

# Latest Features in Embedded Coder

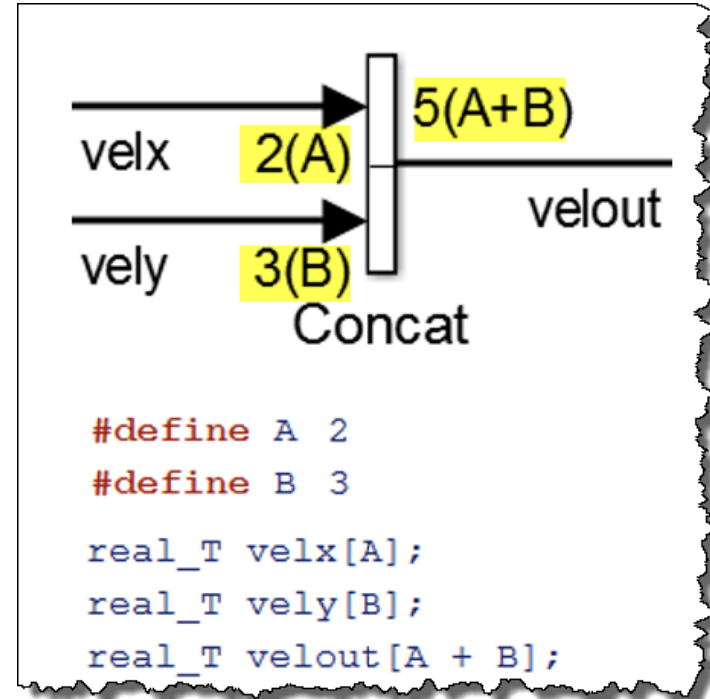
March 2016

**R2016a**

# Compile-Time Dimensions

## Generate compiler directives for signal dimensions

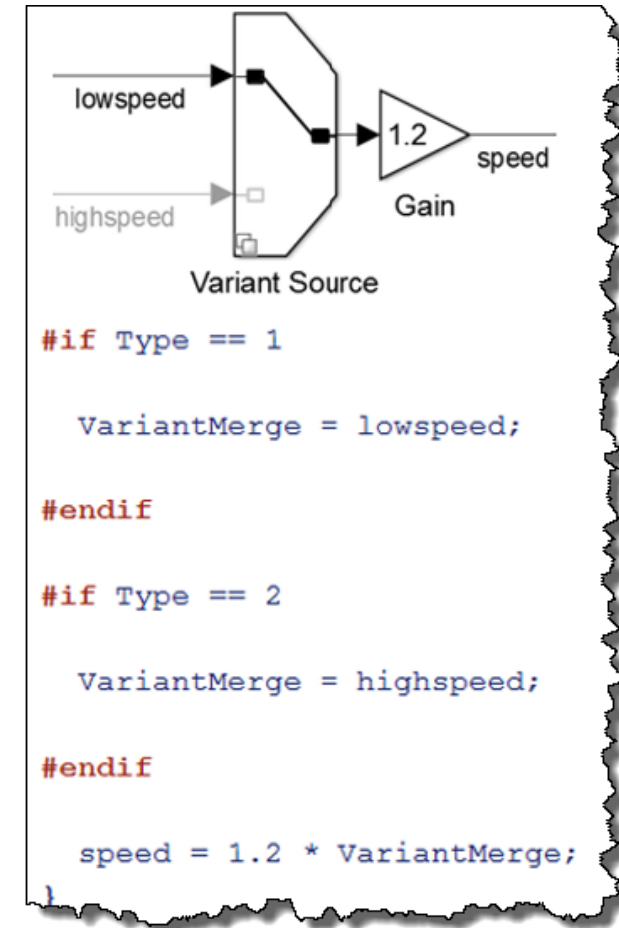
- Use `Simulink.Parameter` (as in a MATLAB expression) to represent a dimension value
- Propagate dimension symbols throughout model during simulation



# Compile-Time Variants

## Generate compiler directives based on Variant Source/Sink blocks

- Finely place variant choices within models
- Generate code for only the active variant, or, generate preprocessor conditionals and decide the active variant at compilation time



# Enhanced C++ Code Generation

## Use referenced models with multitasking, export-functions, and virtual buses

- C++ class interface supports:
  - Multitasking for model references
  - Export function-call subsystems
  - Virtual buses for crossing model boundaries

Tasking and sample time options

Periodic sample time constraint: Unconstrained

Tasking mode for periodic sample times: MultiTasking

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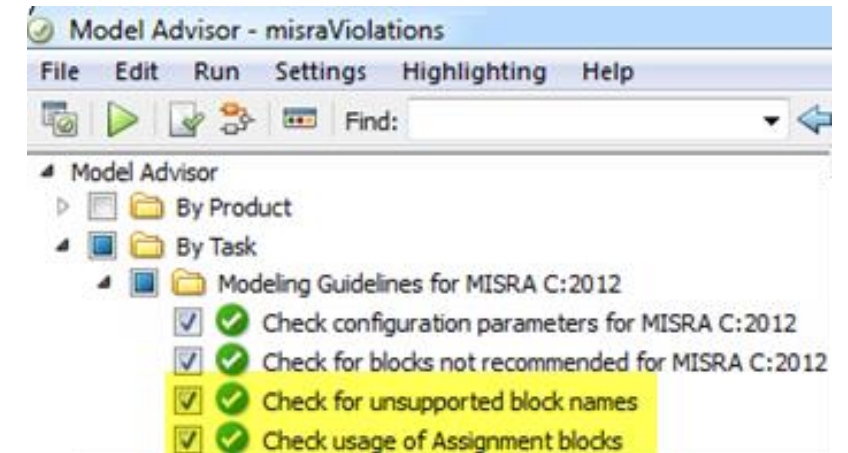
```

class multiclass{
public:
    void initialize();
    void step0();
    void step1();
    multirateClass();
    ~multirateClass();
  
```

# MISRA C:2012 Compliance

## Check block names and Assignment blocks

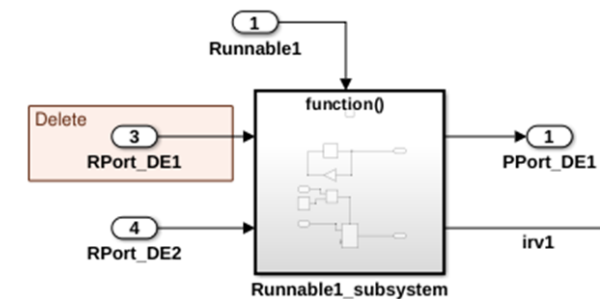
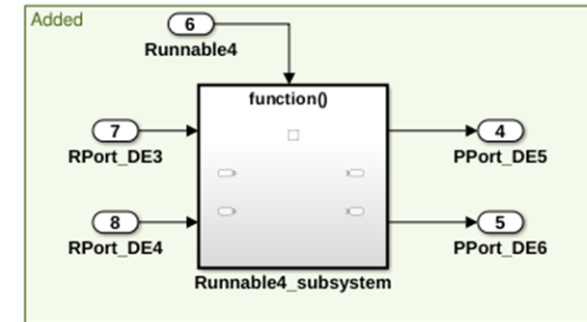
- Use Model Advisor to:
  - Check for block names that contain a / character
  - Check usage of assignment block initializations



# Enhanced AUTOSAR Round-Trip Workflow

Merge AUTOSAR authoring tool changes into Simulink using ARXML files

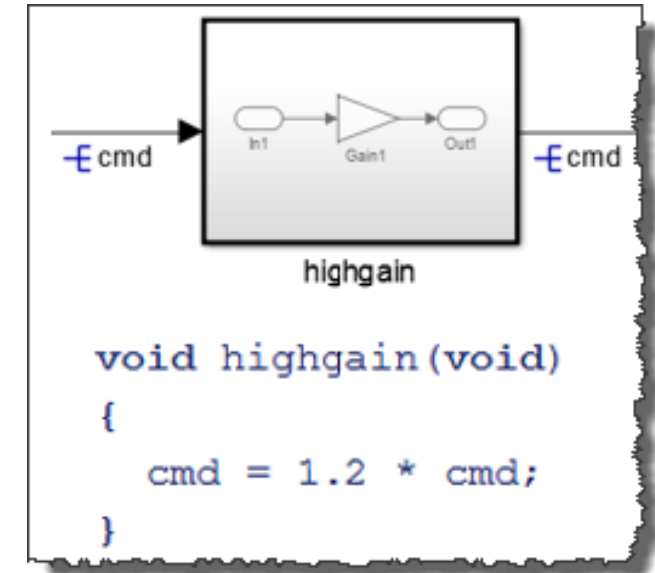
- Automate Simulink block additions and deletions with highlighting
- Support CompuMethods with LINEAR and TEXTTABLE COMPU-SCALES
- Enhance control of AUTOSAR package path specification



# Data Buffer Reuse

Use same variable for signals in a path as input and output

- Specify IN/OUT signals at a block and subsystem boundary, or blocks and subsystems in a path
- Share `Reusable` custom storage class



# Buffer Reuse Across Model Blocks

## Use same variable for input and output arguments of MATLAB Function and Model blocks

- Previously, there was no buffer reuse across model blocks, and a data copy occurred prior to each model step function
- In R2016a, input and output buffers of Model blocks are reused

### R2015b

```
(void) memcpy(&MdlA[0], &Add[0], 9*sizeof(real));
MDLOBJ1.step(&MdlA[0], &Add1[0]);
(void) memcpy(&MdlB[0], &MdlA[0], 9*sizeof(real));
MDLOBJ2.step(&MdlB[0], &Add1[0]);
```

### R2016a

```
MDLOBJ1.step(&MdlAB[0], &Add1[0]);
MDLOBJ2.step(&MdlAB[0], &Add1[0]);
memcpy(&parent.Out1[0], &MdlAB[0],
      (uint32_T)(9U * sizeof(real)));
```



# Data Access Support for SIL and PIL

## Use vector `GetSet` custom storage class and C++ parameter access methods

SIL and PIL support for:

- `GetSet` custom storage class for vector signals and parameters
- Method and Inlined method options

```
double get_inVector(int index)
{
    return ex_getset_data.vectors.inVector[index];
}

void set_inVector(int index, double value)
{
    ex_getset_data.vectors.inVector[index] = value;
}
```

# Dual Core TI C2000 Delfino Support

## Code generation for Texas Instruments Delfino F2833x, F2837xS/D, and C2834x

- Real-time parameter tuning and logging using external mode
- Perform processor-in-the-loop (PIL) with execution profiling
- Block libraries for on-chip peripherals
- Generate code for both cores of F2837xD

