

## R2020b Updates Release Notes

### *Information about bugs fixed and important limitations for R2020b Updates*

#### Bugs Fixed

Each R2020b Update contains bug fixes to R2020b, including all the fixes from previous updates.

- **R2020b Update 6:** [Bugs fixed](#) in this update July 27, 2021  
Update 6 also:
  - Improves performance in AUTOSAR Blockset.
  - Improves stability in MATLAB Coder and System Composer.
- **R2020b Update 5:** [Bugs fixed](#) in this update February 18, 2021
- **R2020b Update 4:** [Bugs fixed](#) in this update January 22, 2021  
Update 4 also:
  - Improves performance of the Display, Gauge, Lamp, and MultiStateImage blocks of the Dashboard Library.
- **R2020b Update 3:** [Bugs fixed](#) in this update December 10, 2020
- **R2020b Update 2:** [Bugs fixed](#) in this update November 17, 2020  
Update 2 also:
  - Improves performance when opening models with Subsystem Reference blocks that contain Stateflow charts.
- **R2020b Update 1:** [Bugs fixed](#) in this update October 15, 2020  
Update 1 also:
  - Improves performance in Simulink Design Verifier analysis.
  - Improves scalability and performance in System Composer.
  - Fixes an example in Simscape Electrical.

To learn more about Updates, see [Updates: Frequently Asked Questions](#).

#### Important Limitations

- MATLAB Parallel Server, MATLAB Parallel Server for Amazon EC2, and MATLAB Parallel Server - Private Cloud: Install the Update on all client and worker installations.
- MATLAB Compiler and MATLAB Compiler SDK: After installing the Update, test your deployed applications using the version of the MATLAB Runtime installed on the system of the end-user or MATLAB Production Server.