_SeatBeltFasten = 0;
    }

    switch (((unsigned short)inputs>>8)) {
        case 0:
            Input_KEY = 0;
            break;
        case 1:
            Input_KEY = 1;
            break;
        case 2:
            Input_KEY = 2;
            break;
    }

    errnumber = lowPassFilter_SpeedSignal(gFiltered_speed, input_Curr_speed);

    if (errnumber == 0) {
        if (KEY_OFF == input_KEY) {
            output_SeatBeltIcon = SB_ICON_OFF;
        } else if (KEY_ON == input_KEY) {
            if (SB_UNFASTENED == input_SeatBeltFasten) {
                if (gFiltered_speed < 15) {
                    output_SeatBeltIcon = SB_ICON_ON;
                } else {
                    if (timer_cnt > COUNT_FOR_BLINK) {
                        if (output_SeatBeltIcon == SB_ICON_OFF) {
                            output_SeatBeltIcon = SB_ICON_ON;
                        } else {
                            output_SeatBeltIcon = SB_ICON_OFF;
                        }
                        timer_cnt++;
                    } else {
                        output_SeatBeltIcon = SB_ICON_OFF;
                    }
                }
            }
        } else {
            output_SeatBeltIcon = SB_ICON_OFF;
        }
    }

    *output = output_SeatBeltIcon;

    return errnumber;
}
```
Exercise 1

Create project and Run it
- Create project manually
- Create project by using Configuration template
- Default project location
  - C:\polyspace_workshop\Polyspace_Workspace

- Download results to
  - C:\polyspace_workshop\Polyspace_Workspace\DownloadResults

- Text editor configuration
  - Notepad++
Exercise 1 - 创建并运行项目

- Create Bug Finder project manually
Exercise 1 - 创建并运行项目

- Add source files in the project, and configure the project

**Major configuration**
- **Language**: C
- **32bit CPU**
  - long long/double/long double: 64 bits
  - pointer: 32 bits
  - align: 32 bits
- Checked all rules of MISRA C:2012
- Detect defects customized for all defects except Security and Tainted data
Exercise 1 - 创建并运行项目

Major configuration
✓ Language : C
✓ 32bit CPU
  - long long/double/long double: 64 bits
  - pointer: 32 bits
  - align: 32 bits
✓ Checked all rules of MISRA C:2012
✓ Detect defects customized for all defects except Security and Tainted data

Bug Finder Analysis
✓ Find defects [custom]
  - Defects
    - Numerical
    - Static memory
    - Dynamic memory
    - Data flow
    - Resource management
    - Programming
    - Concurrency
    - Security
    - Tainted data
    - Good practice
Exercise 1 - 创建并运行项目

- Run the project in Bug Finder
Tip #1 – 项目模板

- Create Bug Finder project by using Configuration Template
Exercise 2

Remove MISRA Violations and Defects
- Create new project file for this exercise
- Remove/Justify MISRA C:2012 Rule violations
Exercise 2 & 3 – 覆盖内容

- Error Prevention
- Error Detection
- Bug Findings (False negative)
- Coding Rules, Code Metrics
- Compiler Warnings
- Formal Methods (No False negative)
Exercise 2 – MISRA检查和软件缺陷查找

- Review all MISRA violations with Bug Finder
- Create new project with source files in 2_Review_MISRA_violations_and_Defects
- Review MISRA violations first
Tip #2 – 获取帮助

- Click �媾 to see Contextual Help
  - Modify the code as you wish to remove this violation
Exercise 2 – MISRA检查和软件缺陷查找

- Review an easy MISRA violation and fix it
  - Check violation related to Directive 4.5 and Directive 4.6
  - Modify the code as you wish to remove this violation
Exercise 2 – MISRA检查和软件缺陷查找

- Review some MISRA violations, and justify it by using pre-justification if necessary
  - Justify violations related to Rule 2.3 and Rule 2.5.
  - Justify violations through Polyspace client GUI or comments
  - Add comments in source code to justify violations.
    - You can use pre-justification for a line or a section.
Exercise 2 – MISRA检查和软件缺陷查找

- **Review all MISRA violations**
  - You may modify source code to remove violations and defects!
  - Refer documentation through Contextual Help

- **Review all defects in the same way**
  - If you remove a defect, MISRA violation can be disappeared.
Tip #3 – 查找功能

- Search whatever you want in Polyspace
  - **Ctrl + F** enables you may search anything in Polyspace project
  - When you select a item, it highlights the location of the item
Exercise 2 – MISRA 检查和软件缺陷查找

- Example answer - MISRA C:2012 - Rule 8.2

```c
extern sint32_t reminder_control (sint16_t, float *, uint8_t *);
extern sint32_t reminder_control (sint16_t inputs, float32_t *curr_speed, uint8_t *output);
```

- Example answer - MISRA C:2012 - Rule 8.7

```c
float32_t gPrev_speed;
static float32_t gPrev_speed;
```

- Example answer - MISRA C:2012 - Rule 8.13

```c
static sint32_t lowPassFilter_speedSignal (sint32_t *output_filtered_speed, float32_t *input_curr_speed);
static sint32_t lowPassFilter_speedSignal (sint32_t *output_filtered_speed, const float32_t *input_curr_speed);
```
Exercise 2 – MISRA检查和软件缺陷查找

- Example answer - MISRA C:2012 - Rule 9.1 and Non-initialized variable

```c
} else {
    if (tmp_filtered_speed < 0.5F) {
        *output_Filtered_speed = 0;
    } else {
        *output_Filtered_speed = 0;
    }
}

gPrev_speed = tmp_filtered_speed;
return errnumber;
```

```c
} else {
    if (tmp_filtered_speed < 0.5F) {
        *output_Filtered_speed = 0;
    } else {
        *output_Filtered_speed = 0;
    }
    errnumber = 0;
}

gPrev_speed = tmp_filtered_speed;
return errnumber;
```
Exercise 2 – MISRA检查和软件缺陷查找

- Example answer - MISRA C:2012 - Rule 16.4

```c
switch (((uint16_t)inputs&0xFFFF00)>>8)) {
    case 0:
        input_KEY = 0;
        break;
    case 1:
        input_KEY = 1;
        break;
    case 2:
        input_KEY = 2;
        break;
    }
```

```c
switch (((uint16_t)inputs&0xFFFF00)>>8)) {
    case 0:
        input_KEY = 0;
        break;
    case 1:
        input_KEY = 1;
        break;
    case 2:
        input_KEY = 2;
        break;
    default:
        input_KEY = 3;
        break;
    }
```
Exercise 2 – MISRA检查和软件缺陷查找

- Example answer - MISRA C:2012 - Rule 10.1 and 10.4

```c
if (((uint16_t)inputs&0x00FF) == 1) {
    input_SeatBeltFasten = 1;
} else {
    input_SeatBeltFasten = 0;
}
```

```c
if (((uint16_t)inputs&0x00FF) == 1) {
    input_SeatBeltFasten = 1;
} else {
    input_SeatBeltFasten = 0;
}
switch (((uint16_t)inputs&0x2000)>>8)) {  
```

- Example answer - MISRA C:2012 - Rule 16.4 and Dead Code

```c
} else {
    if (tmp_filtered_speed < 0.5) {
        *output_filtered_speed = 0;
    } else {
        *output_filtered_speed = 0;
    }  
    errnumber = 0;
}
```

```c
} else {
    *output_filtered_speed = 0;
    errnumber = 0;
}
```
Exercise 2 – 结果对比

<table>
<thead>
<tr>
<th>Family</th>
<th>ID</th>
<th>Information</th>
</tr>
</thead>
<tbody>
<tr>
<td>Defect</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>Data flow</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>MISRA C:2012</td>
<td>22</td>
<td></td>
</tr>
<tr>
<td>2 Unused code</td>
<td>6</td>
<td></td>
</tr>
<tr>
<td>4 Code design</td>
<td>8</td>
<td></td>
</tr>
<tr>
<td>7 Literals and constants</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>8 Declarations and definitions</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>9 Initialization</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>10 The essential type model</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>14 Control statement expressions</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>16 Switch statements</td>
<td>1</td>
<td></td>
</tr>
</tbody>
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<td>2</td>
<td></td>
</tr>
<tr>
<td>8 Declarations and definitions</td>
<td>1</td>
<td></td>
</tr>
</tbody>
</table>
Exercise 3

Review Code Metrics and Increase/Decrease it
- Create new project file for this exercise
  - Comply with HIS metrics
Exercise 3 - 代码度量

- Review all Code Metrics and refer documentation through Contextual Help
  - Create new project with source files in 3_Review_Code_Metrics
  - Enable option to calculate Code Metrics and Run analysis
Exercise 3 - 代码度量

- Check which metrics cannot comply with HIS metrics
  - Apply review scope for HIS
  - Open user-defined review scope to see MISRA violations and Code Metrics together.

![Image of software interfaces showing integration of MISRA violations and Code Metrics]
Exercise 3 - 代码度量

- Apply user-defined review scope for Defects, MISRA and HIS metrics
  - You may make a new review scope to see MISRA violations and Code Metrics together.
  - How do you make it to comply with HIS metrics?
Exercise 3 - 代码度量

- Consider how to decrease/increase code metrics
  - Let’s see Cyclomatic Complexity and Number of Call Levels

<table>
<thead>
<tr>
<th>Cyclomatic Complexity</th>
<th>Number of Call Levels</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Description</strong></td>
<td></td>
</tr>
<tr>
<td>This metric specifies the number of linearly independent paths through the source code. To calculate this metric, add 1 to the number of decision points in your code. A decision point is a statement that causes your program to branch into two paths. For example, at an if statement, your program can either enter the if branch or not. The recommended upper limit for this metric is 10. If the cyclomatic complexity is high, the code is difficult to read and can cause more runtime checks. Therefore, try to limit the value of this metric.</td>
<td>Maximum depth of nesting of control flow structures</td>
</tr>
<tr>
<td><strong>Description</strong></td>
<td></td>
</tr>
<tr>
<td>This metric specifies the maximum nesting depth of control flow statements such as if, switch, for, or while in a function. A function without control-flow statements has a call level 1. The recommended upper limit for this metric is 4. For better readability of your code, try to enforce an upper limit for this metric.</td>
<td></td>
</tr>
</tbody>
</table>

- Recommended upper limit: 10 for Cyclomatic Complexity, 4 for Number of Call Levels
- If you want to decrease calculated value,
  - ✓ Decrease the number of decision points such as if condition, switch/case and for/while loop.
Let’s see example code to improve code metrics - 1

This is not the best answer but an example answer.

Replacement of left code with right code can decrease another metrics.

```c
/* 0(LSB) ~ 7th bit of inputs variable means status of SeatBeltFasten. */
if (((uint16_t)inputs&0x00FF) == 3) {
    input_SeatBeltFasten = 1;
} else {
    input_SeatBeltFasten = 0;
}

/* 8 ~ 15th bit (MSB) of inputs variable means status of Key. */
switch (((uint16_t)inputs&0xFFFF)>>8)) {  
   case 0:  
     /* Key is at Off position */
     input_KEY = 0;
     break;
   case 1:  
     /* Key is at On position */
     input_KEY = 1;
     break;
   case 2:  
     /* Key is at Crank position */
     input_KEY = 2;
     break;
   default:  
     /* erroneous status */
     input_KEY = 3;
     break;
}

/* Below code separates the incorporated inputs for Key and SeatBeltFasten. */
/* 0(LSB) ~ 7th bit of inputs variable means status of SeatBeltFasten. */
/* 8 ~ 15th bit (MSB) of inputs variable means status of Key. */
input_KEY = (uint8_t)((((uint16_t)inputs&0x00FF)<<8));
input_SeatBeltFasten = (uint8_t)((uint16_t)inputs&0xFFFF);

if (((input_KEY > 1)&&(input_SeatBeltFasten < 1)) {  
    /* all inputs are strange */
    errnum = -1;
} else if (input_KEY > 2) {  
    /* input_KEY input is strange */
    errnum = -2;
} else if (input_SeatBeltFasten > 1) {
    /* input_SeatBeltFasten is strange */
    errnum = -3;
} else {
    errnum = 0;
}
```
Exercise 3 - 代码度量

- Let’s see example code to improve code metrics - 1
  - Replacement of left code with right code can decrease some metrics.

```c
if (errnumber == 0) {
  if (KEY_OFF == input_KEY) {
    output_SealetBeltIcon = SB_ICON_OFF;
  } else if (KEY_ON == input_KEY) {
    if (SB_UNFASTENED == input_SealetBeltFasten) {
      if (gFiltered_speed < 15) {
        output_SealetBeltIcon = SB_ICON_ON;
      } else {
        if (timer_cnt > COUNT_FOR_BLINK) {
          if (output_SealetBeltIcon == SB_ICON_OFF) {
            output_SealetBeltIcon = SB_ICON_ON;
          } else {
            output_SealetBeltIcon = SB_ICON_OFF;
          }
        }
        timer_cnt++;
      }
    } else {
      output_SealetBeltIcon = SB_ICON_OFF;
    }
  } else if (KEY_CRANK == input_KEY) {
    output_SealetBeltIcon = SB_ICON_ON;
  } else {
    errnumber = -1;
  }
}
```
Exercise 3 - 代码度量

- Consider how to decrease Language Scope

<table>
<thead>
<tr>
<th>Language Scope</th>
</tr>
</thead>
<tbody>
<tr>
<td>Language scope</td>
</tr>
</tbody>
</table>

**Description**

This metric measures the cost of maintaining or changing a function. It is calculated as:

\[
\frac{(N1 + N2)}{(n1 + n2)}
\]

Here:
- \(N1\) is the number of occurrences of operators.
- \(N2\) is the number of occurrences of operands.
- \(n1\) is the number of distinct operators.
- \(n2\) is the number of distinct operands.

The recommended upper limit for this metric is 10. For lower maintenance cost for a function, try to enforce an upper limit on this metric. For instance, if the same operand occurs many times, to change the operand name, you have to make many substitutions.

- Recommended upper limit: 4
- If you want to decrease calculated value,
  - Increase the number of distinct operators/operands
  - Decrease the number of occurrences of operator/operands
- If a function has very high value, it's better to separate the function to multiple functions.

- Previous activities already affected this metrics to be decreased.
- BUT! *It doesn't comply with limit of HIS metrics. What will you do?*
Exercise 3 - 代码度量

- Let’s see example code to improve Language Scope
  - Separate a part of source code as a function.

```c
input_KEY = (uint8_t)(((uint16_t)inputs&0x22000)>>8);
input_SeatBeltFasten = (uint8_t)(((uint16_t)inputs&0x00ff00)>>8);

if ((input_KEY > 2)&&(input_SeatBeltFasten > 1)){
    /* all inputs are strange */
    errnumber = -4;
} else if (input_KEY > 2) {
    /* input_KEY input is strange */
    errnumber = -5;
} else if (input_SeatBeltFasten > 1) {
    /* input_SeatBeltFasten is strange */
    errnumber = -6;
} else {
    errnumber = 0;
}
```

```c
static sint32_t separate_inputs_to_Key_and_SeatBeltFasten(sint16_t inputs, &input_SeatBeltFasten, &input_KEY);

KEY = (uint8_t)(((uint16_t)inputs&0x22000)>>8);
SeatBeltFasten = (uint8_t)(((uint16_t)inputs&0x00ff00)>>8);

if ((KEY > 2)&&(SeatBeltFasten > 1)){
    /* all inputs are strange */
    errnumber = -4;
} else if (KEY > 2) {
    /* KEY input is strange */
    errnumber = -5;
} else if (SeatBeltFasten > 1) {
    /* SeatBeltFasten is strange */
    errnumber = -6;
} else {
    *input_SeatBeltFasten = SeatBeltFasten;
    *input_KEY = KEY;
    errnumber = 0;
}

return errnumber;
```
Exercise 3 – 结果对比

Defects, HIS, ...

<table>
<thead>
<tr>
<th>Family</th>
<th>ID</th>
<th>Information</th>
</tr>
</thead>
<tbody>
<tr>
<td>MISRA C:2012</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>2 Unused code</td>
<td>3</td>
<td></td>
</tr>
<tr>
<td>8 Declarations and definitions</td>
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</tr>
<tr>
<td>Code Metrics</td>
<td>4</td>
<td></td>
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<td></td>
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<tr>
<td>Comment Density</td>
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</tr>
<tr>
<td>! ⋆ 8</td>
<td>Value: 8</td>
<td></td>
</tr>
<tr>
<td>Function Metrics</td>
<td>3</td>
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</tr>
<tr>
<td>Cyclomatic Complexity</td>
<td>1</td>
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</tr>
<tr>
<td>! ⋆ 12</td>
<td>Value: 13</td>
<td></td>
</tr>
<tr>
<td>Language Scope</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>! ⋆ 22</td>
<td>Value: 4.9</td>
<td></td>
</tr>
<tr>
<td>Number of Call Levels</td>
<td>1</td>
<td></td>
</tr>
<tr>
<td>! ⋆ 20</td>
<td>Value: 7</td>
<td></td>
</tr>
</tbody>
</table>
Exercise 4

Review Runtime errors and additional issues
- Import previously used project file for this exercise
  - Review red or orange checks
  - Do anything to make ALL GREEN
Exercise 4 – 内容

- Error Prevention
  - Coding Rules, Code Metrics
  - Compiler Warnings

- Error Detection
  - Formal Methods (No False negative)
  - Bug Findings (False negative)
功能对比

**Bug Finder**
- Nothing Found
- Probable Bug

**Code Prover**
- Orange - Vulnerability
- Green - Reliable
- Grey – Unreachable / Dead
- Red - Faulty

Purple - coding rule violations
To prove the absence of errors, the Polyspace verification accounts for all possible execution paths using abstract interpretation.

```c
signed char x, y;

x = random_char();
if (x > 0) {
    x = 5;
} else if (x != 0) {
    y = 100 / (x + 1);
} else {
    y = 200 / x;
}

printf("%d", x);
```
Exercise 4 – 运行时错误检查

- How to run from Bug Finder to Code Prover in 2017a
Exercise 4 – 运行时错误检查

- Run the project in Code Prover
Exercise 4 – 运行时错误检查

- Review all orange checks and additional MISRA violations
  - Use the imported project
  - Or Create new project with source files in 4_Review_RTEs
  - Code Prover considers all of possible inputs and paths by default
Exercise 4 – 运行时错误检查

- Review all orange checks and additional MISRA violations
  - Analyze orange checks if it’s really problem or not
  - For instance, let’s see Illegally dereferenced pointer (IDP)
Exercise 4 – 运行时错误检查

- Review all orange checks and additional MISRA violations
  - Analyze orange checks if it’s really problem or not
  - For instance, let’s see Illegally dereferenced pointer (IDP)

```c
static s1nt32_t lowPassFilter_SpeedSignal (s1nt32_t *output_Filtered_speed, const float32_t *input_curr_speed)
{
    s1nt32_t errnumber;
    float32_t tmp_filtered_speed;

    /* This is relevant to requirement 5.5. 
     * weight for previous input is 0.9 and weight for current input is 0.1. 
     */
    tmp_filtered_speed = (0.1F * (*input_curr_speed)) + (0.9F * (*gPrev_speed));
```

- Illegally dereferenced pointer
  Warning: pointer may be outside its bounds

  This check may be an issue related to unbounded input values

  If appropriate, applying DRS to curr_speed (argument number 2 of function reminder_control, defines Dereference of parameter 'input_curr_speed' (pointer to const float 32, size: 32 bits):
    Pointer may be null.
Exercise 4 – 运行时错误检查

- Add a code to check NULL pointer
  - Modify source code to add NULL_PTR
  - Check pointer before use if it’s not NULLs

```c
if (((void*)1) != input_curr_speed) {
    tmp_filtered_speed = (0.1F * (-input_curr_speed)) + (0.9F * (aPrev_speed));
```

- You may use Constraint setup to specify data range for function inputs
  - It can specify data range for global variable and return values of stubbed function

```c
if (tmp_filtered_speed >= 0.5F)
    if (tmp_filtered_speed
        errnumber = -1;
```

- What will you do for the variable for *output*?
Tip #5 - 数据约束设置

- Specify constraints for global variables, function inputs and return values of stubbed functions
Exercise 4 – 运行时错误检查

- Review another orange check (Overflow)
  - What is the problem of orange overflow check?
    ```
    if (gFiltered_speed >= 15) {
        if (timer_cnt > COUNT_FOR_BLINK)
        {
            output_SeatBeltIcon := 0x1U;
        }
        timer_cnt++;
    }
    ```
  - Signed integer overflow leads to undefined behavior. **How can I fix it?**
  - **Oops**, I forgot to set it to zero when the value exceeds COUNT_FOR_BLINK.
    ```
    if (gFiltered_speed >= 15) {
        if (timer_cnt > COUNT_FOR_BLINK)
        {
            output_SeatBeltIcon := 0x1U;
            timer_cnt = 0;
        }
        timer_cnt++;
    }
    ```
Exercise 4 – 结果对比

Two ISRA violations are disappeared by removal of orange checks.
内容

- Polyspace Overview
  - Category of Static analysis
  - Use case of Polyspace products

- Polyspace Hands-on workshop
  - Description of the logic
  - Exercise 1 / 2 / 3 / 4 (Review MISRA, Defect, Code Metrics, Runtime Error)
  - Conclusion

- Q&A
Conclusion

Let’s simulate the final version of source code
Conclusion – 最终结果仿真

- Simulate the final version of source code
### Summary of Issues…

<table>
<thead>
<tr>
<th>Issues we faced!</th>
<th>What’s improved!</th>
</tr>
</thead>
</table>
| Lamp doesn’t work if speed is slower than 0.5. or Errnumber shows strange value. | - Remove Non-initialized variable and dead code  
  - Initialize `errnumber` in `lowPassFilter_SpeedSignal`  
  - This is detected by Bug Finder’s Defects and MISRA C:2012 checker.  
  - Dead code is directly related to this bug but it’s meaningless. |
| Lamp flickers too fast if speed is faster than 15.                             | - Remove overflow occurs by `timer_cnt`  
  - Set `timer_cnt` to zero(0) in `reminder_control` function.  
  - This runtime error is detected as orange overflow check by Code Prover. |
| MISRA C:2012 Guide line          | Modify / Justify source code  
  - It’s helpful to avoid runtime errors. |
| Code Metrics                     | Improve structure of source code by modification  
  - It’s good to improve readability and maintenance cost. |
Use Verification tools early in the lifecycle:

- Developers and testers – Prior to functional tests
- Project managers – Check progress of a project
- External quality assessor – Audit supplier’s code
- Model-Based Design – On generated code

Make yours Bug Free ZONE EARLIER!
Q & A