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Parallel Computing Toolbox Product Description

Perform parallel computations on multicore computers, GPUs, and computer clusters

Parallel Computing Toolbox lets you solve computationally and data-intensive problems using multicore processors, GPUs, and computer clusters. High-level constructs—parallel for-loops, special array types, and parallelized numerical algorithms—let you parallelize MATLAB® applications without CUDA or MPI programming. You can use the toolbox with Simulink® to run multiple simulations of a model in parallel.

The toolbox lets you use the full processing power of multicore desktops by executing applications on workers (MATLAB computational engines) that run locally. Without changing the code, you can run the same applications on a computer cluster or a grid computing service (using MATLAB Distributed Computing Server™). You can run parallel applications interactively or in batch.

Key Features

- Parallel for-loops (parfor) for running task-parallel algorithms on multiple processors
- Support for CUDA-enabled NVIDIA GPUs
- Full use of multicore processors on the desktop via workers that run locally
- Computer cluster and grid support (with MATLAB Distributed Computing Server)
- Interactive and batch execution of parallel applications
- Distributed arrays and spmd (single-program-multiple-data) for large dataset handling and data-parallel algorithms
Parallel Computing Support in MathWorks Products

Parallel Computing Toolbox provides you with tools for a local cluster of workers on your client machine. MATLAB Distributed Computing Server software allows you to run as many MATLAB workers on a remote cluster of computers as your licensing allows.

Most MathWorks products enable you to run applications in parallel. For example, Simulink models can run simultaneously in parallel, as described in “Run Multiple Simulations” (Simulink). MATLAB Compiler™ and MATLAB Compiler SDK™ software let you build and deploy parallel applications; for example, see the “Parallel Computing” section of MATLAB Compiler “Standalone Applications” (MATLAB Compiler).

Several MathWorks products now offer built-in support for the parallel computing products, without requiring extra coding. For the current list of these products and their parallel functionality, see:

Key Problems Addressed by Parallel Computing

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Run Parallel for-Loops (parfor)

Many applications involve multiple segments of code, some of which are repetitive. Often you can use for-loops to solve these cases. The ability to execute code in parallel, on one computer or on a cluster of computers, can significantly improve performance in many cases:

- Parameter sweep applications
  - Many iterations — A sweep might take a long time because it comprises many iterations. Each iteration by itself might not take long to execute, but to complete thousands or millions of iterations in serial could take a long time.
  - Long iterations — A sweep might not have a lot of iterations, but each iteration could take a long time to run.

Typically, the only difference between iterations is defined by different input data. In these cases, the ability to run separate sweep iterations simultaneously can improve performance. Evaluating such iterations in parallel is an ideal way to sweep through large or multiple data sets. The only restriction on parallel loops is that no iterations be allowed to depend on any other iterations.

- Test suites with independent segments — For applications that run a series of unrelated tasks, you can run these tasks simultaneously on separate resources. You might not have used a for-loop for a case such as this comprising distinctly different tasks, but a parfor-loop could offer an appropriate solution.

Parallel Computing Toolbox software improves the performance of such loop execution by allowing several MATLAB workers to execute individual loop iterations simultaneously. For example, a loop of 100 iterations could run on a cluster of 20 MATLAB workers, so that simultaneously, the workers each execute only five iterations of the loop. You might not get quite 20 times improvement in speed because of communications overhead and
network traffic, but the speedup should be significant. Even running local workers all on the same machine as the client, you might see significant performance improvement on a multicore/multiprocessor machine. So whether your loop takes a long time to run because it has many iterations or because each iteration takes a long time, you can improve your loop speed by distributing iterations to MATLAB workers.

**Execute Batch Jobs in Parallel**

When working interactively in a MATLAB session, you can offload work to a MATLAB worker session to run as a batch job. The command to perform this job is asynchronous, which means that your client MATLAB session is not blocked, and you can continue your own interactive session while the MATLAB worker is busy evaluating your code. The MATLAB worker can run either on the same machine as the client, or if using MATLAB Distributed Computing Server, on a remote cluster machine.

**Partition Large Data Sets**

If you have an array that is too large for your computer's memory, it cannot be easily handled in a single MATLAB session. Parallel Computing Toolbox software allows you to distribute that array among multiple MATLAB workers, so that each worker contains only a part of the array. Yet you can operate on the entire array as a single entity. Each worker operates only on its part of the array, and workers automatically transfer data between themselves when necessary, as, for example, in matrix multiplication. A large number of matrix operations and functions have been enhanced to work directly with these arrays without further modification; see “Using MATLAB Functions on Distributed Arrays” on page 5-24 and “Using MATLAB Constructor Functions” on page 5-9.
Introduction to Parallel Solutions

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“Run a Batch Parallel Loop” on page 1-7  
“Run Script as Batch Job from the Current Folder Browser” on page 1-8

**Run a Batch Job**

To offload work from your MATLAB session to run in the background in another session, you can use the `batch` command. This example uses the `for`-loop from the previous example, inside a script.

1. To create the script, type:
   ```matlab
eedit mywave
```
2. In the MATLAB Editor, enter the text of the `for`-loop:
   ```matlab
   for i = 1:1024
       A(i) = sin(i*2*pi/1024);
   end
   ```
3. Save the file and close the Editor.
4. Use the `batch` command in the MATLAB Command Window to run your script on a separate MATLAB worker:
   ```matlab
   job = batch('mywave')
   ```
5. The `batch` command does not block MATLAB, so you must wait for the job to finish before you can retrieve and view its results:
   ```matlab
   wait(job)
   ```
6. The `load` command transfers variables created on the worker to the client workspace, where you can view the results:
When the job is complete, permanently delete its data and remove its reference from the workspace:

```
delete(job)
clear job
```

The `batch` command runs your code on a local worker or a cluster worker, but does not require a parallel pool.

You can use `batch` to run either scripts or functions. For more details, see the `batch` reference page.

## Run a Batch Parallel Loop

You can combine the abilities to offload a job and run a parallel loop. In the previous two examples, you modified a `for`-loop to make a `parfor`-loop, and you submitted a script with a `for`-loop as a batch job. This example combines the two to create a batch `parfor`-loop.

1. Open your script in the MATLAB Editor:
   ```
   edit mywave
   ```
2. Modify the script so that the `for` statement is a `parfor` statement:
   ```
   parfor i = 1:1024
       A(i) = sin(i*2*pi/1024);
   end
   ```
3. Save the file and close the Editor.
4. Run the script in MATLAB with the `batch` command as before, but indicate that the script should use a parallel pool for the loop:
   ```
   job = batch('mywave','Pool',3)
   ```

This command specifies that three workers (in addition to the one running the batch script) are to evaluate the loop iterations. Therefore, this example uses a total of four local workers, including the one worker running the batch script. Altogether, there are five MATLAB sessions involved, as shown in the following diagram.
To view the results:

```matlab
wait(job)
load(job,'A')
plot(A)
```

The results look the same as before, however, there are two important differences in execution:

- The work of defining the `parfor`-loop and accumulating its results are offloaded to another MATLAB session by `batch`.
- The loop iterations are distributed from one MATLAB worker to another set of workers running simultaneously ('Pool' and `parfor`), so the loop might run faster than having only one worker execute it.

When the job is complete, permanently delete its data and remove its reference from the workspace:

```matlab
delete(job)
clear job
```

**Run Script as Batch Job from the Current Folder Browser**

From the Current Folder browser, you can run a MATLAB script as a batch job by browsing to the file’s folder, right-clicking the file, and selecting **Run Script as Batch**
Job. The batch job runs on the cluster identified by the default cluster profile. The following figure shows the menu option to run the script file `script1.m`:

Running a script as a batch from the browser uses only one worker from the cluster. So even if the script contains a `parfor` loop or `spmd` block, it does not open an additional pool of workers on the cluster. These code blocks execute on the single worker used for the batch job. If your batch script requires opening an additional pool of workers, you can run it from the command line, as described in “Run a Batch Parallel Loop” on page 1-7.

When you run a batch job from the browser, this also opens the Job Monitor. The Job Monitor is a tool that lets you track your job in the scheduler queue. For more information about the Job Monitor and its capabilities, see “Job Monitor” on page 6-38.
Create and Use Distributed Arrays

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If your data is currently in the memory of your local machine, you can use the `distributed` function to distribute an existing array from the client workspace to the workers of a parallel pool. Distributed arrays use the combined memory of multiple workers in a parallel pool to store the elements of an array. For alternative ways of partitioning data, see “Distributing Arrays” on page 3-12. You can use distributed arrays to scale up your big data computation. Consider distributed arrays when you have access to a cluster, as you can combine the memory of multiple machines in your cluster.

A distributed array is a single variable, split over multiple workers in your parallel pool. You can work with this variable as one single entity, without having to worry about its distributed nature. Explore the functionalities available for distributed arrays in the Parallel Computing Toolbox: “Using MATLAB Functions on Distributed Arrays” on page 5-24.

When you create a distributed array, you cannot control the details of the distribution. On the other hand, codistributed arrays allow you to control all aspects of distribution, including dimensions and partitions. In the following, you learn how to create both distributed and codistributed arrays.

Creating Distributed Arrays

You can create a distributed array in different ways:

- Use the `distributed` function to distribute an existing array from the client workspace to the workers of a parallel pool.
- You can directly construct a distributed array on the workers. You do not need to first create the array in the client, so that client workspace memory requirements are reduced. The functions available include `eye(___,'distributed')`, `rand(___,'distributed')`, etc. For a full list, see the distributed object reference page.
Create a codistributed array inside an spmd statement, see “Single Program Multiple Data (spmd)” on page 1-22. Then access it as a distributed array outside the spmd statement. This lets you use distribution schemes other than the default.

In this example, you create an array in the client workspace, then turn it into a distributed array:

```plaintext
parpool('local',4)  % Create pool
A = magic(4);       % Create magic 4-by-4 matrix
B = distributed(A); % Distribute to the workers
B                   % View results in client.
whos                % B is a distributed array here.
delete(gcf)         % Stop pool
```

You have created B as a distributed array, split over the workers in your parallel pool. This is shown in the figure.

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<td>4</td>
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</table>

Creating Codistributed Arrays

Unlike distributed arrays, codistributed arrays allow you to control all aspects of distribution, including dimensions and partitions. You can create a codistributed array in different ways:

- “Partitioning a Larger Array” on page 5-7 — Start with a large array that is replicated on all workers, and partition it so that the pieces are distributed across the workers. This is most useful when you have sufficient memory to store the initial replicated array.
- “Building from Smaller Arrays” on page 5-8 — Start with smaller replicated arrays stored on each worker, and combine them so that each array becomes a segment of a larger codistributed array. This method reduces memory requirements as it lets you build a codistributed array from smaller pieces.
“Using MATLAB Constructor Functions” on page 5-9 — Use any of the MATLAB constructor functions like rand or zeros with a codistributor object argument. These functions offer a quick means of constructing a codistributed array of any size in just one step.

In this example, you create a codistributed array inside an spmd statement, using a nondefault distribution scheme. First, define 1-D distribution along the third dimension, with 4 parts on worker 1, and 12 parts on worker 2. Then create a 3-by-3-by-16 array of zeros.

```
parpool('local',2) % Create pool
spmd
    codist = codistributor1d(3,[4,12]);
    Z = zeros(3,3,16,codist);
    Z = Z + labindex;
end
Z           % View results in client.
whos        % Z is a distributed array here.
delete(gcp) % Stop pool
```

For more details on codistributed arrays, see “Working with Codistributed Arrays” on page 5-5.

See Also

Related Examples

- “Distributing Arrays” on page 3-12
- “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
- “Single Program Multiple Data (spmd)” on page 1-22
Determine Product Installation and Versions

To determine if Parallel Computing Toolbox software is installed on your system, type this command at the MATLAB prompt.

`ver`

When you enter this command, MATLAB displays information about the version of MATLAB you are running, including a list of all toolboxes installed on your system and their version numbers.

If you want to run your applications on a cluster, see your system administrator to verify that the version of Parallel Computing Toolbox you are using is the same as the version of MATLAB Distributed Computing Server installed on your cluster.
Interactively Run a Loop in Parallel Using parfor

In this example, you start with a slow for-loop, and you speed up the calculation using a parfor-loop instead. parfor splits the execution of for-loop iterations over the workers in a parallel pool.

This example calculates the spectral radius of a matrix and converts a for-loop into a parfor-loop. Find out how to measure the resulting speedup.

1 In the MATLAB Editor, enter the following for-loop. Add tic and toc to measure the time elapsed.

```matlab
tic
n = 200;
A = 500;
a = zeros(n);
for i = 1:n
    a(i) = max(abs(eig(rand(A))));
end
toc
```

2 Run the script, and note the elapsed time.

Elapsed time is 31.935373 seconds.

3 In the script, replace the for-loop with a parfor-loop.

```matlab
tic
n = 200;
A = 500;
a = zeros(n);
```
parfor i = 1:n
    a(i) = max(abs(eig(rand(A))));
end

toc

Run the new script, and run it again. Note that the first run is slower than the second run, because the parallel pool takes some time to start and make the code available to the workers. Note the elapsed time for the second run.

By default, MATLAB automatically opens a parallel pool of workers on your local machine.

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers ...
Elapsed time is 10.760068 seconds.

The parfor run on four workers is about three times faster than the corresponding for-loop run. The speed-up is smaller than the ideal speed-up of a factor of four on four workers. This is due to parallel overhead, including the time required to transfer data from the client to the workers and back. This example shows a good speed-up with relatively small parallel overhead, and benefits from conversion into a parfor-loop. Not all for-loop iterations can be turned into faster parfor-loops. To learn more, see “Decide When to Use parfor” on page 2-2.

One key requirement for using parfor-loops is that the individual iterations must be independent. Independent problems suitable for parfor processing include Monte Carlo simulations and parameter sweeps. For next steps, see “Convert for-Loops Into parfor-Loops” on page 2-8.

In this example, you managed to speed up the calculation by converting the for-loop into a parfor-loop on four workers. You might reduce the elapsed time further by increasing the number of workers in your parallel pool, see “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23.

You can modify your cluster profiles to control how many workers run your loops, and whether the workers are local or on a cluster. For more information on profiles, see “Discover Clusters and Use Cluster Profiles” on page 6-18.

Modify your parallel preferences to control whether a parallel pool is created automatically, and how long it remains available before timing out. For more information on preferences, see “Specify Your Parallel Preferences” on page 6-12.
You can run Simulink models in parallel with the `parsim` command instead of using `parfor`-loops. For more information and examples of using Simulink in parallel, see “Run Multiple Simulations” (Simulink).

**See Also**
parfor | parpool | tic | toc

**More About**
- “Decide When to Use parfor” on page 2-2
- “Convert for-Loops Into parfor-Loops” on page 2-8
- “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
Run Batch Parallel Jobs

Run a Batch Job

To offload work from your MATLAB session to run in the background in another session, you can use the `batch` command inside a script.

1. To create the script, type:
   ```matlab
   edit mywave
   ```

2. In the MATLAB Editor, create a `for`-loop:
   ```matlab
   for i = 1:1024
       A(i) = sin(i*2*pi/1024);
   end
   ```

3. Save the file and close the Editor.

4. Use the `batch` command in the MATLAB Command Window to run your script on a separate MATLAB worker:
   ```matlab
   job = batch('mywave')
   ```

5. The `batch` command does not block MATLAB, so you must wait for the job to finish before you can retrieve and view its results:
   ```matlab
   wait(job)
   ```

6. The `load` command transfers variables created on the worker to the client workspace, where you can view the results:
   ```matlab
   load(job,'A')
   plot(A)
   ```

7. When the job is complete, permanently delete its data and remove its reference from the workspace:
   ```matlab
   delete(job)
   clear job
   ```
batch runs your code on a local worker or a cluster worker, but does not require a parallel pool.

You can use batch to run either scripts or functions. For more details, see the batch reference page.

**Run a Batch Job with a Parallel Pool**

You can combine the abilities to offload a job and run a loop in a parallel pool. This example combines the two to create a simple batch `parfor`-loop.

1. To create a script, type:
   ```
   edit mywave
   ```

2. In the MATLAB Editor, create a `parfor`-loop:
   ```
   parfor i = 1:1024
       A(i) = sin(i*2*pi/1024);
   end
   ```

3. Save the file and close the Editor.

4. Run the script in MATLAB with the `batch` command. Indicate that the script should use a parallel pool for the loop:
   ```
   job = batch('mywave','Pool',3)
   ```

   This command specifies that three workers (in addition to the one running the batch script) are to evaluate the loop iterations. Therefore, this example uses a total of four local workers, including the one worker running the batch script. Altogether, there are five MATLAB sessions involved, as shown in the following diagram.
To view the results:

```matlab
wait(job)
load(job,'A')
plot(A)
```

The results look the same as before, however, there are two important differences in execution:

- The work of defining the `parfor`-loop and accumulating its results are offloaded to another MATLAB session by `batch`.
- The loop iterations are distributed from one MATLAB worker to another set of workers running simultaneously ('Pool' and `parfor`), so the loop might run faster than having only one worker execute it.

When the job is complete, permanently delete its data and remove its reference from the workspace:

```matlab
delete(job)
clear job
```
See Also

batch
Run Script as Batch Job from the Current Folder Browser

From the Current Folder browser, you can run a MATLAB script as a batch job by browsing to the file’s folder, right-clicking the file, and selecting Run Script as Batch Job. The batch job runs on the cluster identified by the default cluster profile. The following figure shows the menu option to run the script file script1.m:

Running a script as a batch from the browser uses only one worker from the cluster. So even if the script contains a parfor loop or spmd block, it does not open an additional pool of workers on the cluster. These code blocks execute on the single worker used for the batch job. If your batch script requires opening an additional pool of workers, you can run it from the command line, as described in “Run a Batch Parallel Loop” on page 1-7.

When you run a batch job from the browser, this also opens the Job Monitor. The Job Monitor is a tool that lets you track your job in the scheduler queue. For more information about the Job Monitor and its capabilities, see “Job Monitor” on page 6-38.
Distribute Arrays and Run SPMD

Distributed Arrays

The workers in a parallel pool communicate with each other, so you can distribute an array among the workers. Each worker contains part of the array, and all the workers are aware of which portion of the array each worker has.

Use the `distributed` function to distribute an array among the workers:

```matlab
M = magic(4) % a 4-by-4 magic square in the client workspace
MM = distributed(M)
```

Now `MM` is a distributed array, equivalent to `M`, and you can manipulate or access its elements in the same way as any other array.

```matlab
M2 = 2*MM; % M2 is also distributed, calculation performed on workers
x = M2(1,1) % x on the client is set to first element of M2
```

Single Program Multiple Data (spmd)

The single program multiple data (`spmd`) construct lets you define a block of code that runs in parallel on all the workers in a parallel pool. The `spmd` block can run on some or all the workers in the pool.

```matlab
spmd     % By default creates pool and uses all workers
    R = rand(4);
end
```

This code creates an individual 4-by-4 matrix, `R`, of random numbers on each worker in the pool.

Composites

Following an `spmd` statement, in the client context, the values from the block are accessible, even though the data is actually stored on the workers. On the client, these variables are called `Composite` objects. Each element of a composite is a symbol referencing the value (data) on a worker in the pool. Note that because a variable might not be defined on every worker, a Composite might have undefined elements.
Continuing with the example from above, on the client, the Composite \( R \) has one element for each worker:

\[
X = R\{3\}; \quad \% \text{Set } X \text{ to the value of } R \text{ from worker 3.}
\]

The line above retrieves the data from worker 3 to assign the value of \( X \). The following code sends data to worker 3:

\[
X = X + 2;
\]

\[
R\{3\} = X; \quad \% \text{Send the value of } X \text{ from the client to worker 3.}
\]

If the parallel pool remains open between `spmd` statements and the same workers are used, the data on each worker persists from one `spmd` statement to another.

\[
\text{spmd}
\]

\[
R = R + \text{labindex} \quad \% \text{Use values of } R \text{ from previous } \text{spmd.}
\]

\[
\text{end}
\]

A typical use for `spmd` is to run the same code on a number of workers, each of which accesses a different set of data. For example:

\[
\text{spmd}
\]

\[
\text{INP} = \text{load}(['\text{somedatafile}\ ' \text{num2str(labindex)} \ '.mat']);
\]

\[
\text{RES} = \text{somefun(INP)}
\]

\[
\text{end}
\]

Then the values of \( \text{RES} \) on the workers are accessible from the client as \( \text{RES}\{1\} \) from worker 1, \( \text{RES}\{2\} \) from worker 2, etc.

There are two forms of indexing a Composite, comparable to indexing a cell array:

- \( \text{AA}\{n\} \) returns the values of \( \text{AA} \) from worker \( n \).
- \( \text{AA}(n) \) returns a cell array of the content of \( \text{AA} \) from worker \( n \).

Although data persists on the workers from one `spmd` block to another as long as the parallel pool remains open, data does not persist from one instance of a parallel pool to another. That is, if the pool is deleted and a new one created, all data from the first pool is lost.

For more information about using distributed arrays, `spmd`, and Composites, see “Distributed Arrays”.

1-23
What Is Parallel Computing?

Parallel computing allows you to carry out many calculations simultaneously. Large problems can often be split into smaller ones, which are then solved at the same time.

The main reasons to consider parallel computing are to

- Save time by distributing tasks and executing these simultaneously
- Solve big data problems by distributing data
- Take advantage of your desktop computer resources and scale up to clusters and cloud computing

With Parallel Computing Toolbox, you can

- Accelerate your code using interactive parallel computing tools, such as `parfor` and `parfeval`
- Scale up your computation using interactive Big Data processing tools, such as `distributed`, `tall`, `datastore`, and `mapreduce`
- Use `gpuArray` to speed up your calculation on the GPU of your computer
- Use `batch` to offload your calculation to computer clusters or cloud computing facilities

Here are some useful Parallel Computing concepts:

- **CPU**: Central Processing Unit, comprising multiple cores or processors
- **GPU**: Graphics Processing Unit, now widely used for general purpose (GP) GPU computing
- **Node**: standalone computer, containing one or more CPUs / GPUs. Nodes are networked to form a cluster or supercomputer
- **Thread**: smallest set of instructions that can be managed independently by a scheduler. On a GPU, multiprocessor or multicore system, multiple threads can be executed simultaneously (multi-threading)
- **Batch**: off-load execution of a functional script to run in the background
- **Scalability**: increase in parallel speedup with the addition of more resources

What tools do MATLAB and Parallel Computing Toolbox offer?
• MATLAB workers: MATLAB computational engines for parallel computing, associated with the cores in a multicore machine
• Parallel pool: a parallel pool of MATLAB workers can be created using parpool
• Speed up: Accelerate your code by running on multiple MATLAB workers, using parfor and parfeval
• Scale up: Partition your big data across multiple MATLAB workers, using distributed arrays and mapreduce
• Asynchronous processing: Use parfeval to execute a computing task without waiting for it to complete

See Also

Related Examples
• “Choose a Parallel Computing Solution” on page 1-26
• “Identify and Select a GPU Device” on page 9-19
• “Decide When to Use parfor” on page 2-2
• “Run Single Programs on Multiple Data Sets” on page 3-2
• “Evaluate Functions in the Background Using parfeval” on page 1-31
• “Distributing Arrays” on page 3-12
• “Run Batch Parallel Jobs” on page 1-17
Choose a Parallel Computing Solution

Process your data faster or scale up your big data computation using the capabilities of MATLAB, Parallel Computing Toolbox and MATLAB Distributed Computing Server.

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<td>“Vectorization” (MATLAB)</td>
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<td>Are you looking for other ways to speed up your processing?</td>
<td>Try parfeval.</td>
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<tr>
<td>Do you want to scale up your big data calculation?</td>
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<td>MATLAB</td>
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</tr>
<tr>
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<td>This workflow is well suited to data analytics and machine learning.</td>
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1 Getting Started
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<td>Use tall arrays in parallel on your cluster.</td>
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<tr>
<td>If your data is large in multiple dimensions, use distributed instead. This workflow is well suited to linear algebra problems.</td>
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<td>Do you want to offload to a cluster? Use batch to run your code on clusters and clouds.</td>
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See Also

Related Examples

- “Profile to Improve Performance” (MATLAB)
- “Vectorization” (MATLAB)
- Built-in Parallel Computing Support
- “Identify and Select a GPU Device” on page 9-19
- “Interactively Run a Loop in Parallel Using parfor” on page 1-14
- “Evaluate Functions in the Background Using parfeval” on page 1-31
- “Run Single Programs on Multiple Data Sets” on page 3-2
- “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
- “Use Tall Arrays on a Parallel Pool” on page 6-70
- “Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
- “Distributing Arrays” on page 3-12
- “Run Batch Parallel Jobs” on page 1-17
Run Non-Blocking Code in Parallel Using parfeval

You can execute a function on one or all parallel pool workers, without waiting for it to complete, using `parfeval` or `parfevalOnAll`. This can be useful if you want to be able to plot intermediate results. In addition, `parfeval` allows you to break out of a loop early, if you have established that your results are good enough. This may be convenient in e.g. optimization procedures. Note that this is different from using `parfor`, where you have to wait for the loop to complete.
Evaluate Functions in the Background Using `parfeval`

This example shows how you can use `parfeval` to evaluate a function in the background and to collect results as they become available. In this example, you submit a vector of multiple future requests in a for-loop and retrieve the individual future outputs as they become available.

```matlab
p = gcp();
% To request multiple evaluations, use a loop.
for idx = 1:10
    f(idx) = parfeval(p,@magic,1,idx); % Square size determined by idx
end
% Collect the results as they become available.
magicResults = cell(1,10);
for idx = 1:10
    % fetchNext blocks until next results are available.
    [completedIdx,value] = fetchNext(f);
    magicResults{completedIdx} = value;
    fprintf('Got result with index: %d.
', completedIdx);
end
```

Got result with index: 1.
Got result with index: 2.
Got result with index: 3.
Got result with index: 4.
Got result with index: 5.
Got result with index: 6.
Got result with index: 7.
Got result with index: 8.
Got result with index: 9.
Got result with index: 10.

See Also

Related Examples

- “Parfeval Blackjack”
What Is Different About Using Parallel Computing Toolbox Online?

The following features are different when you use Parallel Computing Toolbox online:

• The menu choice Parallel > Default Cluster is not available. However, you can manage cluster profiles in Parallel > Manage Cluster Profiles.
• Parallel > Parallel Preferences is not available.
• Parallel > Test Cloud Connection is not available.
• The Parallel Status Indicator pop-up menu does not include the Parallel Status Preferences menu item.
• The functionality in the Cluster Profile Manager looks different:
  1. the toolstrip buttons are disabled individually;
  2. when you are in the Edit menu, you cannot select the Cluster Profile, nor the Properties / Validation Results tabs.
Parallel for-Loops (parfor)

- “Decide When to Use parfor” on page 2-2
- “Convert for-Loops Into parfor-Loops” on page 2-8
- “Ensure That parfor-Loop Iterations are Independent” on page 2-12
- “Nested parfor-Loops and for-Loops” on page 2-15
- “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
- “Use parfor-Loops for Reduction Assignments” on page 2-28
- “Use Objects and Handles in parfor-Loops” on page 2-30
- “Troubleshoot Variables in parfor-Loops” on page 2-32
- “Loop Variables” on page 2-38
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- “Broadcast Variables” on page 2-45
- “Reduction Variables” on page 2-46
- “Temporary Variables” on page 2-53
- “Ensure Transparency in parfor-Loops” on page 2-56
- “Improve parfor Performance” on page 2-59
- “Run Code on Parallel Pools” on page 2-65
- “Repeat Random Numbers in parfor-Loops” on page 2-71
Decide When to Use parfor

**In this section...**

| “parfor-Loops in MATLAB” on page 2-2 |
| “Deciding When to Use parfor” on page 2-2 |
| “Example of parfor With Low Parallel Overhead” on page 2-3 |
| “Example of parfor With High Parallel Overhead” on page 2-6 |

**parfor-Loops in MATLAB**

A *parfor*-loop in MATLAB executes a series of statements in the loop body in parallel. The MATLAB client issues the *parfor* command and coordinates with MATLAB workers to execute the loop iterations in parallel on the workers in a *parallel pool*. The client sends the necessary data on which *parfor* operates to workers, where most of the computation is executed. The results are sent back to the client and assembled.

A *parfor*-loop can provide significantly better performance than its analogous *for*-loop, because several MATLAB workers can compute simultaneously on the same loop.

Each execution of the body of a *parfor*-loop is an iteration. MATLAB workers evaluate iterations in no particular order and independently of each other. Because each iteration is independent, there is no guarantee that the iterations are synchronized in any way, nor is there any need for this. If the number of workers is equal to the number of loop iterations, each worker performs one iteration of the loop. If there are more iterations than workers, some workers perform more than one loop iteration; in this case, a worker might receive multiple iterations at once to reduce communication time.

**Deciding When to Use parfor**

A *parfor*-loop can be useful if you have a slow *for*-loop. Consider *parfor* if you have:

- Some loop iterations that take a long time to execute. In this case, the workers can execute the long iterations simultaneously. Make sure that the number of iterations exceeds the number of workers. Otherwise, you will not use all workers available.
- Many loop iterations of a simple calculation, such as a Monte Carlo simulation or a parameter sweep. *parfor* divides the loop iterations into groups so that each worker executes some portion of the total number of iterations.
A `parfor`-loop might not be useful if you have:

- Code that has vectorized out the `for`-loops. Generally, if you want to make code run faster, first try to vectorize it. For details how to do this, see “Vectorization” (MATLAB). Vectorizing code allows you to benefit from the built-in parallelism provided by the multithreaded nature of many of the underlying MATLAB libraries. However, if you have vectorized code and you have access only to local workers, then `parfor`-loops may run slower than `for`-loops. Do not devectorize code to allow for `parfor`; in general, this solution does not work well.
- Loop iterations that take a short time to execute. In this case, parallel overhead dominates your calculation.

You cannot use a `parfor`-loop when an iteration in your loop depends on the results of other iterations. Each iteration must be independent of all others. For help dealing with independent loops, see “Ensure That parfor-Loop Iterations are Independent” on page 2-12. The exception to this rule is to accumulate values in a loop using “Reduction Variables” on page 2-46.

In deciding when to use `parfor`, consider parallel overhead. Parallel overhead includes the time required for communication, coordination and data transfer — sending and receiving data — from client to workers and back. If iteration evaluations are fast, this overhead could be a significant part of the total time. Consider two different types of loop iterations:

- `for`-loops with a computationally demanding task. These loops are generally good candidates for conversion into a `parfor`-loop, because the time needed for computation dominates the time required for data transfer.
- `for`-loops with a simple computational task. These loops generally do not benefit from conversion into a `parfor`-loop, because the time needed for data transfer is significant compared with the time needed for computation.

**Example of parfor With Low Parallel Overhead**

In this example, you start with a computationally demanding task inside a `for`-loop. The `for`-loops are slow, and you speed up the calculation using `parfor`-loops instead. `parfor` splits the execution of `for`-loop iterations over the workers in a parallel pool.
This example calculates the spectral radius of a matrix and converts a `for`-loop into a `parfor`-loop. Find out how to measure the resulting speedup and how much data is transferred to and from the workers in the parallel pool.

1. In the MATLAB Editor, enter the following `for`-loop. Add `tic` and `toc` to measure the computation time.

   ```matlab
tic
   n = 200;
   A = 500;
   a = zeros(n);
   for i = 1:n
       a(i) = max(abs(eig(rand(A))));
   end
   toc
   ```

2. Run the script, and note the elapsed time.

   Elapsed time is 31.935373 seconds.

3. In the script, replace the `for`-loop with a `parfor`-loop. Add `ticBytes` and `tocBytes` to measure how much data is transferred to and from the workers in the parallel pool.

   ```matlab
tic
ticBytes(gcp);
   n = 200;
   A = 500;
   a = zeros(n);
   parfor i = 1:n
       a(i) = max(abs(eig(rand(A))));
   end
tocBytes
```
Run the new script on four workers, and run it again. Note that the first run is slower than the second run, because the parallel pool takes some time to start and make the code available to the workers. Note the data transfer and elapsed time for the second run.

By default, MATLAB automatically opens a parallel pool of workers on your local machine.

```
end
tocBytes(gcp)
toc
```

<table>
<thead>
<tr>
<th>BytesSentToWorkers</th>
<th>BytesReceivedFromWorkers</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 15340</td>
<td>7024</td>
</tr>
<tr>
<td>2 13328</td>
<td>5712</td>
</tr>
<tr>
<td>3 13328</td>
<td>5704</td>
</tr>
<tr>
<td>4 13328</td>
<td>5728</td>
</tr>
<tr>
<td>Total  55324</td>
<td>24168</td>
</tr>
</tbody>
</table>

Elapsed time is 10.760068 seconds.

The `parfor` run on four workers is about three times faster than the corresponding `for`-loop calculation. The speed-up is smaller than the ideal speed-up of a factor of four on four workers. This is due to parallel overhead, including the time required to transfer data from the client to the workers and back. Use the `ticBytes` and `tocBytes` results to examine the amount of data transferred. Assume that the time required for data transfer is proportional to the size of the data. This approximation allows you to get an indication of the time required for data transfer, and to compare your parallel overhead with other `parfor`-loop iterations. In this example, the data transfer and parallel overhead are small in comparison with the next example.

The current example has a low parallel overhead and benefits from conversion into a `parfor`-loop. Compare this example with the simple loop iteration in the next example, see “Example of `parfor` With High Parallel Overhead” on page 2-6.

For another example of a `parfor`-loop with computationally demanding tasks, see “Nested `parfor`-Loops and `for`-Loops” on page 2-15.
Example of parfor With High Parallel Overhead

In this example, you write a loop to create a simple sine wave. Replacing the for-loop with a parfor-loop does not speed up your calculation. This loop does not have a lot of iterations, it does not take long to execute and you do not notice an increase in execution speed. This example has a high parallel overhead and does not benefit from conversion into a parfor-loop.

1 Write a loop to create a sine wave. Use tic and toc to measure the time elapsed.

\begin{verbatim}
tic
n = 1024;
A = zeros(n);
for i = 1:n
    A(i,:) = (1:n) .* sin(i*2*pi/1024);
end
toc
\end{verbatim}

Elapsed time is 0.012501 seconds.

2 Replace the for-loop with a parfor-loop. Add ticBytes and tocBytes to measure how much data is transferred to and from the workers in the parallel pool.

\begin{verbatim}
tic
ticBytes(gcp);
A = zeros(n);
parfor (i = 1:n)
    A(i,:) = (1:n) .* sin(i*2*pi/1024);
end
tocBytes(gcp)
toc
\end{verbatim}

3 Run the script on four workers and run the code again. Note that the first run is slower than the second run, because the parallel pool takes some time to start and make the code available to the workers. Note the data transfer and elapsed time for the second run.

\begin{center}
\begin{tabular}{|c|c|c|}
\hline
BytesSentToWorkers & BytesReceivedFromWorkers \\
\hline
1 & 13176 & 2.0615e+06 \\
2 & 15188 & 2.0874e+06 \\
3 & 13176 & 2.4056e+06 \\
4 & 13176 & 1.8567e+06 \\
\hline
\end{tabular}
\end{center}
Total 54716 8.4112e+06

Elapsed time is 0.743855 seconds.

Note that the elapsed time is much smaller for the serial for-loop than for the parfor-loop on four workers. In this case, you do not benefit from turning your for-loop into a parfor-loop. The reason is that the transfer of data is much greater than in the previous example, see “Example of parfor With Low Parallel Overhead” on page 2-3. In the current example, the parallel overhead dominates the computing time. Therefore the sine wave iteration does not benefit from conversion into a parfor-loop.

This example illustrates why high parallel overhead calculations do not benefit from conversion into a parfor-loop. To learn more about speeding up your code, see “Convert for-Loops Into parfor-Loops” on page 2-8

See Also
parfor | ticBytes | tocBytes

Related Examples
• “Decide When to Use parfor” on page 2-2
• “Interactively Run a Loop in Parallel Using parfor” on page 1-14
• “Convert for-Loops Into parfor-Loops” on page 2-8
• “Ensure That parfor-Loop Iterations are Independent” on page 2-12
• “Nested parfor-Loops and for-Loops” on page 2-15
• “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
Convert for-Loops Into parfor-Loops

In some cases, you must modify the code to convert for-loops to parfor-loops. This example shows how to diagnose and fix parfor-loop problems using a simple nested for-loop. Run this code in MATLAB and examine the results.

```matlab
for x = 0:0.1:1
    for k = 2:10
        x(k) = x(k-1) + k;
    end
    x
end
```

To speed up the code, try to convert the for-loops to parfor-loops. Observe that this code produces errors.

```matlab
parfor x = 0:0.1:1
    parfor k = 2:10
        x(k) = x(k-1) + k;
    end
    x
end
```

In this case you cannot simply convert the for-loops to parfor-loops without modification. To make this work, you must change the code in several places. To diagnose the problems, look for Code Analyzer messages in the MATLAB Editor.
This code shows common problems when you try to convert for-loops to parfor-loops.

Noninteger loop variable

parfor x = 0:0.1:1

Nested parallel loops parfor y = 2:10

A(y) = A(y-1) + ...  
end  

Dependent loop body

end

To solve these problems, you must modify the code to use parfor. The body of the parfor-loop is executed in a parallel pool using multiple MATLAB workers in a nondeterministic order. Therefore, you have to meet these requirements for the body of the parfor-loop:
1 The body of the `parfor`-loop must be independent. One loop iteration cannot depend on a previous iteration, because the iterations are executed in parallel in a nondeterministic order. In the example,

\[ x(k) = x(k-1) + k; \]

is not independent, and therefore you cannot use `parfor`. For next steps in dealing with independence issues, see “Ensure That parfor-Loop Iterations are Independent” on page 2-12.

2 You cannot nest a `parfor`-loop inside another `parfor`-loop. The example has two nested `for`-loops, and therefore you can replace only one `for`-loop with a `parfor`-loop. Instead, you can call a function that uses a `parfor`-loop inside the body of the other `parfor`-loop. However, such nested `parfor`-loops give you no computational benefit, because all workers are used to parallelize the outermost loop. For help dealing with nested loops, see “Nested parfor-Loops and for-Loops” on page 2-15.

3 `parfor`-loop variables must be consecutive increasing integers. In the example,

```
parfor x = 0:0.1:1
```

has non-integer loop variables, and therefore you cannot use `parfor` here. You can solve this problem by changing the value of the loop variable to integer values required by the algorithm. For next steps in troubleshooting `parfor`-loop variables, see “Ensure That parfor-Loop Variables Are Consecutive Increasing Integers” on page 2-32.

4 You cannot break out of a `parfor`-loop early, as you can in a `for`-loop. Do not include a return or break statement in the body of your `parfor`-loop. Without communication, the other MATLAB instances running the loop do not know when to stop. As an alternative, consider `parfeval`.

If you still have problems converting `for`-loops to `parfor`-loops, see “Troubleshoot Variables in parfor-Loops” on page 2-32.

**Tip** You can profile a `parfor`-loops using `tic` and `toc` to measure the speedup compared to the corresponding `for`-loop. Use `ticBytes` and `tocBytes` to measure how much data is transferred to and from the workers in the parallel pool. For more information and examples, see “Profiling parfor-loops” on page 2-60.
See Also
parfor | ticBytes | tocBytes

Related Examples
• “Decide When to Use parfor” on page 2-2
• “Ensure That parfor-Loop Iterations are Independent” on page 2-12
• “Nested parfor-Loops and for-Loops” on page 2-15
• “Troubleshoot Variables in parfor-Loops” on page 2-32
Ensure That parfor-Loop Iterations are Independent

If you get an error when you convert for-loops to parfor-loops, ensure that your parfor-loop iterations are independent. parfor-loop iterations have no guaranteed order, while the iteration order in for-loops is sequential. Also parfor-loop iterations are performed on different MATLAB workers in the parallel pool, so that there is no sharing of information between iterations. Therefore one parfor-loop iteration must not depend on the result of a previous iteration. The only exception to this rule is to accumulate values in a loop using “Reduction Variables” on page 2-46.

The following example produces equivalent results, using a for-loop on the left and a parfor-loop on the right. Try the example in your MATLAB Command Window:

```matlab
clear A
for i = 1:8
    A(i) = i;
end
A
```

```matlab
clear A
parfor i = 1:8
    A(i) = i;
end
A
```

Each element of A is equal to its index. The parfor-loop works because each element is determined by the indexed loop variable only and does not depend on other variables. for-loops with independent tasks are ideal candidates for parfor-loops.

**Note** By default, parfor automatically starts a parallel pool of workers, if you have not started one already. parfor creates a pool using your default cluster profile, if you have set your parallel preferences accordingly.

In the example, the array elements are available in the client workspace after the parfor-loop, exactly as with a for-loop.

Now use a nonindexed variable inside the loop, or a variable whose indexing does not depend on the loop variable i. Try these examples, and note the values of d and i afterward:
Although the elements of \( A \) are the same in both examples, the value of \( d \) is not. In the \texttt{for}-loop, the iterations are executed sequentially, so afterward \( d \) has the value it held in the last iteration of the loop. In the \texttt{parfor}-loop, however, the iterations execute in parallel, so it is impossible to assign \( d \) a defined value at the end of the loop. This situation also applies to the loop variable \( i \). Therefore, \texttt{parfor}-loop behavior is defined so that it does not affect the values \( d \) and \( i \) outside the loop. Their values remain the same before and after the loop. If the variables in your \texttt{parfor}-loop are not independent, then you might get different answers from those in the \texttt{for}-loop. In summary, a \texttt{parfor}-loop requires that each iteration be independent of the other iterations. All code that follows the \texttt{parfor} statement should not depend on the loop iteration sequence.

Code Analyzer can help diagnose whether the loop iterations are dependent. The code in the example shows iterations defined in terms of the previous iteration:

\begin{verbatim}
parfor k = 2:10
    x(k) = x(k-1) + k;
end
\end{verbatim}

Look for Code Analyzer messages in the MATLAB Editor. In this case, Code Analyzer reports the dependency problem.
In other cases, however, Code Analyzer is unable to mark dependencies.

For help with other common parfor problems, see “Nested parfor-Loops and for-Loops” on page 2-15.

See Also
parfor

Related Examples
• “Decide When to Use parfor” on page 2-2
• “Convert for-Loops Into parfor-Loops” on page 2-8
• “Nested parfor-Loops and for-Loops” on page 2-15
• “Troubleshoot Variables in parfor-Loops” on page 2-32
• “Reduction Variables” on page 2-46

More About
• “Evaluate Functions in the Background Using parfeval” on page 1-31
Nested parfor-Loops and for-Loops

In this section...

| “Parallellizing Nested Loops” on page 2-15 |
| “Convert Nested for-Loops to parfor” on page 2-16 |
| “Nested Loops: Requirements and Limitations” on page 2-19 |
| “Nested Functions” on page 2-21 |
| “Nested spmd Statements” on page 2-21 |
| “Break and Return Statements” on page 2-21 |
| “P-Code Scripts” on page 2-22 |

Parallellizing Nested Loops

You cannot use a parfor-loop inside another parfor-loop. As an example, the following nesting of parfor-loops is not allowed:

```matlab
parfor i = 1:10
    parfor j = 1:5
        ...
    end
end
end
```

Tip You cannot nest parfor directly within another parfor-loop. A parfor-loop can call a function that contains a parfor-loop, but you do not get any additional parallelism.

Code Analyzer in the MATLAB Editor flags the use of parfor inside another parfor-loop:

> **PARFOR** or **SPMD** cannot be used inside another **PARFOR** loop.

You cannot nest parfor-loops because parallellization can be performed at only one level. Therefore, choose which loop to run in parallel, and convert the other loop to a for-loop.

Consider the following performance issues when dealing with nested loops:
Parallel processing incurs overhead. Generally, you should run the outer loop in parallel, because overhead only occurs once. If you run the inner loop in parallel, then each of the multiple parfor executions incurs an overhead. See “Convert Nested for-Loops to parfor” on page 2-16 for an example how to measure parallel overhead.

- Make sure that the number of iterations exceeds the number of workers. Otherwise, you do not use all available workers.

- Try to balance the parfor-loop iteration times. parfor tries to compensate for some load imbalance.

**Tip** Always run the outermost loop in parallel, because you reduce parallel overhead.

You can also use a function that uses parfor and embed it in a parfor-loop. Parallelization occurs only at the outer level. In the following example, call a function MyFun.m inside the outer parfor-loop. The inner parfor-loop embedded in MyFun.m runs sequentially, not in parallel.

```matlab
parfor i = 1:10
    MyFun(i)
end

function MyFun(i)
    parfor j = 1:5
        ...
    end
end
```

**Tip** Nested parfor-loops generally give you no computational benefit.

### Convert Nested for-Loops to parfor

A typical use of nested loops is to step through an array using a one-loop variable to index one dimension, and a nested-loop variable to index another dimension. The basic form is:

```matlab
X = zeros(n,m);
for a = 1:n
    for b = 1:m
        X(a,b) = fun(a,b)
    end
end
```
The following code shows a simple example. Use `tic` and `toc` to measure the computing time needed.

```matlab
A = 100;
tic
for i = 1:100
    for j = 1:100
        a(i,j) = max(abs(eig(rand(A))));
    end
end
toc
```

Elapsed time is 49.376732 seconds.

You can parallelize either of the nested loops, but you cannot run both in parallel. The reason is that the workers in a parallel pool cannot start or access further parallel pools.

If the loop counted by `i` is converted to a `parfor`-loop, then each worker in the pool executes the nested loops using the `j` loop counter. The `j` loops themselves cannot run as a `parfor` on each worker.

Because parallel processing incurs overhead, you must choose carefully whether you want to convert either the inner or the outer `for`-loop to a `parfor`-loop. The following example shows how to measure the parallel overhead.

First convert only the `outer` `for`-loop to a `parfor`-loop. Use `tic` and `toc` to measure the computing time needed. Use `ticBytes` and `tocBytes` to measure how much data is transferred to and from the workers in the parallel pool.

Run the new code, and run it again. The first run is slower than subsequent runs, because the parallel pool takes some time to start and make the code available to the workers.

```matlab
A = 100;
tic
ticBytes(gcp);
parfor i = 1:100
    for j = 1:100
        a(i,j) = max(abs(eig(rand(A))));
    end
end
```
end
tocBytes(gcp)
toc

<table>
<thead>
<tr>
<th>BytesSentToWorkers</th>
<th>BytesReceivedFromWorkers</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>32984</td>
</tr>
<tr>
<td>2</td>
<td>33784</td>
</tr>
<tr>
<td>3</td>
<td>33784</td>
</tr>
<tr>
<td>4</td>
<td>34584</td>
</tr>
<tr>
<td>Total</td>
<td>1.3514e+05</td>
</tr>
</tbody>
</table>

Elapsed time is 14.130674 seconds.

Next convert only the *inner* loop to a *parfor*-loop. Measure the time needed and data transferred as in the previous case.

A = 100;
tic
ticBytes(gcp);
for i = 1:100
   parfor j = 1:100
      a(i,j) = max(abs(eig(rand(A))));
   end
end
tocBytes(gcp)
toc

<table>
<thead>
<tr>
<th>BytesSentToWorkers</th>
<th>BytesReceivedFromWorkers</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1.3496e+06</td>
</tr>
<tr>
<td>2</td>
<td>1.3496e+06</td>
</tr>
<tr>
<td>3</td>
<td>1.3677e+06</td>
</tr>
<tr>
<td>4</td>
<td>1.3476e+06</td>
</tr>
<tr>
<td>Total</td>
<td>5.4144e+06</td>
</tr>
</tbody>
</table>

Elapsed time is 48.631737 seconds.

If you convert the *inner* loop to a *parfor*-loop, both the time and amount of data transferred are much greater than in the parallel outer loop. In this case, the elapsed time is almost the same as in the nested *for*-loop example. The speedup is smaller than running the outer loop in parallel, because you have more data transfer and thus more
parallel overhead. Therefore if you execute the inner loop in parallel, you get no computational benefit compared to running the serial for-loop.

If you want to reduce parallel overhead and speed up your computation, run the outer loop in parallel.

If you convert the inner loop instead, then each iteration of the outer loop initiates a separate parfor-loop. That is, the inner loop conversion creates 100 parfor-loops. Each of the multiple parfor executions incurs overhead. If you want to reduce parallel overhead, you should run the outer loop in parallel instead, because overhead only occurs once.

**Tip** If you want to speed up your code, always run the outer loop in parallel, because you reduce parallel overhead.

### Nested Loops: Requirements and Limitations

If you want to convert a nested for-loop to a parfor-loop, you must ensure that your loop variables are properly classified, see “Troubleshoot Variables in parfor-Loops” on page 2-32. For proper variable classification, you must define the range of a for-loop nested in a parfor-loop by constant numbers or variables. In the following example, the code on the left does not work because you define the upper limit of the for-loop by a function call. The code on the right provides a workaround by first defining a broadcast or constant variable outside the parfor-loop:

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>A = zeros(100, 200);</code></td>
<td><code>A = zeros(100, 200);</code></td>
</tr>
<tr>
<td><code>parfor i = 1:size(A, 1)</code></td>
<td><code>parfor i = 1:size(A, 1)</code></td>
</tr>
<tr>
<td><code>for j = 1:size(A, 2)</code></td>
<td><code>for j = 1:n</code></td>
</tr>
<tr>
<td><code>A(i, j) = i + j;</code></td>
<td><code>A(i, j) = i + j;</code></td>
</tr>
<tr>
<td><code>end</code></td>
<td><code>end</code></td>
</tr>
</tbody>
</table>

The index variable for the nested for-loop must never be explicitly assigned other than in its for statement. When using the nested for-loop variable for indexing the sliced array, you must use the variable in plain form, not as part of an expression. For example, the following code on the left does not work, but the code on the right does:
If you use a nested for-loop to index into a sliced array, you cannot use that array elsewhere in the parfor-loop. In the following example, the code on the left does not work because \( A \) is sliced and indexed inside the nested for-loop. The code on the right works because \( v \) is assigned to \( A \) outside of the nested loop:

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
</table>
| \[
A = \text{zeros}(4, 11);
\text{parfor} \ i = 1:4
  \text{for} \ j = 1:10
    A(i, j + 1) = i + j;
  \text{end}
\text{end}
\] | \[
A = \text{zeros}(4, 11);
\text{parfor} \ i = 1:4
  \text{for} \ j = 2:11
    A(i, j) = i + j - 1;
  \text{end}
\text{end}
\] |

Suppose that you use multiple for-loops (not nested inside each other) inside a parfor-loop, to index into a single sliced array. In this case, the for-loops must loop over the same range of values. A sliced output variable can be used in only one nested for-loop. In the following example, the code on the left does not work because \( j \) and \( k \) loop over different values. The code on the right works to index different portions of the sliced array \( A \):

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
</table>
| \[
A = \text{zeros}(4, 10);
\text{parfor} \ i = 1:4
  \text{for} \ j = 1:5
    A(i, j) = i + j;
  \text{end}
  \text{for} \ k = 6:10
    A(i, k) = \pi;
  \text{end}
\text{end}
\] | \[
A = \text{zeros}(4, 10);
\text{parfor} \ i = 1:4
  \text{for} \ j = 1:10
    \text{if} \ j < 6
      A(i, j) = i + j;
    \text{else}
      A(i, j) = \pi;
    \text{end}
\text{end}
\] |
Nested Functions

The body of a parfor-loop cannot make reference to a nested function, see “Nested Functions” (MATLAB). However, it can call a nested function by a function handle. Try the following example. Note that $A(idx) = \text{nfcn}(idx)$ in the parfor-loop does not work. You must use feval to invoke the fcn handle in the parfor-loop body:

```matlab
function A = pfeg
    function out = nfcn(in)
        out = 1 + in;
    end
    fcn = @nfcn;
    parfor idx = 1:10
        A(idx) = feval(fcn, idx);
    end
end
```

```matlab
>> pfeg
Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.
ans =
    2     3     4     5     6     7     8     9    10    11
```

**Tip** If you use function handles that refer to nested functions inside a parfor-loop, then the values of externally scoped variables are not synchronized among the workers. For more information on handles, see Copying Objects (MATLAB).

Nested spmd Statements

The body of a parfor-loop cannot contain an spmd statement, and an spmd statement cannot contain a parfor-loop.

Break and Return Statements

The body of a parfor-loop cannot contain break or return statements. Consider parfeval or parfevalOnAll instead.
P-Code Scripts

You can call P-code script files from within a parfor-loop, but P-code script cannot contain a parfor-loop.

However, if a script introduces a variable, you cannot call this script from within a parfor-loop or spmd statement. The reason is that this script would cause a transparency violation. For more details, see “Ensure Transparency in parfor-Loops” on page 2-56.

See Also
break | feval | parfeval | parfevalOnAll | parfor | return

Related Examples
• “Decide When to Use parfor” on page 2-2
• “Convert for-Loops Into parfor-Loops” on page 2-8
• “Ensure That parfor-Loop Iterations are Independent” on page 2-12
• “Troubleshoot Variables in parfor-Loops” on page 2-32
In this example, you start on your local multicore desktop and measure the time required to run a calculation, as a function of increasing numbers of workers. The test is called a strong scaling test. It enables you to measure the decrease in time required for the calculation if you add more workers. This dependence is known as speedup, and allows you to estimate the parallel scalability of your code. You can then decide whether it is useful to increase the number of workers in your parallel pool, and scale up to cluster and cloud computing.

1. Create the function.

   ```matlab
   edit MyCode
   ```

2. In the MATLAB Editor, enter the new `parfor`-loop and add `tic` and `toc` to measure the time elapsed.

   ```matlab
   function a = MyRand(A)
   tic
   parfor i = 1:200
       a(i) = max(abs(eig(rand(A))));
   end
   toc
   ```

3. Save the file, and close the Editor.

4. On the Parallel > Parallel Preferences menu, check that your Default Cluster is local (your desktop machine).

5. In the MATLAB Command Window, define a parallel pool of size 1, and run your function on one worker to calculate the elapsed time. Note the elapsed time for a single worker and shut down your parallel pool.

   ```matlab
   parpool(1);
   a = MyCode(1000);
   Elapsed time is 172.529228 seconds.
   delete(gcp);
   ```

6. Open a new parallel pool of two workers, and run the function again.

   ```matlab
   parpool(2);
   a = MyCode(1000);
   ```
Note the elapsed time; you should see that this now has decreased compared to the single worker case.

Try 4, 8, 12 and 16 workers. Measure the parallel scalability by plotting the elapsed time for each number of workers on a log-log scale.

The figure shows the scalability for a typical multicore desktop PC (blue circle data points). The strong scaling test shows almost linear speedup and significant parallel scalability for up to eight workers. Observe from the figure that, in this case, we do not achieve further speedup for more than eight workers. This result means that, on a local desktop machine, all cores are fully used for 8 workers. You can get a different result on your local desktop, depending on your hardware. To further speed up your parallel application, consider scaling up to cloud or cluster computing.
If you have exhausted your local workers, as in the previous example, you can scale up your calculation to cloud computing. Check your access to cloud computing from the Parallel > Discover Clusters menu.

Open a parallel pool in the cloud and run your application without changing your code.

```matlab
parpool(16);
a = MyCode(1000);
```

Note the elapsed time for increasing numbers of cluster workers. Measure the parallel scalability by plotting the elapsed time as a function of number of workers on a log-log scale.
The figure shows typical performance for workers in the cloud (red plus data points). This strong scaling test shows linear speedup and 100% parallel scalability up to 16 workers in the cloud. Consider further scaling up of your calculation by increasing the number of workers in the cloud or on a compute cluster. Note that the parallel scalability can be different, depending on your hardware, for a larger number of workers and other applications.

If you have direct access to a cluster, you can scale up your calculation using workers on the cluster. Check your access to clusters from the Parallel > Discover Clusters menu. If you have an account, select cluster, open a parallel pool and run your application without changing your code.

parpool(64);
a = MyCode(1000);
The figure shows typical strong scaling performance for workers on a cluster (black x data points). Observe that you achieve 100% parallel scalability, persisting up to at least 80 workers on the cluster. Note that this application scales linearly - the speedup is equal to the number of workers used.

This example shows a speedup equal to the number of workers. Not every task can achieve a similar speedup, see for example “Interactively Run a Loop in Parallel Using parfor” on page 1-14.

You might need different approaches for your particular tasks. To learn more about alternative approaches, see “Choose a Parallel Computing Solution” on page 1-26.

**Tip** You can further profile a parfor-loop by measuring how much data is transferred to and from the workers in the parallel pool by using ticBytes and tocBytes. For more information and examples, see “Profiling parfor-loops” on page 2-60.

### See Also

### Related Examples

- “Discover Clusters” on page 6-19
- “Discover Clusters and Use Cluster Profiles” on page 6-18
- “Profiling parfor-loops” on page 2-60
- “Interactively Run a Loop in Parallel Using parfor” on page 1-14
- “Choose a Parallel Computing Solution” on page 1-26
Use parfor-Loops for Reduction Assignments

These two examples show parfor-loops using reduction assignments. A reduction is an accumulation across iterations of a loop. The example on the left uses x to accumulate a sum across 10 iterations of the loop. The example on the right generates a concatenated array, 1:10. In both of these examples, the execution order of the iterations on the workers does not matter: while the workers calculate individual results for each iteration, the client properly accumulates and assembles the final loop result.

```matlab
x = 0;
parfor i = 1:10
    x = x + i;
end
x

x2 = [];
n = 10;
parfor i = 1:n
    x2 = [x2, i];
end
x2
```

If the loop iterations operate in a nondeterministic sequence, you might expect the concatenation sequence in the example on the right to be nonconsecutive. However, MATLAB recognizes the concatenation operation and yields deterministic results.

The next example, which attempts to compute Fibonacci numbers, is not a valid parfor-loop because the value of an element of \( f \) in one iteration depends on the values of other elements of \( f \) calculated in other iterations.

```matlab
f = zeros(1,50);
f(1) = 1;
f(2) = 2;
parfor n = 3:50
    f(n) = f(n-1) + f(n-2);
end
```

When you are finished with your loop examples, clear your workspace and delete your parallel pool of workers:

```matlab
clear
delete(gcp)
```
See Also

More About

- “Reduction Variables” on page 2-46
- “Ensure That parfor-Loop Iterations are Independent” on page 2-12
Use Objects and Handles in parfor-Loops

In this section...

“Using Objects in parfor-Loops” on page 2-30
“Handle Classes” on page 2-30
“Sliced Variables Referencing Function Handles” on page 2-31

Using Objects in parfor-Loops

If you are passing objects into or out of a parfor-loop, the objects must properly facilitate being saved and loaded. For more information, see “Save and Load Process for Objects” (MATLAB).

You cannot slice the fields of objects because of first-level indexing constraints. For details, see “Sliced Variables” on page 2-40.

For example, in the code on the left, both lines in the loop generate a classification error because of the indexing. In the code on the right, as a workaround for sliced output, you employ separate sliced arrays in the loop. Then you assign the structure fields after the loop is complete.

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>parfor i = 1:4</code></td>
<td><code>parfor i = 1:4</code></td>
</tr>
<tr>
<td>outputData.outArray1(i)</td>
<td>outputArray1(i) = 1/i;</td>
</tr>
<tr>
<td>outputData.outArray2(i)</td>
<td>outputArray2(i) = i^2;</td>
</tr>
<tr>
<td>end</td>
<td>end</td>
</tr>
</tbody>
</table>

Handle Classes

You can send handle objects as inputs to the body of a parfor-loop. However, any changes made to handle objects on the workers during loop iterations are not automatically propagated back to the client. That is, changes made inside the loop are not automatically reflected after the loop.

To get the changes back to the client after the loop, explicitly assign the modified handle objects to output variables of the parfor-loop. In the following example, maps is a sliced input/output variable.
maps = {containers.Map(),containers.Map(),containers.Map()};
parfor ii = 1:numel(maps)
    mymap = maps{ii}; % input slice assigned to local copy
    for jj = 1:1000
        mymap(num2str(jj)) = rand;
    end
    maps{ii} = mymap; % modified local copy assigned to output slice
end

Sliced Variables Referencing Function Handles

You cannot directly call a function handle with the loop index as an input argument, because this variable cannot be distinguished from a sliced input variable. If you must call a function handle with the loop index variable as an argument, use feval.

The following example uses a function handle and a for-loop.

B = @sin;
for ii = 1:100
    A(ii) = B(ii);
end

A corresponding parfor-loop does not allow B to reference a function handle. You can work around the problem using feval.

B = @sin;
parfor ii = 1:100
    A(ii) = feval(B,ii);
end

See Also

More About

- “Troubleshoot Variables in parfor-Loops” on page 2-32
- “Sliced Variables” on page 2-40
Troubleshoot Variables in parfor-Loops

<table>
<thead>
<tr>
<th>In this section...</th>
</tr>
</thead>
<tbody>
<tr>
<td>“Ensure That parfor-Loop Variables Are Consecutive Increasing Integers” on page 2-32</td>
</tr>
<tr>
<td>“Solve Variable Classification Issues in parfor-Loops” on page 2-32</td>
</tr>
<tr>
<td>“Structure Arrays in parfor-Loops” on page 2-35</td>
</tr>
<tr>
<td>“Converting the Body of a parfor-Loop into a Function” on page 2-36</td>
</tr>
<tr>
<td>“Unambiguous Variable Names” on page 2-36</td>
</tr>
<tr>
<td>“Transparent parfor-loops” on page 2-37</td>
</tr>
<tr>
<td>“Global and Persistent Variables” on page 2-37</td>
</tr>
</tbody>
</table>

**Ensure That parfor-Loop Variables Are Consecutive Increasing Integers**

Loop variables in a parfor-loop must be consecutive increasing integers. For this reason, the following examples return errors:

```
parfor i = 0:0.2:1       % not integers
parfor j = 1:2:11       % not consecutive
parfor k = 12:-1:1      % not increasing
```

You can fix these errors by converting the loop variables into a valid range. For example, you can fix the noninteger example as follows:

```
iValues = 0:0.2:1;
parfor idx = 1:numel(iValues)
i = iValues(idx);
... end
```

**Solve Variable Classification Issues in parfor-Loops**

When MATLAB recognizes a name in a parfor-loop as a variable, the variable is classified in one of several categories, shown in the following table. Make sure that your variables are uniquely classified and meet the category requirements. parfor-loops that violate the requirement return an error.
<table>
<thead>
<tr>
<th>Classification</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>&quot;Loop Variables&quot; on page 2-38</td>
<td>Loop indices</td>
</tr>
<tr>
<td>&quot;Sliced Variables&quot; on page 2-40</td>
<td>Arrays whose segments are operated on by different iterations of the loop</td>
</tr>
<tr>
<td>&quot;Broadcast Variables&quot; on page 2-45</td>
<td>Variables defined before the loop whose value is required inside the loop, but never assigned inside the loop</td>
</tr>
<tr>
<td>&quot;Reduction Variables&quot; on page 2-46</td>
<td>Variables that accumulates a value across iterations of the loop, regardless of iteration order</td>
</tr>
<tr>
<td>&quot;Temporary Variables&quot; on page 2-53</td>
<td>Variables created inside the loop, and not accessed outside the loop</td>
</tr>
</tbody>
</table>

To find out which variables you have, examine the code fragment. All variable classifications in the table are represented in this code:

```matlab
a = 0;
c = pi;
z = 0;
r = rand(1,10);
parfor i = 1:10
    temporary variable: a = i;
    reduction variable: z = z+i;
    sliced input variable: b(i) = r(i);
    broadcast variable: if i <= c
                      d = 2*a;
    end
end
```

If you run into variable classification problems, consider these approaches before you resort to the more difficult method of converting the body of a `parfor`-loop into a function.

- If you use a nested `for`-loop to index into a sliced array, you cannot use that array elsewhere in the `parfor`-loop. The code on the left does not work because `A` is sliced
and indexed inside the nested for-loop. The code on the right works because v is assigned to A outside the nested loop. You can compute an entire row, and then perform a single assignment into the sliced output.

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
</table>
| A = zeros(4, 10); parfor i = 1:4  
  for j = 1:10  
    A(i, j) = i + j;  
  end  
  disp(A(i, 1)) | A = zeros(4, 10); parfor i = 1:4  
  v = zeros(1, 10);  
  for j = 1:10  
    v(j) = i + j;  
  end  
  disp(v(1))  
  A(i, :) = v;  
end |

• The code on the left does not work because the variable x in parfor cannot be classified. This variable cannot be classified because there are multiple assignments to different parts of x. Therefore parfor cannot determine whether there is a dependency between iterations of the loop. The code on the right works because you completely overwrite the value of x. parfor can now determine unambiguously that x is a temporary variable.

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
</table>
| parfor idx = 1:10  
  x(1) = 7;  
  x(2) = 8;  
  out(idx) = sum(x);  
end | parfor idx = 1:10  
  x = [7, 8];  
  out(idx) = sum(x);  
end |

• This example shows how to slice the field of a structured array. See struct for details. The code on the left does not work because the variable a in parfor cannot be classified. This variable cannot be classified because the form of indexing is not valid for a sliced variable. The first level of indexing is not the sliced indexing operation, even though the field x of a appears to be sliced correctly. The code on the right works because you extract the field of the struct into a separate variable tmpx. parfor can now determine correctly that this variable is sliced. In general, you cannot use fields of structs or properties of objects as sliced input or output variables in parfor.
Structure Arrays in parfor-Loops

Creating Structures as Temporaries

You cannot create a structure in a `parfor`-loop using dot notation assignment. In the code on the left, both lines inside the loop generate a classification error. In the code on the right, as a workaround you can use the `struct` function to create the structure in the loop or in the first field.

### Invalid

```matlab
a.x = [];
parfor idx = 1:10
  a.x(idx) = 7;
end
```

### Valid

```matlab
tmpx = [];
parfor idx = 1:10
  tmpx(idx) = 7;
end
a.x = tmpx;
```

Slicing Structure Fields

You cannot use structure fields as sliced `input or output` arrays in a `parfor`-loop. In other words, you cannot use the loop variable to index the elements of a structure field. In the code on the left, both lines in the loop generate a classification error because of the indexing. In the code on the right, as a workaround for sliced output, you employ separate sliced arrays in the loop. Then you assign the structure fields after the loop is complete.

### Invalid

```matlab
parfor i = 1:4
  temp.myfield1 = rand();
  temp.myfield2 = i;
end

parfor i = 1:4
  outputData.outArray1(i) = 1/i;
  outputData.outArray2(i) = i^2;
end
```

### Valid

```matlab
parfor i = 1:4
  temp = struct();
  temp.myfield1 = rand();
  temp.myfield2 = i;
end

parfor i = 1:4
  temp = struct('myfield1',rand(),'myfield2',i);
end

parfor i = 1:4
  outputData.outArray1 = [outputData.outArray1; 1/i];
  outputData.outArray2 = [outputData.outArray2; i^2];
end

outputData = struct('outArray1',outputData.outArray1,'outArray2',outputData.outArray2);
```
The workaround for sliced input is to assign the structure field to a separate array before the loop. You can use that new array for the sliced input.

```matlab
ingArray1 = inputData.inArray1;
ingArray2 = inputData.inArray2;
parfor i = 1:4
    temp1 = inArray1(i);
    temp2 = inArray2(i);
end
```

### Converting the Body of a parfor-Loop into a Function

If all else fails, you can usually solve variable classification problems in `parfor`-loops by converting the body of the `parfor`-loop into a function. In the code on the left, Code Analyzer flags a problem with variable `y`, but cannot resolve it. In the code on the right, you solve this problem by converting the body of the `parfor`-loop into a function.

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
<tbody>
<tr>
<td>function parfor_loop_body_bad</td>
<td>function parfor_loop_body_good</td>
</tr>
<tr>
<td>data = rand(5,5);</td>
<td>data = rand(5,5);</td>
</tr>
<tr>
<td>means = zeros(1,5);</td>
<td>means = zeros(1,5);</td>
</tr>
<tr>
<td>parfor X = 1:5</td>
<td>parfor X = 1:5</td>
</tr>
<tr>
<td>% Code Analyzer flags problem</td>
<td>% Call a function instead</td>
</tr>
<tr>
<td>% with variable y below</td>
<td>means(X) = computeMeans(data(:,X));</td>
</tr>
<tr>
<td>y.mean = mean(data(:,X));</td>
<td>end</td>
</tr>
<tr>
<td>means(X) = y.mean;</td>
<td>disp(means);</td>
</tr>
<tr>
<td>end</td>
<td>% This function now contains the body</td>
</tr>
<tr>
<td>disp(means);</td>
<td>% of the parfor-loop</td>
</tr>
<tr>
<td></td>
<td>function meansX = computeMeans(dataX)</td>
</tr>
<tr>
<td></td>
<td>y.mean = mean(dataX);</td>
</tr>
<tr>
<td></td>
<td>meansX = y.mean;</td>
</tr>
</tbody>
</table>

### Unambiguous Variable Names

If you use a name that MATLAB cannot unambiguously distinguish as a variable inside a `parfor`-loop, at parse time MATLAB assumes you are referencing a function. Then at run-time, if the function cannot be found, MATLAB generates an error. See “Variable
Names” (MATLAB). For example, in the following code \( f(5) \) could refer either to the fifth element of an array named \( f \), or to a function named \( f \) with an argument of \( 5 \). If \( f \) is not clearly defined as a variable in the code, MATLAB looks for the function \( f \) on the path when the code runs.

```matlab
parfor i = 1:n
    ...
    a = f(5);
    ...
end
```

**Transparent parfor-loops**

The body of a `parfor`-loop must be *transparent*: all references to variables must be “visible” in the text of the code. For more details about transparency, see “Ensure Transparency in parfor-Loops” on page 2-56.

**Global and Persistent Variables**

The body of a `parfor`-loop cannot contain global or persistent variable declarations.

**See Also**

**More About**

- “Decide When to Use parfor” on page 2-2
- “Convert for-Loops Into parfor-Loops” on page 2-8
- “Ensure That parfor-Loop Iterations are Independent” on page 2-12
- “Nested parfor-Loops and for-Loops” on page 2-15
- “Ensure Transparency in parfor-Loops” on page 2-56
- “Use parfor-Loops for Reduction Assignments” on page 2-28
- “Run Parallel Simulations” (Simulink)
Loop Variables

The loop variable defines the loop index value for each iteration. You set it in the first line of a `parfor` statement.

```matlab
parfor p=1:12
```

For values across all iterations, the loop variable must evaluate to ascending consecutive integers. Each iteration is independent of all others, and each has its own loop index value.

**Required (static):** Assignments to the loop variable are not allowed.

This restriction is required, because changing `p` in the `parfor` body cannot guarantee the independence of iterations.

This example attempts to modify the value of the loop variable `p` in the body of the loop, and thus is invalid.

```matlab
parfor p = 1:n
    p = p + 1;
    a(p) = i;
end
```

**Required (static):** You cannot index or subscript the loop variable in any way.

This restriction is required, because referencing a field of a loop variable cannot guarantee the independence of iterations.

The following code attempts to reference a field (`b`) of the loop variable (`p`) as if it were a structure. Both lines within the loop are invalid.

```matlab
parfor p = 1:n
    p.b = 3
    x(p) = fun(p.b)
end
```

Similarly, the following code is invalid because it attempts to index the loop variable as a 1-by-1 matrix:

```matlab
parfor p = 1:n
    x = p(1)
end
**Required (static):** You cannot use a range increment in `for`-loops nested inside a `parfor`-loop.

Consider the following example:

```plaintext
N = 10;
T = 3;
A = zeros(N,T);
B = zeros(N,T);
```

The following code is invalid.

```plaintext
parfor i = 1:1:N
    for t = 1:1:T
        A(i,t) = t;
    end
end
```

The following code is valid.

```plaintext
parfor i = 1:1:N
    for t = 1:T
        B(i,t) = t;
    end
end
```

**See Also**

`parfor`

**More About**

- “Troubleshoot Variables in parfor-Loops” on page 2-32
Sliced Variables

A sliced variable is one whose value can be broken up into segments, or slices, which are then operated on separately by different workers. Each iteration of the loop works on a different slice of the array. Using sliced variables can reduce communication between the client and workers. Only those slices needed by a worker are sent to it when it starts working on a particular range of indices.

In this example, a slice of A consists of a single element of that array.

```
parfor i = 1:length(A)
    B(i) = f(A(i));
end
```

Characteristics of a Sliced Variable

If a variable in a parfor-loop has all the following characteristics, then the variable is sliced:

- Type of First-Level Indexing — The first level of indexing is either parentheses, (), or braces, {}.
- Fixed Index Listing — Within the first-level parentheses or braces, the list of indices is the same for all occurrences of a given variable.
- Form of Indexing — Within the list of indices for the variable, exactly one index involves the loop variable.
- Shape of Array — The array maintains a constant shape. In assigning to a sliced variable, the right side of the assignment cannot be [], or '.', because these operators attempt to delete elements.

Type of First-Level Indexing. For a sliced variable, the first level of indexing is enclosed in either parentheses, (), or braces, {}.

Here are the forms for the first level of indexing for arrays that are sliced and not sliced.

<table>
<thead>
<tr>
<th>Reference for Variable Not Sliced</th>
<th>Reference for Sliced Variable</th>
</tr>
</thead>
<tbody>
<tr>
<td>A.x</td>
<td>A(...)</td>
</tr>
<tr>
<td>A(...</td>
<td>A{...}</td>
</tr>
</tbody>
</table>

After the first level, you can use any type of valid MATLAB indexing in the second and subsequent levels.
The variable $A$ shown here on the left is not sliced; that shown on the right is sliced:

\[ A.q[i,12] \quad \text{and} \quad A[i,12].q \]

**Fixed Index Listing.** Within the first-level indexing of a sliced variable, the list of indices is the same for all occurrences of a given variable.

The variable $A$ on the left is not sliced because $A$ is indexed by $i$ and $i+1$ in different places. In the code on the right, variable $A$ is sliced correctly.

<table>
<thead>
<tr>
<th>Not sliced</th>
<th>Sliced</th>
</tr>
</thead>
<tbody>
<tr>
<td>\parfor i = 1:k</td>
<td>\parfor i = 1:k</td>
</tr>
<tr>
<td>\hspace{1em} (B(:) = h(A(i), A(i+1)))</td>
<td>\hspace{1em} (B(:) = f(A(i))); C(:) = g(A(i))</td>
</tr>
<tr>
<td>\end</td>
<td>\end</td>
</tr>
</tbody>
</table>

The example on the right shows occurrences of first-level indexing using both parentheses and braces in the same loop, which is acceptable.

The following example on the left does not slice $A$ because the indexing of $A$ is not the same in all places. The example on the right slices both $A$ and $B$. The indexing of $A$ is not the same as the indexing of $B$. However, the indexing of both $A$ and $B$ are individually consistent.

<table>
<thead>
<tr>
<th>Not sliced</th>
<th>Sliced</th>
</tr>
</thead>
<tbody>
<tr>
<td>\parfor i=1:10</td>
<td>A = [ 1 2 3 4 5 6 7 8 9 10; 10 20 30 40 50 60 70 80 90 100];</td>
</tr>
<tr>
<td>\hspace{1em} b = A(1,i) + A(2,i)</td>
<td>\parfor i=1:10</td>
</tr>
<tr>
<td>\end</td>
<td>\hspace{1em} B = zeros(1,10);</td>
</tr>
<tr>
<td></td>
<td>\parfor i=1:10</td>
</tr>
<tr>
<td></td>
<td>\hspace{1em} for n=1:2</td>
</tr>
<tr>
<td></td>
<td>\hspace{1em} B(i) = B(i)+A(n,i)</td>
</tr>
<tr>
<td></td>
<td>\end</td>
</tr>
</tbody>
</table>

**Form of Indexing.** Within the list of indices for a sliced variable, one of these indices is of the form $i, i+k, i-k, k+i,$ or $k-i$. The index $i$ is the loop variable and $k$ is a constant or a simple (nonindexed) broadcast variable. Every other index is a scalar constant, a simple broadcast variable, a nested \for-loop index, colon, or \end.

With $i$ as the loop variable, the $A$ variables shown on the left are not sliced, while the $A$ variables on the right are sliced.
When you use other variables along with the loop variable to index an array, you cannot set these variables inside the loop. In effect, such variables are constant over the execution of the entire `parfor` statement. You cannot combine the loop variable with itself to form an index expression.

**Shape of Array.** A sliced variable must maintain a constant shape. The variable `A` shown here on either line is not sliced:

```matlab
A(i,:) = []; 
A(end + 1) = i; 
```

In the first case, `A` is not sliced because changing the shape of a sliced array would violate assumptions governing communication between the client and workers.

In the second, `A` is not a sliced output because it is not indexed on the loop variable.

**Sliced Input and Output Variables**

All sliced variables have the characteristics of being input or output. A sliced variable can sometimes have both characteristics. MATLAB transmits sliced input variables from the client to the workers, and sliced output variables from workers back to the client. If a variable is both input and output, it is transmitted in both directions.

In this `parfor`-loop, `r` is a sliced input variable and `b` is a sliced output variable.

```matlab
a = 0; 
z = 0; 
r = rand(1, 10); 
parfor ii = 1:10 
a = ii; 
z = z + ii; 
b(ii) = r(ii); 
end 
```

However, if in each iteration, every reference to an array element is set before it is used, the variable is not a sliced input variable. In this example, all elements of `A` are set, and then only those fixed values are used.
parfor ii = 1:n
  if someCondition
    A(ii) = 32;
  else
    A(ii) = 17;
  end
  loop code that uses A(ii)
end

Sliced-output variables can grow dynamically through indexed assignments with default values inserted at intermediate index positions. In this sliced variable example, you can see that the default value of 0 has been inserted at several places in a.

a = [];
parfor idx = 1:10
  if rand < 0.5
    a(idx) = idx;
  end
end
disp(a);

disp(0 2 0 4 5 0 0 8 9 10)

Even if a sliced variable is not explicitly referenced as an input, implicit usage can make it so. In the following example, not all elements of A are necessarily set inside the parfor-loop. Therefore the original values of the array are received, held, and then returned from the loop, making A both a sliced input and output variable.

A = 1:10;
parfor ii = 1:10
  if rand < 0.5
    A(ii) = 0;
  end
end

**Scalar Expansion with Sliced Outputs**

You cannot use scalar expansion to define a set of values assigned to a sliced output array. For example, the following code attempts to expand the value idx for assignment to each element of the vector defined by x(:,idx); this action generates an error.

x = zeros(10,12);
parfor idx = 1:12
The following code offers a suggested workaround for this limitation.

```matlab
x = zeros(10,12);
parfor idx = 1:12
    x(:,idx) = repmat(idx,10,1);
end
```

**See Also**

**More About**

- “Troubleshoot Variables in parfor-Loops” on page 2-32
Broadcast Variables

A broadcast variable is any variable, other than the loop variable or a sliced variable, that does not change inside the loop. At the start of a parfor-loop, the values of any broadcast variables are sent to all workers. This type of variable can be useful or even essential for particular tasks. However, large broadcast variables can cause significant communication between client and workers and increase parallel overhead. Sometimes it is more efficient to use temporary variables for this purpose, creating and assigning them inside the loop.

For more details, see “Temporary Variables” on page 2-53 and “Deciding When to Use parfor” on page 2-2.

See Also

More About

• “Troubleshoot Variables in parfor-Loops” on page 2-32
• “Deciding When to Use parfor” on page 2-2
• “Temporary Variables” on page 2-53
Reduction Variables

MATLAB supports an important exception, called reduction, to the rule that loop iterations must be independent. A reduction variable accumulates a value that depends on all the iterations together, but is independent of the iteration order. MATLAB allows reduction variables in `parfor`-loops.

Reduction variables appear on both sides of an assignment statement, such as any of the following, where `expr` is a MATLAB expression.

<table>
<thead>
<tr>
<th>X = X + expr</th>
<th>X = expr + X</th>
</tr>
</thead>
<tbody>
<tr>
<td>X = X - expr</td>
<td></td>
</tr>
<tr>
<td>X = X .* expr</td>
<td></td>
</tr>
<tr>
<td>X = X * expr</td>
<td></td>
</tr>
<tr>
<td>X = X &amp; expr</td>
<td></td>
</tr>
<tr>
<td>X = X</td>
<td>expr</td>
</tr>
<tr>
<td>X = [X, expr]</td>
<td>X = [expr, X]</td>
</tr>
<tr>
<td>X = [X; expr]</td>
<td>X = [expr; X]</td>
</tr>
<tr>
<td>X = min(X, expr)</td>
<td>X = min(expr, X)</td>
</tr>
<tr>
<td>X = max(X, expr)</td>
<td>X = max(expr, X)</td>
</tr>
<tr>
<td>X = union(X, expr)</td>
<td>X = union(expr, X)</td>
</tr>
<tr>
<td>X = intersect(X, expr)</td>
<td>X = intersect(expr, X)</td>
</tr>
</tbody>
</table>

Each of the allowed statements listed in this table is referred to as a reduction assignment. By definition, a reduction variable can appear only in assignments of this type.

The general form of a reduction assignment is

\[
X = f(X, \text{expr})
\]

The following example shows a typical usage of a reduction variable `X`.

```matlab
X = ...; % Do some initialization of X
parfor i = 1:n
```
\[ X = X + d(i); \]
end

This loop is equivalent to the following, where you calculate each \( d(i) \) by a different iteration.

\[ X = X + d(1) + \ldots + d(n) \]

In a regular for-loop, the variable \( X \) would get its value either before entering the loop or from the previous iteration of the loop. However, this concept does not apply to parfor-loops.

In a parfor-loop, the value of \( X \) is never transmitted from client to workers or from worker to worker. Rather, additions of \( d(i) \) are done in each worker, with \( i \) ranging over the subset of \( 1:n \) being performed on that worker. The results are then transmitted back to the client, which adds the partial sums of the workers into \( X \). Thus, workers do some of the additions, and the client does the rest.

### Notes About Required and Recommended Guidelines

If your parfor code does not adhere to the guidelines and restrictions labeled as Required, you get an error. MATLAB catches some of these errors at the time it reads the code, and others when it executes the code. These errors are labeled as Required (static) or Required (dynamic) respectively. Guidelines that do not cause errors are labeled as Recommended. You can use MATLAB Code Analyzer to help parfor-loops comply with the guidelines.

### Basic Rules for Reduction Variables

The following requirements further define the reduction assignments associated with a given variable.

**Required (static):** For any reduction variable, the same reduction function or operation must be used in all reduction assignments for that variable.

The parfor-loop on the left is not valid because the reduction assignment uses + in one instance, and [ , ] in another. The parfor-loop on the right is valid.
The **parfor**-loop on the left is not valid because the order of items in the concatenation is not consistent throughout the loop. The **parfor**-loop on the right is valid.

<table>
<thead>
<tr>
<th><strong>Invalid</strong></th>
<th><strong>Valid</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td><code>parfor i = 1:n</code></td>
<td><code>parfor i = 1:n</code></td>
</tr>
<tr>
<td><code>if testLevel(k)</code></td>
<td><code>if testLevel(k)</code></td>
</tr>
<tr>
<td><code>A = A + i;</code></td>
<td><code>A = A + i;</code></td>
</tr>
<tr>
<td><code>else</code></td>
<td><code>else</code></td>
</tr>
<tr>
<td><code>A = [A, 4+i];</code></td>
<td><code>A = A + i + 5*k;</code></td>
</tr>
<tr>
<td><code>end</code></td>
<td><code>end</code></td>
</tr>
<tr>
<td><code>% loop body continued</code></td>
<td><code>% loop body continued</code></td>
</tr>
<tr>
<td><code>end</code></td>
<td><code>end</code></td>
</tr>
</tbody>
</table>

**Required (static):** If the reduction assignment uses *, [ , ], or [ ; ], then X must be consistently specified as the first or second argument in every reduction assignment.

**Requirements for Reduction Assignments**

*Reduction Assignments.* In addition to the specific forms of reduction assignment listed in the table in “Reduction Variables” on page 2-46, the only other (and more general) form of a reduction assignment is

\[ X = f(X, \text{expr}) \quad \text{or} \quad X = f(\text{expr}, X) \]

**Required (static):** \( f \) can be a function or a variable. If \( f \) is a variable, then you cannot change \( f \) in the **parfor** body (in other words, it is a broadcast variable).

If \( f \) is a variable, then for all practical purposes its value at run time is a function handle. However, as long as the right side can be evaluated, the resulting value is stored in \( X \).

The **parfor**-loop on the left does not execute correctly because the statement \( f = @times \) causes \( f \) to be classified as a temporary variable. Therefore \( f \) is cleared at the
beginning of each iteration. The parfor-loop on the right is correct, because it does not assign \( f \) inside the loop.

<table>
<thead>
<tr>
<th>Invalid</th>
<th>Valid</th>
</tr>
</thead>
<tbody>
<tr>
<td>( f = @(x,k)x \times k; )</td>
<td>( f = @(x,k)x \times k; )</td>
</tr>
<tr>
<td>\texttt{parfor} ( i = 1:n )</td>
<td>\texttt{parfor} ( i = 1:n )</td>
</tr>
<tr>
<td>( a = f(a,i); )</td>
<td>( a = f(a,i); )</td>
</tr>
<tr>
<td>% loop body continued</td>
<td>% loop body continued</td>
</tr>
<tr>
<td>( f = @times; ) % Affects ( f )</td>
<td>end</td>
</tr>
</tbody>
</table>

The operators \&\& and \|\| are not listed in the table in “Reduction Variables” on page 2-46. Except for \&\& and \|\|, all the matrix operations of MATLAB have a corresponding function \( f \), such that \( u \text{ op } v \) is equivalent to \( f(u,v) \). For \&\& and \|\|, such a function cannot be written because \( u\&\&v \) and \( u\|v \) might or might not evaluate \( v \). However, \( f(u,v) \) always evaluates \( v \) before calling \( f \). Therefore \&\& and \|\| are excluded from the table of allowed reduction assignments for a \texttt{parfor}-loop.

Every reduction assignment has an associated function \( f \). The properties of \( f \) that ensure deterministic behavior of a parfor statement are discussed in the following sections.

**Associativity in Reduction Assignments.** The following practice is recommended for the function \( f \), as used in the definition of a reduction variable. However, this rule does not generate an error if not adhered to. Therefore, it is up to you to ensure that your code meets this recommendation.

**Recommended:** To get deterministic behavior of \texttt{parfor}-loops, the reduction function \( f \) must be associative.

To be associative, the function \( f \) must satisfy the following for all \( a, b, \) and \( c \).

\[
f(a,f(b,c)) = f(f(a,b),c)
\]

The classification rules for variables, including reduction variables, are purely syntactic. They cannot determine whether the \( f \) you have supplied is truly associative or not. Associativity is assumed, but if you violate this rule, each execution of the loop might result in different answers.

**Note** The addition of mathematical real numbers is associative. However, the addition of floating-point numbers is only approximately associative. Different executions of this \texttt{parfor} statement might produce values of \( X \) with different round-off errors. You cannot avoid this cost of parallelism.
For example, the statement on the left yields 1, while the statement on the right returns 1 + \( \varepsilon \):

\[(1 + \varepsilon/2) + \varepsilon/2 \quad 1 + (\varepsilon/2 + \varepsilon/2)\]

Except for the minus operator (\(-\)), all special cases listed in the table in “Reduction Variables” on page 2-46 have a corresponding (approximately) associative function. MATLAB calculates the assignment \( X = X - \text{expr} \) by using \( X = X + (-\text{expr}) \). (So, technically, the function for calculating this reduction assignment is plus, not minus.) However, the assignment \( X = \text{expr} - X \) cannot be written using an associative function, which explains its exclusion from the table.

**Commutativity in Reduction Assignments.** Some associative functions, including \(+, \cdot, \min, \text{ and } \max, \text{ intersect, } \text{ and } \text{union}, \text{ are also commutative. That is, they satisfy the following for all } a \text{ and } b.**

\[f(a, b) = f(b, a)\]

Noncommutative functions include \( \cdot \) (because matrix multiplication is not commutative for matrices in which both dimensions have size greater than one), \([,] \), and \([;] \). Noncommutativity is the reason that consistency in the order of arguments to these functions is required. As a practical matter, a more efficient algorithm is possible when a function is commutative as well as associative, and \texttt{parfor} is optimized to exploit commutativity.

**Recommended:** Except in the cases of \( \cdot, [,] \), and \([;] \), the function \( f \) of a reduction assignment must be commutative. If \( f \) is not commutative, different executions of the loop might result in different answers.

Violating the restriction on commutativity in a function used for reduction could result in unexpected behavior, even if it does not generate an error.

Unless \( f \) is a known noncommutative built-in function, it is assumed to be commutative. There is currently no way to specify a user-defined, noncommutative function in \texttt{parfor}.

**Overloading in Reduction Assignments.** Most associative functions \( f \) have an identity element \( e \), so that for any \( a \), the following holds true.

\[f(e, a) = a = f(a, e)\]

Examples of identity elements for some functions are listed here.
MATLAB uses the identity elements of reduction functions when it knows them. So, in addition to associativity and commutativity, also keep identity elements in mind when overloading these functions.

**Recommended:** An overload of +, *, .*, [ , ], or [ ; ] must be associative if it is used in a reduction assignment in a `parfor`-loop. The overload must treat the respective identity element in the table (all with class `double`) as an identity element.

**Recommended:** An overload of +, .*, `union`, or `intersect` must be commutative.

There is no way to specify the identity element for a function. In these cases, the behavior of `parfor` is less efficient than for functions with a known identity element, but the results are correct.

Similarly, because of the special treatment of \( X = X - expr \), the following is recommended.

**Recommended:** An overload of the minus operator (–) must obey the mathematical law that \( X - (y + z) \) is equivalent to \( (X - y) - z \).

### Using a Custom Reduction Function

Suppose that each iteration of a loop performs some calculation, and you are interested in finding which iteration of a loop produces the maximum value. This reduction exercise makes an accumulation across multiple iterations of a loop. Your reduction function must compare iteration results, until the maximum value can be determined after all iterations are compared.

First consider the reduction function itself. To compare one iteration result against another, the function requires as input the current result and the known maximum from other iterations so far. Each of the two inputs is a vector containing iteration results and iteration number.
function mc = comparemax(A, B)
% Custom reduction function for 2-element vector input

if A(1) >= B(1) % Compare the two input data values
    mc = A; % Return the vector with the larger result
else
    mc = B;
end

Inside the loop, each iteration calls the reduction function (comparemax), passing in a pair of two-element vectors:

- The accumulated maximum and its iteration index, which is the reduction variable cummax
- The iteration value and index

If the data value of the current iteration is greater than the maximum in cummax, the function returns a vector of the new value and its iteration number. Otherwise, the function returns the existing maximum and its iteration number.

Each iteration calls the reduction function comparemax to compare its own data [dat i] to data already accumulated in cummax. Try the following code for this loop.

% First element of cummax is maximum data value
% Second element of cummax is where (iteration) maximum occurs
cummax = [0 0]; % Initialize reduction variable
parfor ii = 1:100
    dat = rand(); % Simulate some actual computation
    cummax = comparemax(cummax, [dat ii]);
end
disp(cummax);

See Also

More About

• “Troubleshoot Variables in parfor-Loops” on page 2-32
• “Use parfor-Loops for Reduction Assignments” on page 2-28
Temporary Variables

A temporary variable is any variable that is the target of a direct, nonindexed assignment, but is not a reduction variable. In the following parfor-loop, a and d are temporary variables:

```matlab
a = 0;
z = 0;
r = rand(1,10);
parfor i = 1:10
    a = i;        % Variable a is temporary
    z = z + i;
    if i <= 5
        d = 2*a;   % Variable d is temporary
    end
end
```

In contrast to the behavior of a for-loop, MATLAB clears any temporary variables before each iteration of a parfor-loop. To help ensure the independence of iterations, the values of temporary variables cannot be passed from one iteration of the loop to another. Therefore, temporary variables must be set inside the body of a parfor-loop, so that their values are defined separately for each iteration.

MATLAB does not send temporary variables back to the client. A temporary variable in a parfor-loop has no effect on a variable with the same name that exists outside the loop. This behavior is different from ordinary for-loops.

Uninitialized Temporaries

Temporary variables in a parfor-loop are cleared at the beginning of every iteration. MATLAB can sometimes detect cases in which loop iterations use a temporary variable before it is set in that iteration. In this case, MATLAB issues a static error rather than a run-time error. There is little point in allowing execution to proceed if a run-time error is guaranteed to occur. This kind of error often arises because of confusion between for and parfor, especially regarding the rules of classification of variables. For example:

```matlab
b = true;
parfor i = 1:n
    if b && some_condition(i)
        do_something(i);
        b = false;
```
This loop is acceptable as an ordinary `for`-loop. However, as a `parfor`-loop, `b` is a temporary variable because it occurs directly as the target of an assignment inside the loop. Therefore it is cleared at the start of each iteration, so its use in the condition of the `if` is guaranteed to be uninitialized. If you change `parfor` to `for`, the value of `b` assumes sequential execution of the loop. In that case, `do_something(i)` is executed only for the lower values of `i` until `b` is set `false`.

Temporary Variables Intended as Reduction Variables

Another common cause of uninitialized temporaries can arise when you have a variable that you intended to be a reduction variable. However, if you use it elsewhere in the loop, then it is classified as a temporary variable. For example:

```matlab
s = 0;
parfor i = 1:n
    s = s + f(i);
    ...
    if (s > whatever)
        ...
    end
end
```

If the only occurrences of `s` are the two in the first statement of the body, `s` would be classified as a reduction variable. But in this example, `s` is not a reduction variable because it has a use outside of reduction assignments in the line `s > whatever`. Because `s` is the target of an assignment (in the first statement), it is a temporary. Therefore MATLAB issues an error, but points out the possible connection with reduction.

If you change `parfor` to `for`, the use of `s` outside the reduction assignment relies on the iterations being performed in a particular order. In a `parfor`-loop, it matters that the loop “does not care” about the value of a reduction variable as it goes along. It is only after the loop that the reduction value becomes usable.
See Also

More About

- “Troubleshoot Variables in parfor-Loops” on page 2-32
- “Reduction Variables” on page 2-46
- “Ensure Transparency in parfor-Loops” on page 2-56
Ensure Transparency in parfor-Loops

The body of a parfor-loop or spmd block must be transparent. Transparency means that all references to variables must be visible in the text of the code.

In the following examples, the variable \( X \) is not transferred to the workers. Only the character vector \( 'X' \) is passed to eval, and \( X \) is not visible as an input variable in the loop or block body. As a result, MATLAB issues an error at run time.

```
X = 5;
parfor ii = 1:4
    eval('X');
end
```

```
X = 5;
spmd
    eval('X');
end
```

Similarly, you cannot clear variables from a workspace by executing clear inside a parfor or spmd statement:

```
parfor ii = 1:4
    <statements...>
    clear('X')  % cannot clear: transparency violation
    <statements...>
end
```
```
spmd; clear('X'); end
```

Alternatively, you can free up memory used by a variable by setting its value to empty when it is no longer needed.

```
parfor ii = 1:4
    <statements...>
    X = [];
    <statements...>
end
```

In the case of spmd blocks, you can clear its Composite from the client workspace.

In general, the requirement for transparency restricts all dynamic access to variables, because the entire variable might not be present in any given worker. In a transparent workspace, you cannot create, delete, modify, access, or query variables if you do not explicitly specify these variables in the code.

Examples of other actions or functions that violate transparency in a parfor-loop include:

- who
- and
- whos
• evalc, evalin, and assignin with the workspace argument specified as 'caller'
• save and load, unless the output of load is assigned to a variable
• If a script attempts to read or write variables of the parent workspace, then running this script can cause a transparency violation. To avoid this issue, convert the script to a function, and call it with the necessary variables as input or output arguments.

**Note** Transparency applies only to the direct body of the parfor or spmd construct, and not to any functions called from there. The workaround for save and load is to hide the calls to save and load inside a function.

MATLAB *does* successfully execute eval and evalc statements that appear in functions called from the parfor body.

### Parallel Simulink Simulations

You can run Simulink models in parallel with the parsim command instead of using parfor-loops. For more information and examples of using Simulink in parallel, see “Run Multiple Simulations” (Simulink).

• If your Simulink model requires access to variables contained in a .mat file, you must load these parameters in the workspace of each worker. You must do this before the parfor-loop, and after opening parpool. To achieve this, you can use spmd or parfevalOnAll, as shown in the examples.

```matlab
spmd
    evalin('base', 'load(''path/to/file'')')
end
parfevalOnAll(@evalin, 0, 'base', 'load(''path/to/file'')')
```

• If your model also requires variables defined in the body of your MATLAB script, you must use assignin or evalin to move these variables to the base workspace of each worker, in every parfor iteration.

### See Also

parfor | spmd
More About

• “Troubleshoot Variables in parfor-Loops” on page 2-32
• “Run Single Programs on Multiple Data Sets” on page 3-2
• “Run Parallel Simulations” (Simulink)
Improve parfor Performance

You can improve the performance of parfor-loops in various ways. This includes parallel creation of arrays inside the loop; profiling parfor-loops; slicing arrays; and optimizing your code on local workers before running on a cluster.

Where to Create Arrays

When you create a large array in the client before your parfor-loop, and access it within the loop, you might observe slow execution of your code. To improve performance, tell each MATLAB worker to create its own arrays, or portions of them, in parallel. You can save the time of transferring data from client to workers by asking each worker to create its own copy of these arrays, in parallel, inside the loop. Consider changing your usual practice of initializing variables before a for-loop, avoiding needless repetition inside the loop. You might find that parallel creation of arrays inside the loop improves performance.

Performance improvement depends on different factors, including

- size of the arrays
- time needed to create arrays
- worker access to all or part of the arrays
- number of loop iterations that each worker performs

Consider all factors in this list when you are considering to convert for-loops to parfor-loops. For more details, see “Convert for-Loops Into parfor-Loops” on page 2-8.

As an alternative, consider the parallel.pool.Constant function to establish variables on the pool workers before the loop. These variables remain on the workers after the loop finishes, and remain available for multiple parfor-loops. You might improve performance using parallel.pool.Constant, because the data is transferred only once to the workers.

In this example, you first create a big data set D and execute a parfor-loop accessing D. Then you use D to build a parallel.pool.Constant object, which allows you to reuse the data by copying D to each worker. Measure the elapsed time using tic and toc for each case and note the difference.
function constantDemo

D = rand(1e7, 1);
tic
for i = 1:20
    a = 0;
    parfor j = 1:60
        a = a + sum(D);
    end
end
toc

tic
D = parallel.pool.Constant(D);
for i = 1:20
    b = 0;
    parfor j = 1:60
        b = b + sum(D.Value);
    end
end
toc

>> constantDemo
Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.
Elapsed time is 63.839702 seconds.
Elapsed time is 10.194815 seconds.

In the second case, you send the data only once. You can enhance the performance of the parfor-loop by using the parallel.pool.Constant object.

Profiling parfor-loops

You can profile a parfor-loop by measuring the time elapsed using tic and toc. You can also measure how much data is transferred to and from the workers in the parallel pool by using ticBytes and tocBytes. Note that this is different from profiling MATLAB code in the usual sense using the MATLAB profiler, see “Profile to Improve Performance” (MATLAB).

This example calculates the spectral radius of a matrix and converts a for-loop into a parfor-loop. Measure the resulting speedup and the amount of transferred data.

1 In the MATLAB Editor, enter the following for-loop. Add tic and toc to measure the time elapsed. Save the file as MyForLoop.m.
function a = MyForLoop(A)

tic
for i = 1:200
    a(i) = max(abs(eig(rand(A))));
end
toc

2 Run the code, and note the elapsed time.

a = MyForLoop(500);

Elapsed time is 31.935373 seconds.

3 In MyForLoop.m, replace the for-loop with a parfor-loop. Add ticBytes and tocBytes to measure how much data is transferred to and from the workers in the parallel pool. Save the file as MyParforLoop.m.

ticBytes(gcp);
parfor i = 1:200
    a(i) = max(abs(eig(rand(A))));
end
tocBytes(gcp)

4 Run the new code, and run it again. Note that the first run is slower than the second run, because the parallel pool has to be started and you have to make the code available to the workers. Note the elapsed time for the second run.

By default, MATLAB automatically opens a parallel pool of workers on your local machine.

a = MyParforLoop(500);

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers ...

<table>
<thead>
<tr>
<th>BytesSentToWorkers</th>
<th>BytesReceivedFromWorkers</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>15340</td>
</tr>
<tr>
<td>2</td>
<td>13328</td>
</tr>
<tr>
<td>3</td>
<td>13328</td>
</tr>
<tr>
<td>4</td>
<td>13328</td>
</tr>
<tr>
<td>Total</td>
<td>55324</td>
</tr>
</tbody>
</table>

Elapsed time is 10.760068 seconds.
The elapsed time is 31.9 seconds in serial and 10.8 seconds in parallel, and shows that this code benefits from converting to a `parfor`-loop.

**Slicing Arrays**

If a variable is initialized before a `parfor`-loop, then used inside the `parfor`-loop, it has to be passed to each MATLAB worker evaluating the loop iterations. Only those variables used inside the loop are passed from the client workspace. However, if all occurrences of the variable are indexed by the loop variable, each worker receives only the part of the array it needs.

As an example, you first run a `parfor`-loop using a sliced variable and measure the elapsed time.

```matlab
% Sliced version
M = 100;
N = 1e6;
data = rand(M, N);

tic
parfor idx = 1:M
    out2(idx) = sum(data(idx, :)) ./ N;
end
toc
Elapsed time is 2.261504 seconds.
```

Now suppose that you accidentally use a reference to the variable `data` instead of `N` inside the `parfor`-loop. The problem here is that the call to `size(data, 2)` converts the sliced variable into a broadcast (non-sliced) variable.

```matlab
% Accidentally non-sliced version
clear
M = 100;
N = 1e6;
data = rand(M, N);

tic
parfor idx = 1:M
    out2(idx) = sum(data(idx, :) ./ size(data, 2));
end
toc
```

2-62
Note that the elapsed time is greater for the accidentally broadcast variable.

In this case, you can easily avoid the non-sliced usage of `data`, because the result is a constant, and can be computed outside the loop. In general, you can perform computations that depend only on broadcast data before the loop starts, since the broadcast data cannot be modified inside the loop. In this case, the computation is trivial, and results in a scalar result, so you benefit from taking the computation out of the loop.

### Optimizing on Local vs. Cluster Workers

Running your code on local workers might offer the convenience of testing your application without requiring the use of cluster resources. However, there are certain drawbacks or limitations with using local workers. Because the transfer of data does not occur over the network, transfer behavior on local workers might not be indicative of how it will typically occur over a network.

With local workers, because all the MATLAB worker sessions are running on the same machine, you might not see any performance improvement from a `parfor`-loop regarding execution time. This can depend on many factors, including how many processors and cores your machine has. The key point here is that a cluster might have more cores available than your local machine. If your code can be multithreaded by MATLAB, then the only way to go faster is to use more cores to work on the problem, using a cluster.

You might experiment to see if it is faster to create the arrays before the loop (as shown on the left below), rather than have each worker create its own arrays inside the loop (as shown on the right).

Try the following examples running a parallel pool locally, and notice the difference in time execution for each loop. First open a local parallel pool:

```matlab
parpool('local')
```

Run the following examples, and execute again. Note that the first run for each case is slower than the second run, because the parallel pool has to be started and you have to make the code available to the workers. Note the elapsed time, for each case, for the second run.
tic;
n = 200;
M = magic(n);
R = rand(n);
parfor i = 1:n
    A(i) = sum(M(i,:).*R(n+1-i,:));
end
toc

Running on a remote cluster, you might find different behavior, as workers can simultaneously create their arrays, saving transfer time. Therefore, code that is optimized for local workers might not be optimized for cluster workers, and vice versa.

See Also
parallel.pool.Constant

More About
• “Ensure Transparency in parfor-Loops” on page 2-56
• “Use parfor-Loops for Reduction Assignments” on page 2-28
Run Code on Parallel Pools

In this section...

“What Is a Parallel Pool?” on page 2-65
“Automatically Start and Stop a Parallel Pool ” on page 2-66
“Alternative Ways to Start and Stop Pools” on page 2-67
“Pool Size and Cluster Selection” on page 2-68

What Is a Parallel Pool?

A parallel pool is a set of MATLAB workers on a compute cluster or desktop. By default, a parallel pool starts automatically when needed by parallel language features such as parfor. You can specify the default pool size and cluster in your parallel preferences. The preferences panel displays your pool size and cluster when you select Parallel Preferences in the Parallel menu. You can change pool size and cluster in the Parallel menu. Alternatively, you can choose cluster and pool size using parcluster and parpool respectively, on the MATLAB command line. See the image for more detail.

The workers in a parallel pool can be used interactively and communicate with each other during the lifetime of the job. You can view your parpool jobs in the “Job Monitor” on page 6-38. While these pool workers are reserved for your interactive use, they are not available to other users. You can have only one parallel pool at a time from a MATLAB client session. In MATLAB, the current parallel pool is represented by a parallel.Pool object.
Automatically Start and Stop a Parallel Pool

By default, a parallel pool starts automatically when needed by certain parallel language features. The following statements and functions can cause a parallel pool to start:

- parfor
- spmd
- distributed
- Composite
- parallel.pool.Constant
- parfeval
- parfevalOnAll
- gcp
- mapreduce
- mapreduce
- tall
- ticBytes and tocBytes
Your parallel preferences specify which cluster the pool runs on, and the preferred number of workers in the pool. To access your preferences, on the Home tab, in the Environment section, click Parallel > Parallel Preferences.

**Alternative Ways to Start and Stop Pools**

In your parallel preferences, you can turn off the option for the pool to open or close automatically. If you choose not to have the pool open automatically, you can control the pool with the following techniques.

**Control the Parallel Pool from the MATLAB Desktop**

You can use the parallel status indicator in the lower left corner of the MATLAB desktop to start a parallel pool manually.

Click the indicator icon, and select Start parallel pool. The pool size and cluster are specified by your parallel preferences and default cluster. Your default cluster is indicated by a check mark on the Parallel > Default Cluster menu.

The menu options are different when a pool is running. You can:

- View the number of workers and cluster name
- Change the time until automatic shut-down
- Shut down the parallel pool

To stop a pool, you can also select Shut down parallel pool.
Programming Interface

Start a Parallel Pool

You can start and stop a parallel pool programmatically by using default settings or specifying alternatives.

To open a parallel pool based on your preference settings:

parpool

To open a pool of a specific size:

parpool(4)

To use a cluster other than your default and specify where the pool runs:

parpool('MyCluster',4)

Shut Down a Parallel Pool

To get the current parallel pool and use that object when you want to shut down the pool:

p = gcp;
delete(p)

Ensure That No Parallel Pool Is Running

When you issue the command gcp without arguments, you might inadvertently open a pool. To avoid this problem:

delete(gcp('nocreate'))

Pool Size and Cluster Selection

There are several places to specify pool size. Several factors might limit the size of a pool. The actual size of your parallel pool is determined by the combination of the following:
Licensing or cluster size

The maximum limit on the number of workers in a pool is restricted by the number of workers in your cluster. This limit might be determined by the number of MATLAB Distributed Computing Server licenses available. In the case of MATLAB job scheduler (MJS), the limit might be determined by the number of workers running in the cluster. A local cluster running on the client machine requires no licensing beyond the one for Parallel Computing Toolbox. The limit on the number of workers is high enough to support the range of known desktop hardware.

Cluster profile number of workers (NumWorkers)

A cluster object can set a hard limit on the number of workers, which you specify in the cluster profile. Even if you request more workers at the command line or in your preferences, you cannot exceed the limit set in the applicable profile. Attempting to exceed this number generates an error.

Command-line argument

If you specify a pool size at the command line, you override the setting of your preferences. This value must fall within the limits of the applicable cluster profile.

Parallel preferences

If you do not specify a pool size at the command line, MATLAB attempts to start a pool with size determined by your parallel preferences. This value is a preference, not a requirement or a request for a specific number of workers. So if a pool cannot start with as many workers as called for in your preferences, you get a smaller pool without any errors. You can set the value of the Preferred number of workers to a large number, so that it never limits the size of the pool that is created. If you need an exact number of workers, specify the number at the command line.

For selection of the cluster on which the pool runs, precedence is determined by the following.

1 The command-line cluster object argument overrides the default profile setting and uses the cluster identified by the profile 'MyProfile'.

```
c = parcluster('MyProfile');
p = parpool(c);
```

2 The cluster is specified in the default profile.

```
p = parpool;
```
See Also
delete | distributed | gcp | parcluster | parfeval | parfor | parpool | spmd

More About
- “How Parallel Computing Products Run a Job” on page 6-2
- “Decide When to Use parfor” on page 2-2
- “Specify Your Parallel Preferences” on page 6-12
- “Discover Clusters and Use Cluster Profiles” on page 6-18
- “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
Repeat Random Numbers in parfor-Loops

As described in “Control Random Number Streams” on page 6-46, each worker in a cluster has an independent random number generator stream. By default, therefore, each worker in a pool, and each iteration in a parfor-loop has a unique, independent set of random numbers. Subsequent runs of the parfor-loop generate different numbers.

In a parfor-loop, you cannot control what sequence the iterations execute in, nor can you control which worker runs which iterations. So even if you reset the random number generators, the parfor-loop can generate the same values in a different sequence.

To reproduce the same set of random numbers in a parfor-loop each time the loop runs, you must control random generation by assigning a particular substream for each iteration.

First, give each worker the same stream, one that supports substreams.

```matlab
parpool('local',4);
spmd
    rng(0,'combRecursive');
end
```

Inside the parfor-loop, set the substream index by the loop index. This ensures that each iteration uses its particular set of random numbers, regardless of which worker runs that iteration or what sequence iterations run in.

```matlab
r = zeros(1,16);
parfor i = 1:16
    stream = RandStream.getGlobalStream();
    stream.Substream = i;
    r(i) = rand;
end
r
```

```matlab
r =

Columns 1 through 8
0.7270  0.5582  0.1666  0.3477  0.5671  0.5502  0.0130  0.9179

Columns 9 through 16
0.1567  0.7076  0.8577  0.8923  0.0891  0.2413  0.6074  0.2369
```
Single Program Multiple Data (spmd)

- “Run Single Programs on Multiple Data Sets” on page 3-2
- “Access Worker Variables with Composites” on page 3-8
- “Distributing Arrays” on page 3-12
Run Single Programs on Multiple Data Sets

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**Introduction**

The single program multiple data (spmd) language construct allows seamless interleaving of serial and parallel programming. The `spmd` statement lets you define a block of code to run simultaneously on multiple workers. Variables assigned inside the `spmd` statement on the workers allow direct access to their values from the client by reference via `Composite` objects.

This chapter explains some of the characteristics of `spmd` statements and `Composite` objects.

**When to Use spmd**

The “single program” aspect of spmd means that the identical code runs on multiple workers. You run one program in the MATLAB client, and those parts of it labeled as `spmd` blocks run on the workers. When the `spmd` block is complete, your program continues running in the client.

The “multiple data” aspect means that even though the `spmd` statement runs identical code on all workers, each worker can have different, unique data for that code. So multiple data sets can be accommodated by multiple workers.

Typical applications appropriate for `spmd` are those that require running simultaneous execution of a program on multiple data sets, when communication or synchronization is required between the workers. Some common cases are:
• Programs that take a long time to execute — spmd lets several workers compute solutions simultaneously.
• Programs operating on large data sets — spmd lets the data be distributed to multiple workers.

Define an spmd Statement

The general form of an spmd statement is:

```
spmd
    <statements>
end
```

**Note** If a parallel pool is not running, spmd creates a pool using your default cluster profile, if your parallel preferences are set accordingly.

The block of code represented by `<statements>` executes in parallel simultaneously on all workers in the parallel pool. If you want to limit the execution to only a portion of these workers, specify exactly how many workers to run on:

```
spmd (n)
    <statements>
end
```

This statement requires that n workers run the spmd code. n must be less than or equal to the number of workers in the open parallel pool. If the pool is large enough, but n workers are not available, the statement waits until enough workers are available. If n is 0, the spmd statement uses no workers, and runs locally on the client, the same as if there were not a pool currently running.

You can specify a range for the number of workers:

```
spmd (m,n)
    <statements>
end
```

In this case, the spmd statement requires a minimum of m workers, and it uses a maximum of n workers.
If it is important to control the number of workers that execute your `spmd` statement, set the exact number in the cluster profile or with the `spmd` statement, rather than using a range.

For example, create a random matrix on three workers:

```matlab
spmd (3)
    R = rand(4,4);
end
```

**Note** All subsequent examples in this chapter assume that a parallel pool is open and remains open between sequences of `spmd` statements.

Unlike a `parfor`-loop, the workers used for an `spmd` statement each have a unique value for `labindex`. This lets you specify code to be run on only certain workers, or to customize execution, usually for the purpose of accessing unique data.

For example, create different sized arrays depending on `labindex`:

```matlab
spmd (3)
    if labindex==1
        R = rand(9,9);
    else
        R = rand(4,4);
    end
end
```

Load unique data on each worker according to `labindex`, and use the same function on each worker to compute a result from the data:

```matlab
spmd (3)
    labdata = load(['datafile_' num2str(labindex) '.ascii'])
    result = MyFunction(labdata)
end
```

The workers executing an `spmd` statement operate simultaneously and are aware of each other. As with a communicating job, you are allowed to directly control communications between the workers, transfer data between them, and use codistributed arrays among them.

For example, use a codistributed array in an `spmd` statement:
spmd (3)
    RR = rand(30, codistributor());
end

Each worker has a 30-by-10 segment of the codistributed array RR. For more information about codistributed arrays, see “Working with Codistributed Arrays” on page 5-5.

Display Output

When running an spmd statement on a parallel pool, all command-line output from the workers displays in the client Command Window. Because the workers are MATLAB sessions without displays, any graphical output (for example, figure windows) from the pool does not display at all.

MATLAB Path

All workers executing an spmd statement must have the same MATLAB search path as the client, so that they can execute any functions called in their common block of code. Therefore, whenever you use cd, addpath, or rmpath on the client, it also executes on all the workers, if possible. For more information, see the parpool reference page. When the workers are running on a different platform than the client, use the function pctRunOnAll to properly set the MATLAB path on all workers.

Error Handling

When an error occurs on a worker during the execution of an spmd statement, the error is reported to the client. The client tries to interrupt execution on all workers, and throws an error to the user.

Errors and warnings produced on workers are annotated with the worker ID (labindex) and displayed in the client’s Command Window in the order in which they are received by the MATLAB client.

The behavior of lastwarn is unspecified at the end of an spmd if used within its body.
**spmd Limitations**

**Nested Functions**

Inside a function, the body of an `spmd` statement cannot make any direct reference to a nested function (MATLAB). However, it can call a nested function by means of a variable defined as a function handle to the nested function.

Because the `spmd` body executes on workers, variables that are updated by nested functions called inside an `spmd` statement do not get updated in the workspace of the outer function.

**Anonymous Functions**

The body of an `spmd` statement cannot define an anonymous function (MATLAB). However, it can reference an anonymous function by means of a function handle.

**Nested `spmd` Statements**

The body of an `spmd` statement cannot directly contain another `spmd`. However, it can call a function that contains another `spmd` statement. The inner `spmd` statement does not run in parallel in another parallel pool, but runs serially in a single thread on the worker running its containing function.

**Nested parfor-Loops**

The body of a `parfor`-loop cannot contain an `spmd` statement, and an `spmd` statement cannot contain a `parfor`-loop.

**Break and Return Statements**

The body of an `spmd` statement cannot contain `break` or `return` statements.

**Global and Persistent Variables**

The body of an `spmd` statement cannot contain `global` or `persistent` variable declarations.
See Also

More About

- “Ensure Transparency in parfor-Loops” on page 2-56
Access Worker Variables with Composites

In this section...

“Introduction to Composites” on page 3-8
“Create Composites in spmd Statements” on page 3-8
“Variable Persistence and Sequences of spmd” on page 3-10
“Create Composites Outside spmd Statements” on page 3-11

Introduction to Composites

Composite objects in the MATLAB client session let you directly access data values on the workers. Most often you assigned these variables within \texttt{spmd} statements. In their display and usage, Composites resemble cell arrays. There are two ways to create Composites:

- Use the \texttt{Composite} function on the client. Values assigned to the Composite elements are stored on the workers.
- Define variables on workers inside an \texttt{spmd} statement. After the \texttt{spmd} statement, the stored values are accessible on the client as Composites.

Create Composites in \texttt{spmd} Statements

When you define or assign values to variables inside an \texttt{spmd} statement, the data values are stored on the workers.

After the \texttt{spmd} statement, those data values are accessible on the client as Composites. Composite objects resemble cell arrays, and behave similarly. On the client, a Composite has one element per worker. For example, suppose you create a parallel pool of three local workers and run an \texttt{spmd} statement on that pool:

```
parpool('local',3)

spmd  \% Uses all 3 workers
    MM = magic(labindex+2);  \% MM is a variable on each worker
end
MM{1}  \% In the client, MM is a Composite with one element per worker
```
A variable might not be defined on every worker. For the workers on which a variable is not defined, the corresponding Composite element has no value. Trying to read that element throws an error.

```
spmd
  if labindex > 1
    HH = rand(4);
  end
end
HH
```

You can also set values of Composite elements from the client. This causes a transfer of data, storing the value on the appropriate worker even though it is not executed within an `spmd` statement:

```
MM{3} = eye(4);
```

In this case, `MM` must already exist as a Composite, otherwise MATLAB interprets it as a cell array.

Now when you do enter an `spmd` statement, the value of the variable `MM` on worker 3 is as set:

```
spmd
  if labindex == 3, MM, end
end
Lab 3:
      MM =
          1     0     0     0
Data transfers from worker to client when you explicitly assign a variable in the client workspace using a Composite element:

\[ M = MM\{1\} \] \% Transfer data from worker 1 to variable M on the client

Assigning an entire Composite to another Composite does not cause a data transfer. Instead, the client merely duplicates the Composite as a reference to the appropriate data stored on the workers:

\[ NN = MM \] \% Set entire Composite equal to another, without transfer

However, accessing a Composite's elements to assign values to other Composites does result in a transfer of data from the workers to the client, even if the assignment then goes to the same worker. In this case, \( NN \) must already exist as a Composite:

\[ NN\{1\} = MM\{1\} \] \% Transfer data to the client and then to worker

When finished, you can delete the pool:

`delete(gcp)`

**Variable Persistence and Sequences of spmd**

The values stored on the workers are retained between \texttt{spmd} statements. This allows you to use multiple \texttt{spmd} statements in sequence, and continue to use the same variables defined in previous \texttt{spmd} blocks.

The values are retained on the workers until the corresponding Composites are cleared on the client, or until the parallel pool is deleted. The following example illustrates data value lifespan with \texttt{spmd} blocks, using a pool of four workers:

```plaintext
parpool('local',4)

spmd
    AA = labindex; \% Initial setting
```
AA(:)  % Composite

[1]
[2]
[3]
[4]

spmd
    AA = AA * 2; % Multiply existing value
end
AA(:)  % Composite

[2]
[4]
[6]
[8]

clear AA % Clearing in client also clears on workers

spmd; AA = AA * 2; end   % Generates error

delete(gcp)

Create Composites Outside spmd Statements

The Composite function creates Composite objects without using an spmd statement. This might be useful to prepopulate values of variables on workers before an spmd statement begins executing on those workers. Assume a parallel pool is already running:

PP = Composite()

By default, this creates a Composite with an element for each worker in the parallel pool. You can also create Composites on only a subset of the workers in the pool. See the Composite reference page for more details. The elements of the Composite can now be set as usual on the client, or as variables inside an spmd statement. When you set an element of a Composite, the data is immediately transferred to the appropriate worker:

for ii = 1:numel(PP)
    PP{ii} = ii;
end
Distributing Arrays

In this section...

| Using Distributed Arrays to Partition Data Across Workers” on page 3-12 |
| “Load Distributed Arrays in Parallel Using datastore” on page 3-12 |
| “Alternative Methods for Creating Distributed and Codistributed Arrays” on page 3-15 |

Using Distributed Arrays to Partition Data Across Workers

Depending on how your data fits in memory, choose one of the following methods:

- If your data is currently in the memory of your local machine, you can use the `distributed` function to distribute an existing array from the client workspace to the workers of a parallel pool. This option can be useful for testing or before performing operations which significantly increase the size of your arrays, such as `repmat`.

- If your data does not fit in the memory of your local machine, but does fit in the memory of your cluster, you can use `datastore` with the `distributed` function to read data into the memory of the workers of a parallel pool.

- If your data does not fit in the memory of your cluster, you can use `datastore` with `tall` arrays to partition and process your data in chunks. See also “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67.

Load Distributed Arrays in Parallel Using datastore

If your data does not fit in the memory of your local machine, but does fit in the memory of your cluster, you can use `datastore` with the `distributed` function to create distributed arrays and partition the data among your workers.

This example shows how to create and load distributed arrays using `datastore`. Create a datastore using a tabular file of airline flight data. This data set is too small to show equal partitioning of the data over the workers. To simulate a large data set, artificially increase the size of the datastore using `repmat`.

```plaintext
files = repmat({'airlinesmall.csv'}, 10, 1);
ds = tabularTextDatastore(files);
```

Select the example variables.
ds.SelectedVariableNames = {'DepTime','DepDelay'};
ds.TreatAsMissing = 'NA';

Create a distributed table by reading the datastore in parallel. Partition the datastore with one partition per worker. Each worker then reads all data from the corresponding partition. The files must be in a shared location that is accessible by the workers.

dt = distributed(ds);

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.

Display summary information about the distributed table.

summary(dt)

Variables:

DepTime: 1,235,230×1 double
  Values:
    min    1
    max   2505
    NaNs  23,510

DepDelay: 1,235,230×1 double
  Values:
    min  -1036
    max   1438
    NaNs  23,510

Determine the size of the tall table.

size(dt)

ans =

    1235230     2

Return the first few rows of dt.

head(dt)

ans =

    DepTime    DepDelay
Finally, check how much data each worker has loaded.

```
spmd, dt, end
```

Lab 1:

This worker stores `dt2(1:370569,:)`.

```
LocalPart: [370569×2 table]
Codistributor: [1×1 codistributor1d]
```

Lab 2:

This worker stores `dt2(370570:617615,:)`.

```
LocalPart: [247046×2 table]
Codistributor: [1×1 codistributor1d]
```

Lab 3:

This worker stores `dt2(617616:988184,:)`.

```
LocalPart: [370569×2 table]
Codistributor: [1×1 codistributor1d]
```

Lab 4:

This worker stores `dt2(988185:1235230,:)`.

```
LocalPart: [247046×2 table]
Codistributor: [1×1 codistributor1d]
```
Note that the data is partitioned equally over the workers. For more details on datastore, see “What Is a Datastore?” (MATLAB)

For more details about workflows for big data, see “Choose a Parallel Computing Solution” on page 1-26.

**Alternative Methods for Creating Distributed and Codistributed Arrays**

If your data fits in the memory of your local machine, you can use distributed arrays to partition the data among your workers. Use the `distributed` function to create a distributed array in the MATLAB client, and store its data on the workers of the open parallel pool. A distributed array is distributed in one dimension, and as evenly as possible along that dimension among the workers. You cannot control the details of distribution when creating a distributed array.

You can create a distributed array in several ways:

- Use the `distributed` function to distribute an existing array from the client workspace to the workers of a parallel pool.
- Use any of the `distributed` functions to directly construct a distributed array on the workers. This technique does not require that the array already exists in the client, thereby reducing client workspace memory requirements. Functions include `eye(___,'distributed')` and `rand(___,'distributed')`. For a full list, see the `distributed` object reference page.
- Create a codistributed array inside an `spmd` statement, and then access it as a distributed array outside the `spmd` statement. This technique lets you use distribution schemes other than the default.

The first two techniques do not involve `spmd` in creating the array, but you can use `spmd` to manipulate arrays created this way. For example:

Create an array in the client workspace, and then make it a distributed array.

```matlab
parpool('local',2) % Create pool
W = ones(6,6);
W = distributed(W); % Distribute to the workers
spmd
    T = W*2; % Calculation performed on workers, in parallel.
    % T and W are both codistributed arrays here.
end
```
Alternatively, you can use the `codistributed` function, which allows you to control more options such as dimensions and partitions, but is often more complicated. You can create a `codistributed` array by executing on the workers themselves, either inside an `spmd` statement, in `pmode`, or inside a communicating job. When creating a `codistributed` array, you can control all aspects of distribution, including dimensions and partitions.

The relationship between distributed and `codistributed` arrays is one of perspective. `Codistributed` arrays are partitioned among the workers from which you execute code to create or manipulate them. When you create a distributed array in the client, you can access it as a `codistributed` array inside an `spmd` statement. When you create a `codistributed` array in an `spmd` statement, you can access it as a distributed array in the client. Only `spmd` statements let you access the same array data from two different perspectives.

You can create a `codistributed` array in several ways:

- Use the `codistributed` function inside an `spmd` statement, a communicating job, or `pmode` to codistribute data already existing on the workers running that job.
- Use any of the `codistributed` functions to directly construct a `codistributed` array on the workers. This technique does not require that the array already exists in the workers. Functions include `eye(___,'codistributed')` and `rand(___,'codistributed')`. For a full list, see the `codistributed` object reference page.
- Create a distributed array outside an `spmd` statement, then access it as a `codistributed` array inside the `spmd` statement running on the same parallel pool.

Create a `codistributed` array inside an `spmd` statement using a nondefault distribution scheme. First, define 1-D distribution along the third dimension, with 4 parts on worker 1, and 12 parts on worker 2. Then create a 3-by-3-by-16 array of zeros.

```matlab
parpool('local',2) % Create pool
spmd
    codist = codistributor1d(3,[4,12]);
    Z = zeros(3,3,16,codist);
    Z = Z + labindex;
end
```
Z  % View results in client.
% Z is a distributed array here.
delete(gcp)  % Stop pool

For more details on codistributed arrays, see “Working with Codistributed Arrays” on page 5-5.

See Also
codistributed | datastore | distributed | eye | rand | repmat | spmd | tall

Related Examples
•  “Using MATLAB Functions on Distributed Arrays” on page 5-24
•  “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
•  “What Is a Datastore?” (MATLAB)
•  “Choose a Parallel Computing Solution” on page 1-26
•  “Use Tall Arrays on a Parallel Pool” on page 6-70

More About
•  “Datastore” (MATLAB)
•  “Tall Arrays” (MATLAB)
Interactive Parallel Computation with \texttt{pmode}

This chapter describes interactive \texttt{pmode} in the following sections:

- “\texttt{pmode Versus spmd}” on page 4-2
- “Run Communicating Jobs Interactively Using \texttt{pmode}” on page 4-3
- “Parallel Command Window” on page 4-10
- “Running \texttt{pmode} Interactive Jobs on a Cluster” on page 4-14
- “Plotting Distributed Data Using \texttt{pmode}” on page 4-15
- “\texttt{pmode} Limitations and Unexpected Results” on page 4-17
- “\texttt{pmode} Troubleshooting” on page 4-18
pmode Versus spmd

pmode lets you work interactively with a communicating job running simultaneously on several workers. Commands you type at the pmode prompt in the Parallel Command Window are executed on all workers at the same time. Each worker executes the commands in its own workspace on its own variables.

The way the workers remain synchronized is that each worker becomes idle when it completes a command or statement, waiting until all the workers working on this job have completed the same statement. Only when all the workers are idle, do they then proceed together to the next pmode command.

In contrast to spmd, pmode provides a desktop with a display for each worker running the job, where you can enter commands, see results, access each worker's workspace, etc. What pmode does not let you do is to freely interleave serial and parallel work, like spmd does. When you exit your pmode session, its job is effectively destroyed, and all information and data on the workers is lost. Starting another pmode session always begins from a clean state.
Run Communicating Jobs Interactively Using pmode

This example uses a local scheduler and runs the workers on your local MATLAB client machine. It does not require an external cluster or scheduler. The steps include the pmode prompt (P>>) for commands that you type in the Parallel Command Window.

1 Start the pmode with the pmode command.

    pmode start local 4

This starts four local workers, creates a communicating job to run on those workers, and opens the Parallel Command Window.

![Parallel Command Window](image)

You can control where the command history appears. For this exercise, the position is set by clicking **Window > History Position > Above Prompt**, but you can set it according to your own preference.

2 To illustrate that commands at the pmode prompt are executed on all workers, ask for help on a function.

    P>> help magic

3 Set a variable at the pmode prompt. Notice that the value is set on all the workers.

    P>> x = pi
A variable does not necessarily have the same value on every worker. The `labindex` function returns the ID particular to each worker working on this communicating job. In this example, the variable `x` exists with a different value in the workspace of each worker.

```matlab
>> x = labindex
```

Return the total number of workers working on the current communicating job with the `numlabs` function.

```matlab
>> all = numlabs
```

Create a replicated array on all the workers.

```matlab
>> segment = [1 2; 3 4; 5 6]
```
Assign a unique value to the array on each worker, dependent on the worker number (labindex). With a different value on each worker, this is a variant array.

\[ P>> \text{segment} = \text{segment} + 10 \times \text{labindex} \]
8 Until this point in the example, the variant arrays are independent, other than having the same name. Use the `codistributed.build` function to aggregate the array segments into a coherent array, distributed among the workers.

```
P>> codist = codistributor1d(2, [2 2 2 2], [3 8])
P>> whole = codistributed.build(segment, codist)
```

This combines four separate 3-by-2 arrays into one 3-by-8 codistributed array. The `codistributor1d` object indicates that the array is distributed along its second dimension (columns), with 2 columns on each of the four workers. On each worker, `segment` provided the data for the local portion of the `whole` array.

9 Now, when you operate on the codistributed array `whole`, each worker handles the calculations on only its portion, or segment, of the array, not the whole array.

```
P>> whole = whole + 1000
```

10 Although the codistributed array allows for operations on its entirety, you can use the `getLocalPart` function to access the portion of a codistributed array on a particular worker.

```
P>> section = getLocalPart(whole)
```

Thus, `section` is now a variant array because it is different on each worker.

```
section =
    1011    1012
    1013    1014
    1015    1016
section =
    1031    1032
    1033    1034
    1035    1036
```

11 If you need the entire array in one workspace, use the `gather` function.
P>> combined = gather(whole)

Notice, however, that this gathers the entire array into the workspaces of all the workers. See the `gather` reference page for the syntax to gather the array into the workspace of only one worker.

12 Because the workers ordinarily do not have displays, if you want to perform any graphical tasks involving your data, such as plotting, you must do this from the client workspace. Copy the array to the client workspace by typing the following commands in the MATLAB (client) Command Window.

```
pmode lab2client combined 1
```

Notice that `combined` is now a 3-by-8 array in the client workspace.

```
whos combined
```

To see the array, type its name.

```
combined
```

13 Many matrix functions that might be familiar can operate on codistributed arrays. For example, the `eye` function creates an identity matrix. Now you can create a codistributed identity matrix with the following commands in the Parallel Command Window.

```
P>> distobj = codistributor1d();
P>> I = eye(6, distobj)
P>> getLocalPart(I)
```

Calling the `codistributor1d` function without arguments specifies the default distribution, which is by columns in this case, distributed as evenly as possible.
If you require distribution along a different dimension, you can use the `redistribute` function. In this example, the argument 1 to `codistributor1d` specifies distribution of the array along the first dimension (rows).

```matlab
P>> distobj = codistributor1d(1);
P>> I = redistribute(I, distobj)
P>> getLocalPart(I)
```

```
distobj = codistributor1d(1):
I = redistribute(I, distobj)
getLocalPart(I)
```
Exit pmode and return to the regular MATLAB desktop.

P>> pmode exit
Parallel Command Window

When you start pmode on your local client machine with the command

```plaintext
pmode start local 4
```

four workers start on your local machine and a communicating job is created to run on them. The first time you run pmode with these options, you get a tiled display of the four workers.

The Parallel Command Window offers much of the same functionality as the MATLAB desktop, including command line, output, and command history.

When you select one or more lines in the command history and right-click, you see the following context menu.
You have several options for how to arrange the tiles showing your worker outputs. Usually, you will choose an arrangement that depends on the format of your data. For example, the data displayed until this point in this section, as in the previous figure, is distributed by columns. It might be convenient to arrange the tiles side by side.

This arrangement results in the following figure, which might be more convenient for viewing data distributed by columns.

Alternatively, if the data is distributed by rows, you might want to stack the worker tiles vertically. For the following figure, the data is reformatted with the command
P>> distobj = codistributor('1d',1);
P>> I = redistribute(I, distobj)

When you rearrange the tiles, you see the following.

You can control the relative positions of the command window and the worker output. The following figure shows how to set the output to display beside the input, rather than above it.

You can choose to view the worker outputs by tabs.
You can have multiple workers send their output to the same tile or tab. This allows you to have fewer tiles or tabs than workers.

In this case, the window provides shading to help distinguish the outputs from the various workers.
Running pmode Interactive Jobs on a Cluster

When you run pmode on a cluster of workers, you are running a job that is much like any other communicating job, except it is interactive. The cluster can be heterogeneous, but with certain limitations described at System Requirements; carefully locate your scheduler on that page and note that pmode sessions run as jobs described as “parallel applications that use inter-worker communication.”

Many of the job’s properties are determined by the cluster profile. For more details about creating and using profiles, see “Discover Clusters and Use Cluster Profiles” on page 6-18.

The general form of the command to start a pmode session is

```
pmode start <profile-name> <num-workers>
```

where `<profile-name>` is the name of the cluster profile you want to use, and `<num-workers>` is the number of workers you want to run the pmode job on. If `<num-workers>` is omitted, the number of workers is determined by the profile. Coordinate with your system administrator when creating or using a profile.

If you omit `<profile-name>`, pmode uses the default profile (see the `parallel.defaultClusterProfile` reference page).

For details on all the command options, see the `pmode` reference page.
Plotting Distributed Data Using pmode

Because the workers running a job in pmode are MATLAB sessions without displays, they cannot create plots or other graphic outputs on your desktop.

When working in pmode with codistributed arrays, one way to plot a codistributed array is to follow these basic steps:

1. Use the `gather` function to collect the entire array into the workspace of one worker.
2. Transfer the whole array from any worker to the MATLAB client with `pmode lab2client`.
3. Plot the data from the client workspace.

The following example illustrates this technique.

Create a 1-by-100 codistributed array of 0s. With four workers, each has a 1-by-25 segment of the whole array.

```matlab
P>> D = zeros(1,100,codistributor1d())
Lab 1: This lab stores D(1:25).
Lab 2: This lab stores D(26:50).
Lab 3: This lab stores D(51:75).
Lab 4: This lab stores D(76:100).
```

Use a `for`-loop over the distributed range to populate the array so that it contains a sine wave. Each worker does one-fourth of the array.

```matlab
P>> for i = drange(1:100)
    D(i) = sin(i*2*pi/100);
end;
```

Gather the array so that the whole array is contained in the workspace of worker 1.

```matlab
P>> P = gather(D, 1);
```

Transfer the array from the workspace of worker 1 to the MATLAB client workspace, then plot the array from the client. Note that both commands are entered in the MATLAB (client) Command Window.

```matlab
pmode lab2client P 1
plot(P)
```
This is not the only way to plot codistributed data. One alternative method, especially useful when running noninteractive communicating jobs, is to plot the data to a file, then view it from a later MATLAB session.
pmode Limitations and Unexpected Results

Using Graphics in pmode

Displaying a GUI

The workers that run the tasks of a communicating job are MATLAB sessions without displays. As a result, these workers cannot display graphical tools and so you cannot do things like plotting from within pmode. The general approach to accomplish something graphical is to transfer the data into the workspace of the MATLAB client using

```
 pmode lab2client var labindex
```

Then use the graphical tool on the MATLAB client.

Using Simulink Software

Because the workers running a pmode job do not have displays, you cannot use Simulink software to edit diagrams or to perform interactive simulation from within pmode. If you type `simulink` at the pmode prompt, the Simulink Library Browser opens in the background on the workers and is not visible.

You can use the `sim` command to perform noninteractive simulations in parallel. If you edit your model in the MATLAB client outside of pmode, you must save the model before accessing it in the workers via pmode; also, if the workers had accessed the model previously, they must close and open the model again to see the latest saved changes.
pmode Troubleshooting

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<tr>
<th>In this section...</th>
</tr>
</thead>
<tbody>
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<tr>
<td>“Hostname Resolution” on page 4-18</td>
</tr>
<tr>
<td>“Socket Connections” on page 4-18</td>
</tr>
</tbody>
</table>

**Connectivity Testing**

For testing connectivity between the client machine and the machines of your compute cluster, you can use Admin Center. For more information about Admin Center, including how to start it and how to test connectivity, see “Start Admin Center” (MATLAB Distributed Computing Server) and “Test Connectivity” (MATLAB Distributed Computing Server).

**Hostname Resolution**

If a worker cannot resolve the hostname of the computer running the MATLAB client, use `pctconfig` to change the hostname by which the client machine advertises itself.

**Socket Connections**

If a worker cannot open a socket connection to the MATLAB client, try the following:

- Use `pctconfig` to change the hostname by which the client machine advertises itself.
- Make sure that firewalls are not preventing communication between the worker and client machines.
- Use `pctconfig` to change the client's `pmodeport` property. This determines the port that the workers will use to contact the client in the next pmode session.
Math with Codistributed Arrays

This chapter describes the distribution or partition of data across several workers, and the functionality provided for operations on that data in `spmd` statements, communicating jobs, and `pmode`. The sections are as follows.

- “Nondistributed Versus Distributed Arrays” on page 5-2
- “Working with Codistributed Arrays” on page 5-5
- “Looping Over a Distributed Range (for-dranger)” on page 5-20
- “Using MATLAB Functions on Distributed Arrays” on page 5-24
In this section...

“Introduction” on page 5-2
“Nondistributed Arrays” on page 5-2
“Codistributed Arrays” on page 5-4

Introduction

Many built-in data types and data structures supported by MATLAB software are also supported in the MATLAB parallel computing environment. This includes arrays of any number of dimensions containing numeric, character, logical values, cells, or structures. In addition to these basic building blocks, the MATLAB parallel computing environment also offers different types of arrays.

Nondistributed Arrays

When you create a nondistributed array, MATLAB constructs a separate array in the workspace of each worker, using the same variable name on all workers. Any operation performed on that variable affects all individual arrays assigned to it. If you display from worker 1 the value assigned to this variable, all workers respond by showing the array of that name that resides in their workspace.

The state of a nondistributed array depends on the value of that array in the workspace of each worker:

• “Replicated Arrays” on page 5-2
• “Variant Arrays” on page 5-3
• “Private Arrays” on page 5-3

Replicated Arrays

A replicated array resides in the workspaces of all workers, and its size and content are identical on all workers. When you create the array, MATLAB assigns it to the same variable on all workers. If you display in spmd the value assigned to this variable, all workers respond by showing the same array.

spmd, A = magic(3), end
Variant Arrays

A variant array also resides in the workspaces of all workers, but its content differs on one or more workers. When you create the array, MATLAB assigns a different value to the same variable on all workers. If you display the value assigned to this variable, all workers respond by showing their version of the array.

```
spmd, A = magic(3) + labindex - 1, end
```

A replicated array can become a variant array when its value becomes unique on each worker.

```
spmd
    B = magic(3); %replicated on all workers
    B = B + labindex; %now a variant array, different on each worker
end
```

Private Arrays

A private array is defined on one or more, but not all workers. You could create this array by using `labindex` in a conditional statement, as shown here:

```
spmd
    if labindex >= 3, A = magic(3) + labindex - 1, end
end
```

```
spmd
    if labindex >= 3, A = magic(3) + labindex - 1, end
end
```

```
WORKER 1 | WORKER 2 | WORKER 3 | WORKER 4
---------|---------|---------|---------
 8 1 6 | 9 2 7 | 10 3 8 | 11 4 9
 3 5 7 | 4 6 9 | 5 7 9 | 6 8 10
 4 9 2 | 5 10 3 | 6 11 4 | 7 12 5
```

A is undefined | A is undefined | 10 3 8 | 11 4 9
undefined | undefined | 5 7 9 | 6 8 10
| 6 11 4 | 7 12 5

Nondistributed Versus Distributed Arrays
Codistributed Arrays

With replicated and variant arrays, the full content of the array is stored in the workspace of each worker. Codistributed arrays, on the other hand, are partitioned into segments, with each segment residing in the workspace of a different worker. Each worker has its own array segment to work with. Reducing the size of the array that each worker has to store and process means a more efficient use of memory and faster processing, especially for large data sets.

This example distributes a 3-by-10 replicated array A across four workers. The resulting array D is also 3-by-10 in size, but only a segment of the full array resides on each worker.

```matlab
spmd
    A = [11:20; 21:30; 31:40];
    D = codistributed(A);
    getLocalPart(D)
end
```

<table>
<thead>
<tr>
<th>WORKER 1</th>
<th>WORKER 2</th>
<th>WORKER 3</th>
<th>WORKER 4</th>
</tr>
</thead>
<tbody>
<tr>
<td>11 12 13</td>
<td>14 15 16</td>
<td>17 18</td>
<td>19 20</td>
</tr>
<tr>
<td>21 22 23</td>
<td>24 25 26</td>
<td>27 28</td>
<td>29 30</td>
</tr>
<tr>
<td>31 32 33</td>
<td>34 35 36</td>
<td>37 38</td>
<td>39 40</td>
</tr>
</tbody>
</table>

For more details on using codistributed arrays, see “Working with Codistributed Arrays” on page 5-5.
Working with Codistributed Arrays

How MATLAB Software Distributes Arrays

When you distribute an array to a number of workers, MATLAB software partitions the array into segments and assigns one segment of the array to each worker. You can partition a two-dimensional array horizontally, assigning columns of the original array to the different workers, or vertically, by assigning rows. An array with N dimensions can be partitioned along any of its N dimensions. You choose which dimension of the array is to be partitioned by specifying it in the array constructor command.

For example, to distribute an 80-by-1000 array to four workers, you can partition it either by columns, giving each worker an 80-by-250 segment, or by rows, with each worker getting a 20-by-1000 segment. If the array dimension does not divide evenly over the number of workers, MATLAB partitions it as evenly as possible.

The following example creates an 80-by-1000 replicated array and assigns it to variable A. In doing so, each worker creates an identical array in its own workspace and assigns it to variable A, where A is local to that worker. The second command distributes A, creating a single 80-by-1000 array D that spans all four workers. Worker 1 stores columns 1 through 250, worker 2 stores columns 251 through 500, and so on. The default distribution is by the last nonsingleton dimension, thus, columns in this case of a 2-dimensional array.

```matlab
spmd
    A = zeros(80, 1000);
    D = codistributed(A)
end
```
Lab 1: This lab stores D(:,1:250).
Lab 2: This lab stores D(:,251:500).
Lab 3: This lab stores D(:,501:750).
Lab 4: This lab stores D(:,751:1000).

Each worker has access to all segments of the array. Access to the local segment is faster than to a remote segment, because the latter requires sending and receiving data between workers and thus takes more time.

How MATLAB Displays a Codistributed Array

For each worker, the MATLAB Parallel Command Window displays information about the codistributed array, the local portion, and the codistributor. For example, an 8-by-8 identity matrix codistributed among four workers, with two columns on each worker, displays like this:

```matlab
>> spmd
II = eye(8,'codistributed')
end
Lab 1:
This lab stores II(:,1:2).
  LocalPart: [8x2 double]
  Codistributor: [1x1 codistributor1d]
Lab 2:
This lab stores II(:,3:4).
  LocalPart: [8x2 double]
  Codistributor: [1x1 codistributor1d]
Lab 3:
This lab stores II(:,5:6).
  LocalPart: [8x2 double]
  Codistributor: [1x1 codistributor1d]
Lab 4:
This lab stores II(:,7:8).
  LocalPart: [8x2 double]
  Codistributor: [1x1 codistributor1d]
```

To see the actual data in the local segment of the array, use the `getLocalPart` function.

How Much Is Distributed to Each Worker

In distributing an array of \( N \) rows, if \( N \) is evenly divisible by the number of workers, MATLAB stores the same number of rows \( (N/\text{numlabs}) \) on each worker. When this
number is not evenly divisible by the number of workers, MATLAB partitions the array as evenly as possible.

MATLAB provides codistributor object properties called **Dimension** and **Partition** that you can use to determine the exact distribution of an array. See “Indexing into a Codistributed Array” on page 5-14 for more information on indexing with codistributed arrays.

**Distribution of Other Data Types**

You can distribute arrays of any MATLAB built-in data type, and also numeric arrays that are complex or sparse, but not arrays of function handles or object types.

**Creating a Codistributed Array**

You can create a codistributed array in any of the following ways:

- “Partitioning a Larger Array” on page 5-7 — Start with a large array that is replicated on all workers, and partition it so that the pieces are distributed across the workers. This is most useful when you have sufficient memory to store the initial replicated array.
- “Building from Smaller Arrays” on page 5-8 — Start with smaller variant or replicated arrays stored on each worker, and combine them so that each array becomes a segment of a larger codistributed array. This method reduces memory requirements as it lets you build a codistributed array from smaller pieces.
- “Using MATLAB Constructor Functions” on page 5-9 — Use any of the MATLAB constructor functions like `rand` or `zeros` with a codistributor object argument. These functions offer a quick means of constructing a codistributed array of any size in just one step.

**Partitioning a Larger Array**

If you have a large array already in memory that you want MATLAB to process more quickly, you can partition it into smaller segments and distribute these segments to all of the workers using the `codistributed` function. Each worker then has an array that is a fraction the size of the original, thus reducing the time required to access the data that is local to each worker.

As a simple example, the following line of code creates a 4-by-8 replicated matrix on each worker assigned to the variable `A`:
A =
  11  12  13  14  15  16  17  18
  21  22  23  24  25  26  27  28
  31  32  33  34  35  36  37  38
  41  42  43  44  45  46  47  48

The next line uses the `codistributed` function to construct a single 4-by-8 matrix D that is distributed along the second dimension of the array:

spmd
    D = codistributed(A);
    getLocalPart(D)
end

1: Local Part | 2: Local Part | 3: Local Part | 4: Local Part
  11  12 |  13  14 | 15  16 | 17  18
  21  22 |  23  24 | 25  26 | 27  28
  31  32 |  33  34 | 35  36 | 37  38
  41  42 |  43  44 | 45  46 | 47  48

Arrays A and D are the same size (4-by-8). Array A exists in its full size on each worker, while only a segment of array D exists on each worker.

spmd, size(A), size(D), end

Examining the variables in the client workspace, an array that is codistributed among the workers inside an `spmd` statement, is a distributed array from the perspective of the client outside the `spmd` statement. Variables that are not codistributed inside the `spmd`, are Composites in the client outside the `spmd`.

whos
Name      Size            Bytes  Class
A         1x4               613  Composite
D         4x8               649  distributed

See the `codistributed` function reference page for syntax and usage information.

Building from Smaller Arrays

The `codistributed` function is less useful for reducing the amount of memory required to store data when you first construct the full array in one workspace and then partition it into distributed segments. To save on memory, you can construct the smaller pieces
(local part) on each worker first, and then use `codistributed.build` to combine them into a single array that is distributed across the workers.

This example creates a 4-by-250 variant array `A` on each of four workers and then uses `codistributor` to distribute these segments across four workers, creating a 4-by-1000 codistributed array. Here is the variant array, `A`:

```matlab
spmd
A = [1:250; 251:500; 501:750; 751:1000] + 250 * (labindex - 1);
end
```

<table>
<thead>
<tr>
<th>WORKER 1</th>
<th>WORKER 2</th>
<th>WORKER 3</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>251</td>
<td>501</td>
</tr>
<tr>
<td>2</td>
<td>252</td>
<td>502</td>
</tr>
<tr>
<td>251</td>
<td>252</td>
<td>502</td>
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<td>752</td>
</tr>
<tr>
<td>751</td>
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<td>752</td>
</tr>
</tbody>
</table>

Now combine these segments into an array that is distributed by the first dimension (rows). The array is now 16-by-250, with a 4-by-250 segment residing on each worker:

```matlab
spmd
D = codistributed.build(A, codistributor1d(1,[4 4 4 4],[16 250]))
end
```

Lab 1:

- This lab stores `D(1:4,:)`.
- LocalPart: [4x250 double]
- Codistributor: [1x1 codistributor1d]

You could also use replicated arrays in the same fashion, if you wanted to create a codistributed array whose segments were all identical to start with. See the `codistributed` function reference page for syntax and usage information.

### Using MATLAB Constructor Functions

MATLAB provides several array constructor functions that you can use to build codistributed arrays of specific values, sizes, and classes. These functions operate in the same way as their nondistributed counterparts in the MATLAB language, except that they distribute the resultant array across the workers using the specified codistributor object, `codist`. 

---

5-9
Constructor Functions

The codistributed constructor functions are listed here. Use the codist argument (created by the codistributor function: codist=codistributor()) to specify over which dimension to distribute the array. See the individual reference pages for these functions for further syntax and usage information.

eye(___,codist)
false(___,codist)
Inf(___,codist)
NaN(___,codist)
one(___,codist)
rand(___ codist)
randi(___ codist)
randn(___ codist)
true(___,codist)
zeros(___,codist)
codistributed.cell(m,n,...,codist)
codistributed.colon(a,d,b)
codistributed.linspace(m,n,...,codist)
codistributed.logspace(m,n,...,codist)
sparse(m,n,codist)
codistributed.speye(m,...,codist)
codistributed.sprand(m,n,density,codist)
codistributed.sprandn(m,n,density,codist)

Local Arrays

That part of a codistributed array that resides on each worker is a piece of a larger array. Each worker can work on its own segment of the common array, or it can make a copy of that segment in a variant or private array of its own. This local copy of a codistributed array segment is called a local array.

Creating Local Arrays from a Codistributed Array

The getLocalPart function copies the segments of a codistributed array to a separate variant array. This example makes a local copy L of each segment of codistributed array D. The size of L shows that it contains only the local part of D for each worker. Suppose you distribute an array across four workers:

```
spmD(4)
    A = [1:80; 81:160; 161:240];
```
D = codistributed(A);
size(D)
    L = getLocalPart(D);
size(L)
end

returns on each worker:

3   80
3   20

Each worker recognizes that the codistributed array D is 3-by-80. However, notice that the size of the local part, L, is 3-by-20 on each worker, because the 80 columns of D are distributed over four workers.

Creating a Codistributed from Local Arrays

Use the codistributed.build function to perform the reverse operation. This function, described in “Building from Smaller Arrays” on page 5-8, combines the local variant arrays into a single array distributed along the specified dimension.

Continuing the previous example, take the local variant arrays L and put them together as segments to build a new codistributed array X.

spmd
codist = codistributor1d(2,[20 20 20 20],[3 80]);
X = codistributed.build(L,codist);
size(X)
end

returns on each worker:

3   80

Obtaining information About the Array

MATLAB offers several functions that provide information on any particular array. In addition to these standard functions, there are also two functions that are useful solely with codistributed arrays.
Determining Whether an Array Is Codistributed

The `iscodistributed` function returns a logical 1 (true) if the input array is codistributed, and logical 0 (false) otherwise. The syntax is

```
spmd, TF = iscodistributed(D), end
```

where `D` is any MATLAB array.

Determining the Dimension of Distribution

The codistributor object determines how an array is partitioned and its dimension of distribution. To access the codistributor of an array, use the `getCodistributor` function. This returns two properties, `Dimension` and `Partition`:

```matlab
spmd, getCodistributor(X), end
    Dimension: 2
    Partition: [20 20 20 20]
end
```

The `Dimension` value of 2 means the array `X` is distributed by columns (dimension 2); and the `Partition` value of `[20 20 20 20]` means that twenty columns reside on each of the four workers.

To get these properties programmatically, return the output of `getCodistributor` to a variable, then use dot notation to access each property:

```matlab
spmd
    C = getCodistributor(X);
    part = C.Partition
    dim  = C.Dimension
end
```

Other Array Functions

Other functions that provide information about standard arrays also work on codistributed arrays and use the same syntax.

- `length` — Returns the length of a specific dimension.
- `ndims` — Returns the number of dimensions.
- `numel` — Returns the number of elements in the array.
• `size` — Returns the size of each dimension.
• `is*` — Many functions that have names beginning with 'is', such as `ischar` and `issparse`.

### Changing the Dimension of Distribution

When constructing an array, you distribute the parts of the array along one of the array's dimensions. You can change the direction of this distribution on an existing array using the `redistribute` function with a different codistributor object.

Construct an 8-by-16 codistributed array `D` of random values distributed by columns on four workers:

```matlab
spmd
    D = rand(8,16,codistributor());
    size(getLocalPart(D))
end
```

returns on each worker:

8  4

Create a new codistributed array distributed by rows from an existing one already distributed by columns:

```matlab
spmd
    X = redistribute(D, codistributor1d(1));
    size(getLocalPart(X))
end
```

returns on each worker:

2  16

### Restoring the Full Array

You can restore a codistributed array to its undistributed form using the `gather` function. `gather` takes the segments of an array that reside on different workers and combines them into a replicated array on all workers, or into a single array on one worker.

Distribute a 4-by-10 array to four workers along the second dimension:
spmd,  A = [11:20; 21:30; 31:40; 41:50],  end
A =
    11    12    13    14    15    16    17    18    19    20
    21    22    23    24    25    26    27    28    29    30
    31    32    33    34    35    36    37    38    39    40
    41    42    43    44    45    46    47    48    49    50

spmd,  D = codistributed(A),  end

<table>
<thead>
<tr>
<th>WORKER 1</th>
<th>WORKER 2</th>
<th>WORKER 3</th>
<th>WORKER 4</th>
</tr>
</thead>
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<tr>
<td>11 12 13</td>
<td>14 15 16</td>
<td>17 18</td>
<td>19 20</td>
</tr>
<tr>
<td>21 22 23</td>
<td>24 25 26</td>
<td>27 28</td>
<td>29 30</td>
</tr>
<tr>
<td>31 32 33</td>
<td>34 35 36</td>
<td>37 38</td>
<td>39 40</td>
</tr>
<tr>
<td>41 42 43</td>
<td>44 45 46</td>
<td>47 48</td>
<td>49 50</td>
</tr>
</tbody>
</table>

spmd,  size(getLocalPart(D)),  end
Lab 1:
  4   3
Lab 2:
  4   3
Lab 3:
  4   2
Lab 4:
  4   2

Restore the undistributed segments to the full array form by gathering the segments:

spmd,  X = gather(D),  end
X =
    11    12    13    14    15    16    17    18    19    20
    21    22    23    24    25    26    27    28    29    30
    31    32    33    34    35    36    37    38    39    40
    41    42    43    44    45    46    47    48    49    50

spmd,  size(X),  end
  4   10

Indexing into a Codistributed Array

While indexing into a nondistributed array is fairly straightforward, codistributed arrays require additional considerations. Each dimension of a nondistributed array is indexed within a range of 1 to the final subscript, which is represented in MATLAB by the end
keyword. The length of any dimension can be easily determined using either the \texttt{size} or \texttt{length} function.

With codistributed arrays, these values are not so easily obtained. For example, the second segment of an array (that which resides in the workspace of worker 2) has a starting index that depends on the array distribution. For a 200-by-1000 array with a default distribution by columns over four workers, the starting index on worker 2 is 251. For a 1000-by-200 array also distributed by columns, that same index would be 51. As for the ending index, this is not given by using the \texttt{end} keyword, as \texttt{end} in this case refers to the end of the entire array; that is, the last subscript of the final segment. The length of each segment is also not given by using the \texttt{length} or \texttt{size} functions, as they only return the length of the entire array.

The MATLAB \texttt{colon} operator and \texttt{end} keyword are two of the basic tools for indexing into nondistributed arrays. For codistributed arrays, MATLAB provides a version of the \texttt{colon} operator, called \texttt{codistributed.colon}. This actually is a function, not a symbolic operator like \texttt{colon}.

\begin{quote}
\textbf{Note} When using arrays to index into codistributed arrays, you can use only replicated or codistributed arrays for indexing. The toolbox does not check to ensure that the index is replicated, as that would require global communications. Therefore, the use of unsupported variants (such as \texttt{labindex}) to index into codistributed arrays might create unexpected results.
\end{quote}

Example: Find a Particular Element in a Codistributed Array

Suppose you have a row vector of 1 million elements, distributed among several workers, and you want to locate its element number 225,000. That is, you want to know what worker contains this element, and in what position in the local part of the vector on that worker. The \texttt{globalIndices} function provides a correlation between the local and global indexing of the codistributed array.

\begin{verbatim}
D = rand(1,1e6,'distributed'); %Distributed by columns
spmd
    globalInd = globalIndices(D,2);
    pos = find(globalInd == 225e3);
    if ~isempty(pos)
        fprintf(...
            'Element is in position %d on worker %d.
', pos, labindex);
\end{verbatim}

\end{verbatim}
If you run this code on a pool of four workers you get this result:

Lab 1:
  Element is in position 225000 on worker 1.

If you run this code on a pool of five workers you get this result:

Lab 2:
  Element is in position 25000 on worker 2.

Notice if you use a pool of a different size, the element ends up in a different location on a different worker, but the same code can be used to locate the element.

2-Dimensional Distribution

As an alternative to distributing by a single dimension of rows or columns, you can distribute a matrix by blocks using '2dbc' or two-dimensional block-cyclic distribution. Instead of segments that comprise a number of complete rows or columns of the matrix, the segments of the codistributed array are 2-dimensional square blocks.

For example, consider a simple 8-by-8 matrix with ascending element values. You can create this array in an spmd statement, communicating job, or pmode. This example uses pmode for a visual display.

P>> A = reshape(1:64, 8, 8)

The result is the replicated array:

<p>| | | | | | | | |</p>
<table>
<thead>
<tr>
<th></th>
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<th></th>
<th></th>
<th></th>
<th></th>
</tr>
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<td>21</td>
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<td>45</td>
<td>53</td>
<td>61</td>
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<tr>
<td>6</td>
<td>14</td>
<td>22</td>
<td>30</td>
<td>38</td>
<td>46</td>
<td>54</td>
<td>62</td>
</tr>
</tbody>
</table>
Suppose you want to distribute this array among four workers, with a 4-by-4 block as the local part on each worker. In this case, the lab grid is a 2-by-2 arrangement of the workers, and the block size is a square of four elements on a side (i.e., each block is a 4-by-4 square). With this information, you can define the codistributor object:

```matlab
P>> DIST = codistributor2dbc([2 2], 4)
```

Now you can use this codistributor object to distribute the original matrix:

```matlab
P>> AA = codistributed(A, DIST)
```

This distributes the array among the workers according to this scheme:

```plaintext
LAB 1  |  LAB 2  \\
-------|--------\\
 1     |  9 17 25 33 41 49 57\\
 2     | 10 18 26 34 42 50 58\\
 3     | 11 19 27 35 43 51 59\\
 4     | 12 20 28 36 44 52 60\\
 5     | 13 21 29 37 45 53 61\\
 6     | 14 22 30 38 46 54 62\\
 7     | 15 23 31 39 47 55 63\\
 8     | 16 24 32 40 48 56 64\\
```

If the lab grid does not perfectly overlay the dimensions of the codistributed array, you can still use '2dbc' distribution, which is block cyclic. In this case, you can imagine the lab grid being repeatedly overlaid in both dimensions until all the original matrix elements are included.

Using the same original 8-by-8 matrix and 2-by-2 lab grid, consider a block size of 3 instead of 4, so that 3-by-3 square blocks are distributed among the workers. The code looks like this:
P>> DIST = codistributor2dbc([2 2], 3)
P>> AA = codistributed(A, DIST)

The first “row” of the lab grid is distributed to worker 1 and worker 2, but that contains only six of the eight columns of the original matrix. Therefore, the next two columns are distributed to worker 1. This process continues until all columns in the first rows are distributed. Then a similar process applies to the rows as you proceed down the matrix, as shown in the following distribution scheme:

The diagram above shows a scheme that requires four overlays of the lab grid to accommodate the entire original matrix. The following pmode session shows the code and resulting distribution of data to each of the workers:
The following points are worth noting:

• '2dbc' distribution might not offer any performance enhancement unless the block size is at least a few dozen. The default block size is 64.
• The lab grid should be as close to a square as possible.
• Not all functions that are enhanced to work on '1d' codistributed arrays work on '2dbc' codistributed arrays.
Looping Over a Distributed Range (for-dranger)

In this section...

“Parallelizing a for-Loop” on page 5-20
“Codistributed Arrays in a for-dranger Loop” on page 5-21

Note Using a for-loop over a distributed range (dranger) is intended for explicit indexing of the distributed dimension of codistributed arrays (such as inside an spmd statement or a communicating job). For most applications involving parallel for-loops you should first try using parfor loops. See “Parallel for-Loops (parfor)”.

Parallelizing a for-Loop

If you already have a coarse-grained application to perform, but you do not want to bother with the overhead of defining jobs and tasks, you can take advantage of the ease-of-use that pmode provides. Where an existing program might take hours or days to process all its independent data sets, you can shorten that time by distributing these independent computations over your cluster.

For example, suppose you have the following serial code:

```matlab
results = zeros(1, numDataSets);
for i = 1:numDataSets
    load(['\central\myData\dataSet' int2str(i) '.mat'])
    results(i) = processDataSet(i);
end
plot(1:numDataSets, results);
save \central\myResults\today.mat results
```

The following changes make this code operate in parallel, either interactively in spmd or pmode, or in a communicating job:

```matlab
results = zeros(1, numDataSets, codistributor());
for i = drange(1:numDataSets)
    load(['\central\myData\dataSet' int2str(i) '.mat'])
    results(i) = processDataSet(i);
end
res = gather(results, 1);
if labindex == 1
```

plot(1:numDataSets, res);
print -dtiff -r300 fig.tiff;
save \central\myResults\today.mat res
end

Note that the length of the for iteration and the length of the codistributed array results need to match in order to index into results within a for drange loop. This way, no communication is required between the workers. If results was simply a replicated array, as it would have been when running the original code in parallel, each worker would have assigned into its part of results, leaving the remaining parts of results 0. At the end, results would have been a variant, and without explicitly calling labSend and labReceive or gcat, there would be no way to get the total results back to one (or all) workers.

When using the load function, you need to be careful that the data files are accessible to all workers if necessary. The best practice is to use explicit paths to files on a shared file system.

Correspondingly, when using the save function, you should be careful to only have one worker save to a particular file (on a shared file system) at a time. Thus, wrapping the code in if labindex == 1 is recommended.

Because results is distributed across the workers, this example uses gather to collect the data onto worker 1.

A worker cannot plot a visible figure, so the print function creates a viewable file of the plot.

**Codistributed Arrays in a for-drange Loop**

When a for-loop over a distributed range is executed in a communicating job, each worker performs its portion of the loop, so that the workers are all working simultaneously. Because of this, no communication is allowed between the workers while executing a for-drange loop. In particular, a worker has access only to its partition of a codistributed array. Any calculations in such a loop that require a worker to access portions of a codistributed array from another worker will generate an error.

To illustrate this characteristic, you can try the following example, in which one for loop works, but the other does not.
At the pmode prompt, create two codistributed arrays, one an identity matrix, the other set to zeros, distributed across four workers.

\[
D = \text{eye}(8, 8, \text{codistributor}()) \\
E = \text{zeros}(8, 8, \text{codistributor}())
\]

By default, these arrays are distributed by columns; that is, each of the four workers contains two columns of each array. If you use these arrays in a `for-drangelfor-drang` loop, any calculations must be self-contained within each worker. In other words, you can only perform calculations that are limited within each worker to the two columns of the arrays that the workers contain.

For example, suppose you want to set each column of array \(E\) to some multiple of the corresponding column of array \(D\):

\[
\text{for } j = \text{drange}(1:\text{size}(D,2)); E(:,j) = j*D(:,j); \text{ end}
\]

This statement sets the \(j\)-th column of \(E\) to \(j\) times the \(j\)-th column of \(D\). In effect, while \(D\) is an identity matrix with 1s down the main diagonal, \(E\) has the sequence 1, 2, 3, etc., down its main diagonal.

This works because each worker has access to the entire column of \(D\) and the entire column of \(E\) necessary to perform the calculation, as each worker works independently and simultaneously on two of the eight columns.

Suppose, however, that you attempt to set the values of the columns of \(E\) according to different columns of \(D\):

\[
\text{for } j = \text{drange}(1:\text{size}(D,2)); E(:,j) = j*D(:,j+1); \text{ end}
\]

This method fails, because when \(j\) is 2, you are trying to set the second column of \(E\) using the third column of \(D\). These columns are stored in different workers, so an error occurs, indicating that communication between the workers is not allowed.

**Restrictions**

To use `for-drangelfor-drange` on a codistributed array, the following conditions must exist:

- The codistributed array uses a 1-dimensional distribution scheme (not 2\text{dbc}).
- The distribution complies with the default partition scheme.
- The variable over which the `for-drangelfor-drange` loop is indexing provides the array subscript for the distribution dimension.
• All other subscripts can be chosen freely (and can be taken from for-loops over the full range of each dimension).

To loop over all elements in the array, you can use for-drange on the dimension of distribution, and regular for-loops on all other dimensions. The following example executes in an spmd statement running on a parallel pool of 4 workers:

```matlab
spmd
    PP = zeros(6,8,12,'codistributed');
    RR = rand(6,8,12,codistributor());
    % Default distribution:
    % by third dimension, evenly across 4 workers.

    for ii = 1:6
        for jj = 1:8
            for kk = drange(1:12)
                PP(ii,jj,kk) = RR(ii,jj,kk) + labindex;
            end
        end
    end
end
```

To view the contents of the array, type:

```matlab
PP
```
Using MATLAB Functions on Distributed Arrays

Many functions in MATLAB software are enhanced so that they operate on distributed arrays in much the same way that they operate on arrays contained in a single workspace.

In most cases, if any of the input arguments to these functions is a distributed or codistributed array, their output arrays are distributed or codistributed, respectively. If the output is always scalar, it is replicated on each worker. All these functions with codistributed array inputs must reference the same inputs at the same time on all workers; therefore, you cannot use variant arrays for input arguments.

The following table lists the enhanced MATLAB functions that operate on distributed or codistributed arrays.

A few of these functions might exhibit certain limitations when operating on a distributed or codistributed array. Click any function name to see specific help, including limitations.
<table>
<thead>
<tr>
<th>MATLAB Function</th>
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<th>MATLAB Function</th>
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<td>rem</td>
<td>tri</td>
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<td></td>
</tr>
<tr>
<td>besseli</td>
<td>cumprod</td>
<td>ifft2</td>
<td>rdivide(./)</td>
<td>tril</td>
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<td></td>
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<td>besselj</td>
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<td>tf</td>
<td>uint16</td>
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<tr>
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<td>diff</td>
<td>int16</td>
<td>mode</td>
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<td>NaN</td>
<td>uint32</td>
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<td></td>
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<tr>
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<td>double</td>
<td>int64</td>
<td>ndims</td>
<td>rot90</td>
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<td></td>
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<td>int8</td>
<td>ngrid</td>
<td>uint64</td>
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<td></td>
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<tr>
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<td>eigs</td>
<td>inv</td>
<td>ne(~)</td>
<td>sec</td>
<td></td>
<td></td>
</tr>
<tr>
<td>bigcgstab</td>
<td>end</td>
<td>ipermute</td>
<td>nextpow2</td>
<td>secd</td>
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<td>bitand</td>
<td>eps</td>
<td>isbanded</td>
<td>nnz</td>
<td>sech</td>
<td></td>
<td></td>
</tr>
<tr>
<td>bitbor</td>
<td>eq(==)</td>
<td>ischar</td>
<td>sign</td>
<td>vander</td>
<td></td>
<td></td>
</tr>
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<td>erf</td>
<td>isdiag</td>
<td>sin</td>
<td>var</td>
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<td></td>
</tr>
<tr>
<td>bounds</td>
<td>erfc</td>
<td>isempty</td>
<td>sind</td>
<td>vertcat([;])</td>
<td></td>
<td></td>
</tr>
<tr>
<td>bsxfun</td>
<td>erfcinv</td>
<td>isequal</td>
<td>single</td>
<td>write</td>
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<td></td>
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<td>erfcx</td>
<td>isequaln</td>
<td>sinh</td>
<td>xor</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>zeros</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Sparse Distributed Arrays

The following list shows functions that can help you work with sparse distributed arrays. In addition to this list, most element-wise functions in MATLAB also work for distributed arrays.

<table>
<thead>
<tr>
<th>bandwidth</th>
<th>diag</th>
<th>isdiag</th>
<th>normest</th>
<th>sparse</th>
<th>triu</th>
</tr>
</thead>
<tbody>
<tr>
<td>bicg</td>
<td>diff</td>
<td>istril</td>
<td>pcg</td>
<td>spfun</td>
<td>uminus(-)</td>
</tr>
<tr>
<td>cat</td>
<td>find</td>
<td>istriu</td>
<td>power(.^)</td>
<td>spones</td>
<td>uplus(+)</td>
</tr>
<tr>
<td>cgs</td>
<td>flip</td>
<td>ldivide(.)</td>
<td>qmr</td>
<td>tfqmr</td>
<td>vertcat([])</td>
</tr>
<tr>
<td>ctranspose(')</td>
<td>flipl</td>
<td>minus(-)</td>
<td>rdivide(.)</td>
<td>transpose('.')</td>
<td></td>
</tr>
<tr>
<td>cummax</td>
<td>flipud</td>
<td>mldivide()</td>
<td>rot90</td>
<td>tril</td>
<td></td>
</tr>
<tr>
<td>cummin</td>
<td>gmres</td>
<td>mrdivide(/)</td>
<td>sort</td>
<td></td>
<td></td>
</tr>
<tr>
<td>cumprod</td>
<td>horzcat([])</td>
<td>mtimes(*)</td>
<td>sortrows</td>
<td></td>
<td></td>
</tr>
<tr>
<td>cumsum</td>
<td>isbanded</td>
<td>isbanded</td>
<td>tril</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Support for Distributed calendarDuration Arrays

<table>
<thead>
<tr>
<th>calendarDuration</th>
<th>calquarters</th>
<th>cellstr</th>
</tr>
</thead>
<tbody>
<tr>
<td>caldays</td>
<td>calweeks</td>
<td>datevec</td>
</tr>
<tr>
<td>calmonths</td>
<td>calyears</td>
<td>iscalendarDuration</td>
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</table>

Support for Distributed categorical Arrays

<table>
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<tr>
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<th>iscategorical</th>
<th>isundefined</th>
</tr>
</thead>
<tbody>
<tr>
<td>addcats</td>
<td>iscategory</td>
<td>removecats</td>
</tr>
<tr>
<td>categories</td>
<td>isordinal</td>
<td>renamecats</td>
</tr>
<tr>
<td>countcats</td>
<td>isprotected</td>
<td>reordercats</td>
</tr>
</tbody>
</table>

Support for Distributed datetime Arrays

<table>
<thead>
<tr>
<th>datetime</th>
<th>exceltime</th>
<th>isweekend</th>
<th>string</th>
</tr>
</thead>
<tbody>
<tr>
<td>between</td>
<td>hms</td>
<td>juliandate</td>
<td>timeofday</td>
</tr>
<tr>
<td>cellstr</td>
<td>hour</td>
<td>minute</td>
<td>timeofday</td>
</tr>
<tr>
<td>datenum</td>
<td>isbetween</td>
<td>month</td>
<td>tzoffset</td>
</tr>
<tr>
<td>dateshift</td>
<td>isdatetime</td>
<td>posixtime</td>
<td>week</td>
</tr>
<tr>
<td>datevec</td>
<td>isdst</td>
<td>quarter</td>
<td>year</td>
</tr>
<tr>
<td>day</td>
<td>isnat</td>
<td>second</td>
<td>ymd</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>yyyyymmdd</td>
</tr>
</tbody>
</table>
### Support for Distributed duration Arrays

<table>
<thead>
<tr>
<th>duration</th>
<th>datevec</th>
<th>hours</th>
<th>minutes</th>
</tr>
</thead>
<tbody>
<tr>
<td>cellstr</td>
<td>days</td>
<td>isduration</td>
<td>seconds</td>
</tr>
<tr>
<td>datenum</td>
<td>hms</td>
<td>milliseconds</td>
<td>years</td>
</tr>
</tbody>
</table>

### Support for Distributed string Arrays

<table>
<thead>
<tr>
<th>string</th>
<th>erase</th>
<th>insertBefore</th>
<th>replaceBetween</th>
</tr>
</thead>
<tbody>
<tr>
<td>cellstr</td>
<td>eraseBetween</td>
<td>ismissing</td>
<td>reverse</td>
</tr>
<tr>
<td>compose</td>
<td>extractAfter</td>
<td>isstring</td>
<td>startsWith</td>
</tr>
<tr>
<td>contains</td>
<td>extractBefore</td>
<td>lower</td>
<td>strip</td>
</tr>
<tr>
<td>count</td>
<td>extractBetween</td>
<td>pad</td>
<td>strlength</td>
</tr>
<tr>
<td>endsWith</td>
<td>insertAfter</td>
<td>replace</td>
<td>upper</td>
</tr>
</tbody>
</table>

### Support for Distributed table Arrays

<table>
<thead>
<tr>
<th>table</th>
<th>istable</th>
<th>table2cell</th>
</tr>
</thead>
<tbody>
<tr>
<td>head</td>
<td>standardizeMissing</td>
<td>tail</td>
</tr>
<tr>
<td>ismissing</td>
<td>table2array</td>
<td></td>
</tr>
</tbody>
</table>
Programming Overview

This chapter provides information you need for programming with Parallel Computing Toolbox software. Further details of evaluating functions in a cluster, programming independent jobs, and programming communicating jobs are covered in later chapters. This chapter describes features common to programming all kinds of jobs. The sections are as follows.

- “How Parallel Computing Products Run a Job” on page 6-2
- “Program a Job on a Local Cluster” on page 6-10
- “Specify Your Parallel Preferences” on page 6-12
- “MATLAB Parallel Cloud” on page 6-15
- “Discover Clusters and Use Cluster Profiles” on page 6-18
- “Apply Callbacks to MJS Jobs and Tasks” on page 6-34
- “Job Monitor” on page 6-38
- “Programming Tips” on page 6-41
- “Control Random Number Streams” on page 6-46
- “Profiling Parallel Code” on page 6-51
- “HPC Challenge Benchmarks” on page 6-60
- “Benchmarking Performance” on page 6-61
- “Troubleshooting and Debugging” on page 6-62
- “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
- “Use Tall Arrays on a Parallel Pool” on page 6-70
- “Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
- “Run mapreduce on a Parallel Pool” on page 6-78
- “Run mapreduce on a Hadoop Cluster” on page 6-82
- “Partition a Datastore in Parallel” on page 6-86
How Parallel Computing Products Run a Job

Overview

Parallel Computing Toolbox and MATLAB Distributed Computing Server software let you solve computationally and data-intensive problems using MATLAB and Simulink on multicore and multiprocessor computers. Parallel processing constructs such as parallel for-loops and code blocks, distributed arrays, parallel numerical algorithms, and message-passing functions let you implement task-parallel and data-parallel algorithms at a high level in MATLAB without programming for specific hardware and network architectures.

A job is some large operation that you need to perform in your MATLAB session. A job is broken down into segments called tasks. You decide how best to divide your job into tasks. You could divide your job into identical tasks, but tasks do not have to be identical.

The MATLAB session in which the job and its tasks are defined is called the client session. Often, this is on the machine where you program MATLAB. The client uses Parallel Computing Toolbox software to perform the definition of jobs and tasks and to run them on a cluster local to your machine. MATLAB Distributed Computing Server software is the product that performs the execution of your job on a cluster of machines.

The MATLAB job scheduler (MJS) is the process that coordinates the execution of jobs and the evaluation of their tasks. The MJS distributes the tasks for evaluation to the server's individual MATLAB sessions called workers. Use of the MJS to access a cluster is optional; the distribution of tasks to cluster workers can also be performed by a third-party scheduler, such as Microsoft® Windows® HPC Server (including CCS) or Platform LSF®.

See the Glossary for definitions of the parallel computing terms used in this manual.
Basic Parallel Computing Setup

Toolbox and Server Components

- “MJS, Workers, and Clients” on page 6-3
- “Local Cluster” on page 6-5
- “Third-Party Schedulers” on page 6-5
- “Components on Mixed Platforms or Heterogeneous Clusters” on page 6-6
- “mdce Service” on page 6-7
- “Components Represented in the Client” on page 6-7

MJS, Workers, and Clients

The MJS can be run on any machine on the network. The MJS runs jobs in the order in which they are submitted, unless any jobs in its queue are promoted, demoted, canceled, or deleted.

Each worker is given a task from the running job by the MJS, executes the task, returns the result to the MJS, and then is given another task. When all tasks for a running job have been assigned to workers, the MJS starts running the next job on the next available worker.
A MATLAB Distributed Computing Server software setup usually includes many workers that can all execute tasks simultaneously, speeding up execution of large MATLAB jobs. It is generally not important which worker executes a specific task. In an independent job, the workers evaluate tasks one at a time as available, perhaps simultaneously, perhaps not, returning the results to the MJS. In a communicating job, the workers evaluate tasks simultaneously. The MJS then returns the results of all the tasks in the job to the client session.

**Note** For testing your application locally or other purposes, you can configure a single computer as client, worker, and MJS host. You can also have more than one worker session or more than one MJS session on a machine.

### Interactions of Parallel Computing Sessions

A large network might include several MJSs as well as several client sessions. Any client session can create, run, and access jobs on any MJS, but a worker session is registered with and dedicated to only one MJS at a time. The following figure shows a configuration with multiple MJSs.
Cluster with Multiple Clients and MJSs

Local Cluster

A feature of Parallel Computing Toolbox software is the ability to run a local cluster of workers on the client machine, so that you can run jobs without requiring a remote cluster or MATLAB Distributed Computing Server software. In this case, all the processing required for the client, scheduling, and task evaluation is performed on the same computer. This gives you the opportunity to develop, test, and debug your parallel applications before running them on your network cluster.

Third-Party Schedulers

As an alternative to using the MJS, you can use a third-party scheduler. This could be a Microsoft Windows HPC Server (including CCS), Platform LSF scheduler, PBS Pro® scheduler, TORQUE scheduler, or a generic scheduler.

Choosing Between a Third-Party Scheduler and an MJS

You should consider the following when deciding to use a third-party scheduler or the MATLAB job scheduler (MJS) for distributing your tasks:

- Does your cluster already have a scheduler?

If you already have a scheduler, you may be required to use it as a means of controlling access to the cluster. Your existing scheduler might be just as easy to use as an MJS, so there might be no need for the extra administration involved.
• Is the handling of parallel computing jobs the only cluster scheduling management you need?

The MJS is designed specifically for MathWorks® parallel computing applications. If other scheduling tasks are not needed, a third-party scheduler might not offer any advantages.

• Is there a file sharing configuration on your cluster already?

The MJS can handle all file and data sharing necessary for your parallel computing applications. This might be helpful in configurations where shared access is limited.

• Are you interested in batch mode or managed interactive processing?

When you use an MJS, worker processes usually remain running at all times, dedicated to their MJS. With a third-party scheduler, workers are run as applications that are started for the evaluation of tasks, and stopped when their tasks are complete. If tasks are small or take little time, starting a worker for each one might involve too much overhead time.

• Are there security concerns?

Your own scheduler might be configured to accommodate your particular security requirements.

• How many nodes are on your cluster?

If you have a large cluster, you probably already have a scheduler. Consult your MathWorks representative if you have questions about cluster size and the MJS.

• Who administers your cluster?

The person administering your cluster might have a preference for how jobs are scheduled.

• Do you need to monitor your job's progress or access intermediate data?

A job run by the MJS supports events and callbacks, so that particular functions can run as each job and task progresses from one state to another.

**Components on Mixed Platforms or Heterogeneous Clusters**

Parallel Computing Toolbox software and MATLAB Distributed Computing Server software are supported on Windows, UNIX®, and Macintosh operating systems. Mixed platforms are supported, so that the clients, MJS, and workers do not have to be on the same platform. Other limitations are described at System Requirements.
In a mixed-platform environment, system administrators should be sure to follow the proper installation instructions for the local machine on which you are installing the software.

**mdce Service**

If you are using the MJS, every machine that hosts a worker or MJS session must also run the mdce service.

The mdce service controls the worker and MJS sessions and recovers them when their host machines crash. If a worker or MJS machine crashes, when the mdce service starts up again (usually configured to start at machine boot time), it automatically restarts the MJS and worker sessions to resume their sessions from before the system crash. More information about the mdce service is available in the MATLAB Distributed Computing Server documentation.

**Components Represented in the Client**

A client session communicates with the MJS by calling methods and configuring properties of an *MJS cluster object*. Though not often necessary, the client session can also access information about a worker session through a *worker object*.

When you create a job in the client session, the job actually exists in the MJS job storage location. The client session has access to the job through a *job object*. Likewise, tasks that you define for a job in the client session exist in the MJS data location, and you access them through *task objects*.

**Life Cycle of a Job**

When you create and run a job, it progresses through a number of stages. Each stage of a job is reflected in the value of the job object’s *State* property, which can be *pending*, *queued*, *running*, or *finished*. Each of these stages is briefly described in this section.

The figure below illustrates the stages in the life cycle of a job. In the MJS (or other scheduler), the jobs are shown categorized by their state. Some of the functions you use for managing a job are *createJob*, *submit*, and *fetchOutputs*. 
Stages of a Job

The following table describes each stage in the life cycle of a job.

<table>
<thead>
<tr>
<th>Job Stage</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pending</td>
<td>You create a job on the scheduler with the <code>createJob</code> function in your client session of Parallel Computing Toolbox software. The job's first state is <code>pending</code>. This is when you define the job by adding tasks to it.</td>
</tr>
<tr>
<td>Queued</td>
<td>When you execute the <code>submit</code> function on a job, the MJS or scheduler places the job in the queue, and the job's state is <code>queued</code>. The scheduler executes jobs in the queue in the sequence in which they are submitted, all jobs moving up the queue as the jobs before them are finished. You can change the sequence of the jobs in the queue with the <code>promote</code> and <code>demote</code> functions.</td>
</tr>
<tr>
<td>Running</td>
<td>When a job reaches the top of the queue, the scheduler distributes the job's tasks to worker sessions for evaluation. The job's state is now <code>running</code>. If more workers are available than are required for a job's tasks, the scheduler begins executing the next job. In this way, there can be more than one job running at a time.</td>
</tr>
<tr>
<td>Finished</td>
<td>When all of a job's tasks have been evaluated, the job is moved to the <code>finished</code> state. At this time, you can retrieve the results from all the tasks in the job with the function <code>fetchOutputs</code>.</td>
</tr>
<tr>
<td>Job Stage</td>
<td>Description</td>
</tr>
<tr>
<td>-----------</td>
<td>-------------</td>
</tr>
<tr>
<td>Failed</td>
<td>When using a third-party scheduler, a job might fail if the scheduler encounters an error when attempting to execute its commands or access necessary files.</td>
</tr>
<tr>
<td>Deleted</td>
<td>When a job’s data has been removed from its data location or from the MJS with the delete function, the state of the job in the client is deleted. This state is available only as long as the job object remains in the client.</td>
</tr>
</tbody>
</table>

Note that when a job is finished, its data remains in the MJS’s JobStorageLocation folder, even if you clear all the objects from the client session. The MJS or scheduler keeps all the jobs it has executed, until you restart the MJS in a clean state. Therefore, you can retrieve information from a job later or in another client session, so long as the MJS has not been restarted with the -clean option.

You can permanently remove completed jobs from the MJS or scheduler's storage location using the Job Monitor GUI or the delete function.
Program a Job on a Local Cluster

In some situations, you might need to define the individual tasks of a job, perhaps because they might evaluate different functions or have uniquely structured arguments. To program a job like this, the typical Parallel Computing Toolbox client session includes the steps shown in the following example.

This example illustrates the basic steps in creating and running a job that contains a few simple tasks. Each task evaluates the \( \text{sum} \) function for an input array.

1. Identify a cluster. Use `parallel.defaultClusterProfile` to indicate that you are using the local cluster; and use `parcluster` to create the object \( c \) to represent this cluster. (For more information, see “Create a Cluster Object” on page 7-4.)

   ```matlab
   parallel.defaultClusterProfile('local');
   c = parcluster();
   ```

2. Create a job. Create job \( j \) on the cluster. (For more information, see “Create a Job” on page 7-4.)

   ```matlab
   j = createJob(c)
   ```

3. Create three tasks within the job \( j \). Each task evaluates the \( \text{sum} \) of the array that is passed as an input argument. (For more information, see “Create Tasks” on page 7-5.)

   ```matlab
   createTask(j, @sum, 1, {[1 1]});
   createTask(j, @sum, 1, {[2 2]});
   createTask(j, @sum, 1, {[3 3]});
   ```

4. Submit the job to the queue for evaluation. The scheduler then distributes the job’s tasks to MATLAB workers that are available for evaluating. The local cluster might now start MATLAB worker sessions. (For more information, see “Submit a Job to the Cluster” on page 7-5.)

   ```matlab
   submit(j);
   ```

5. Wait for the job to complete, then get the results from all the tasks of the job. (For more information, see “Fetch the Job Results” on page 7-6.)

   ```matlab
   wait(j)
   results = fetchOutputs(j)
   results =
   [2]
   [4]
   [6]
6  Delete the job. When you have the results, you can permanently remove the job from the scheduler's storage location.

`delete(j)`
Specify Your Parallel Preferences

You can access your parallel preferences in any of the following ways:

- On the Home tab in the Environment section, select Parallel > Parallel Preferences.
- Select the desktop pool indicator icon, and select Parallel preferences.
- In the command window, type preferences.

In the navigation tree of the Preferences dialog box, select Parallel Computing Toolbox.

You can control your parallel preference settings as follows:

- Default Cluster — Choose the cluster you want to use. The default cluster is local. For more information, see “Create and Modify Cluster Profiles” on page 6-24.
• **Preferred number of workers** — Specify the number of workers in your parallel pool. The actual pool size is limited by licensing, cluster size, and cluster profile settings on page 6-24. See “Pool Size and Cluster Selection” on page 2-68. For the local profile, do not choose a preferred number of workers larger than 512. See also “Create and Modify Cluster Profiles” on page 6-24. Check your access to cloud computing from the Parallel > Discover Clusters menu.

• **Automatically create a parallel pool** — Select this option to start a pool automatically (if a pool does not yet exist), when you execute one of the following parallel language constructs:
  
  • parfor
  • spmd
  • distributed
  • Composite
  • parfeval
  • parfevalOnAll
  • gcp
  • mapreduce
  • mapreducer

  If you have selected **Automatically create a parallel pool**, you do not need to open a pool manually using the parpool function. If a pool automatically opens, you can still access the pool object with gcp.

• **Shut down and delete a parallel pool** — To shut down a parallel pool automatically if the pool has been idle for the specified amount of time, use the IdleTimeout setting. If you use the pool (for example, using parfor or parfeval), the timeout counter is reset. When the timeout is about to expire, a tooltip on the desktop pool indicator warns you and allows you to reset the timer.

**See Also**

**More About**

• “Decide When to Use parfor” on page 2-2
• “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
· “Create and Modify Cluster Profiles” on page 6-24
MATLAB Parallel Cloud

MATLAB Parallel Cloud allows you to run your applications that use `parfor`-loops and other Parallel Computing Toolbox features on MATLAB workers on MathWorks Cloud. Develop your application on a multicore computer using Parallel Computing Toolbox, and scale up to the cloud with just a few clicks in MATLAB. Using MATLAB Parallel Cloud saves you the work and capital costs of setting up and running your own computer cluster hardware. MATLAB Parallel Cloud currently supports only interactive (`parpool`-based) parallelism. For availability, prerequisites, current features, billing and access, see MATLAB Parallel Cloud. For a comparison with other MATLAB cloud computing options, see Scale Your Parallel Applications to the Cloud.

MATLAB Parallel Cloud is the default profile in MATLAB Online™.

Control the Size of Your MATLAB Parallel Cloud Cluster

Your MATLAB Parallel Cloud cluster changes size automatically based on your usage. When more workers are required, machines are automatically added to the cluster up to the value of the `MaxNumMachines` property. To configure the cluster, on the MATLAB Home tab, select Parallel > Manage Cluster Profiles. In the Cluster Profile Manager, select the MATLAB Parallel Cloud profile. See “Create and Modify Cluster Profiles” on page 6-24.

To view and edit all properties of the cluster programmatically, use the `parallel.cluster.Cloud` object. For details, see the Cloud properties here: `parallel.Cluster`.

Use MATLAB Drive to Share Files With a MATLAB Parallel Cloud Cluster

You can use MATLAB Drive™ for cloud storage provided by MathWorks. Use workers in a MATLAB Parallel Cloud cluster to access files in your MATLAB Drive.

Why should I use MATLAB Drive with MATLAB Parallel Cloud?

You can reduce time spent transferring data between your workstation and your MATLAB Parallel Cloud cluster by uploading files to MATLAB Drive.
How do I use MATLAB Drive with MATLAB Parallel Cloud?

1. Set up MATLAB Drive
   - Sign up for MATLAB Drive, see MATLAB Drive. The web page prompts you to sign up.
   - Install MATLAB Drive alongside your MATLAB installation.

2. Set up MATLAB Parallel Cloud
   - Sign up for MATLAB Parallel Cloud.
   - On the Home tab in the MATLAB Toolstrip, select Parallel > Default Cluster and choose the MATLAB Parallel Cloud profile.

3. Use MATLAB Drive and MATLAB Parallel Cloud
   - Change your current folder in your MATLAB client to a folder inside your MATLAB Drive folder. Then you can use files in your MATLAB Drive on your cluster.
   - When you add folders to your MATLAB path on your MATLAB client, they are automatically on the MATLAB path of workers in a parallel pool on your cluster.
Are there any restrictions?

- Your current working folder must be within your MATLAB Drive folder on your workstation before you access files from your MATLAB Drive on a MATLAB Parallel Cloud cluster.
- Note that there are limits to the amount of data you can transfer to a cluster.
  
  - For MATLAB Parallel Cloud, the combined size of all attached files for a job is limited to 4 GB. See also “Transmitting Large Amounts of Data” on page 6-44.
  - For MATLAB Drive, the maximum file size is equal to the quota of a licensed MATLAB Drive user (currently 5 GB).
- The workers in your parallel pool can only access the files in your MATLAB Drive if your MATLAB client can see these files. You can achieve this, for example, if
  
  - your current working folder in your MATLAB client is in your MATLAB Drive;
  - your MATLAB client path contains folders in your MATLAB Drive.

See Also
Discover Clusters and Use Cluster Profiles

In this section...

- “Cluster Profile Manager” on page 6-18
- “Use Parallel Menu and Cluster Profiles” on page 6-18
- “Discover Clusters” on page 6-19
- “Import and Export Cluster Profiles” on page 6-22
- “Create and Modify Cluster Profiles” on page 6-24
- “Validate Cluster Profiles” on page 6-30
- “Apply Cluster Profiles in Client Code” on page 6-32

Cluster Profile Manager

Cluster profiles let you define certain properties for your cluster, then have these properties applied when you create cluster, job, and task objects in the MATLAB client. Some of the functions that support the use of cluster profiles are:

- `batch`
- `parpool`
- `parcluster`

To create, edit, and import cluster profiles, you can use the Cluster Profile Manager. To open the Cluster Profile Manager, on the Home tab in the Environment section, select Parallel > Manage Cluster Profiles.

Use Parallel Menu and Cluster Profiles

Parallel Computing Toolbox comes pre-configured with two cluster profiles:

- `local`: for running on your local desktop machine.
- MATLAB Parallel Cloud: for MATLAB Parallel Cloud clusters running on Amazon EC2. Updates on availability can be found here. MATLAB Parallel Cloud supports interactive `parpool`-based parallelism. See “MATLAB Parallel Cloud” on page 6-15.

Use the Parallel menu on the MATLAB Home tab for the following tasks:
Discover Clusters and Use Cluster Profiles

- Discover other clusters running on your network or on Amazon EC2 using the **Parallel > Discover Clusters** User Interface.
- If you have trouble connecting to MATLAB Parallel Cloud, select **Parallel > Test Cloud Connection**.
- If you want to view your license usage, select **Parallel > View License Usage**. Alternatively, see: https://www.mathworks.com/licensecenter to view your license usage.
- If you want to open MathWorks Cloud Center from MATLAB in an external web browser, select **Parallel > Cloud Center Web Application**. For more information about Cloud Center, see: http://www.mathworks.com/help/cloudcenter/.

**Discover Clusters**

You can let MATLAB discover clusters for you. Use either of the following techniques to discover those clusters which are available for you to use:

- On the **Home** tab in the **Environment** section, select **Parallel > Discover Clusters**
- In the Cluster Profile Manager, select **Discover Clusters**

This opens the Discover Clusters dialog box, where you can search for MATLAB Distributed Computing Server clusters:
If you select **On your network**, you see a new window. Select this option if your clusters use a MATLAB job scheduler (MJS) or Microsoft Windows HPC server. As clusters are discovered, they populate a list for your selection. If you already have a profile for any of the listed clusters, those profile names are included in the list. If you want to create a new profile for one of the discovered clusters, select the name of the cluster you want to use, and select **Next**. The subsequent dialog box lets you choose if you want to set the new profile as your default.
If you select **On Amazon EC2**, you search for clusters running on Amazon EC2. To access these clusters, you must provide your MathWorks Account login information:
Requirements for Cluster Discovery

Cluster discovery is supported only for MATLAB job schedulers (MJS), Microsoft Windows HPC Server, and Amazon EC2 cloud clusters. The following requirements apply to these clusters.

- **MJS** — MJS clusters support two different means of discovery:
  - Multicast: The discover clusters functionality uses the multicast networking protocol from the client to search for head nodes where an MJS is running. This requires that the multicast networking protocol is enabled and working on the network that connects the MJS head nodes (where the schedulers are running) and the client machines. This form of discovery might be limited to the client local subnet, and therefore not always able to discover an MJS elsewhere in your network.
  - DNS SRV: An alternative discovery technique is to search for clusters by DNS service records.

  The Domain Name System (DNS) is a standard for identifying host names with IP addresses, either on the Internet or in a private network. Using DNS allows discovery of MJS clusters by identifying specific hosts rather than broadcasting across your network.

  A DNS service (SRV) record defines the location of hosts and ports of services, such as those related to the clusters you want to discover. Your system administrator creates DNS SRV records in your organization’s DNS infrastructure. For a description of the required record, and validation information, see “DNS SRV Record” (MATLAB Distributed Computing Server).

- **HPC Server** — The discover clusters functionality uses Active Directory Domain Services to discover head nodes. HPC Server head nodes are added to the Active Directory during installation of the HPC Server software.

- **Amazon EC2** — The discover clusters functionality requires a working network connection between the client and the Cloud Center web services running in mathworks.com.

Import and Export Cluster Profiles

Cluster profiles are stored as part of your MATLAB preferences, so they are generally available on an individual user basis. To make a cluster profile available to someone else,
you can export it to a separate .settings file. In this way, a repository of profiles can be created so that all users of a computing cluster can share common profiles.

To export a cluster profile:

1. In the Profile Clusters Manager, select (highlight) the profile you want to export.
2. Select **Export > Export**. (Alternatively, you can right-click the profile in the listing and select **Export**.)

   If you want to export all your profiles to a single file, select **Export > Export All**

3. In the Export profiles to file dialog box, specify a location and name for the file. The default file name is the same as the name of the profile it contains, with a .settings extension appended; you can alter the names if you want to.

Profiles saved in this way can then be imported by other MATLAB users:

1. In the Cluster Profile Manager, select **Import**.
2. In the Import profiles from file dialog box, browse to find the .settings file for the profile you want to import. Select the file and select **Open**.

   The imported profile appears in your Cluster Profile Manager list. Note that the list contains the profile name, which is not necessarily the file name. If you already have a profile with the same name as the one you are importing, the imported profile gets an extension added to its name so you can distinguish it.

You can also export and import profiles programmatically with the `parallel.exportProfile` and `parallel.importProfile` functions.

**Export Profiles for MATLAB Compiler**

You can use an exported profile with MATLAB Compiler and MATLAB Compiler SDK to identify cluster setup information for running compiled applications on a cluster. For example, the `setmcruserdata` function can use the exported profile file name to set the value for the key `ParallelProfile`. For more information and examples of deploying parallel applications, see “Pass Parallel Computing Toolbox Profile at Run Time” (MATLAB Compiler), and “Use Parallel Computing Toolbox in Deployed Applications” (MATLAB Compiler SDK).

A compiled application has the same default profile and the same list of alternative profiles that the compiling user had when the application was compiled. This means that in many cases the profile file is not needed, as might be the case when using the `local`
profile for local workers. If an exported file is used, the first profile in the file becomes the
default when imported. If any of the imported profiles have the same name as any of the
existing profiles, they are renamed during import (though their names in the file remain
unchanged).

Create and Modify Cluster Profiles

The first time you open the Cluster Profile Manager, it lists two profiles: local and
MATLAB Parallel Cloud.

You can specify profile properties including:
• **NumWorkers**: the number of workers to start a pool. The actual pool size might be limited by licensing, cluster size, and cluster profile settings. See “Pool Size and Cluster Selection” on page 2-68.

• **NumThreads**: the number of computational threads to use on each worker. You can change **NumThreads**, so that your workers can run in multithreaded mode and use all the cores on your cluster. This allows you to increase the number of computational threads **NumThreads** on each worker, without increasing the number of workers **NumWorkers**. If you have more cores available, increase **NumThreads** to take full advantage of the built-in parallelism provided by the multithreaded nature of many of the underlying MATLAB libraries. For details, see Run MATLAB on multicore and multiprocessor machines.

**Note** Do not increase the number of threads across all workers on a machine to exceed the number of physical cores. In other words, make sure that **NumWorkers** x **NumThreads** ≤ number of physical cores on your machine. Otherwise you might have reduced performance.

• **MaxNumMachines**: Maximum number of machines that MATLAB Parallel Cloud can use. When more workers are required, machines are automatically added to the cluster up to this maximum value. See “MATLAB Parallel Cloud” on page 6-15.

To view and edit all properties of the cluster programmatically, use the `parallel.cluster.Cloud` object. For details, see the Cloud properties here: `parallel.Cluster`.

The following example provides instructions on how to create and modify profiles using the Cluster Profile Manager.

Suppose you want to create a profile to set several properties for jobs to run in an MJS cluster. The following example illustrates a possible workflow, where you create two profiles differentiated only by the number of workers they use.

1. In the Cluster Profile Manager, select **Add > Custom > MATLAB Job Scheduler (MJS)**. This specifies that you want a new profile for an MJS cluster.
This creates and displays a new profile, called MJSProfile1.

2 Double-click the new profile name in the listing, and modify the profile name to be MyMJSProfile1.

3 Select **Edit** in the tool strip so that you can set your profile property values.

   In the Description field, enter the text **MJS with 4 workers**, as shown in the following figure. Enter the host name for the machine on which the MJS is running, and the name of the MJS. If you are entering information for an actual MJS already running on your network, enter the appropriate text. If you are unsure about the MJS (formerly known as a job manager) names and locations on your network, ask your system administrator for help.
Note  If the MJS is using a nondefault `BASE_PORT` setting as defined in the `mdce_def` file, the `Host` property in the cluster profile must be appended with this `BASE_PORT` number. For example, `MJS-Host:40000`.

4 Scroll down to the Workers section, and for the Range of number of workers, enter the two-element vector `[4 4]`. This specifies that jobs using this profile require at least four workers and no more than four workers. Therefore, a job using this profile runs on exactly four workers, even if it has to wait until four workers are available before starting.
You might want to edit other properties depending on your particular network and cluster situation.

5 Select **Done** to save the profile settings.

To create a similar profile with just a few differences, you can duplicate an existing profile and modify only the parts you need to change, as follows:

1 In the Cluster Profile Manager, right-click the profile name **MyMJSProfile1** in the list and select **Duplicate**.

   This creates a duplicate profile with a name based on the original profile name appended with **_Copy**.

2 Double-click the new profile name and edit its name to be **MyMJSProfile2**.
3 Select **Edit** to allow you to change the profile property values.

4 Edit the description field to change its text to **MJS with any workers**.

5 Scroll down to the Workers section, and for the Range of number of workers, clear the [4 4] and leave the field blank, as highlighted in the following figure:

6 Select **Done** to save the profile settings and to close the properties editor.

You now have two profiles that differ only in the number of workers required for running a job.
When creating a job, you can apply either profile to that job as a way of specifying how many workers it should run on.

You can see examples of profiles for different kinds of supported schedulers in the MATLAB Distributed Computing Server installation instructions at “Configure Your Cluster” (MATLAB Distributed Computing Server).

**Validate Cluster Profiles**

The Cluster Profile Manager includes the ability to validate profiles. Validation assures that the MATLAB client session can access the cluster, and that the cluster can run the various types of jobs with the settings of your profile.

You can choose to run a subset of the validation stages and specify the number of workers to use when validating your profile. In some cases, you may find it more appropriate or faster to do so.

To validate a profile, follow these steps:

1. Open the Cluster Profile Manager on the **Home** tab in the **Environment** section, by selecting **Parallel > Manage Cluster Profiles**.
2. In the Cluster Profile Manager, select the name of the profile you want to test. You can highlight a profile without changing the selected default profile. So a profile selected for validation does not need to be your default profile.
3. Select the validation stages you want to run.
4. Select the Number of workers using the spinning wheel.
5. Select **Validate**.

If you have selected all stages, profile validation includes five steps:

1. Connects to the cluster (**parcluster**)
2. Runs an independent job (**createJob**) on the cluster using the profile
3. Runs an SPMD-type communicating job on the cluster using the profile
4. Runs a pool-type communicating job on the cluster using the profile
5. Runs a parallel pool job on the cluster using the profile

While the tests are running, the Cluster Profile Manager displays progress as shown here:
You can see details of the different stages by selecting the corresponding row in the pane under Number of workers to use.

**Note** Validation will fail if you already have a parallel pool open.

When the tests are complete, you can select **Show Report** to get more information about test results. This information includes any error messages, debug logs, and other data that might be useful in diagnosing problems or helping to determine proper network settings.

The Validation Results tab keeps the test results available until the current MATLAB session closes.
Apply Cluster Profiles in Client Code

In the MATLAB client where you create and define your parallel computing cluster, job, and task objects, you can use cluster profiles when creating these objects.

Select a Default Cluster Profile

Some functions support default profiles, so that if you do not specify a profile for them, they automatically apply the default. There are several ways to specify which of your profiles should be used as the default profile:

- On the **Home** tab in the **Environment** section, select **Parallel > Default Cluster**, and from there, all your profiles are available. The default profile is indicated. You can select any profile in the list as the default.
- The Cluster Profile Manager indicates which is the default profile. You can select any profile in the list, then select **Set as Default**.
- You can get or set the default profile programmatically by using the `parallel.defaultClusterProfile` function. The following sets of commands achieve the same thing:

  ```matlab
  parallel.defaultClusterProfile('MyMJSProfile1')
  parpool
  
  or
  
  parpool('MyMJSProfile1')
  ```

Create Cluster Object

The `parcluster` function creates a cluster object in your workspace according to the specified profile. The profile identifies a particular cluster and applies property values. For example,

```matlab
    c = parcluster('MyMJSProfile1')
```

This command finds the cluster defined by the settings of the profile named `MyMJSProfile1` and sets property values on the cluster object based on settings in the profile. By applying different profiles, you can alter your cluster choices without changing your MATLAB application code.
Create Jobs and Tasks

Because the properties of cluster, job, and task objects can be defined in a profile, you do not have to explicitly define them in your application. Therefore, your code can accommodate any type of cluster without being modified. For example, the following code uses one profile to set properties on cluster, job, and task objects:

```matlab
cl = parcluster('MyMJSProfile1');
job1 = createJob(cl); % Uses profile of cluster object cl.
createTask(job1,@rand,1,{3}) % Uses profile of cluster object cl.
```

See Also

batch | createJob | parallel.exportProfile | parallel.importProfile | parcluster | parpool | setmcruserdata

Related Examples

• “Pool Size and Cluster Selection” on page 2-68
• “Pass Parallel Computing Toolbox Profile at Run Time” (MATLAB Compiler)
• “Use Parallel Computing Toolbox in Deployed Applications” (MATLAB Compiler SDK)
• “DNS SRV Record” (MATLAB Distributed Computing Server)

More About

• “Configure Your Cluster” (MATLAB Distributed Computing Server)

External Websites

• http://www.mathworks.com/help/cloudcenter/
• https://www.mathworks.com/licensecenter
Apply Callbacks to MJS Jobs and Tasks

The MATLAB job scheduler (MJS) has the ability to trigger callbacks in the client session whenever jobs or tasks in the MJS cluster change to specific states.

Client objects representing jobs and tasks in an MJS cluster include the following properties:

<table>
<thead>
<tr>
<th>Callback Property</th>
<th>Object</th>
<th>Cluster Profile Manager Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>QueuedFcn</td>
<td>Job only</td>
<td>JobQueuedFcn</td>
<td>Specifies the function to execute in the client when a job is submitted to the MJS queue</td>
</tr>
<tr>
<td>RunningFcn</td>
<td>Job or task</td>
<td>JobRunningFcn</td>
<td>Specifies the function to execute in the client when a job or task begins its execution</td>
</tr>
<tr>
<td></td>
<td></td>
<td>TaskRunningFcn</td>
<td></td>
</tr>
<tr>
<td>FinishedFcn</td>
<td>Job or task</td>
<td>JobFinishedFcn</td>
<td>Specifies the function to execute in the client when a job or task completes its execution</td>
</tr>
<tr>
<td></td>
<td></td>
<td>TaskFinishedFcn</td>
<td></td>
</tr>
</tbody>
</table>

You can set each of these properties to any valid MATLAB callback value in the Cluster Profile Manager, see the table and “Create and Modify Cluster Profiles” on page 6-24. The callback follows the same behavior for Handle Graphics®, passing into the callback function the object (job or task) that makes the call and an empty argument of event data.

These properties apply only in the client MATLAB session in which they are set. Later sessions that access the same job or task objects do not inherit the settings from previous sessions. You can apply the properties to existing jobs and tasks at the command-line, but the cluster profile settings apply only at the time these objects are first created.
**Note** The callback properties are available only when using an MJS cluster.

### Example 6.1. Create Callbacks at the Command Line

This example shows how to create job and task callbacks at the client session command line.

Create and save a callback function `clientTaskCompleted.m` on the path of the MATLAB client, with the following content:

```matlab
function clientTaskCompleted(task, eventdata)
    disp(['Finished task: ' num2str(task.ID)])
end
```

Create a job and set its `QueuedFcn`, `RunningFcn`, and `FinishedFcn` properties, using a function handle to an anonymous function that sends information to the display.

```matlab
c = parcluster('MyMJS');
j = createJob(c,'Name','Job_52a');
j.QueuedFcn = @(job,eventdata) disp([job.Name ' now ' job.State]);
j.RunningFcn = @(job,eventdata) disp([job.Name ' now ' job.State]);
j.FinishedFcn = @(job,eventdata) disp([job.Name ' now ' job.State]);
```

Create a task whose `FinishedFcn` is a function handle to the separate function.

```matlab
createTask(j,@rand,1,{2,4}, ...
    'FinishedFcn',@clientTaskCompleted);
```

Run the job and note the output messages from both the job and task callbacks.

```matlab
submit(j)
```

```
Job_52a now queued
Job_52a now running
Finished task: 1
Job_52a now finished
```

To use the same callbacks for any jobs and tasks on a given cluster, you should set these properties in the cluster profile. For details on editing profiles in the profile manager, see “Discover Clusters and Use Cluster Profiles” on page 6-18. These property settings apply to any jobs and tasks created using a cluster derived from this profile. The sequence is important, and must occur in this order:

1. Set the callback property values for the profile in the profile manager.
2 Use the cluster profile to create a cluster object in MATLAB.
3 Use the cluster object to create jobs and then tasks.

**Example 6.2. Set Callbacks in a Cluster Profile**

This example shows how to set several job and task callback properties using the profile manager.

Edit your MJS cluster profile in the profile manager so that you can set the callback properties to the same values in the previous example. The saves profile looks like this:

Create and save a callback function `clientTaskCompleted.m` on the path of the MATLAB client, with the following content. (If you created this function for the previous example, you can use that.)

```matlab
function clientTaskCompleted(task,eventdata)
    disp(['Finished task: ' num2str(task.ID)])
end
```

Create objects for the cluster, job, and task. Then submit the job. All the callback properties are set from the profile when the objects are created.

```matlab
c = parcluster('MyMJS');
j = createJob(c,'Name','Job_52a');
createTask(j,@rand,1,{2,4});
submit(j)
```
Tips

• You should avoid running code in your callback functions that might cause conflicts. For example, if every task in a job has a callback that plots its results, there is no guarantee to the order in which the tasks finish, so the plots might overwrite each other. Likewise, the FinishFcn callback for a job might be triggered to start before the FinishFcn callbacks for all its tasks are complete.

• Submissions made with `batch` use applicable job and task callbacks. Parallel pools can trigger job callbacks defined by their cluster profile.
Job Monitor

The Job Monitor displays the jobs in the queue for the scheduler determined by your selection of a cluster profile. Open the Job Monitor from the MATLAB desktop on the Home tab in the Environment section, by selecting Parallel > Monitor Jobs.

The job monitor lists all the jobs that exist for the cluster specified in the selected profile. You can choose any one of your profiles (those available in your current session Cluster Profile Manager), and whether to display jobs from all users or only your own jobs.

Typical Use Cases

The Job Monitor lets you accomplish many different goals pertaining to job tracking and queue management. Using the Job Monitor, you can:

- Discover and monitor all jobs submitted by a particular user
- Determine the status of a job
- Determine the cause of errors in a job
- Delete old jobs you no longer need
- Create a job object in MATLAB for access to a particular job in the queue
Manage Jobs Using the Job Monitor

Using the Job Monitor you can manage the listed jobs for your cluster. Right-click on any job in the list, and select any of the following options from the context menu. The available options depend on the type of job.

- **Cancel** — Stops a running job and changes its state to 'finished'. If the job is pending or queued, the state changes to 'finished' without its ever running. This is the same as the command-line cancel function for the job.
- **Delete** — Deletes the job data and removes the job from the queue. This is the same as the command-line delete function for the job. Also closes and deletes an interactive pool job.
- **Show details** — This displays detailed information about the job in the Command Window.
- **Show errors** — This displays all the tasks that generated an error in that job, with their error properties.
- **Fetch outputs** — This collects all the task output arguments from the job into the client workspace.

Identify Task Errors Using the Job Monitor

Because the Job Monitor indicates if a job had a run-time error, you can use it to identify the tasks that generated the errors in that job. For example, the following script generates an error because it attempts to perform a matrix inverse on a vector:

```matlab
A = [2 4 6 8];
B = inv(A);
```

If you save this script in a file named `invert_me.m`, you can try to run the script as a batch job on the default cluster:

```matlab
batch('invert_me')
```

When updated after the job runs, the Job Monitor includes the job created by the `batch` command, with an error icon (⚠️) for this job. Right-click the job in the list, and select **Show Errors**. For all the tasks with an error in that job, the task information, including properties related to the error, display in the MATLAB command window:

```
Task ID 1 from Job ID 2 Information
```

---

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State : finished
Function : @parallel.internal.cluster.executeScript
Running Duration : 0 days 0h 0m 1s

- Task Result Properties
  ErrorIdentifier : MATLAB:square
  ErrorMessage : Matrix must be square.
  Error Stack : invert_me (line 2)
Programming Tips

Program Development Guidelines

When writing code for Parallel Computing Toolbox software, you should advance one step at a time in the complexity of your application. Verifying your program at each step prevents your having to debug several potential problems simultaneously. If you run into any problems at any step along the way, back up to the previous step and reverify your code.

The recommended programming practice for distributed or parallel computing applications is

1. **Run code normally on your local machine.** First verify all your functions so that as you progress, you are not trying to debug the functions and the distribution at the same time. Run your functions in a single instance of MATLAB software on your local computer. For programming suggestions, see “Techniques to Improve Performance” (MATLAB).

2. **Decide whether you need an independent or communicating job.** If your application involves large data sets on which you need simultaneous calculations performed, you might benefit from a communicating job with distributed arrays. If your application involves looped or repetitive calculations that can be performed independently of each other, an independent job might be appropriate.
Modify your code for division. Decide how you want your code divided. For an independent job, determine how best to divide it into tasks; for example, each iteration of a for-loop might define one task. For a communicating job, determine how best to take advantage of parallel processing; for example, a large array can be distributed across all your workers.

Use pmode to develop parallel functionality. Use pmode with the local scheduler to develop your functions on several workers in parallel. As you progress and use pmode on the remote cluster, that might be all you need to complete your work.

Run the independent or communicating job with a local scheduler. Create an independent or communicating job, and run the job using the local scheduler with several local workers. This verifies that your code is correctly set up for batch execution, and in the case of an independent job, that its computations are properly divided into tasks.

Run the independent job on only one cluster node. Run your independent job with one task to verify that remote distribution is working between your client and the cluster, and to verify proper transfer of additional files and paths.

Run the independent or communicating job on multiple cluster nodes. Scale up your job to include as many tasks as you need for an independent job, or as many workers as you need for a communicating job.

Note The client session of MATLAB must be running the Java® Virtual Machine (JVM™) to use Parallel Computing Toolbox software. Do not start MATLAB with the -nojvm flag.

Current Working Directory of a MATLAB Worker

The current directory of a MATLAB worker at the beginning of its session is

CHECKPOINTBASE\HOSTNAME_WORKERNAME_mlworker_log\work

where CHECKPOINTBASE is defined in the mdce_def file, HOSTNAME is the name of the node on which the worker is running, and WORKERNAME is the name of the MATLAB worker session.

For example, if the worker named worker22 is running on host nodeA52, and its CHECKPOINTBASE value is C:\TEMP\MDCE\Checkpoint, the starting current directory for that worker session is
Writing to Files from Workers

When multiple workers attempt to write to the same file, you might end up with a race condition, clash, or one worker might overwrite the data from another worker. This might be likely to occur when:

- There is more than one worker per machine, and they attempt to write to the same file.
- The workers have a shared file system, and use the same path to identify a file for writing.

In some cases an error can result, but sometimes the overwriting can occur without error. To avoid an issue, be sure that each worker or parfor iteration has unique access to any files it writes or saves data to. There is no problem when multiple workers read from the same file.

Saving or Sending Objects

Do not use the save or load function on Parallel Computing Toolbox objects. Some of the information that these objects require is stored in the MATLAB session persistent memory and would not be saved to a file.

Similarly, you cannot send a parallel computing object between parallel computing processes by means of an object's properties. For example, you cannot pass an MJS, job, task, or worker object to MATLAB workers as part of a job's JobData property.

Also, system objects (e.g., Java classes, .NET classes, shared libraries, etc.) that are loaded, imported, or added to the Java search path in the MATLAB client, are not available on the workers unless explicitly loaded, imported, or added on the workers, respectively. Other than in the task function code, typical ways of loading these objects might be in taskStartup, jobStartup, and in the case of workers in a parallel pool, in poolStartup and using pctRunOnAll.

Using clear functions

Executing

clear functions
clears all Parallel Computing Toolbox objects from the current MATLAB session. They
still remain in the MJS. For information on recreating these objects in the client session,
see “Recover Objects” on page 7-14.

Running Tasks That Call Simulink Software

The first task that runs on a worker session that uses Simulink software can take a long
time to run, as Simulink is not automatically started at the beginning of the worker
session. Instead, Simulink starts up when first called. Subsequent tasks on that worker
session will run faster, unless the worker is restarted between tasks.

Using the pause Function

On worker sessions running on Macintosh or UNIX operating systems, `pause(Inf)`
returns immediately, rather than pausing. This is to prevent a worker session from
hanging when an interrupt is not possible.

Transmitting Large Amounts of Data

Operations that involve transmitting many objects or large amounts of data over the
network can take a long time. For example, getting a job’s `Tasks` property or the results
from all of a job’s tasks can take a long time if the job contains many tasks. See also
“Attached Files Size Limitations” on page 6-62.

Interrupting a Job

Because jobs and tasks are run outside the client session, you cannot use `Ctrl+C` (^C) in
the client session to interrupt them. To control or interrupt the execution of jobs and
tasks, use such functions as `cancel`, `delete`, `demote`, `promote`, `pause`, and `resume`.

Speeding Up a Job

You might find that your code runs slower on multiple workers than it does on one
desktop computer. This can occur when task startup and stop time is significant relative
to the task run time. The most common mistake in this regard is to make the tasks too
small, i.e., too fine-grained. Another common mistake is to send large amounts of input
or output data with each task. In both of these cases, the time it takes to transfer data
and initialize a task is far greater than the actual time it takes for the worker to evaluate
the task function.
Control Random Number Streams

Different Workers

By default, each worker in a cluster working on the same job has a unique random number stream. This example uses two workers in a parallel pool to show they generate unique random number sequences.

```matlab
p = parpool(2);
spmd
    R = rand(1,4);  % Different on each worker
end
R{1},R{2}
```

```
0.3246    0.6618    0.6349    0.6497
0.2646    0.0968    0.5052    0.4866
```

```matlab
delete(p)
```

If you need all workers to generate the same sequence of numbers, you can seed their generators all the same.

```matlab
p = parpool(2);
spmd
    s = RandStream('twister');  % Default seed 0.
    RandStream.setGlobalStream(s);
    R = rand(1,4);  % Same on all workers
end
R{1},R{2}
```

```
0.8147    0.9058    0.1270    0.9134
0.8147    0.9058    0.1270    0.9134
```

```matlab
delete(p)
```
Note  Because `rng('shuffle')` seeds the random number generator based on the current time, you should not use this command to set the random number stream on different workers if you want to assure independent streams. This is especially true when the command is sent to multiple workers simultaneously, such as inside a `parfor`, `spmd`, or a communicating job. For independent streams on the workers, use the default behavior; or if that is not sufficient for your needs, consider using a unique substream on each worker.

For instructions on how to generate a reproducible set of random numbers in a `parfor`-loop, see “Repeat Random Numbers in parfor-Loops” on page 2-71.

**Client and Workers**

By default, the MATLAB client and MATLAB workers use different random number generators, even if the workers are part of a local cluster on the same machine with the client. For the client, the default is the Mersenne Twister generator (`'twister'`), and for the workers the default is the Combined Multiple Recursive generator (`'CombRecursive'` or `'mrg32k3a'`). If it is necessary to generate the same stream of numbers in the client and workers, you can set one to match the other.

For example, you might run a script as a batch job on a worker, and need the same generator or sequence as the client. Suppose you start with a script file named `randScript1.m` that contains the line:

```matlab
R = rand(1,4);
```

You can run this script in the client, and then as a batch job on a worker. Notice that the default generated random number sequences in the results are different.

```matlab
randScript1; % In client
R
R =
 0.8147   0.9058   0.1270   0.9134
```

```matlab
parallel.defaultClusterProfile('local')
c = parcluster();
j = batch(c,'randScript1'); % On worker
wait(j);load(j);
R
```
For identical results, you can set the client and worker to use the same generator and seed. Here the file `randScript2.m` contains the following code:

```matlab
s = RandStream('CombRecursive','Seed',1);
RandStream.setGlobalStream(s);
R = rand(1,4);

Now, run the new script in the client and on a worker:

```matlab
randScript2; % In client
R
```
```
R =
0.4957 0.2243 0.2073 0.6823
```
```
j = batch(c,'randScript2'); % On worker
wait(j); load(j);
R
```
```
R =
0.4957 0.2243 0.2073 0.6823
```

**Client and GPU**

By default MATLAB clients use different random generators than code running on a GPU. GPUs are more like workers in this regard, and use the Combined Multiple Recursive generator ('CombRecursive' or 'mrg32k3a') unless otherwise specified.

This example shows a default generation of random numbers comparing CPU and GPU in a fresh session.

```matlab
Rc = rand(1,4)
Rc =
0.8147 0.9058 0.1270 0.9134

Rg = rand(1,4,'gpuArray')
Rg =
0.7270 0.4522 0.9387 0.2360
```
Be aware that the GPU supports only three generators ('CombRecursive', 'Philox4x32-10', and 'Threefry4x64-20'). The following table lists the algorithms for these generators and their properties.

<table>
<thead>
<tr>
<th>Keyword</th>
<th>Generator</th>
<th>Multiple Stream and Substream Support</th>
<th>Approximate Period In Full Precision</th>
</tr>
</thead>
<tbody>
<tr>
<td>'CombRecursive' or 'mrg32k3a'</td>
<td>Combined multiple recursive generator</td>
<td>Yes</td>
<td>$2^{127}$</td>
</tr>
<tr>
<td>'Philox4x32-10'</td>
<td>Philox 4x32 generator with 10 rounds</td>
<td>Yes</td>
<td>$2^{129}$</td>
</tr>
<tr>
<td>'Threefry4x64-20'</td>
<td>Threefry 4x64 generator with 20 rounds</td>
<td>Yes</td>
<td>$2^{258}$</td>
</tr>
</tbody>
</table>

None of these is the default client generator for the CPU. To generate the same sequence on CPU and GPU, you must use the only generator supported by both: 'CombRecursive'.

```matlab
sc = RandStream('CombRecursive','Seed',1);
RandStream.setGlobalStream(sc);
Rc = rand(1,4)
Rc =
   0.4957    0.2243    0.2073    0.6823
sg = parallel.gpu.RandStream('CombRecursive','Seed',1);
parallel.gpu.RandStream.setGlobalStream(sg);
Rg = rand(1,4,'gpuArray')
Rg =
   0.4957    0.2243    0.2073    0.6823
```

For normally distributed random numbers created by `randn`, CPU code by default uses a random stream with a `NormalTransform` setting of Ziggurat, while GPU code uses a setting of Inversion. You can set CPU and GPU generators the same to get the same `randn` sequence. The GPU supports only Inversion, so set the CPU to match:

```matlab
sc = RandStream('CombRecursive','NormalTransform','Inversion','Seed',1);
RandStream.setGlobalStream(sc)
sg = parallel.gpu.RandStream('CombRecursive','NormalTransform','Inversion','Seed',1);
parallel.gpu.RandStream.setGlobalStream(sg);
Rc = randn(1,4)
```
Worker CPU and Worker GPU

Code running on a worker’s CPU uses the same generator to create random numbers as code running on a worker’s GPU, but they do not share the same stream. You can use a common seed to generate the same sequence of numbers, as shown in this example, where each worker creates the same sequence on GPU and CPU, but different from the sequence on the other worker.

```matlab
p = parpool(2);
spmd
    sc = RandStream('CombRecursive','Seed',labindex);
    RandStream.setGlobalStream(sc);
    Rc = rand(1,4)
    sg = parallel.gpu.RandStream('CombRecursive','Seed',labindex);
    parallel.gpu.RandStream.setGlobalStream(sg);
    Rg = rand(1,4,'gpuArray')
end
delete(p)
```

For normally distributed random numbers from `randn`, by default a worker CPU uses a NormalTransform setting of Ziggurat while a worker GPU uses a setting of Inversion. You can set them both to use Inversion if you need the same sequence from CPU and GPU.
**Profiling Parallel Code**

**Introduction**

The parallel profiler provides an extension of the `profile` command and the profile viewer specifically for communicating jobs, to enable you to see how much time each worker spends evaluating each function and how much time communicating or waiting for communications with the other workers. Before using the parallel profiler, familiarize yourself with the standard profiler and its views, as described in “Profile to Improve Performance” (MATLAB).

**Note** The parallel profiler works on communicating jobs, including inside pmode. It does not work on `parfor`-loops.

**Collecting Parallel Profile Data**

For parallel profiling, you use the `mpiprofile` command within your communicating job (often within pmode) in a similar way to how you use `profile`.

To turn on the parallel profiler to start collecting data, enter the following line in your communicating job task code file, or type at the pmode prompt in the Parallel Command Window:

```plaintext
mpiprofile on
```

Now the profiler is collecting information about the execution of code on each worker and the communications between the workers. Such information includes:

- Execution time of each function on each worker
- Execution time of each line of code in each function
- Amount of data transferred between each worker
• Amount of time each worker spends waiting for communications

With the parallel profiler on, you can proceed to execute your code while the profiler collects the data.

In the pmode Parallel Command Window, to find out if the profiler is on, type:

```
P>> mpiprofile status
```

For a complete list of options regarding profiler data details, clearing data, etc., see the `mpiprofile` reference page.

**Viewing Parallel Profile Data**

To open the parallel profile viewer from pmode, type in the Parallel Command Window:

```
P>> mpiprofile viewer
```

The remainder of this section is an example that illustrates some of the features of the parallel profile viewer. This example executes in a pmode session running on four local workers. Initiate pmode by typing in the MATLAB Command Window:

```
pmode start local 4
```

When the Parallel Command Window (pmode) starts, type the following code at the pmode prompt:

```
P>> R1 = rand(16, codistributor())
P>> R2 = rand(16, codistributor())
P>> mpiprofile on
P>> P = R1*R2
P>> mpiprofile off
P>> mpiprofile viewer
```

The last command opens the Profiler window, first showing the Parallel Profile Summary (or function summary report) for worker (lab) 1.
The function summary report displays the data for each function executed on a worker in sortable columns with the following headers:

<table>
<thead>
<tr>
<th>Column Header</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Calls</td>
<td>How many times the function was called on this worker</td>
</tr>
<tr>
<td>Total Time</td>
<td>The total amount of time this worker spent executing this function</td>
</tr>
<tr>
<td>Self Time</td>
<td>The time this worker spent inside this function, not within children or local functions</td>
</tr>
<tr>
<td>Total Comm Time</td>
<td>The total time this worker spent transferring data with other workers, including waiting time to receive data</td>
</tr>
<tr>
<td>Self Comm Waiting Time</td>
<td>The time this worker spent during this function waiting to receive data from other workers</td>
</tr>
<tr>
<td>Total Interlab Data</td>
<td>The amount of data transferred to and from this worker for this function</td>
</tr>
<tr>
<td>Computation Time Ratio</td>
<td>The ratio of time spent in computation for this function vs. total time (which includes communication time) for this function</td>
</tr>
<tr>
<td>Column Header</td>
<td>Description</td>
</tr>
<tr>
<td>----------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Total Time Plot</td>
<td>Bar graph showing relative size of Self Time, Self Comm Waiting Time, and Total Time for this function on this worker</td>
</tr>
</tbody>
</table>

Select the name of any function in the list for more details about the execution of that function. The function detail report for `codistributed.mtimes` includes this listing:

![Profile screenshot](image)

The code that is displayed in the report is taken from the client. If the code has changed on the client since the communicating job ran on the workers, or if the workers are running a different version of the functions, the display might not accurately reflect what actually executed.

You can display information for each worker, or use the comparison controls to display information for several workers simultaneously. Two buttons provide **Automatic Comparison Selection**, allowing you to compare the data from the workers that took the most versus the least amount of time to execute the code, or data from the workers that spent the most versus the least amount of time in performing interworker communication. **Manual Comparison Selection** allows you to compare data from specific workers or workers that meet certain criteria.
The following listing from the summary report shows the result of using the **Automatic Comparison Selection** of **Compare (max vs. min TotalTime)**. The comparison shows data from worker (lab) 3 compared to worker (lab) 1 because these are the workers that spend the most versus least amount of time executing the code.

![Image of data table]

The following figure shows a summary of all the functions executed during the profile collection time. The **Manual Comparison Selection** of **max Time Aggregate** means that data is considered from all the workers for all functions to determine which worker spent the maximum time on each function. Next to each function's name is the worker that took the longest time to execute that function. The other columns list the data from that worker.
The next figure shows a summary report for the workers that spend the most versus least time for each function. A Manual Comparison Selection of max Time Aggregate against min Time >0 Aggregate generated this summary. Both aggregate settings indicate that the profiler should consider data from all workers for all functions, for both maximum and minimum. This report lists the data for codistributed.mtimes from workers 3 and 1, because they spent the maximum and minimum times on this function. Similarly, other functions are listed.
Select a function name in the summary listing of a comparison to get a detailed comparison. The detailed comparison for `codistributed.mtimes` looks like this, displaying line-by-line data from both workers:
To see plots of communication data, select **Plot All PerLab Communication** in the **Show Figures** menu. The top portion of the plot view report plots how much data each worker receives from each other worker for all functions.

To see only a plot of interworker communication times, select **Plot CommTimePerLab** in the **Show Figures** menu.
Plots like those in the previous two figures can help you determine the best way to balance work among your workers, perhaps by altering the partition scheme of your codistributed arrays.
HPC Challenge Benchmarks

Several MATLAB files are available to illustrate HPC Challenge benchmark performance. You can find the files in the folder `matlabroot/toolbox/distcomp/examples/benchmark/hpcchallenge`. Each file is self-documented with explanatory comments. These files are not self-contained examples, but rather require that you know enough about your cluster to be able to provide the necessary information when using these files.
Benchmarking Performance
Troubleshooting and Debugging

In this section...

“Attached Files Size Limitations” on page 6-62
“File Access and Permissions” on page 6-62
“No Results or Failed Job” on page 6-64
“Connection Problems Between the Client and MJS” on page 6-64
“SFTP Error: Received Message Too Long” on page 6-65

Attached Files Size Limitations

The combined size of all attached files for a job is limited to 4 GB.

File Access and Permissions

Ensuring That Workers on Windows Operating Systems Can Access Files

By default, a worker on a Windows operating system is installed as a service running as LocalSystem, so it does not have access to mapped network drives.

Often a network is configured to not allow services running as LocalSystem to access UNC or mapped network shares. In this case, you must run the mdce service under a different user with rights to log on as a service. See the section “Set the User” (MATLAB Distributed Computing Server) in the MATLAB Distributed Computing Server System Administrator's Guide.

Task Function Is Unavailable

If a worker cannot find the task function, it returns the error message

Error using ==> feval
    Undefined command/function 'function_name'.

The worker that ran the task did not have access to the function function_name. One solution is to make sure the location of the function’s file, function_name.m, is included in the job’s AdditionalPaths property. Another solution is to transfer the function file to the worker by adding function_name.m to the AttachedFiles property of the job.
Load and Save Errors

If a worker cannot save or load a file, you might see the error messages

```plaintext
??? Error using ==> save
Unable to write file myfile.mat: permission denied.
??? Error using ==> load
Unable to read file myfile.mat: No such file or directory.
```

In determining the cause of this error, consider the following questions:

- What is the worker’s current folder?
- Can the worker find the file or folder?
- What user is the worker running as?
- Does the worker have permission to read or write the file in question?

Tasks or Jobs Remain in Queued State

A job or task might get stuck in the queued state. To investigate the cause of this problem, look for the scheduler’s logs:

- Platform LSF schedulers might send emails with error messages.
- Microsoft Windows HPC Server (including CCS), LSF®, PBS Pro, and TORQUE save output messages in a debug log. See the `getDebugLog` reference page.
- If using a generic scheduler, make sure the submit function redirects error messages to a log file.

Possible causes of the problem are:

- The MATLAB worker failed to start due to licensing errors, the executable is not on the default path on the worker machine, or is not installed in the location where the scheduler expected it to be.
- MATLAB could not read/write the job input/output files in the scheduler’s job storage location. The storage location might not be accessible to all the worker nodes, or the user that MATLAB runs as does not have permission to read/write the job files.
- If using a generic scheduler:
  - The environment variable `MDCE DECODE FUNCTION` was not defined before the MATLAB worker started.
• The decode function was not on the worker’s path.

No Results or Failed Job

Task Errors

If your job returned no results (i.e., `fetchOutputs(job)` returns an empty cell array), it is probable that the job failed and some of its tasks have their Error properties set.

You can use the following code to identify tasks with error messages:

```matlab
ermsgs = get(yourjob.Tasks, {'ErrorMessage'});
onempty = ~cellfun(@isempty, errmsgs);
celldisp(errmsgs(nonempty));
```

This code displays the nonempty error messages of the tasks found in the job object `yourjob`.

Debug Logs

If you are using a supported third-party scheduler, you can use the `getDebugLog` function to read the debug log from the scheduler for a particular job or task.

For example, find the failed job on your LSF scheduler, and read its debug log:

```matlab
c = parcluster('my_lsf_profile')
failedjob = findJob(c, 'State', 'failed');
message = getDebugLog(c, failedjob(1))
```

Connection Problems Between the Client and MJS

For testing connectivity between the client machine and the machines of your compute cluster, you can use Admin Center. For more information about Admin Center, including how to start it and how to test connectivity, see “Start Admin Center” (MATLAB Distributed Computing Server) and “Test Connectivity” (MATLAB Distributed Computing Server).

Detailed instructions for other methods of diagnosing connection problems between the client and MJS can be found in some of the Bug Reports listed on the MathWorks Web site.
The following sections can help you identify the general nature of some connection problems.

**Client Cannot See the MJS**

If you cannot locate or connect to your MJS with parcluster, the most likely reasons for this failure are:

- The MJS is currently not running.
- Firewalls do not allow traffic from the client to the MJS.
- The client and the MJS are not running the same version of the software.
- The client and the MJS cannot resolve each other’s short hostnames.
- The MJS is using a nondefault BASE_PORT setting as defined in the mdce_def file, and the Host property in the cluster profile does not specify this port.

**MJS Cannot See the Client**

If a warning message says that the MJS cannot open a TCP connection to the client computer, the most likely reasons for this are

- Firewalls do not allow traffic from the MJS to the client.
- The MJS cannot resolve the short hostname of the client computer. Use pctconfig to change the hostname that the MJS will use for contacting the client.

**SFTP Error: Received Message Too Long**

The example code for generic schedulers with non-shared file systems contacts an sftp server to handle the file transfer to and from the cluster’s file system. This use of sftp is subject to all the normal sftp vulnerabilities. One problem that can occur results in an error message similar to this:

```
Caused by:    
Error using --> RemoteClusterAccess>RemoteClusterAccess.waitForChoreToFinishOrError at 780
The following errors occurred in the
   com.mathworks.toolbox.distcomp.clusteraccess.UploadFilesChore:
Could not send Job3.common.mat for job 3:
One of your shell's init files contains a command that is writing to stdout,
interfering with sftp. Access help
com.mathworks.toolbox.distcomp.remote.spi.plugin.SftpExtraBytesFromShellException:
One of your shell's init files contains a command that is writing to stdout,
interfering with sftp.
Find and wrap the command with a conditional test, such as
   if ($ TERM != 0) then
```

6-65
if ($TERM != "dumb") then
    /your command/
endif
endif
: 4: Received message is too long: 1718579037

The telling symptom is the phrase "Received message is too long:" followed by a very large number.

The sftp server starts a shell, usually bash or tcsh, to set your standard read and write permissions appropriately before transferring files. The server initializes the shell in the standard way, calling files like .bashrc and .cshrc. This problem happens if your shell emits text to standard out when it starts. That text is transferred back to the sftp client running inside MATLAB, and is interpreted as the size of the sftp server's response message.

To work around this error, locate the shell startup file code that is emitting the text, and either remove it or bracket it within if statements to see if the sftp server is starting the shell:

if ($?TERM != 0) then
    if ($TERM != "dumb") then
        /your command/
    endif
endif

You can test this outside of MATLAB with a standard UNIX or Windows sftp command-line client before trying again in MATLAB. If the problem is not fixed, the error message persists:

> sftp yourSubmitMachine
Connecting to yourSubmitMachine...
Received message too long 1718579042

If the problem is fixed, you should see:

> sftp yourSubmitMachine
Connecting to yourSubmitMachine...
The illustration shows a typical workflow that uses tall arrays to analyze a large data set. In this workflow, you analyze a small subset of the data before scaling up to analyze the entire data set. Parallel computing can help you scale up from steps six to seven. That is, after checking that your code works on the small data set, run it on the whole data set. You can use MATLAB to enhance this workflow.

<table>
<thead>
<tr>
<th>Problem</th>
<th>Solution</th>
<th>Required Products</th>
<th>More Information</th>
</tr>
</thead>
<tbody>
<tr>
<td>Is your data too big?</td>
<td>To work with out-of-memory data with any number of rows, use tall arrays. This workflow is well suited to data analytics and machine learning.</td>
<td>MATLAB</td>
<td>“Tall Arrays” (MATLAB)</td>
</tr>
</tbody>
</table>
Running Tall Arrays in Parallel

Parallel Computing Toolbox can immediately speed up your tall array calculations by using the full processing power of multicore computers to execute applications with a parallel pool of workers. If you already have Parallel Computing Toolbox installed, then you probably do not need to do anything special to take advantage of these capabilities. For more information about using tall arrays with Parallel Computing Toolbox, see “Use Tall Arrays on a Parallel Pool” on page 6-70.

Use mapreducer to Control Where Your Code Runs

When you execute tall arrays, the default execution environment uses either the local MATLAB session, or a local parallel pool if you have Parallel Computing Toolbox. The default pool uses local workers, typically one worker for each core in your machine. Use the mapreducer function to change the execution environment of tall arrays to use a different cluster.
One of the benefits of developing your algorithms with tall arrays is that you only need to write the code once. You can develop your code locally, then use `mapreducer` to scale up and take advantage of the capabilities offered by Parallel Computing Toolbox and MATLAB Distributed Computing Server.

**See Also**

datastore | gather | mapreducer | tall

**Related Examples**

- “Use Tall Arrays on a Parallel Pool” on page 6-70
- “Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
- “Tall Arrays” (MATLAB)
- “Choose a Parallel Computing Solution” on page 1-26

**More About**

- “Datastore” (MATLAB)
Use Tall Arrays on a Parallel Pool

If you have Parallel Computing Toolbox, you can use tall arrays in your local MATLAB session, or on a local parallel pool. You can also run tall array calculations on a cluster if you have MATLAB Distributed Computing Server installed. This example uses the workers in a local cluster on your machine. You can develop code locally, and then scale up, to take advantage of the capabilities offered by Parallel Computing Toolbox and MATLAB Distributed Computing Server without having to rewrite your algorithm. See also “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67.

Create a datastore and convert it into a tall table.

ds = datastore('airlinesmall.csv');
varnames = {'ArrDelay', 'DepDelay'};
ds.SelectedVariableNames = varnames;
ds.TreatAsMissing = 'NA';

If you have Parallel Computing Toolbox installed, when you use the `tall` function, MATLAB automatically starts a parallel pool of workers, unless you turn off the default parallel pool preference. The default cluster uses local workers on your machine.

**Note** If you want to turn off automatically opening a parallel pool, change your parallel preferences. If you turn off the **Automatically create a parallel pool** option, then you must explicitly start a pool if you want the `tall` function to use it for parallel processing. See “Specify Your Parallel Preferences” on page 6-12.

If you have Parallel Computing Toolbox, you can run the same code as the MATLAB tall table example (MATLAB) and automatically execute it in parallel on the workers of your local machine.

Create a tall table `tt` from the datastore.

```
tt = tall(ds)
Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.
tt =
M×2 tall table
    ArrDelay    DepDelay
```
The display indicates that the number of rows, \( M \), is not yet known. \( M \) is a placeholder until the calculation completes.

Extract the arrival delay \( \text{ArrDelay} \) from the tall table. This action creates a new tall array variable to use in subsequent calculations.

\[
a = \text{tt.ArrDelay};
\]

You can specify a series of operations on your tall array, which are not executed until you call \texttt{gather}. Doing so enables you to batch up commands that might take a long time. For example, calculate the mean and standard deviation of the arrival delay. Use these values to construct the upper and lower thresholds for delays that are within 1 standard deviation of the mean.

\[
m = \text{mean}(a, \text{'omitnan'});
s = \text{std}(a, \text{'omitnan'});
one\_sigma\_bounds = [m-s \ m \ m+s];
\]

\textbf{Use \texttt{gather} to calculate \texttt{one\_sigma\_bounds}, and bring the answer into memory.}

\[
sig1 = \text{gather}(\text{one\_sigma\_bounds})
\]

\texttt{Evaluating tall expression using the Parallel Pool 'local':}\n\texttt{Evaluation completed in 0 sec}\n
\[
sig1 = \\
-23.4572 \ 7.1201 \ 37.6975
\]
You can specify multiple inputs and outputs to `gather` if you want to evaluate several things at once. Doing so is faster than calling `gather` separately on each tall array. As an example, calculate the minimum and maximum arrival delay.

```matlab
[max_delay, min_delay] = gather(max(a),min(a))
```

Evaluating tall expression using the Parallel Pool 'local':
- Pass 1 of 1: Completed in 1 sec
Evaluation completed in 1 sec

```matlab
max_delay =  
    1014
min_delay =  
    -64
```

If you want to develop in serial and not use local workers or your specified cluster, enter the following command.

```matlab
mapreducer(0);
```

If you use `mapreducer` to change the execution environment after creating a tall array, then the tall array is invalid and you must recreate it. To use local workers or your specified cluster again, enter the following command.

```matlab
mapreducer(gcp);
```

**Note** One of the benefits of developing algorithms with tall arrays is that you only need to write the code once. You can develop your code locally, and then use `mapreducer` to scale up to a cluster, without needing to rewrite your algorithm. For an example, see “Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74.

**See Also**
- `datastore`
- `gather`
- `mapreducer`
- `parpool`
- `table`
- `tall`

**Related Examples**
- “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
• “Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
• “Tall Arrays” (MATLAB)

More About
• “Datastore” (MATLAB)
Use Tall Arrays on a Spark Enabled Hadoop Cluster

Creating and Using Tall Tables

This example shows how to modify a MATLAB example of creating a tall table to run on a Spark enabled Hadoop® cluster. You can use this tall table to create tall arrays and calculate statistical properties. You can develop code locally and then scale up, to take advantage of the capabilities offered by Parallel Computing Toolbox and MATLAB Distributed Computing Server without having to rewrite your algorithm. See also “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67 and “Configure a Hadoop Cluster” (MATLAB Distributed Computing Server).

First, you must set environment variables and cluster properties as appropriate for your specific Spark enabled Hadoop cluster configuration. See your system administrator for the values for these and other properties necessary for submitting jobs to your cluster.

```matlab
setenv('HADOOP_HOME', '/path/to/hadoop/install')
setenv('SPARK_HOME', '/path/to/spark/install');
cluster = parallel.cluster.Hadoop;

% Optionally, if you want to control the exact number of workers:
cluster.SparkProperties('spark.executor.instances') = '16';

mapreducer(cluster);
```

**Note** In the setup step, you use `mapreducer` to set the cluster execution environment. In the next step, you create a tall array. If you modify or delete the cluster execution environment after creating a tall array, then the tall array is invalid and you must recreate it.

**Note** If you want to develop in serial and not use local workers, enter the following command.

```matlab
mapreducer(0);
```

After setting your environment variables and cluster properties, you can run the MATLAB tall table example (MATLAB) on the Spark enabled Hadoop cluster instead of
on your local machine. Create a datastore and convert it into a tall table. MATLAB automatically starts a Spark job to run subsequent calculations on the tall table.

```matlab
ds = datastore('airlinesmall.csv');
varnames = {'ArrDelay', 'DepDelay'};
ds.SelectedVariableNames = varnames;
ds.TreatAsMissing = 'NA';

Create a tall table `tt` from the datastore.

```matlab
tt = tall(ds)
```

Starting a Spark Job on the Hadoop cluster. This could take a few minutes ...done.

```matlab
tt =
M×2 tall table

<table>
<thead>
<tr>
<th>ArrDelay</th>
<th>DepDelay</th>
</tr>
</thead>
<tbody>
<tr>
<td>8</td>
<td>12</td>
</tr>
<tr>
<td>8</td>
<td>1</td>
</tr>
<tr>
<td>21</td>
<td>20</td>
</tr>
<tr>
<td>13</td>
<td>12</td>
</tr>
<tr>
<td>4</td>
<td>-1</td>
</tr>
<tr>
<td>59</td>
<td>63</td>
</tr>
<tr>
<td>3</td>
<td>-2</td>
</tr>
<tr>
<td>11</td>
<td>-1</td>
</tr>
<tr>
<td>:</td>
<td>:</td>
</tr>
<tr>
<td>:</td>
<td>:</td>
</tr>
</tbody>
</table>
```

The display indicates that the number of rows, \( M \), is not yet known. \( M \) is a placeholder until the calculation completes.

Extract the arrival delay `ArrDelay` from the tall table. This action creates a new tall array variable to use in subsequent calculations.

```matlab
a = tt.ArrDelay;
```

You can specify a series of operations on your tall array, which are not executed until you call `gather`. Doing so allows you to batch up commands that might take a long time. As an example, calculate the mean and standard deviation of the arrival delay. Use these
values to construct the upper and lower thresholds for delays that are within 1 standard deviation of the mean.

\[
\begin{align*}
m &= \text{mean}(a, 'omitnan'); \\
s &= \text{std}(a, 'omitnan'); \\
\text{one_sigma_bounds} &= [m-s \ m \ m+s];
\end{align*}
\]

Use \texttt{gather} to calculate \texttt{one_sigma_bounds}, and bring the answer into memory.

\[
\text{sig1} = \text{gather}([m-s \ m \ m+s])
\]

Evaluating tall expression using the Spark Cluster:
Evaluation completed in 0 sec

\[
\text{sig1} = \\
-23.4572 \ 7.1201 \ 37.6975
\]

You can specify multiple inputs and outputs to \texttt{gather} if you want to evaluate several things at once. Doing so is faster than calling \texttt{gather} separately on each tall array. For example, calculate the minimum and maximum arrival delay.

\[
[\text{max_delay}, \text{min_delay}] = \text{gather}([\text{max}(a), \text{min}(a)])
\]

Evaluating tall expression using the Spark Cluster:
- Pass 1 of 1: Completed in 1 sec
Evaluation completed in 1 sec

\[
\text{max_delay} = \\
1014
\]

\[
\text{min_delay} = \\
-64
\]

\textbf{Note} These examples take more time to complete the first time if MATLAB is starting on the cluster workers.

When using tall arrays on a Spark enabled Hadoop cluster, compute resources from the Hadoop cluster will be reserved for the lifetime of the mapreducer execution environment. To clear these resources, you must delete the mapreducer:
delete(gcmr);

Alternatively, you can change to a different execution environment, for example:
mapreducer(0);

See Also
datastore | gather | mapreducer | parallel.cluster.Hadoop | table | tall

Related Examples
- “Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
- “Use Tall Arrays on a Parallel Pool” on page 6-70
- “Configure a Hadoop Cluster” (MATLAB Distributed Computing Server)
- “Tall Arrays” (MATLAB)
- “Read and Analyze Hadoop Sequence File” (MATLAB)

More About
- “Datastore” (MATLAB)
Run mapreduce on a Parallel Pool

Start Parallel Pool

If you have Parallel Computing Toolbox installed, execution of `mapreduce` can open a parallel pool on the cluster specified by your default profile, for use as the execution environment.

You can set your parallel preferences so that a pool does not automatically open. In this case, you must explicitly start a pool if you want `mapreduce` to use it for parallelization of its work. See “Specify Your Parallel Preferences” on page 6-12.

For example, the following conceptual code starts a pool, and some time later uses that open pool for the `mapreducer` configuration.

```matlab
p = parpool('local',n);
mr = mapreducer(p);
outds = mapreduce(tds,@MeanDistMapFun,@MeanDistReduceFun,mr)
```

**Note** `mapreduce` can run on any cluster that supports parallel pools. The examples in this topic use a local cluster, which works for all Parallel Computing Toolbox installations.

Compare Parallel mapreduce

The following example calculates the mean arrival delay from a datastore of airline data. First it runs `mapreduce` in the MATLAB client session, then it runs in parallel on a local cluster. The `mapreducer` function explicitly controls the execution environment.

Begin by starting a parallel pool on a local cluster.

```matlab
p = parpool('local',4);
```

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.
Create two MapReducer objects for specifying the different execution environments for mapreduce.

```
inMatlab = mapreducer(0);
inPool = mapreducer(p);
```

Create and preview the datastore. The data set used in this example is available in `matlabroot/toolbox/matlab/demos`.

```
ds = datastore('airlinesmall.csv','TreatAsMissing','NA',...    'SelectedVariableNames','ArrDelay','ReadSize',1000);    preview(ds)
```

```
ArrDelay
____
 8
 8
21
 4
 3
 4
 3
11
```

Next, run the `mapreduce` calculation in the MATLAB client session. The map and reduce functions are available in `matlabroot/toolbox/matlab/demos`.

```
meanDelay = mapreduce(ds,@meanArrivalDelayMapper,@meanArrivalDelayReducer,inMatlab);
```

```
*******************************
*      MAPREDUCE PROGRESS      *
*******************************
Map   0% Reduce   0%
Map   10% Reduce  0%
Map   20% Reduce  0%
Map   30% Reduce  0%
Map   40% Reduce  0%
Map   50% Reduce  0%
Map   60% Reduce  0%
Map   70% Reduce  0%
Map   80% Reduce  0%
Map   90% Reduce  0%
Map  100% Reduce 100%
```
readall(meanDelay)

<table>
<thead>
<tr>
<th>Key</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>'MeanArrivalDelay'</td>
<td>[7.1201]</td>
</tr>
</tbody>
</table>

Then, run the calculation on the current parallel pool. Note that the output text indicates a parallel mapreduce.

```matlab
meanDelay = mapreduce(ds,@meanArrivalDelayMapper,@meanArrivalDelayReducer,inPool);
```

Parallel mapreduce execution on the parallel pool:
```
********************************
*      MAPREDUCE PROGRESS      *
********************************
Map 0% Reduce 0%
Map 100% Reduce 50%
Map 100% Reduce 100%
```

readall(meanDelay)

<table>
<thead>
<tr>
<th>Key</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>'MeanArrivalDelay'</td>
<td>[7.1201]</td>
</tr>
</tbody>
</table>

With this relatively small data set, a performance improvement with the parallel pool is not likely. This example is to show the mechanism for running mapreduce on a parallel pool. As the data set grows, or the map and reduce functions themselves become more computationally intensive, you might expect to see improved performance with the parallel pool, compared to running mapreduce in the MATLAB client session.

**Note** When running parallel mapreduce on a cluster, the order of the key-value pairs in the output is different compared to running mapreduce in MATLAB. If your application depends on the arrangement of data in the output, you must sort the data according to your own requirements.

**See Also**

**Functions**
datastore | mapreduce | mapreducer
Related Examples

• “Getting Started with MapReduce” (MATLAB)
• “Run mapreduce on a Hadoop Cluster” on page 6-82

More About

• “MapReduce” (MATLAB)
• “Datastore” (MATLAB)
Run mapreduce on a Hadoop Cluster

Cluster Preparation

Before you can run mapreduce on a Hadoop cluster, make sure that the cluster and client machine are properly configured. Consult your system administrator, or see “Configure a Hadoop Cluster” (MATLAB Distributed Computing Server).

Output Format and Order

When running mapreduce on a Hadoop cluster with binary output (the default), the resulting KeyValueDatastore points to Hadoop Sequence files, instead of binary MAT-files as generated by mapreduce in other environments. For more information, see the 'OutputType' argument description on the mapreduce reference page.

When running mapreduce on a Hadoop cluster, the order of the key-value pairs in the output is different compared to running mapreduce in other environments. If your application depends on the arrangement of data in the output, you must sort the data according to your own requirements.

Calculate Mean Delay

This example shows how to modify the MATLAB example for calculating mean airline delays to run on a Hadoop cluster.

First, you must set environment variables and cluster properties as appropriate for your specific Hadoop configuration. See your system administrator for the values for these and other properties necessary for submitting jobs to your cluster.

```matlab
setenv('HADOOP_HOME', '/path/to/hadoop/install')
cluster = parallel.cluster.Hadoop;
```
Note The specified outputFolder must not already exist. The mapreduce output from a Hadoop cluster cannot overwrite an existing folder.

You will lose your data, if mapreducer is changed or deleted.

Create a MapReducer object to specify that mapreduce should use your Hadoop cluster.

```matlab
mr = mapreducer(cluster);
```

Create and preview the datastore. The data set is available in `matlabroot/toolbox/matlab/demos`.

```matlab
ds = datastore('airlinesmall.csv','TreatAsMissing','NA',... 'SelectedVariableNames','ArrDelay','ReadSize',1000);
preview(ds)
```

```
ArrDelay
     _____
    8
    8
   21
   13
    4
   59
    3
   11
```

Next, specify your output folder, output outds and call mapreduce to execute on the Hadoop cluster specified by `mr`. The map and reduce functions are available in `matlabroot/toolbox/matlab/demos`.

```matlab
outputFolder = 'hdfs:///home/myuser/out1';
outds = mapreduce(ds,@myMapperFcn,@myReducerFcn,'OutputFolder',outputFolder);
meanDelay = mapreduce(ds,@meanArrivalDelayMapper,@meanArrivalDelayReducer,mr,... 'OutputFolder',outputFolder)
```

Parallel mapreduce execution on the Hadoop cluster:

```
                         ******************
                        *    MAPREDUCE PROGRESS    *
                         ******************
Map  0% Reduce  0%
Map  66% Reduce  0%
```
Map 100% Reduce 66%
Map 100% Reduce 100%

meanDelay =

KeyValueDatastore with properties:

Files: {
    './tmp/alafleur/tpc00621b1_4eeef_4abc_8078_646aa916e7d9/part0.seq'
}
ReadSize: 1 key-value pairs
FileType: 'seq'

Read the result.

readall(meanDelay)

<table>
<thead>
<tr>
<th>Key</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>'MeanArrivalDelay'</td>
<td>[7.1201]</td>
</tr>
</tbody>
</table>

Although for demonstration purposes this example uses a local data set, it is likely when using Hadoop that your data set is stored in an HDFS™ file system. Likewise, you might be required to store the mapreduce output in HDFS. For details about accessing HDFS in MATLAB, see “Read Remote Data” (MATLAB).

See Also

Functions
datastore | mapreduce | mapreducer | parallel.cluster.Hadoop

Related Examples

• “Getting Started with MapReduce” (MATLAB)
• “Run mapreduce on a Parallel Pool” on page 6-78

More About

• “MapReduce” (MATLAB)
• “Datastore” (MATLAB)
Partition a Datastore in Parallel

Partitioning a datastore in parallel, with a portion of the datastore on each worker in a parallel pool, can provide benefits in many cases:

- Perform some action on only one part of the whole datastore, or on several defined parts simultaneously.
- Search for specific values in the data store, with all workers acting simultaneously on their own partitions.
- Perform a reduction calculation on the workers across all partitions.

This example shows how to use partition to parallelize the reading of data from a datastore. It uses a small datastore of airline data provided in MATLAB, and finds the mean of the non-NaN values from its 'ArrDelay' column.

A simple way to calculate the mean is to divide the sum of all the non-NaN values by the number of non-NaN values. The following code does this for the datastore first in a non-parallel way. To begin, you define a function to amass the count and sum. If you want to run this example, copy and save this function in a folder on the MATLAB command search path.

```matlab
function [total,count] = sumAndCountArrivalDelay(ds)
    total = 0;
    count = 0;
    while hasdata(ds)
        data = read(ds);
        total = total + sum(data.ArrDelay,1,'OmitNaN');
        count = count + sum(~isnan(data.ArrDelay));
    end
end
```

The following code creates a datastore, calls the function, and calculates the mean without any parallel execution. The tic and toc functions are used to time the execution, here and in the later parallel cases.

```matlab
ds = datastore(repmat({'airlinesmall.csv'},20,1),'TreatAsMissing','NA');
ds.SelectedVariableNames = 'ArrDelay';
```
reset(ds);
tic
    [total,count] = sumAndCountArrivalDelay(ds)
sumtime = toc
mean = total/count

total =
    17211680

count =
    2417320

sumtime =
    12.2815

mean =
    7.1201

The partition function allows you to partition the datastore into smaller parts, each represented as a datastore itself. These smaller datastores work completely independently of each other, so that you can work with them inside of parallel language features such as parfor loops and spmd blocks.

The number of partitions in the following code is set by the numpartitions function, based on the datastore itself (ds) and the parallel pool (gcp) size. This does not necessarily equal the number of workers in the pool. In this case, the number of loop iterations is then set to the number of partitions (N).

The following code starts a parallel pool on a local cluster, then partitions the datastore among workers for iterating over the loop. Again, a separate function is called, which includes the parfor loop to amass the count and sum totals. Copy and save this function if you want to run the example.
function [total, count] = parforSumAndCountArrivalDelay(ds)

N = numpartitions(ds,gcp);
total = 0;
count = 0;
parfor ii = 1:N
    % Get partition ii of the datastore.
    subds = partition(ds,N,ii);
    [localTotal,localCount] = sumAndCountArrivalDelay(subds);
total = total + localTotal;
count = count + localCount;
end
end

Now the MATLAB code calls this new function, so that the counting and summing of the non-NAN values can occur in parallel loop iterations.

p = parpool('local',4);
reset(ds);
tic
    [total, count] = parforSumAndCountArrivalDelay(ds)
parfortime = toc
mean = total/count

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.

total =

    17211680

count =

    2417320

parfortime =
Rather than let the software calculate the number of partitions, you can explicitly set this value, so that the data can be appropriately partitioned to fit your algorithm. For example, to parallelize data from within an `spmd` block, you can specify the number of workers (`numlabs`) as the number of partitions to use. The following function uses an `spmd` block to perform a parallel read, and explicitly sets the number of partitions equal to the number of workers. To run this example, copy and save the function.

```matlab
% Copyright 2015 The MathWorks, Inc.
function [total,count] = spmdSumAndCountArrivalDelay(ds)
    spmd
        subds = partition(ds,numlabs,labindex);
        [total,count] = sumAndCountArrivalDelay(subds);
    end
    total = sum([total{:}]);
    count = sum([count{:}]);
end

Now the MATLAB code calls the function that uses an `spmd` block.

```matlab
reset(ds);
tic
    [total,count] = spmdSumAndCountArrivalDelay(ds)
spmdtime = toc
mean = total/count
```

```
total =
    17211680
```

```
6.6485

mean =

7.1201
```
count =
2417320

spmdtime =
6.5906

mean =
7.1201

delete(p);
Parallel pool using the 'local' profile is shutting down.

You might get some idea of modest performance improvements by comparing the times recorded in the variables sumtime, parfortime, and spmdtime. Your results might vary, as the performance can be affected by the datastore size, parallel pool size, hardware configuration, and other factors.
Program Independent Jobs

- “Program Independent Jobs” on page 7-2
- “Program Independent Jobs on a Local Cluster” on page 7-3
- “Program Independent Jobs for a Supported Scheduler” on page 7-8
- “Share Code with the Workers” on page 7-17
- “Program Independent Jobs for a Generic Scheduler” on page 7-22
Program Independent Jobs

The tasks in an independent job do not directly communicate with each other and are independent. The tasks do not need to run simultaneously, and a worker can run several tasks of the same job in succession. Typically, all tasks perform the same or similar functions on different data sets in an *embarrassingly parallel* configuration.

Some of the details of a job and its tasks can depend on the type of scheduler you are using:

- “Program Independent Jobs on a Local Cluster” on page 7-3
- “Program Independent Jobs for a Supported Scheduler” on page 7-8
- “Program Independent Jobs for a Generic Scheduler” on page 7-22
Program Independent Jobs on a Local Cluster

Create and Run Jobs with a Local Cluster

Some jobs require more control than the functionality offered by high-level constructs like spmd and parfor. In such cases, you have to program all the steps for creating and running the job. Using the local cluster (or local scheduler) on your machine lets you create and test your jobs without using the resources of your network cluster. Distributing tasks to workers that are all running on your client machine do not offer any performance enhancement. Therefore this feature is provided primarily for code development, testing, and debugging.

Note Workers running in a local cluster on a Microsoft Windows operating system can display Simulink graphics and the output from certain functions such as uigetfile and uigetdir. (With other platforms or schedulers, workers cannot display any graphical output.) This behavior is subject to removal in a future release.

This section details the steps of a typical programming session with Parallel Computing Toolbox software using a local cluster:

- “Create a Cluster Object” on page 7-4
- “Create a Job” on page 7-4
- “Create Tasks” on page 7-5
- “Submit a Job to the Cluster” on page 7-5
- “Fetch the Job Results” on page 7-6

The objects used by the client session to interact with the cluster are only references to data in the cluster job storage location, not in the client session. After jobs and tasks are created, you can close your client session and restart it, and your job still resides in the storage location. You can find existing jobs using the findJob function or the Jobs property of the cluster object.
**Create a Cluster Object**

You use the `parcluster` function to create an object in your local MATLAB session representing the local scheduler.

```matlab
parallel.defaultClusterProfile('local');
c = parcluster();
```

**Create a Job**

You create a job with the `createJob` function. This statement creates a job in the cluster job storage location and creates the job object `job1` in the client session. If you omit the semicolon at the end of the command, it displays some information about the job.

```matlab
job1 = createJob(c)
```

Job

Properties:

- **ID**: 2
- **Type**: Independent
- **Username**: eng864
- **State**: pending
- **SubmitTime**: 
- **StartTime**: 
- **Running Duration**: 0 days 0h 0m 0s
- **AutoAttachFiles**: true
- **Auto Attached Files**: List files
- **AttachedFiles**: {}
- **AdditionalPaths**: {}

Associated Tasks:

- **Number Pending**: 0
- **Number Running**: 0
- **Number Finished**: 0
- **Task ID of Errors**: []

The `State` property of the job is `pending`. This means that the job has not yet been submitted (queued) for running, so you can now add tasks to it.

The scheduler display now indicates the existence of your job, which is the pending one, as appears in this partial listing:
Create Tasks

After you have created your job, you can create tasks for the job using the createTask function. Tasks define the functions to be evaluated by the workers during the running of the job. Often, the tasks of a job are all identical. In this example, five tasks each generate a 3-by-3 matrix of random numbers.

createTask(job1, @rand, 1, {{3,3} {3,3} {3,3} {3,3} {3,3}});

The Tasks property of job1 is now a 5-by-1 matrix of task objects.

job1.Tasks

<table>
<thead>
<tr>
<th>ID</th>
<th>State</th>
<th>FinishTime</th>
<th>Function</th>
<th>Error</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
</tbody>
</table>

Submit a Job to the Cluster

To run your job and have its tasks evaluated, you submit the job to the cluster with the submit function.

submit(job1)

The local scheduler starts the workers on your machine, and distributes the tasks of job1 to these workers for evaluation.
Fetch the Job Results

The results of each task evaluation are stored in the task object `OutputArguments` property as a cell array. After waiting for the job to complete, use the function `fetchOutputs` to retrieve the results from all the tasks in the job.

```matlab
wait(job1)
results = fetchOutputs(job1);
```

Display the results from each task.

```matlab
results{1:5}
```

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0.9501</td>
<td>0.4860</td>
<td>0.4565</td>
</tr>
<tr>
<td>0.2311</td>
<td>0.8913</td>
<td>0.0185</td>
</tr>
<tr>
<td>0.6068</td>
<td>0.7621</td>
<td>0.8214</td>
</tr>
<tr>
<td>0.4447</td>
<td>0.9218</td>
<td>0.4057</td>
</tr>
<tr>
<td>0.6154</td>
<td>0.7382</td>
<td>0.9355</td>
</tr>
<tr>
<td>0.7919</td>
<td>0.1763</td>
<td>0.9169</td>
</tr>
<tr>
<td>0.4103</td>
<td>0.3529</td>
<td>0.1389</td>
</tr>
<tr>
<td>0.8936</td>
<td>0.8132</td>
<td>0.2028</td>
</tr>
<tr>
<td>0.0579</td>
<td>0.0099</td>
<td>0.1987</td>
</tr>
<tr>
<td>0.6038</td>
<td>0.0153</td>
<td>0.9318</td>
</tr>
<tr>
<td>0.2722</td>
<td>0.7468</td>
<td>0.4660</td>
</tr>
<tr>
<td>0.1988</td>
<td>0.4451</td>
<td>0.4186</td>
</tr>
<tr>
<td>0.8462</td>
<td>0.6721</td>
<td>0.6813</td>
</tr>
<tr>
<td>0.5252</td>
<td>0.8381</td>
<td>0.3795</td>
</tr>
<tr>
<td>0.2026</td>
<td>0.0196</td>
<td>0.8318</td>
</tr>
</tbody>
</table>

After the job is complete, you can repeat the commands to examine the updated status of the cluster, job, and task objects:

```matlab
c
job1
job1.Tasks
```

Local Cluster Behavior

The local scheduler runs in the MATLAB client session, so you do not have to start any separate scheduler or MJS process for the local scheduler. When you submit a job to the
local cluster, the scheduler starts a MATLAB worker for each task in the job. You can do this for as many workers as allowed by the local profile. If your job has more tasks than allowed workers, the scheduler waits for one of the current tasks to complete before starting another MATLAB worker to evaluate the next task. You can modify the number of allowed workers in the local cluster profile. If not specified, the default is to run only as many workers as computational cores on the machine.

The local cluster has no interaction with any other scheduler or MJS, nor with any other workers that can also be running on your client machine under the mdc service. Multiple MATLAB sessions on your computer can each start its own local scheduler with its own workers, but these groups do not interact with each other.

When you end your MATLAB client session, its local scheduler and any workers that happen to be running also stop immediately.
Program Independent Jobs for a Supported Scheduler

In this section...

“Create and Run Jobs” on page 7-8
“Manage Objects in the Scheduler” on page 7-13

Create and Run Jobs

This section details the steps of a typical programming session with Parallel Computing Toolbox software using a supported job scheduler on a cluster. Supported schedulers include the MATLAB job scheduler (MJS), Platform LSF (Load Sharing Facility), Microsoft Windows HPC Server (including CCS), PBS Pro, or a TORQUE scheduler.

This section assumes that you have an MJS, LSF, PBS Pro, TORQUE, or Windows HPC Server (including CCS and HPC Server 2008) scheduler installed and running on your network. For more information about LSF, see http://www.platform.com/Products/. For more information about Windows HPC Server, see http://www.microsoft.com/hpc/. With all of these cluster types, the basic job programming sequence is the same:

- “Define and Select a Profile” on page 7-8
- “Find a Cluster” on page 7-9
- “Create a Job” on page 7-10
- “Create Tasks” on page 7-11
- “Submit a Job to the Job Queue” on page 7-12
- “Retrieve Job Results” on page 7-13

Note that the objects that the client session uses to interact with the MJS are only references to data that is actually contained in the MJS, not in the client session. After jobs and tasks are created, you can close your client session and restart it, and your job is still stored in the MJS. You can find existing jobs using the findJob function or the Jobs property of the MJS cluster object.

Define and Select a Profile

A cluster profile identifies the type of cluster to use and its specific properties. In a profile, you define how many workers a job can access, where the job data is stored,
where MATLAB is accessed and many other cluster properties. The exact properties are
determined by the type of cluster.

The step in this section all assume the profile with the name MyProfile identifies the
cluster you want to use, with all necessary property settings. With the proper use of a
profile, the rest of the programming is the same, regardless of cluster type. After you
define or import your profile, you can set it as the default profile in the Profile Manager
GUI, or with the command:

```matlab
parallel.defaultClusterProfile('MyProfile')
```

A few notes regarding different cluster types and their properties:

**Notes** In a shared file system, all nodes require access to the folder specified in the
cluster object's `JobStorageLocation` property.

Because Windows HPC Server requires a shared file system, all nodes require access to
the folder specified in the cluster object's `JobStorageLocation` property.

In a shared file system, MATLAB clients on many computers can access the same job
data on the network. Properties of a particular job or task should be set from only one
client computer at a time.

When you use an LSF scheduler in a nonshared file system, the scheduler might report
that a job is in the finished state even though the LSF scheduler might not yet have
completed transferring the job’s files.

**Find a Cluster**

You use the `parcluster` function to identify a cluster and to create an object
representing the cluster in your local MATLAB session.

To find a specific cluster, user the cluster profile to match the properties of the cluster
you want to use. In this example, `MyProfile` is the name of the profile that defines the
specific cluster.

```matlab
c = parcluster('MyProfile');
```

MJS Cluster

Properties

Name: my_mjs
Create a Job

You create a job with the `createJob` function. Although this command executes in the client session, it actually creates the job on the cluster, `c`, and creates a job object, `job1`, in the client session.

```matlab
job1 = createJob(c)
```

**Job**

**Properties:**

- **ID:** 1
- **Type:** Independent
- **Username:** mylogin
- **State:** pending
- **SubmitTime:**
- **StartTime:**
- **Running Duration:** 0 days 0h 0m 0s

- **AutoAttachFiles:** true
- **Auto Attached Files:** List files
- **AttachedFiles:** {}

**Associated Tasks:**
Note that the job’s State property is pending. This means the job has not been queued for running yet, so you can now add tasks to it.

The cluster’s display now includes one pending job, as shown in this partial listing:

c

c

You can transfer files to the worker by using the AttachedFiles property of the job object. For details, see “Share Code with the Workers” on page 7-17.

**Create Tasks**

After you have created your job, you can create tasks for the job using the `createTask` function. Tasks define the functions to be evaluated by the workers during the running of the job. Often, the tasks of a job are all identical. In this example, each task will generate a 3-by-3 matrix of random numbers.

```matlab
createTask(job1, @rand, 1, {3,3});
createTask(job1, @rand, 1, {3,3});
createTask(job1, @rand, 1, {3,3});
createTask(job1, @rand, 1, {3,3});
createTask(job1, @rand, 1, {3,3});
```

The Tasks property of `job1` is now a 5-by-1 matrix of task objects.

```
job1.Tasks

<table>
<thead>
<tr>
<th>ID</th>
<th>State</th>
<th>FinishTime</th>
<th>Function</th>
<th>Error</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>pending</td>
<td></td>
<td>@rand</td>
<td></td>
</tr>
</tbody>
</table>
```
Alternatively, you can create the five tasks with one call to `createTask` by providing a cell array of five cell arrays defining the input arguments to each task.

```
T = createTask(job1, @rand, 1, {{3,3} {3,3} {3,3} {3,3} {3,3}});
```

In this case, T is a 5-by-1 matrix of task objects.

**Submit a Job to the Job Queue**

To run your job and have its tasks evaluated, you submit the job to the job queue with the `submit` function.

```
submit(job1)
```

The job manager distributes the tasks of `job1` to its registered workers for evaluation.

Each worker performs the following steps for task evaluation:

1. Receive `AttachedFiles` and `AdditionalPaths` from the job. Place files and modify the path accordingly.
2. Run the `jobStartup` function the first time evaluating a task for this job. You can specify this function in `AttachedFiles` or `AdditionalPaths`. When using an MJS, if the same worker evaluates subsequent tasks for this job, `jobStartup` does not run between tasks.
3. Run the `taskStartup` function. You can specify this function in `AttachedFiles` or `AdditionalPaths`. This runs before every task evaluation that the worker performs, so it could occur multiple times on a worker for each job.
4. If the worker is part of forming a new parallel pool, run the `poolStartup` function. (This occurs when executing `parpool` or when running other types of jobs that form and use a parallel pool, such as `batch`.)
5. Receive the task function and arguments for evaluation.
6. Evaluate the task function, placing the result in the task’s `OutputArguments` property. Any error information goes in the task’s `Error` property.
7. Run the `taskFinish` function.
Retrieve Job Results

The results of each task's evaluation are stored in that task object's `OutputArguments` property as a cell array. Use the function `fetchOutputs` to retrieve the results from all the tasks in the job.

```matlab
wait(job1)
results = fetchOutputs(job1);
```

Display the results from each task.

```matlab
results{1:5}
0.9501 0.4860 0.4565
0.2311 0.8913 0.0185
0.6068 0.7621 0.8214
0.4447 0.9218 0.4057
0.6154 0.7382 0.9355
```

Manage Objects in the Scheduler

Because all the data of jobs and tasks resides in the cluster job storage location, these objects continue to exist even if the client session that created them has ended. The following sections describe how to access these objects and how to permanently remove them:

- “What Happens When the Client Session Ends” on page 7-14
- “Recover Objects” on page 7-14
What Happens When the Client Session Ends

When you close the client session of Parallel Computing Toolbox software, all of the objects in the workspace are cleared. However, the objects in MATLAB Distributed Computing Server software or other cluster resources remain in place. When the client session ends, only the local reference objects are lost, not the actual job and task data in the cluster.

Therefore, if you have submitted your job to the cluster job queue for execution, you can quit your client session of MATLAB, and the job will be executed by the cluster. You can retrieve the job results later in another client session.

Recover Objects

A client session of Parallel Computing Toolbox software can access any of the objects in MATLAB Distributed Computing Server software, whether the current client session or another client session created these objects.

You create cluster objects in the client session by using the `parcluster` function.

\[ c = \text{parcluster}('MyProfile'); \]

When you have access to the cluster by the object \( c \), you can create objects that reference all those job contained in that cluster. The jobs are accessible in cluster object's `Jobs` property, which is an array of job objects:

\[ \text{all\_jobs} = c.\text{Jobs} \]

You can index through the array `all_jobs` to locate a specific job.

Alternatively, you can use the `findJob` function to search in a cluster for any jobs or a particular job identified by any of its properties, such as its `State`.

\[ \text{all\_jobs} = \text{findJob}(c); \]
\[ \text{finished\_jobs} = \text{findJob}(c, '\text{State}', '\text{finished}') \]

This command returns an array of job objects that reference all finished jobs on the cluster \( c \).
Reset Callback Properties (MJS Only)

When restarting a client session, you lose the settings of any callback properties (for example, the `FinishedFcn` property) on jobs or tasks. These properties are commonly used to get notifications in the client session of state changes in their objects. When you create objects in a new client session that reference existing jobs or tasks, you must reset these callback properties if you intend to use them.

Remove Objects Permanently

Jobs in the cluster continue to exist even after they are finished, and after the MJS is stopped and restarted. The ways to permanently remove jobs from the cluster are explained in the following sections:

- “Delete Selected Objects” on page 7-15
- “Start an MJS from a Clean State” on page 7-15

Delete Selected Objects

From the command line in the MATLAB client session, you can call the `delete` function for any job or task object. If you delete a job, you also remove all tasks contained in that job.

For example, find and delete all finished jobs in your cluster that belong to the user `joep`.

```matlab
c = parcluster('MyProfile')
finished_jobs = findJob(c,'State','finished','Username','joep')
delete(finished_jobs)
clear finished_jobs
```

The `delete` function permanently removes these jobs from the cluster. The `clear` function removes the object references from the local MATLAB workspace.

Start an MJS from a Clean State

When an MJS starts, by default it starts so that it resumes its former session with all jobs intact. Alternatively, an MJS can start from a clean state with all its former history deleted. Starting from a clean state permanently removes all job and task data from the MJS of the specified name on a particular host.
As a network administration feature, the -clean flag of the startjobmanager script is described in “Start in a Clean State” (MATLAB Distributed Computing Server) in the MATLAB Distributed Computing Server System Administrator's Guide.
Share Code with the Workers

Because the tasks of a job are evaluated on different machines, each machine must have access to all the files needed to evaluate its tasks. The basic mechanisms for sharing code are explained in the following sections:

<table>
<thead>
<tr>
<th>In this section...</th>
</tr>
</thead>
<tbody>
<tr>
<td>“Workers Access Files Directly” on page 7-17</td>
</tr>
<tr>
<td>“Pass Data to and from Worker Sessions” on page 7-18</td>
</tr>
<tr>
<td>“Pass MATLAB Code for Startup and Finish” on page 7-20</td>
</tr>
</tbody>
</table>

Workers Access Files Directly

If the workers all have access to the same drives on the network, they can access the necessary files that reside on these shared resources. This is the preferred method for sharing data, as it minimizes network traffic.

You must define each worker session’s search path so that it looks for files in the right places. You can define the path:

- **By using the job’s** `AdditionalPaths` **property.** This is the preferred method for setting the path, because it is specific to the job.

  `AdditionalPaths` identifies folders to be added to the top of the command search path of worker sessions for this job. If you also specify `AttachedFiles`, the `AttachedFiles` are above `AdditionalPaths` on the workers’ path.

  **When you specify** `AdditionalPaths` **at the time of creating a job,** the settings are combined with those specified in the applicable cluster profile. Setting `AdditionalPaths` on a job object after it is created does not combine the new setting with the profile settings, but overwrites existing settings for that job.

  `AdditionalPaths` is empty by default. For a mixed-platform environment, the character vectors can specify both UNIX and Microsoft Windows style paths; those setting that are not appropriate or not found for a particular machine generate warnings and are ignored.
This example sets the MATLAB worker path in a mixed-platform environment to use functions in both the central repository /central/funcs and the department archive /dept1/funcs, which each also have a Windows UNC path.

```matlab
c = parcluster(); % Use default
job1 = createJob(c);
ap = {'/central/funcs','/dept1/funcs', ...
      '\OurDomain\central\funcs','\OurDomain\dept1\funcs'};
job1.AdditionalPaths = ap;
```

- By putting the path command in any of the appropriate startup files for the worker:
  - `matlabroot\toolbox\local\startup.m`
  - `matlabroot\toolbox\distcomp\user\jobStartup.m`
  - `matlabroot\toolbox\distcomp\user\taskStartup.m`

Access to these files can be passed to the worker by the job’s `AttachedFiles` or `AdditionalPaths` property. Otherwise, the version of each of these files that is used is the one highest on the worker’s path.

Access to files among shared resources can depend upon permissions based on the user name. You can set the user name with which the MJS and worker services of MATLAB Distributed Computing Server software run by setting the `MDCEUSER` value in the `mdce_def` file before starting the services. For Microsoft Windows operating systems, there is also `MDCEPASS` for providing the account password for the specified user. For an explanation of service default settings and the `mdce_def` file, see “Define Script Defaults” (MATLAB Distributed Computing Server) in the MATLAB Distributed Computing Server System Administrator's Guide.

### Pass Data to and from Worker Sessions

A number of properties on task and job objects are designed for passing code or data from client to scheduler to worker, and back. This information could include MATLAB code necessary for task evaluation, or the input data for processing or output data resulting from task evaluation. The following properties facilitate this communication:

- **InputArguments** — This property of each task contains the input data you specified when creating the task. This data gets passed into the function when the worker performs its evaluation.
- **OutputArguments** — This property of each task contains the results of the function’s evaluation.
• **JobData** — This property of the job object contains data that gets sent to every worker that evaluates tasks for that job. This property works efficiently because the data is passed to a worker only once per job, saving time if that worker is evaluating more than one task for the job. (Note: Do not confuse this property with the **UserData** property on any objects in the MATLAB client. Information in **UserData** is available only in the client, and is not available to the scheduler or workers.)

• **AttachedFiles** — This property of the job object is a cell array in which you manually specify all the folders and files that get sent to the workers. On the worker, the files are installed and the entries specified in the property are added to the search path of the worker session.

**AttachedFiles** contains a list of folders and files that the worker need to access for evaluating a job’s tasks. The value of the property (empty by default) is defined in the cluster profile or in the client session. You set the value for the property as a cell array of character vectors. Each character vector is an absolute or relative pathname to a folder or file. (Note: If these files or folders change while they are being transferred, or if any of the folders are empty, a failure or error can result. If you specify a pathname that does not exist, an error is generated.)

The first time a worker evaluates a task for a particular job, the scheduler passes to the worker the files and folders in the **AttachedFiles** property. On the worker machine, a folder structure is created that is exactly the same as that accessed on the client machine where the property was set. Those entries listed in the property value are added to the top of the command search path in the worker session. (Subfolders of the entries are not added to the path, even though they are included in the folder structure.) To find out where the files are placed on the worker machine, use the function `getAttachedFilesFolder` in code that runs on the worker.

When the worker runs subsequent tasks for the same job, it uses the folder structure already set up by the job’s **AttachedFiles** property for the first task it ran for that job.

When you specify **AttachedFiles** at the time of creating a job, the settings are combined with those specified in the applicable profile. Setting **AttachedFiles** on a job object after it is created does not combine the new setting with the profile settings, but overwrites the existing settings for that job.

The **transfer** of **AttachedFiles** occurs for each worker running a task for that particular job on a machine, regardless of how many workers run on that machine.
Normally, the attached files are deleted from the worker machine when the job is completed, or when the next job begins.

- **AutoAttachFiles** — This property of the job object uses a logical value to specify that you want MATLAB to perform an analysis on the task functions in the job and on manually attached files to determine which code files are necessary for the workers, and to automatically send those files to the workers. You can set this property value in a cluster profile using the Profile Manager, or you can set it programmatically on a job object at the command line.

```matlab
c = parcluster();
j = createJob(c);
j.AutoAttachFiles = true;
```

The supported code file formats for automatic attachment are MATLAB files (.m extension), P-code files (.p), and MEX-files (.mex). Note that **AutoAttachFiles** does not include data files for your job; use the **AttachedFiles** property to explicitly transfer these files to the workers.

Use **listAutoAttachedFiles** to get a listing of the code files that are automatically attached to a job.

If the **AutoAttachFiles** setting is `true` for the cluster profile used when starting a parallel pool, MATLAB performs an analysis on `spmd` blocks, `parfor`-loops, and other attached files to determine what other code files are necessary for execution, then automatically attaches those files to the parallel pool so that the code is available to the workers.

**Note** There is a default maximum amount of data that can be sent in a single call for setting properties. This limit applies to the **OutputArguments** property as well as to data passed into a job as input arguments or **AttachedFiles**. If the limit is exceeded, you get an error message. For more information about this data transfer size limit, see “Attached Files Size Limitations” on page 6-62.

### Pass MATLAB Code for Startup and Finish

As a session of MATLAB, a worker session executes its `startup.m` file each time it starts. You can place the `startup.m` file in any folder on the worker’s MATLAB search path, such as `toolbox/distcomp/user`. 
These additional files can initialize and clean up a worker session as it begins or completes evaluations of tasks for a job:

- **jobStartup.m** automatically executes on a worker when the worker runs its first task of a job.
- **taskStartup.m** automatically executes on a worker each time the worker begins evaluation of a task.
- **poolStartup.m** automatically executes on a worker each time the worker is included in a newly started parallel pool.
- **taskFinish.m** automatically executes on a worker each time the worker completes evaluation of a task.

Empty versions of these files are provided in the folder:

```
matlabroot/toolbox/distcomp/user
```

You can edit these files to include whatever MATLAB code you want the worker to execute at the indicated times.

Alternatively, you can create your own versions of these files and pass them to the job as part of the `AttachedFiles` property, or include the path names to their locations in the `AdditionalPaths` property.

The worker gives precedence to the versions provided in the `AttachedFiles` property, then to those pointed to in the `AdditionalPaths` property. If any of these files is not included in these properties, the worker uses the version of the file in the `toolbox/distcomp/user` folder of the worker’s MATLAB installation.
Program Independent Jobs for a Generic Scheduler

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<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
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<td></td>
</tr>
<tr>
<td>“MATLAB Client Submit Function” on page 7-23</td>
<td></td>
</tr>
<tr>
<td>“Example — Write the Submit Function” on page 7-26</td>
<td></td>
</tr>
<tr>
<td>“MATLAB Worker Decode Function” on page 7-28</td>
<td></td>
</tr>
<tr>
<td>“Example — Write the Decode Function” on page 7-30</td>
<td></td>
</tr>
<tr>
<td>“Example — Program and Run a Job in the Client” on page 7-31</td>
<td></td>
</tr>
<tr>
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</tr>
<tr>
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<td></td>
</tr>
<tr>
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<td></td>
</tr>
</tbody>
</table>

Overview

Parallel Computing Toolbox software provides a generic interface that lets you interact with third-party schedulers, or use your own scripts for distributing tasks to other nodes on the cluster for evaluation. For this purpose, you also need MATLAB Distributed Computing Server running on your cluster.

Because each job in your application is comprised of several tasks, the purpose of your scheduler is to allocate a cluster node for the evaluation of each task, or to distribute each task to a cluster node. The scheduler starts remote MATLAB worker sessions on the cluster nodes to evaluate individual tasks of the job. To evaluate its task, a MATLAB worker session needs access to certain information, such as where to find the job and task data. The generic scheduler interface provides a means of getting tasks from your Parallel Computing Toolbox client session to your scheduler and thereby to your cluster nodes.

To evaluate a task, a worker requires five parameters that you must pass from the client to the worker. The parameters can be passed any way you want to transfer them, but because a particular one must be an environment variable, the examples in this section pass all parameters as environment variables.
The workflow for programming independent jobs for a generic scheduler is as follows.

1. Write a MATLAB client submit function.
2. Write a MATLAB worker decode function.
3. Create a scheduler object, a job and a task.
4. Submit a job to the queue and retrieve the results.

Examine details of the workflow in the following section.

**Note** Whereas the MJS keeps MATLAB workers running between tasks, a third-party scheduler runs MATLAB workers for only as long as it takes each worker to evaluate its one task.

**MATLAB Client Submit Function**

When you submit an independent job to a cluster, the `independentSubmitFcn.m` function executes in the MATLAB client session. You must set the `IntegrationScriptsLocation` property to specify the folder containing the submit functions for this cluster. See “Example — Program and Run a Job in the Client” on page 7-31.

The submit function is called with three arguments, in the following order: cluster, job, and props. The declaration line of the function must be:

```matlab
function independentSubmitFcn(cluster, job, props)
```
You can use the `AdditionalProperties` property to pass additional information into the submit function. For example:

```matlab
c.AdditionalProperties.TimeLimit = 300;
c.AdditionalProperties.TestLocation = 'Plant30';
```

You can then write a submit function which checks for the existence of these properties and behaves accordingly:

```matlab
if isprop(cluster.AdditionalProperties, 'TimeLimit')
    time_limit = cluster.AdditionalProperties.TimeLimit;
    % Add code to appropriately handle this property for your particular scheduler
end
```

This submit function has three main purposes:

- To identify the decode function that MATLAB workers run when they start
- To make information about job and task data locations available to the workers via their decode function
- To instruct your scheduler how to start a MATLAB worker on the cluster for each task of your job

**Identify the Decode Function**

The client’s submit function and the worker’s decode function work together as a pair. Therefore, the submit function must identify its corresponding decode function. The submit function does this by setting the environment variable `MDCE_DECODE_FUNCTION`. The value of this variable is a character vector identifying the name of the decode function on the path of the MATLAB worker. Neither the decode function itself nor its
name can be passed to the worker in a job or task property; the file must already exist before the worker starts. For more information on the decode function, see “MATLAB Worker Decode Function” on page 7-28. Standard decode functions for independent and communicating jobs are provided with the product. If your submit functions make use of the definitions in these decode functions, you do not have to provide your own decode functions. For example, to use the standard decode function for independent jobs, in your submit function set `MDCE_DECODE_FUNCTION` to `'parallel.cluster.generic.independentDecodeFcn'`.

### Pass Job and Task Data

The third input argument (after cluster and job) to the submit function is the object with the properties listed in the following table.

You do not set the values of any of these properties. They are automatically set by the toolbox so that you can program your submit function to forward them to the worker nodes.

<table>
<thead>
<tr>
<th>Property Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>StorageConstructor</td>
<td>Character vector. Used internally to indicate that a file system is used to contain job and task data.</td>
</tr>
<tr>
<td>StorageLocation</td>
<td>Character vector. Derived from the cluster JobStorageLocation property.</td>
</tr>
<tr>
<td>JobLocation</td>
<td>Character vector. Indicates where this job’s data is stored.</td>
</tr>
<tr>
<td>TaskLocations</td>
<td>Cell array. Indicates where each task’s data is stored. Each element of this array is passed to a separate worker.</td>
</tr>
<tr>
<td>NumberOfTasks</td>
<td>Double. Indicates the number of tasks in the job. You do not need to pass this value to the worker, but you can use it within your submit function.</td>
</tr>
</tbody>
</table>

With these values passed into your submit function, the function can pass them to the worker nodes by any of several means. However, because the name of the decode function must be passed as an environment variable, the examples that follow pass all the other necessary property values also as environment variables.
The submit function writes the values of these object properties out to environment variables with the `setenv` function.

**Define Scheduler Command to Run MATLAB Workers**

The submit function must define the command necessary for your scheduler to start MATLAB workers. The actual command is specific to your scheduler and network configuration. The commands for some popular schedulers are listed in the following table. This table also indicates whether or not the scheduler automatically passes environment variables with its submission. If not, your command to the scheduler must accommodate these variables.

<table>
<thead>
<tr>
<th>Scheduler</th>
<th>Scheduler Command</th>
<th>Passes Environment Variables</th>
</tr>
</thead>
<tbody>
<tr>
<td>LSF</td>
<td><code>bsub</code></td>
<td>Yes, by default.</td>
</tr>
<tr>
<td>PBS</td>
<td><code>qsub</code></td>
<td>Command must specify which variables to pass.</td>
</tr>
<tr>
<td>Sun™ Grid Engine</td>
<td><code>qsub</code></td>
<td>Command must specify which variables to pass.</td>
</tr>
</tbody>
</table>

Your submit function might also use some of these properties and others when constructing and invoking your scheduler command. `cluster`, `job`, and `props` (so named only for this example) refer to the three arguments to the submit function.

<table>
<thead>
<tr>
<th>Argument Object</th>
<th>Property</th>
</tr>
</thead>
<tbody>
<tr>
<td>cluster</td>
<td>MatlabCommandToRun</td>
</tr>
<tr>
<td>cluster</td>
<td>ClusterMatlabRoot</td>
</tr>
<tr>
<td>job</td>
<td>NumWorkersRange</td>
</tr>
<tr>
<td>props</td>
<td>NumberOfTasks</td>
</tr>
</tbody>
</table>

**Example — Write the Submit Function**

The submit function in this example uses environment variables to pass the necessary information to the worker nodes. Each step below indicates the lines of code you add to your submit function.

1. Create the function declaration. Three objects are automatically passed into the submit function as input arguments: the cluster object, the job object, and the props object.
function independentSubmitFcn(cluster, job, props)

You can use the AdditionalProperties property to pass additional information into the submit function, as discussed in “MATLAB Client Submit Function” on page 7-23.

2 Identify the values you want to send to your environment variables. For convenience, you define local variables for use in this function.

    decodeFcn = 'mydecodefunc';
    jobLocation = get(props, 'JobLocation');
    taskLocations = get(props, 'TaskLocations'); %This is a cell array
    storageLocation = get(props, 'StorageLocation');
    storageConstructor = get(props, 'StorageConstructor');

The name of the decode function that must be available on the MATLAB worker path is mydecodefunc.

3 Set the environment variables, other than the task locations. All the MATLAB workers use these values when evaluating tasks of the job.

    setenv('MDCE_DECODE_FUNCTION', decodeFcn);
    setenv('MDCE_JOB_LOCATION', jobLocation);
    setenv('MDCE_STORAGE_LOCATION', storageLocation);
    setenv('MDCE_STORAGE_CONSTRUCTOR', storageConstructor);

Your submit function can use any names you choose for the environment variables, with the exception of MDCE_DECODE_FUNCTION; the MATLAB worker looks for its decode function identified by this variable. If you use alternative names for the other environment variables, be sure that the corresponding decode function also uses your alternative variable names. You can see the variable names used in the standard decode function by typing

    edit parallel.cluster.generic.independentDecodeFcn

4 Set the task-specific variables and scheduler commands. This is where you instruct your scheduler to start MATLAB workers for each task.

    for i = 1:props.NumberOfTasks
        setenv('MDCE_TASK_LOCATION', taskLocations{i});
        constructSchedulerCommand;
    end

The line constructSchedulerCommand represents the code you write to construct and execute your scheduler’s submit command. This command is typically a
character vector that combines the scheduler command with necessary flags, arguments, and values derived from the values of your object properties. This command is inside the for-loop so that your scheduler gets a command to start a MATLAB worker on the cluster for each task.

**Note** If you are not familiar with your network scheduler, ask your system administrator for help.

**MATLAB Worker Decode Function**

The sole purpose of the MATLAB worker’s decode function is to read certain job and task information into the MATLAB worker session. This information could be stored in disk files on the network, or it could be available as environment variables on the worker node. Because the discussion of the submit function illustrated only the usage of environment variables, so does this discussion of the decode function.

When working with the decode function, you must be aware of the

- Name and location of the decode function itself
- Names of the environment variables this function must read

**Diagram:**

![Diagram of MATLAB Worker Decode Function](image)

**Note** Standard decode functions are now included in the product. If your submit functions make use of the definitions in these decode functions, you do not have to provide your own decode functions. For example, to use the standard decode function for independent jobs, in your submit function set `MDCE_DECODE_FUNCTION` to
'parallel.cluster.generic.independentDecodeFcn'. The remainder of this section is useful only if you use names and settings other than the standards used in the provided decode functions.

Identify File Name and Location

The client's submit function and the worker's decode function work together as a pair. For more information on the submit function, see “MATLAB Client Submit Function” on page 7-23. The decode function on the worker is identified by the submit function as the value of the environment variable `MDCE_DECODE_FUNCTION`. The environment variable must be copied from the client node to the worker node. Your scheduler might perform this task for you automatically; if it does not, you must arrange for this copying.

The value of the environment variable `MDCE_DECODE_FUNCTION` defines the filename of the decode function, but not its location. The file cannot be passed as part of the job `AdditionalPaths` or `AttachedFiles` property, because the function runs in the MATLAB worker before that session has access to the job. Therefore, the file location must be available to the MATLAB worker as that worker starts.

Note The decode function must be available on the MATLAB worker's path.

You can get the decode function on the worker's path by either moving the file into a folder on the path (for example, `matlabroot/toolbox/local`), or by having the scheduler use `cd` in its command so that it starts the MATLAB worker from within the folder that contains the decode function.

In practice, the decode function might be identical for all workers on the cluster. In this case, all workers can use the same decode function file if it is accessible on a shared drive.

When a MATLAB worker starts, it automatically runs the file identified by the `MDCE_DECODE_FUNCTION` environment variable. This decode function runs before the worker does any processing of its task.

Read the Job and Task Information

When the environment variables have been transferred from the client to the worker nodes (either by the scheduler or some other means), the decode function of the MATLAB worker can read them with the `getenv` function.
With those values from the environment variables, the decode function must set the appropriate property values of the object that is its argument. The property values that must be set are the same as those in the corresponding submit function, except that instead of the cell array `TaskLocations`, each worker has only the individual character vector `TaskLocation`, which is one element of the `TaskLocations` cell array. Therefore, the properties you must set within the decode function on its argument object are as follows:

- `StorageConstructor`
- `StorageLocation`
- `JobLocation`
- `TaskLocation`

**Example — Write the Decode Function**

The decode function must read four environment variables and use their values to set the properties of the object that is the function’s output.

In this example, the decode function’s argument is the object `props`.

```matlab
function props = workerDecodeFunc(props)
    % Read the environment variables:
    storageConstructor = getenv('MDCE_STORAGE_CONSTRUCTOR');
    storageLocation = getenv('MDCE_STORAGE_LOCATION');
    jobLocation = getenv('MDCE_JOB_LOCATION');
    taskLocation = getenv('MDCE_TASK_LOCATION');

    % Set props object properties from the local variables:
    set(props, 'StorageConstructor', storageConstructor);
    set(props, 'StorageLocation', storageLocation);
    set(props, 'JobLocation', jobLocation);
    set(props, 'TaskLocation', taskLocation);
```

When the object is returned from the decode function to the MATLAB worker session, its values are used internally for managing job and task data.
Example — Program and Run a Job in the Client

1. Create a Scheduler Object

You use the `parcluster` function to create an object representing the cluster in your local MATLAB client session. Use a profile based on the generic type of cluster

```matlab
c = parcluster('MyGenericProfile')
```

If your cluster uses a shared file system for workers to access job and task data, set the `JobStorageLocation` and `HasSharedFilesystem` properties to specify where the job data is stored and that the workers should access job data directly in a shared file system.

```matlab
c.JobStorageLocation = '\share\scratch\jobdata'
c.HasSharedFilesystem = true
```

**Note** All nodes require access to the folder specified in the cluster object’s `JobStorageLocation` property.

If `JobStorageLocation` is not set, the default location for job data is the current working directory of the MATLAB client the first time you use `parcluster` to create an object for this type of cluster, which might not be accessible to the worker nodes.

If MATLAB is not on the worker’s system path, set the `ClusterMatlabRoot` property to specify where the workers are to find the MATLAB installation.

```matlab
c.ClusterMatlabRoot = '\\apps\matlab\'
```

You can look at all the property settings on the scheduler object. If no jobs are in the `JobStorageLocation` folder, the `Jobs` property is a 0-by-1 array. All settable property values on a scheduler object are local to the MATLAB client, and are lost when you close the client session or when you remove the object from the client workspace with `delete` or `clear all`.

```matlab
c
```

You must set the `IntegrationScriptsLocation` property to specify the folder containing the submit functions for this cluster.

```matlab
c.IntegrationScriptsLocation = '\\scripts\myIntegrationScripts';
```
You can now define the scheduler object, and the user-defined submit and decode functions. Programming and running a job is now similar to doing so with any other type of supported scheduler.

2. Create a Job

You create a job with the createJob function, which creates a job object in the client session. The job data is stored in the folder specified by the cluster object's JobStorageLocation property.

```matlab
j = createJob(c)
```

This statement creates the job object `j` in the client session.

**Note** Properties of a particular job or task should be set from only one computer at a time.

This generic scheduler job has somewhat different properties than a job that uses an MJS. For example, this job has no callback functions.

The job's State property is pending. This state means the job has not been queued for running yet. This new job has no tasks, so its Tasks property is a 0-by-1 array.

The cluster's Jobs property is now a 1-by-1 array of job objects, indicating the existence of your job.

`c`

3. Create Tasks

After you have created your job, you can create tasks for the job. Tasks define the functions to be evaluated by the workers during the running of the job. Often, the tasks of a job are identical except for different arguments or data. In this example, each task generates a 3-by-3 matrix of random numbers.

```matlab
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
createTask(j, @rand, 1, {3,3});
```

The Tasks property of `j` is now a 5-by-1 matrix of task objects.
j.Tasks

Alternatively, you can create the five tasks with one call to `createTask` by providing a cell array of five cell arrays defining the input arguments to each task.

\[
T = \text{createTask}(@\text{rand}, 1, \{\{3,3\} \{3,3\} \{3,3\} \{3,3\} \{3,3\}\});
\]

In this case, \( T \) is a 5-by-1 matrix of task objects.

4. Submit a Job to the Job Queue

To run your job and have its tasks evaluated, you submit the job to the scheduler’s job queue.

\[
\text{submit}(j)
\]

The scheduler distributes the tasks of \( j \) to MATLAB workers for evaluation.

The job runs asynchronously. If you need to wait for it to complete before you continue in your MATLAB client session, you can use the `wait` function.

\[
\text{wait}(j)
\]

This function pauses MATLAB until the State property of \( j \) is 'finished' or 'failed'.

5. Retrieve the Job’s Results

The results of each task’s evaluation are stored in that task object’s `OutputArguments` property as a cell array. Use `fetchOutputs` to retrieve the results from all the tasks in the job.

\[
\text{results} = \text{fetchOutputs}(j);
\]

Display the results from each task.

\[
\text{results}\{1:5\}
\]

\[
\begin{align*}
0.9501 & \quad 0.4860 & \quad 0.4565 \\
0.2311 & \quad 0.8913 & \quad 0.0185 \\
0.6068 & \quad 0.7621 & \quad 0.8214 \\
0.4447 & \quad 0.9218 & \quad 0.4057 \\
0.6154 & \quad 0.7382 & \quad 0.9355
\end{align*}
\]
Support Scripts

To use the generic scheduler interface, you can install templates and scripts from the following locations:

- IBM Platform LSF
- Grid Engine family
- PBS family
- SLURM

Each installer provides templates and scripts for the supported submission modes for shared file system, nonshared file system, or remote submission. Each submission mode has its own subfolder within the installation folder. The subfolder contains a file named README that provides specific instructions on how to use the scripts. To use these support scripts with your cluster object, set the IntegrationScriptsLocation property to the location of this subfolder.

For more information on programming jobs for generic schedulers, see:

- “Program Communicating Jobs for a Generic Scheduler” on page 8-7

For each scheduler type, the folder (or configuration subfolder) contains wrappers, submit functions, and other job management scripts for independent and communicating jobs. For example, you can install the following files for use with a PBS scheduler:

<table>
<thead>
<tr>
<th>Filename</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>independentSubmitFcn.m</td>
<td>Submit function for a independent job</td>
</tr>
<tr>
<td>Filename</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>communicatingSubmitFcn.m</td>
<td>Submit function for a communicating job</td>
</tr>
<tr>
<td>independentJobWrapper.sh</td>
<td>Script that is submitted to PBS to start workers that evaluate the tasks of an independent job</td>
</tr>
<tr>
<td>communicatingJobWrapper.sh</td>
<td>Script that is submitted to PBS to start workers that evaluate the tasks of a communicating job</td>
</tr>
<tr>
<td>deleteJobFcn.m</td>
<td>Script to delete a job from the scheduler</td>
</tr>
<tr>
<td>extractJobId.m</td>
<td>Script to get the job's ID from the scheduler</td>
</tr>
<tr>
<td>getJobStateFcn.m</td>
<td>Script to get the job's state from the scheduler</td>
</tr>
<tr>
<td>getSubmitString.m</td>
<td>Script to get the submission character vector for the scheduler</td>
</tr>
<tr>
<td>postConstructFcn.m</td>
<td>Script that is run following cluster object creation</td>
</tr>
</tbody>
</table>

These files are all programmed to use the standard decode functions provided with the product, so they do not have specialized decode functions.

The folders for other scheduler types contain similar files.

As more files or solutions for more schedulers might become available at any time, visit the product page at http://www.mathworks.com/products/distriben/. This Web page provides links to updates, supported schedulers, requirements, and contact information in case you have any questions.

**Manage Jobs with Generic Scheduler**

While you can use the `cancel` and `delete` methods on jobs that use the generic scheduler interface, by default these methods access or affect only the job data where it is stored on disk. To cancel or delete a job or task that is currently running or queued, you must provide instructions to the scheduler directing it what to do and when to do it. To accomplish this, the toolbox provides a means of saving data associated with each job or task from the scheduler, and a set of properties to define instructions for the scheduler upon each cancel or destroy request.

**Save Job Scheduler Data**

The first requirement for job management is to identify the job from the cluster’s perspective. When you submit a job to the cluster, the command to do the submission in
your submit function can return from the scheduler some data about the job. This data typically includes a job ID. By storing that job ID with the job, you can later refer to the job by this ID when you send management commands to the scheduler. Similarly, you can store information, such as an ID, for each task. The toolbox function that stores this cluster data is `setJobClusterData`.

If your scheduler accommodates submission of entire jobs (collection of tasks) in a single command, you might get back data for the whole job and/or for each task. Part of your submit function might be structured like this:

```matlab
for ii = 1:props.NumberOfTasks
    define scheduler command per task
end
submit job to scheduler
data_array = parse data returned from scheduler %possibly NumberofTasks-by-2 matrix
setJobClusterData(cluster, job, data_array)
```

If your scheduler accepts only submissions of individual tasks, you might get return data pertaining to only each individual tasks. In this case, your submit function might have code structured like this:

```matlab
for ii = 1:props.NumberOfTasks
    submit task to scheduler
    %Per-task settings:
    data_array(1,ii) = ... parse character vector returned from scheduler
    data_array(2,ii) = ... save ID returned from scheduler
    etc
end
setJobClusterData(scheduler, job, data_array)
```

**Define Scheduler Commands in User Functions**

You now have the scheduler data (such as the scheduler's ID for the job or task) stored on disk along with the rest of the job data. You can then write code to control what the scheduler should do when that particular job or task is canceled or destroyed.

To do so, create the following functions:

- `cancelJobFcn.m`
- `deleteJobFcn.m`
- `cancelTaskFcn.m`
- `deleteTaskFcn.m`

Your `cancelJobFcn.m` function defines what you want to communicate to your scheduler in the event that you use the `cancel` function on your job from the MATLAB...
client. The toolbox takes care of the job state and any data management with the job data on disk. Therefore your `cancelJobFcn.m` function needs to deal only with the part of the job currently running or queued with the scheduler. The toolbox function that retrieves scheduler data from the job is `getJobClusterData`. Your cancel function must have the following signature:

```
function cancelJobFcn(sched, job)
    array_data = getJobClusterData(clust, job)
    job_id = array_data(...) % Extract the ID from the data, depending on how
    % it was stored in the submit function above.
    command to scheduler canceling job job_id
```

In a similar way, you can define what you want your scheduler to do when deleting a job, or when canceling and deleting tasks.

**Delete or Cancel a Running Job**

To use your functions with your cluster, you must locate the functions in the folder identified by the `IntegrationScriptsLocation` property of your cluster object.

Continue with job creation and submission as usual.

```
j1 = createJob(c);
for ii = 1:n
    t(ii) = createTask(j1,...)
end
submit(j1)
```

While the job is running or queued, you can cancel or delete the job or a task.

This command cancels the task and moves it to the finished state. The `cancelJobFcn` function is executed, and sends the appropriate commands to the scheduler:

```
cancel(t(4))
```

This command deletes job data for `j1`. The `deleteJobFcn` function is executed, and sends the appropriate commands to the scheduler:

```
delete(j1)
```

**Get State Information About a Job or Task**

When using a third-party scheduler, it is possible that the scheduler itself can have more up-to-date information about your jobs than what is available to the toolbox from the job.
storage location. To retrieve that information from the scheduler, you can write a function called `getJobStateFcn.m`. You must place this function in the folder identified by the `IntegrationScriptsLocation` property of your cluster object. The function must have the following signature:

```matlab
function getJobStateFcn (cluster, job, state)
```

Suppose that you use a toolbox function such as `wait`, etc., that accesses the state of a job on the generic scheduler. After retrieving the state from storage, the toolbox runs the `getJobStateFcn.m` function located in `IntegrationScriptsLocation`. The result is returned in place of the stored state. The function you write for this purpose must return a valid value for the `State` of a job object.

When using the generic scheduler interface in a nonshared file system environment, the remote file system might be slow in propagating large data files back to your local data location. Therefore, a job’s `State` property might indicate that the job is finished some time before all its data is available to you.

**Summary**

The following list summarizes the sequence of events that occur when running a job that uses the generic scheduler interface:

1. Provide a submit function and a decode function. Be sure the decode function is on all the MATLAB workers’ search paths.

The following steps occur in the MATLAB client session:

1. Define the `IntegrationScriptsLocation` property of your scheduler object to the folder containing your submit function.
2. Send your job to the scheduler.
   ```matlab
   submit(job)
   ```
3. The client session runs the submit function.
4. The submit function sets environment variables with values derived from its arguments.
5. The submit function makes calls to the scheduler — generally, a call for each task (with environment variables identified explicitly, if necessary).

The following step occurs in your network:
1  For each task, the scheduler starts a MATLAB worker session on a cluster node.

The following steps occur in each MATLAB worker session:

1  The MATLAB worker automatically runs the decode function, finding it on the path.
2  The decode function reads the pertinent environment variables.
3  The decode function sets the properties of its argument object with values from the environment variables.
4  The MATLAB worker uses these object property values in processing its task without your further intervention.
Program Communicating Jobs

- “Program Communicating Jobs” on page 8-2
- “Program Communicating Jobs for a Supported Scheduler” on page 8-4
- “Program Communicating Jobs for a Generic Scheduler” on page 8-7
- “Further Notes on Communicating Jobs” on page 8-10
Program Communicating Jobs

Communicating jobs are those in which the workers can communicate with each other during the evaluation of their tasks. A communicating job consists of only a single task that runs simultaneously on several workers, usually with different data. More specifically, the task is duplicated on each worker, so each worker can perform the task on a different set of data, or on a particular segment of a large data set. The workers can communicate with each other as each executes its task. The function that the task runs can take advantage of a worker’s awareness of how many workers are running the job, which worker this is among those running the job, and the features that allow workers to communicate with each other.

In principle, you create and run communicating jobs similarly to the way you “Program Independent Jobs” on page 7-2:

1. Define and select a cluster profile.
2. Find a cluster.
3. Create a communicating job.
4. Create a task.
5. Submit the job for running. For details about what each worker performs for evaluating a task, see “Submit a Job to the Job Queue” on page 7-12.
6. Retrieve the results.

The differences between independent jobs and communicating jobs are summarized in the following table.

<table>
<thead>
<tr>
<th>Independent Job</th>
<th>Communicating Job</th>
</tr>
</thead>
<tbody>
<tr>
<td>MATLAB workers perform the tasks but do not communicate with each other.</td>
<td>MATLAB workers can communicate with each other during the running of their tasks.</td>
</tr>
<tr>
<td>You define any number of tasks in a job.</td>
<td>You define only one task in a job.</td>
</tr>
<tr>
<td>Tasks need not run simultaneously. Tasks are distributed to workers as the</td>
<td>Tasks run simultaneously, so you can run the job only on as many workers as are</td>
</tr>
<tr>
<td>workers become available, so a worker can perform several of the tasks in a job.</td>
<td>available at run time. The start of the job might be delayed until the required</td>
</tr>
<tr>
<td></td>
<td>number of workers is available.</td>
</tr>
</tbody>
</table>
Some of the details of a communicating job and its tasks might depend on the type of scheduler you are using. The following sections discuss different schedulers and explain programming considerations:

- “Program Communicating Jobs for a Supported Scheduler” on page 8-4
- “Program Communicating Jobs for a Generic Scheduler” on page 8-7
- “Further Notes on Communicating Jobs” on page 8-10
Program Communicating Jobs for a Supported Scheduler

<table>
<thead>
<tr>
<th>In this section...</th>
</tr>
</thead>
<tbody>
<tr>
<td>“Schedulers and Conditions” on page 8-4</td>
</tr>
<tr>
<td>“Code the Task Function” on page 8-4</td>
</tr>
<tr>
<td>“Code in the Client” on page 8-5</td>
</tr>
</tbody>
</table>

Schedulers and Conditions

You can run a communicating job using any type of scheduler. This section illustrates how to program communicating jobs for supported schedulers (MJS, local scheduler, Microsoft Windows HPC Server (including CCS), Platform LSF, PBS Pro, or TORQUE).

To use this supported interface for communicating jobs, the following conditions must apply:

- You must have a shared file system between client and cluster machines
- You must be able to submit jobs directly to the scheduler from the client machine

Note When using any third-party scheduler for running a communicating job, if all these conditions are not met, you must use the generic scheduler interface. (Communicating jobs also include pmode, parpool, spmd, and parfor.) See “Program Communicating Jobs for a Generic Scheduler” on page 8-7.

Code the Task Function

In this section a simple example illustrates the basic principles of programming a communicating job with a third-party scheduler. In this example, the worker whose labindex value is 1 creates a magic square comprised of a number of rows and columns that is equal to the number of workers running the job (numlabs). In this case, four workers run a communicating job with a 4-by-4 magic square. The first worker broadcasts the matrix with labBroadcast to all the other workers, each of which calculates the sum of one column of the matrix. All of these column sums are combined with the gplus function to calculate the total sum of the elements of the original magic square.

The function for this example is shown below.
function total_sum = colsum
if labindex == 1
    % Send magic square to other workers
    A = labBroadcast(1,magic(numlabs))
else
    % Receive broadcast on other workers
    A = labBroadcast(1)
end

% Calculate sum of column identified by labindex for this worker
column_sum = sum(A(:,labindex))

% Calculate total sum by combining column sum from all workers
total_sum = gplus(column_sum)

This function is saved as the file colsum.m on the path of the MATLAB client. It will be sent to each worker by the job’s AttachedFiles property.

While this example has one worker create the magic square and broadcast it to the other workers, there are alternative methods of getting data to the workers. Each worker could create the matrix for itself. Alternatively, each worker could read its part of the data from a file on disk, the data could be passed in as an argument to the task function, or the data could be sent in a file contained in the job’s AttachedFiles property. The solution to choose depends on your network configuration and the nature of the data.

**Code in the Client**

As with independent jobs, you choose a profile and create a cluster object in your MATLAB client by using the parcluster function. There are slight differences in the profiles, depending on the scheduler you use, but using profiles to define as many properties as possible minimizes coding differences between the scheduler types.

You can create and configure the cluster object with this code:

c = parcluster('MyProfile')

where 'MyProfile' is the name of a cluster profile for the type of scheduler you are using. Any required differences for various cluster options are controlled in the profile. You can have one or more separate profiles for each type of scheduler. For complete details, see “Discover Clusters and Use Cluster Profiles” on page 6-18. Create or modify profiles according to the instructions of your system administrator.
When your cluster object is defined, you create the job object with the `createCommunicatingJob` function. The job `Type` property must be set as 'SPMD' when you create the job.

```matlab
cjob = createCommunicatingJob(c,'Type','SPMD');
```

The function file `colsum.m` (created in “Code the Task Function” on page 8-4) is on the MATLAB client path, but it has to be made available to the workers. One way to do this is with the job’s `AttachedFiles` property, which can be set in the profile you used, or by:

```matlab
cjob.AttachedFiles = {'colsum.m'}
```

Here you might also set other properties on the job, for example, setting the number of workers to use. Again, profiles might be useful in your particular situation, especially if most of your jobs require many of the same property settings. To run this example on four workers, you can established this in the profile, or by the following client code:

```matlab
cjob.NumWorkersRange = 4
```

You create the job’s one task with the usual `createTask` function. In this example, the task returns only one argument from each worker, and there are no input arguments to the `colsum` function.

```matlab
t = createTask(cjob, @colsum, 1, {})
```

Use `submit` to run the job.

```matlab
submit(cjob)
```

Make the MATLAB client wait for the job to finish before collecting the results. The results consist of one value from each worker. The `gplus` function in the task shares data between the workers, so that each worker has the same result.

```matlab
wait(cjob)
results = fetchOutputs(cjob)
results =
    [136]
    [136]
    [136]
    [136]
Program Communicating Jobs for a Generic Scheduler

In this section...

“Introduction” on page 8-7
“Code in the Client” on page 8-7

Introduction

This section discusses programming communicating jobs using the generic scheduler interface. This interface lets you execute jobs on your cluster with any scheduler you might have.

The principles of using the generic scheduler interface for communicating jobs are the same as those for independent jobs. The overview of the concepts and details of submit and decode functions for independent jobs are discussed fully in “Program Independent Jobs for a Generic Scheduler” on page 7-22. For this purpose, you need to have Parallel Computing Toolbox as well as MATLAB Distributed Computing Server running on your cluster.

The basic steps follow.

Code in the Client

Configure the Scheduler Object

Coding a communicating job for a generic scheduler involves the same procedure as coding an independent job.

1. Create an object representing your cluster with parcluster.
2. Set the appropriate properties on the cluster object if they are not defined in the profile. Because the scheduler itself is often used by many users and applications, it is probably best to use a profile for programming these properties. See “Discover Clusters and Use Cluster Profiles” on page 6-18.

Among the properties required for a communicating job is IntegrationScriptsLocation. This property points to the location of the communicatingSubmitFcn.m function that executes when a communicating job is submitted. You can write your own communicating submit and decode functions, or
use those that come with the product for various schedulers and platforms; see the following section, “Troubleshooting and Debugging” on page 6-62.

3 Use `createCommunicatingJob` to create a communicating job object for your cluster.

4 Create a task, run the job, and retrieve the results as usual.

**Support Scripts**

To support usage of the generic scheduler interface, templates and scripts can be installed from the following locations:

- IBM Platform LSF
- Grid Engine family
- PBS family
- SLURM

Each installer provides templates and scripts for the supported submission modes for shared file system, nonshared file system, or remote submission. Each submission mode has its own subfolder within the installation folder, which contains a file named `README` that provides specific instructions on how to use the scripts. To use these support scripts with your cluster object, set its `IntegrationScriptsLocation` property to the location of this subfolder.

For more information on programming jobs for generic schedulers, see:

- “Program Independent Jobs for a Generic Scheduler” on page 7-22

For each scheduler type, the folder (or configuration subfolder) contains wrappers, submit functions, and other job management scripts for independent and communicating jobs. For example, you can install the following files for use with a PBS scheduler:

<table>
<thead>
<tr>
<th>Filename</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>independentSubmitFcn.m</td>
<td>Submit function for an independent job</td>
</tr>
<tr>
<td>communicatingSubmitFcn.m</td>
<td>Submit function for a communicating job</td>
</tr>
<tr>
<td>independentJobWrapper.sh</td>
<td>Script that is submitted to PBS to start workers that evaluate the tasks of an independent job</td>
</tr>
<tr>
<td>communicatingJobWrapper.sh</td>
<td>Script that is submitted to PBS to start workers that evaluate the tasks of a communicating job</td>
</tr>
<tr>
<td>Filename</td>
<td>Description</td>
</tr>
<tr>
<td>---------------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>deleteJobFcn.m</td>
<td>Script to delete a job from the scheduler</td>
</tr>
<tr>
<td>extractJobId.m</td>
<td>Script to get the job’s ID from the scheduler</td>
</tr>
<tr>
<td>getJobStateFcn.m</td>
<td>Script to get the job’s state from the scheduler</td>
</tr>
<tr>
<td>getSubmitString.m</td>
<td>Script to get the submission character vector for the scheduler</td>
</tr>
<tr>
<td>postConstructFcn.m</td>
<td>Script that is run following cluster object creation</td>
</tr>
</tbody>
</table>

These files are all programmed to use the standard decode functions provided with the product, so they do not have specialized decode functions. For communicating jobs, the standard decode function provided with the product is `parallel.cluster.generic.communicatingDecodeFcn`. You can view the required variables in this file by typing

```matlab
edit parallel.cluster.generic.communicatingDecodeFcn
```

The folders for other scheduler types contain similar files.

As more files or solutions for more schedulers might become available at any time, visit the product page at [http://www.mathworks.com/products/distriben/](http://www.mathworks.com/products/distriben/). This Web page provides links to updates, supported schedulers, requirements, and contact information in case you have any questions.
Further Notes on Communicating Jobs

In this section...

| “Number of Tasks in a Communicating Job” on page 8-10 |
| “Avoid Deadlock and Other Dependency Errors” on page 8-10 |

Number of Tasks in a Communicating Job

Although you create only one task for a communicating job, the system copies this task for each worker that runs the job. For example, if a communicating job runs on four workers, the Tasks property of the job contains four task objects. The first task in the job’s Tasks property corresponds to the task run by the worker whose labindex is 1, and so on, so that the ID property for the task object and labindex for the worker that ran that task have the same value. Therefore, the sequence of results returned by the fetchOutputs function corresponds to the value of labindex and to the order of tasks in the job’s Tasks property.

Avoid Deadlock and Other Dependency Errors

Because code running in one worker for a communicating job can block execution until some corresponding code executes on another worker, the potential for deadlock exists in communicating jobs. This is most likely to occur when transferring data between workers or when making code dependent upon the labindex in an if statement. Some examples illustrate common pitfalls.

Suppose you have a codistributed array D, and you want to use the gather function to assemble the entire array in the workspace of a single worker.

```matlab
if labindex == 1
    assembled = gather(D);
end
```

The reason this fails is because the gather function requires communication between all the workers across which the array is distributed. When the if statement limits execution to a single worker, the other workers required for execution of the function are not executing the statement. As an alternative, you can use gather itself to collect the data into the workspace of a single worker: assembled = gather(D, 1).
In another example, suppose you want to transfer data from every worker to the next worker on the right (defined as the next higher \texttt{labindex}). First you define for each worker what the workers on the left and right are.

\begin{verbatim}
from\_lab\_left = \text{mod}(\text{labindex} - 2, \text{numlabs}) + 1;
\text{to\_lab\_right} = \text{mod}(\text{labindex}, \text{numlabs}) + 1;
\end{verbatim}

Then try to pass data around the ring.

\begin{verbatim}
\text{labSend} (\text{outdata}, \text{to\_lab\_right});
\text{indata} = \text{labReceive} (\text{from\_lab\_left});
\end{verbatim}

The reason this code might fail is because, depending on the size of the data being transferred, the \texttt{labSend} function can block execution in a worker until the corresponding receiving worker executes its \texttt{labReceive} function. In this case, all the workers are attempting to send at the same time, and none are attempting to receive while \texttt{labSend} has them blocked. In other words, none of the workers get to their \texttt{labReceive} statements because they are all blocked at the \texttt{labSend} statement. To avoid this particular problem, you can use the \texttt{labSendReceive} function.
GPU Computing

• “GPU Capabilities and Performance” on page 9-2
• “Establish Arrays on a GPU” on page 9-3
• “Run Built-In Functions on a GPU” on page 9-8
• “Run Element-wise MATLAB Code on GPU” on page 9-14
• “Identify and Select a GPU Device” on page 9-19
• “Run CUDA or PTX Code on GPU” on page 9-22
• “Run MEX-Functions Containing CUDA Code” on page 9-33
• “Measure and Improve GPU Performance” on page 9-37
GPU Capabilities and Performance

In this section...

“Capabilities” on page 9-2
“Performance Benchmarking” on page 9-2

Capabilities

Parallel Computing Toolbox enables you to program MATLAB to use your computer’s graphics processing unit (GPU) for matrix operations. In many cases, execution in the GPU is faster than in the CPU, so this feature might offer improved performance.

Toolbox capabilities with the GPU let you:

- “Identify and Select a GPU Device” on page 9-19
- “Transfer Arrays Between Workspace and GPU” on page 9-3
- “Run Built-In Functions on a GPU” on page 9-8
- “Run Element-wise MATLAB Code on GPU” on page 9-14
- “Run CUDA or PTX Code on GPU” on page 9-22
- “Run MEX-Functions Containing CUDA Code” on page 9-33

Performance Benchmarking

You can use gputimeit to measure the execution time of functions that run on the GPU. For more details, see “Measure and Improve GPU Performance” on page 9-37.

The MATLAB Central file exchange offers a function called gpuBench, which measures the execution time for various MATLAB GPU tasks and estimates the peak performance of your GPU. See http://www.mathworks.com/matlabcentral/fileexchange/34080-gpubench.
Establish Arrays on a GPU

In this section...

“Transfer Arrays Between Workspace and GPU” on page 9-3
“Create GPU Arrays Directly” on page 9-4
“Examine gpuArray Characteristics” on page 9-7

Transfer Arrays Between Workspace and GPU

Send Arrays to the GPU

A gpuArray in MATLAB represents an array that is stored on the GPU. Use the gpuArray function to transfer an array from MATLAB to the GPU:

\[
N = 6; \\
M = magic(N); \\
G = gpuArray(M); \\
\]

G is now a MATLAB gpuArray object that represents the magic square stored on the GPU. The input provided to gpuArray must be numeric (for example: single, double, int8, etc.) or logical. (See also “Considerations for Complex Numbers” on page 9-12.)

Retrieve Arrays from the GPU

Use the gather function to retrieve arrays from the GPU to the MATLAB workspace. This takes an array that is on the GPU represented by a gpuArray object, and transfers it to the MATLAB workspace as a regular MATLAB array. You can use isequal to verify that you get the correct values back:

\[
G = gpuArray(ones(100,'uint32')); \\
D = gather(G); \\
OK = isequal(D,ones(100,'uint32')) \\
\]

Examples: Transfer Array

Transfer Array to the GPU

Create a 1000-by-1000 random matrix in MATLAB, and then transfer it to the GPU:

\[
X = rand(1000); \\
G = gpuArray(X); \\
\]
Transfer Array of a Specified Precision

Create a matrix of double-precision random values in MATLAB, and then transfer the matrix as single-precision from MATLAB to the GPU:

\[
X = \text{rand}(1000); \\
G = \text{gpuArray}(	ext{single}(X));
\]

Construct an Array for Storing on the GPU

Construct a 100-by-100 matrix of \texttt{uint32} ones and transfer it to the GPU. You can accomplish this with a single line of code:

\[
G = \text{gpuArray}(	ext{ones}(100,'\text{uint32}'));
\]

Create GPU Arrays Directly

A number of methods on the \texttt{gpuArray} class allow you to directly construct arrays on the GPU without having to transfer arrays from the MATLAB workspace. These constructors require only array size and data class information, so they can construct an array without any elements from the workspace. Use any of the following to directly create an array on the GPU:

<table>
<thead>
<tr>
<th>Constructor</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{eye}</td>
<td>Create an \texttt{eye} matrix</td>
</tr>
<tr>
<td>\texttt{false}</td>
<td>Create a \texttt{false} matrix</td>
</tr>
<tr>
<td>\texttt{Inf}</td>
<td>Create an \texttt{Inf} matrix</td>
</tr>
<tr>
<td>\texttt{NaN}</td>
<td>Create a \texttt{NaN} matrix</td>
</tr>
<tr>
<td>\texttt{ones}</td>
<td>Create a matrix of ones</td>
</tr>
<tr>
<td>\texttt{true}</td>
<td>Create a \texttt{true} matrix</td>
</tr>
<tr>
<td>\texttt{zeros}</td>
<td>Create a matrix of zeros</td>
</tr>
<tr>
<td>\texttt{rand}</td>
<td>Create a random matrix</td>
</tr>
<tr>
<td>\texttt{randi}</td>
<td>Create a random integer matrix</td>
</tr>
<tr>
<td>\texttt{randn}</td>
<td>Create a normal distribution</td>
</tr>
<tr>
<td>\texttt{randn}</td>
<td>Create an \texttt{randn} matrix</td>
</tr>
<tr>
<td>\texttt{freqspace}</td>
<td>Create a frequency matrix</td>
</tr>
<tr>
<td>\texttt{linspace}</td>
<td>Create a linearly spaced matrix</td>
</tr>
<tr>
<td>\texttt{logspace}</td>
<td>Create a logarithmically spaced matrix</td>
</tr>
</tbody>
</table>

For a complete list of available static methods in any release, type

\[
\text{methods('gpuArray')}
\]

The constructors appear at the bottom of the output from this command.

For help on any one of the constructors, type

\[
\text{help gpuArray/functionname}
\]
For example, to see the help on the colon constructor, type

```matlab
help gpuArray/colon
```

**Example: Construct an Identity Matrix on the GPU**

To create a 1024-by-1024 identity matrix of type `int32` on the GPU, type

```matlab
II = eye(1024,'int32','gpuArray');
size(II)
```

```
1024    1024
```

With one numerical argument, you create a 2-dimensional matrix.

**Example: Construct a Multidimensional Array on the GPU**

To create a 3-dimensional array of ones with data class `double` on the GPU, type

```matlab
G = ones(100,100,50,'gpuArray');
size(G)
```

```
100    100    50
```

```matlab
classUnderlying(G)
double
```

The default class of the data is `double`, so you do not have to specify it.

**Example: Construct a Vector on the GPU**

To create a 8192-element column vector of zeros on the GPU, type

```matlab
Z = zeros(8192,1,'gpuArray');
size(Z)
```

```
8192     1
```

For a column vector, the size of the second dimension is 1.

**Control the Random Stream for gpuArray**

The following functions control the random number stream on the GPU:
These functions perform in the same way as `rng` and `RandStream` in MATLAB, but with certain limitations on the GPU. For more information on the use and limits of these functions, type

```
help parallel.gpu.rng
help parallel.gpu.RandStream
```

The GPU uses the combined multiplicative recursive generator by default to create uniform random values, and uses inversion for creating normal values. This is not the default stream in a client MATLAB session on the CPU, but is the equivalent of

```
RandStream('CombRecursive','NormalTransform','Inversion');
```

However, a MATLAB worker session has the same default stream as its GPU, even if it is a worker in a local cluster on the same machine. That is, a MATLAB client and workers do not have the same default stream.

In most cases, it does not matter that the default random stream on the GPU is not the same as the default stream in MATLAB on the CPU. But if you need to reproduce the same stream on both GPU and CPU, you can set the CPU random stream accordingly, and use the same seed to set both streams:

```matlab
seed=0; n=4;

cpu_stream = RandStream('CombRecursive','Seed',seed,'NormalTransform','Inversion');
RandStream.setGlobalStream(cpu_stream);

gpu_stream = parallel.gpu.RandStream('CombRecursive','Seed',seed);
parallel.gpu.RandStream.setGlobalStream(gpu_stream);

r = rand(n); % On CPU
R = rand(n,'gpuArray'); % On GPU
OK = isequal(r,R)

1
```

There are three supported random generators on the GPU. The combined multiplicative recursive generator (MRG32K3A) is the default because it is a popular and reliable industry standard generator for parallel computing. You can choose the GPU random generator with any of the following commands:
parallel.gpu.RandStream('combRecursive')
parallel.gpu.RandStream('Philox4x32-10')
parallel.gpu.RandStream('Threefry4x64-20')

For more information about generating random numbers on a GPU, and a comparison between GPU and CPU generation, see “Control Random Number Streams” on page 6-46. For an example that shows performance comparisons for different random generators, see Generating Random Numbers on a GPU.

Examine gpuArray Characteristics

There are several functions available for examining the characteristics of a gpuArray object:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>classUnderlying</td>
<td>Class of the underlying data in the array</td>
</tr>
<tr>
<td>existsOnGPU</td>
<td>Indication if array exists on the GPU and is accessible</td>
</tr>
<tr>
<td>isreal</td>
<td>Indication if array data is real</td>
</tr>
<tr>
<td>length</td>
<td>Length of vector or largest array dimension</td>
</tr>
<tr>
<td>ndims</td>
<td>Number of dimensions in the array</td>
</tr>
<tr>
<td>size</td>
<td>Size of array dimensions</td>
</tr>
</tbody>
</table>

For example, to examine the size of the gpuArray object G, type:

```matlab
G = rand(100, 'gpuArray');
s = size(G)
```

```
100   100
```

See Also

“GPU Capabilities and Performance” on page 9-2 | “Run Built-In Functions on a GPU” on page 9-8 | “Identify and Select a GPU Device” on page 9-19 | “Measure and Improve GPU Performance” on page 9-37
Run Built-In Functions on a GPU

MATLAB Functions with gpuArray Arguments

Many MATLAB built-in functions support gpuArray input arguments. Whenever any of these functions is called with at least one gpuArray as an input argument, the function executes on the GPU and generates a gpuArray as the result. You can mix inputs using both gpuArray and MATLAB arrays in the same function call; the MATLAB arrays are transferred to the GPU for the function execution. Supporting functions include the discrete Fourier transform (fft), matrix multiplication (mtimes), and left matrix division (mldivide).

The following functions and their symbol operators are enhanced to accept gpuArray input arguments so that they execute on the GPU:
<table>
<thead>
<tr>
<th>Function</th>
<th>Function</th>
<th>Function</th>
<th>Function</th>
<th>Function</th>
<th>Function</th>
<th>Function</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>abs</td>
<td>compan</td>
<td>flip</td>
<td>isnan</td>
<td>pcg</td>
<td>sph2cart</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acos</td>
<td>complex</td>
<td>fliplr</td>
<td>isnumeric</td>
<td>perms</td>
<td>sprand</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acosd</td>
<td>cond</td>
<td>flipud</td>
<td>isreal</td>
<td>permute</td>
<td>sprandn</td>
<td></td>
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</tr>
<tr>
<td>acosh</td>
<td>conj</td>
<td>floor</td>
<td>isrow</td>
<td>pinv</td>
<td>sprandsym</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acot</td>
<td>conv</td>
<td>fprintf</td>
<td>issorted</td>
<td>planerot</td>
<td>sprandn</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acotd</td>
<td>conv2</td>
<td>full</td>
<td>issparse</td>
<td>printf</td>
<td>sprand</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acoth</td>
<td>convn</td>
<td>gamma</td>
<td>issymmetric</td>
<td>plus</td>
<td>sprand</td>
<td></td>
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</tr>
<tr>
<td>acsc</td>
<td>corrcosf</td>
<td>gammaint</td>
<td>istr1</td>
<td>p2cart</td>
<td>sprandn</td>
<td></td>
<td></td>
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<tr>
<td>acscd</td>
<td>cos</td>
<td>gammairc</td>
<td>istriu</td>
<td>poly</td>
<td>sprandsym</td>
<td></td>
<td></td>
</tr>
<tr>
<td>acsch</td>
<td>cosd</td>
<td>gammaln</td>
<td>isvector</td>
<td>polyarea</td>
<td>sqrt</td>
<td></td>
<td></td>
</tr>
<tr>
<td>accumarray</td>
<td>cosh</td>
<td>gather</td>
<td>kron</td>
<td>polyarea</td>
<td>sqrt</td>
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<tr>
<td>all</td>
<td>cot</td>
<td>ge</td>
<td>ldivide</td>
<td>polyder</td>
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<tr>
<td>and</td>
<td>cotd</td>
<td>gmrres</td>
<td>le</td>
<td>polyfit</td>
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<tr>
<td>angle</td>
<td>coth</td>
<td>gradient</td>
<td>legendre</td>
<td>squeeze</td>
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<tr>
<td>any</td>
<td>cov</td>
<td>gt</td>
<td>length</td>
<td>std</td>
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<tr>
<td>arrayfun</td>
<td>cross</td>
<td>hankel</td>
<td>log</td>
<td>sub2ind</td>
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<td>csc</td>
<td>head</td>
<td>log10</td>
<td>polyval</td>
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<tr>
<td>asecd</td>
<td>csd</td>
<td>histcounts</td>
<td>loglp</td>
<td>subasgn</td>
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<td>asech</td>
<td>csch</td>
<td>horzcat</td>
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<td>pow2</td>
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<td>asin</td>
<td>ctranspose</td>
<td>hsv2rgb</td>
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<td>subsindex</td>
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<td>asind</td>
<td>cummax</td>
<td>hypot</td>
<td>lsqr</td>
<td>superimpose</td>
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<td>asinh</td>
<td>cummin</td>
<td>idivide</td>
<td>it</td>
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<td>lu</td>
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<td>atan</td>
<td>cumsum</td>
<td>ifft</td>
<td>max</td>
<td>svs</td>
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<td>atan2</td>
<td>deg2rad</td>
<td>ifft2</td>
<td>mat2str</td>
<td>rand</td>
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<td>atan2d</td>
<td>del2</td>
<td>ifftn</td>
<td>max</td>
<td>randi</td>
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<td>atand</td>
<td>det</td>
<td>ifftshift</td>
<td>median</td>
<td>randn</td>
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<td>atanh</td>
<td>detrend</td>
<td>ind2sub</td>
<td>mean</td>
<td>tand</td>
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<tr>
<td>bandwidth</td>
<td>diag</td>
<td>ind2sub2</td>
<td>meshgrid</td>
<td>rank</td>
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<td>besselj</td>
<td>diff</td>
<td>inf</td>
<td>min</td>
<td>rdivide</td>
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<td>bessely</td>
<td>discrete</td>
<td>iinfof2</td>
<td>logical</td>
<td>rdivide2</td>
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</tr>
<tr>
<td>beta</td>
<td>disp</td>
<td>int2str</td>
<td>max</td>
<td>rectint</td>
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<tr>
<td>betainc</td>
<td>display</td>
<td>int32</td>
<td>mode</td>
<td>rem</td>
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<td>betaincinv</td>
<td>dot</td>
<td>int64</td>
<td>movmean</td>
<td>rem</td>
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<td>betaln</td>
<td>double</td>
<td>int8</td>
<td>movstd</td>
<td>repelem</td>
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<td>eig</td>
<td>interp1</td>
<td>movsum</td>
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<td>bigcgstab</td>
<td>eps</td>
<td>interp2</td>
<td>movvar</td>
<td>repmat</td>
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</tr>
<tr>
<td>bitand</td>
<td>eq</td>
<td>interp3</td>
<td>mpower</td>
<td>typeof</td>
<td></td>
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</tr>
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<td>bitcmp</td>
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<td>mrdivide</td>
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<td>erfcinv</td>
<td>inv</td>
<td>NaN</td>
<td>roots</td>
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<td>erfcx</td>
<td>ipermute</td>
<td>ndgrid</td>
<td>uint64</td>
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<td>cart2pol</td>
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<td>norm</td>
<td>setxor</td>
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<td>cast</td>
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<td>not</td>
<td>sign</td>
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<tr>
<td>cat</td>
<td>fft</td>
<td>isfloat</td>
<td>nargout</td>
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<td>cdf2rdf</td>
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<td>sinh</td>
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<td>ceil</td>
<td>ffin</td>
<td>isinf</td>
<td>num2str</td>
<td>single</td>
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<tr>
<td>cgs</td>
<td>fftshift</td>
<td>isinteger</td>
<td>numel</td>
<td>sort</td>
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<tr>
<td>chol</td>
<td>filter</td>
<td>islogical</td>
<td>ones</td>
<td>sortrows</td>
<td></td>
<td></td>
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</tr>
</tbody>
</table>
See the release notes for information about updates to individual functions.

To get information about any restrictions or limitations concerning the support of any of these functions for gpuArray objects, type:

```
help gpuArray/functionname
```

For example, to see the help on the overload of `lu`, type

```
help gpuArray/lu
```

In most cases, if any of the input arguments to these functions is a gpuArray, any output arrays are gpuArrays. If the output is always scalar, it returns as MATLAB data in the workspace. If the result is a gpuArray of complex data and all the imaginary parts are zero, these parts are retained and the data remains complex. This could have an impact when using `sort`, `isreal`, etc.

**Example: Functions with gpuArray Input and Output**

This example uses the `fft` and `real` functions, along with the arithmetic operators `+` and `*`. All the calculations are performed on the GPU, then `gather` retrieves the data from the GPU back to the MATLAB workspace.

```matlab
Ga = rand(1000,'single','gpuArray');
Gfft = fft(Ga);
Gb = (real(Gfft) + Ga) * 6;
G = gather(Gb);
```

The `whos` command is instructive for showing where each variable's data is stored.

```
whos
```

```
Name      Size      Bytes  Class
-------    ------    -----  ----
G         1000x1000  4000000 single
Ga        1000x1000   108  gpuArray
Gb        1000x1000   108  gpuArray
Gfft      1000x1000   108  gpuArray
```
Notice that all the arrays are stored on the GPU (gpuArray), except for G, which is the result of the gather function.

**Sparse Arrays on a GPU**

The following functions support sparse gpuArrays.

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>abs</code></td>
<td></td>
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<tr>
<td><code>angle</code></td>
<td></td>
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<tr>
<td><code>bicg</code></td>
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<td><code>bicgstab</code></td>
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<tr>
<td><code>ceil</code></td>
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<tr>
<td><code>classUnderlying</code></td>
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<td><code>conj</code></td>
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<td><code>ctranspose</code></td>
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<td><code>deg2rad</code></td>
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<tr>
<td><code>end</code></td>
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<td><code>expm1</code></td>
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<td><code>find</code></td>
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<td><code>fix</code></td>
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<td><code>floor</code></td>
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<td><code>full</code></td>
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<td><code>gmres</code></td>
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<tr>
<td><code>gpuArray.speye</code></td>
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<tr>
<td><code>imag</code></td>
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<td><code>isaUnderlying</code></td>
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<td><code>isdiag</code></td>
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<td><code>log1p</code></td>
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<td><code>rad2deg</code></td>
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<td><code>real</code></td>
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<td><code>realsqrt</code></td>
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<td><code>sprandsym</code></td>
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<td><code>sqrt</code></td>
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<td><code>sum</code></td>
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<td><code>uminus</code></td>
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<td><code>uplus</code></td>
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</tbody>
</table>

You can create a sparse gpuArray either by calling `sparse` with a gpuArray input, or by calling `gpuArray` with a sparse input. For example,

```matlab
x = [0 1 0 0 0; 0 0 0 0 1]
  0    1    0    0    0
  0    0    0    0    1
s = sparse(x)
  (1,2)  1
  (2,5)  1
```

```matlab
g = gpuArray(s);  % g is a sparse gpuArray
gt = transpose(g); % gt is a sparse gpuArray
f = full(gt)       % f is a full gpuArray
```
Considerations for Complex Numbers

If the output of a function running on the GPU could potentially be complex, you must explicitly specify its input arguments as complex. This applies to gpuArray or to functions called in code run by arrayfun.

For example, if creating a gpuArray which might have negative elements, use \( G = \text{gpuArray}(\text{complex}(p)) \), then you can successfully execute \( \text{sqrt}(G) \).

Or, within a function passed to arrayfun, if \( x \) is a vector of real numbers, and some elements have negative values, \( \text{sqrt}(x) \) will generate an error; instead you should call \( \text{sqrt(\text{complex}(x))} \).

The following table lists the functions that might return complex data, along with the input range over which the output remains real.

<table>
<thead>
<tr>
<th>Function</th>
<th>Input Range for Real Output</th>
</tr>
</thead>
<tbody>
<tr>
<td>acos(x)</td>
<td>abs(x) &lt;= 1</td>
</tr>
<tr>
<td>acosh(x)</td>
<td>x &gt;= 1</td>
</tr>
<tr>
<td>acoth(x)</td>
<td>abs(x) &gt;= 1</td>
</tr>
<tr>
<td>acsc(x)</td>
<td>abs(x) &gt;= 1</td>
</tr>
<tr>
<td>asec(x)</td>
<td>abs(x) &gt;= 1</td>
</tr>
<tr>
<td>asech(x)</td>
<td>0 &lt;= x &lt;= 1</td>
</tr>
<tr>
<td>asin(x)</td>
<td>abs(x) &lt;= 1</td>
</tr>
<tr>
<td>atanh</td>
<td>abs(x) &lt;= 1</td>
</tr>
<tr>
<td>log(x)</td>
<td>x &gt;= 0</td>
</tr>
<tr>
<td>log1p(x)</td>
<td>x &gt;= -1</td>
</tr>
<tr>
<td>log10(x)</td>
<td>x &gt;= 0</td>
</tr>
<tr>
<td>log2(x)</td>
<td>x &gt;= 0</td>
</tr>
<tr>
<td>power(x,y)</td>
<td>x &gt;= 0</td>
</tr>
<tr>
<td>Function</td>
<td>Input Range for Real Output</td>
</tr>
<tr>
<td>---------------</td>
<td>-----------------------------</td>
</tr>
<tr>
<td>reallog(x)</td>
<td>x &gt;= 0</td>
</tr>
<tr>
<td>realsqrt(x)</td>
<td>x &gt;= 0</td>
</tr>
<tr>
<td>sqrt(x)</td>
<td>x &gt;= 0</td>
</tr>
</tbody>
</table>

**Acknowledgments**

MAGMA is a library of linear algebra routines that take advantage of GPU acceleration. Linear algebra functions implemented for gpuArrays in Parallel Computing Toolbox leverage MAGMA to achieve high performance and accuracy.

**See Also**

“Identify and Select a GPU Device” on page 9-19 | “GPU Capabilities and Performance” on page 9-2 | “Establish Arrays on a GPU” on page 9-3 | MAGMA
Run Element-wise MATLAB Code on GPU

In this section...

| “MATLAB Code vs. gpuArray Objects” on page 9-14 |
| “Run Your MATLAB Functions on a GPU” on page 9-14 |
| “Example: Run Your MATLAB Code” on page 9-15 |
| “Supported MATLAB Code” on page 9-15 |

MATLAB Code vs. gpuArray Objects

You have options for performing MATLAB calculations on the GPU:

- You can transfer or create data on the GPU, and use the resulting gpuArray as input to enhanced built-in functions that support them. For more information and a list of functions that support gpuArray as inputs, see “Run Built-In Functions on a GPU” on page 9-8.
- You can run your own MATLAB function of element-wise operations on a GPU.

Your decision on which solution to adopt depends on whether the functions you require are enhanced to support gpuArray, and the performance impact of transferring data to/from the GPU.

Run Your MATLAB Functions on a GPU

To execute your MATLAB function on a GPU, call arrayfun or bsxfun with a function handle to the MATLAB function as the first input argument:

\[
\text{result} = \text{arrayfun}(@\text{myFunction}, \text{arg1}, \text{arg2});
\]

Subsequent arguments provide inputs to the MATLAB function. These input arguments can be workspace data or gpuArray. If any of the input arguments is a gpuArray, the function executes on the GPU and returns a gpuArray. (If none of the inputs is a gpuArray, then arrayfun and bsxfun execute in the CPU.)

**Note** arrayfun and bsxfun support only element-wise operations on a GPU.

See the arrayfun and bsxfun reference pages for descriptions of their available options.
Example: Run Your MATLAB Code

In this example, a small function applies correction data to an array of measurement data. The function defined in the file myCal.m is:

```matlab
function c = myCal(rawdata, gain, offst)
    c = (rawdata .* gain) + offst;
```

The function performs only element-wise operations when applying a gain factor and offset to each element of the rawdata array.

Create some nominal measurement:

```matlab
meas = ones(1000)*3; % 1000-by-1000 matrix
```

The function allows the gain and offset to be arrays of the same size as rawdata, so that unique corrections can be applied to individual measurements. In a typical situation, you might keep the correction data on the GPU so that you do not have to transfer it for each application:

```matlab
gn   = rand(1000,'gpuArray')/100 + 0.995;
offs = rand(1000,'gpuArray')/50  - 0.01;
```

Run your calibration function on the GPU:

```matlab
corrected = arrayfun(@myCal,meas,gn,offs);
```

This runs on the GPU because the input arguments gn and offs are already in GPU memory.

Retrieve the corrected results from the GPU to the MATLAB workspace:

```matlab
results = gather(corrected);
```

Supported MATLAB Code

The function you pass into arrayfun or bsxfun can contain the following built-in MATLAB functions and operators:
abs        double        log10         sinh
and        eps           log1p          sqrt
acos       eq            logical         tan
acosh      erf            lt             tanh
acot       erfc           max            times
acoth      erfcinv       min            true
acsc       erfcx          minus          uint8
acsch      erfinv        mod            uint16
asec       exp            NaN            uint32
asech      expml          ne             uint64
asin       false          not            xor
asinh      fix            or             
atan       floor          pi             
atan2      gamma          plus           +
atanh      gammaln        pow2          -
beta       ge             power         .* 
betain     gt             rand          ./ 
bitand     hypot          randi         .\ 
bitor      imag           randn         .^ 
bitget     Inf            rdivide        ==
bitor      int8           real           ~=
bitset     int16          reallog       <
bitshift   int32          reallmax      <=
bitxor     int64          realmin       >
ceil       intmax         reallpow      >=
complex    intmin         realsqrt      &
conj       isfinite       rem            |
cos        isnan          sec            &&
cosh       isnan          sec            &
cot        ldivide        sech           ||
coth       le             sign           
csc        log            sin
csch       log2           single

Scalar expansion versions of the following:

*    
/    \
^    

Branching instructions:

break
continue
else
elseif
for
if
return
while

Generate Random Numbers on a GPU

The function you pass to arrayfun or bsxfun for execution on a GPU can contain the random number generator functions rand, randi, and randn. However, the GPU does not support the complete functionality that MATLAB does.

arrayfun and bsxfun support the following functions for random matrix generation on the GPU:
You do not specify the array size for random generation. Instead, the number of generated random values is determined by the sizes of the input variables to your function. In effect, there will be enough random number elements to satisfy the needs of any input or output variables.

For example, suppose your function myfun.m contains the following code that includes generating and using the random matrix R:

```matlab
function Y = myfun(X)
    R = rand();
    Y = R.*X;
end
```

If you use arrayfun to run this function with an input variable that is a gpuArray, the function runs on the GPU, where the number of random elements for R is determined by the size of X, so you do not need to specify it. The following code passes the gpuArray matrix G to myfun on the GPU.

```matlab
G = 2*ones(4,4,'gpuArray')
H = arrayfun(@myfun, G)
```

Because G is a 4-by-4 gpuArray, myfun generates 16 random value scalar elements for R, one for each calculation with an element of G.

Random number generation by arrayfun and bsxfun on the GPU uses the same global stream as gpuArray random generation as described in “Control the Random Stream for gpuArray” on page 9-5. For more information about generating random numbers on a GPU, and a comparison between GPU and CPU generation, see “Control Random Number Streams” on page 6-46. For an example that shows performance comparisons for different random generators, see Generating Random Numbers on a GPU.
**Tips and Restrictions**

The following limitations apply to the code within the function that `arrayfun` or `bsxfun` is evaluating on a GPU.

- Like `arrayfun` in MATLAB, matrix exponential power, multiplication, and division (^, *, /, \) perform element-wise calculations only.
- Operations that change the size or shape of the input or output arrays (cat, reshape, etc.), are not supported.
- When generating random matrices with `rand`, `randi`, or `randn`, you do not need to specify the matrix size, and each element of the matrix has its own random stream. See “Generate Random Numbers on a GPU” on page 9-16.
- `arrayfun` and `bsxfun` support read-only indexing (subsref) and access to variables of the parent (outer) function workspace from within nested functions, i.e., those variables that exist in the function before the `arrayfun/bsxfun` evaluation on the GPU. Assignment or `subsasgn` indexing of these variables from within the nested function is not supported. For an example of the supported usage see Stencil Operations on a GPU
- Anonymous functions do not have access to their parent function workspace.
- Overloading the supported functions is not allowed.
- The code cannot call scripts.
- There is no ans variable to hold unassigned computation results. Make sure to explicitly assign to variables the results of all calculations that you need to access.
- The following language features are not supported: persistent or global variables, `parfor`, `spmd`, `switch`, and `try/catch`.
- P-code files cannot contain a call to `arrayfun` or `bsxfun` with `gpuArray` data.
Identify and Select a GPU Device

In this section...

“Example: Select a GPU” on page 9-19
“Example: Print message when a GPU is selected” on page 9-20

If you have only one GPU in your computer, that GPU is the default. If you have more than one GPU device in your computer, you can use the following functions to identify and select which device you want to use:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>gpuDeviceCount</td>
<td>The number of GPU devices in your computer</td>
</tr>
<tr>
<td>gpuDevice</td>
<td>Select which device to use, or see which device is selected and view its properties</td>
</tr>
</tbody>
</table>

You can also find out whenever a GPU device is selected, deselected or reset, using GPUDeviceManager:

<table>
<thead>
<tr>
<th>Class</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPUDeviceManager</td>
<td>Manager for GPU Devices</td>
</tr>
</tbody>
</table>

After you have identified and selected your GPU, you can use it, for example, to “Run Built-In Functions on a GPU” on page 9-8.

Example: Select a GPU

This example shows how to identify and select a GPU for your computations.

1. Determine how many GPU devices are in your computer:

   ```matlab
gpuDeviceCount
   ``

2. With two devices, the first is the default. You can examine its properties to determine if that is the one you want to use:

   ```matlab
d = gpuDevice
```
CUDA Device with properties:

Name: 'Tesla K20c'
Index: 1
ComputeCapability: '3.5'
SupportsDouble: 1
DriverVersion: 7.5000
ToolkitVersion: 7.5000
MaxThreadsPerBlock: 1024
MaxShmemPerBlock: 49152
MaxThreadBlockSize: [1024 1024 64]
MaxGridSize: [2.1475e+09 65535 65535]
SIMDWidth: 32
TotalMemory: 5.0330e+09
AvailableMemory: 4.7858e+09
MultiprocessorCount: 13
ClockRateKHz: 705500
ComputeMode: 'Default'
GPUOverlapsTransfers: 1
KernelExecutionTimeout: 0
CanMapHostMemory: 1
DeviceSupported: 1
DeviceSelected: 1

If this is the device you want to use, you can proceed.

3 To use another device, call `gpuDevice` with the index of the other device, and view its properties to verify that it is the one you want. For example, this step chooses and views the second device (indexing is 1-based):

```matlab
gpuDevice(2)
```

**Note** If you select a device that does not have sufficient compute capability, you are warned that you cannot use that device.

---

**Example: Print message when a GPU is selected**

This example shows how to print out messages when the device is being selected or deselected:

1 First, ensure that you have no `gpuDevice` selected before you start:

```matlab
gpuDevice([])
```
Deselecting: 1

2 Print out messages when the device is being selected:

```matlab
mgr = parallel.gpu.GPUDeviceManager.instance();
l1 = event.listener(mgr, 'DeviceSelected', @(src, data) fprintf('Selected: %d\n', data.DeviceIndex));
l2 = event.listener(mgr, 'DeviceDeselecting', @(src, data) fprintf('Deselecting: %d\n', data.DeviceIndex));
a1 = gpuArray(1:10);
Selected: 1
```

Deselecting: 1

3 Print out messages when the device is being deselected:

```matlab
reset(mgr.SelectedDevice)
```

Deselecting: 1
Selected: 1

**Note** If you select a device that does not have sufficient compute capability, you are warned that you cannot use that device.

**See Also**

“Run Built-In Functions on a GPU” on page 9-8 | “GPU Capabilities and Performance” on page 9-2 | “Establish Arrays on a GPU” on page 9-3 | “Measure and Improve GPU Performance” on page 9-37
Run CUDA or PTX Code on GPU

Overview

This topic explains how to create an executable kernel from CU or PTX (parallel thread execution) files, and run that kernel on a GPU from MATLAB. The kernel is represented in MATLAB by a CUDAKernel object, which can operate on MATLAB array or gpuArray variables.

The following steps describe the CUDAKernel general workflow:

1. Use compiled PTX code to create a CUDAKernel object, which contains the GPU executable code.
2. Set properties on the CUDAKernel object to control its execution on the GPU.
3. Call feval on the CUDAKernel with the required inputs, to run the kernel on the GPU.

MATLAB code that follows these steps might look something like this:

```matlab
% 1. Create CUDAKernel object.
k = parallel.gpu.CUDAKernel('myfun.ptx','myfun.cu','entryPt1');

% 2. Set object properties.
k.GridSize = [8 1];
k.ThreadBlockSize = [16 1];

% 3. Call feval with defined inputs.
g1 = gpuArray(in1); % Input gpuArray.
g2 = gpuArray(in2); % Input gpuArray.
result = feval(k,g1,g2);
```

The following sections provide details of these commands and workflow steps.
Create a CUDAKernel Object

- “Compile a PTX File from a CU File” on page 9-23
- “Construct CUDAKernel Object with CU File Input” on page 9-23
- “Construct CUDAKernel Object with C Prototype Input” on page 9-23
- “Supported Data Types” on page 9-24
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- “Specify Number of Threads” on page 9-28

Compile a PTX File from a CU File

If you have a CU file you want to execute on the GPU, you must first compile it to create a PTX file. One way to do this is with the `nvcc` compiler in the NVIDIA® CUDA® Toolkit. For example, if your CU file is called `myfun.cu`, you can create a compiled PTX file with the shell command:

```
nvcc -ptx myfun.cu
```

This generates the file named `myfun.ptx`.

Construct CUDAKernel Object with CU File Input

With a .cu file and a .ptx file you can create a CUDAKernel object in MATLAB that you can then use to evaluate the kernel:

```matlab
k = parallel.gpu.CUDAKernel('myfun.ptx','myfun.cu');
```

**Note** You cannot save or load CUDAKernel objects.

Construct CUDAKernel Object with C Prototype Input

If you do not have the CU file corresponding to your PTX file, you can specify the C prototype for your C kernel instead of the CU file. For example:

```matlab
k = parallel.gpu.CUDAKernel('myfun.ptx','float *, const float *, float');
```
Another use for C prototype input is when your source code uses an unrecognized renaming of a supported data type. (See the supported types below.) Suppose your kernel comprises the following code.

```c
typedef float ArgType;
__global__ void add3( ArgType * v1, const ArgType * v2 )
{
    int idx = threadIdx.x;
    v1[idx] += v2[idx];
}
```

ArgType itself is not recognized as a supported data type, so the CU file that includes it cannot be directly used as input when creating the CUDAKernel object in MATLAB. However, the supported input types to the add3 kernel can be specified as C prototype input to the CUDAKernel constructor. For example:

```matlab
k = parallel.gpu.CUDAKernel('test.ptx','float *, const float *','add3');
```

**Supported Data Types**

The supported C/C++ standard data types are listed in the following table.

<table>
<thead>
<tr>
<th>Float Types</th>
<th>Integer Types</th>
<th>Boolean and Character Types</th>
</tr>
</thead>
<tbody>
<tr>
<td>double, double2</td>
<td>short, unsigned short, short2, ushort2</td>
<td>bool</td>
</tr>
<tr>
<td>float, float2</td>
<td>int, unsigned int, int2, uint2</td>
<td>char, unsigned char, char2, uchar2</td>
</tr>
<tr>
<td></td>
<td>long, unsigned long, long2, ulong2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>long long, unsigned long long, longlong2, ulonglong2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>ptrdiff_t, size_t</td>
<td></td>
</tr>
</tbody>
</table>

Also, the following integer types are supported when you include the tmwtypes.h header file in your program.
### Integer Types

<table>
<thead>
<tr>
<th>int8_T, int16_T, int32_T, int64_T</th>
</tr>
</thead>
<tbody>
<tr>
<td>uint8_T, uint16_T, uint32_T, uint64_T</td>
</tr>
</tbody>
</table>

The header file is shipped as `matlabroot/extern/include/tmwtypes.h`. You include the file in your program with the line:

```
#include "tmwtypes.h"
```

### Argument Restrictions

All inputs can be scalars or pointers, and can be labeled `const`.

The C declaration of a kernel is always of the form:

```c
__global__ void aKernel(inputs ...)
```

- The kernel must return nothing, and operate only on its input arguments (scalars or pointers).
- A kernel is unable to allocate any form of memory, so all outputs must be pre-allocated before the kernel is executed. Therefore, the sizes of all outputs must be known before you run the kernel.
- In principle, all pointers passed into the kernel that are not `const` could contain output data, since the many threads of the kernel could modify that data.

When translating the definition of a kernel in C into MATLAB:

- All scalar inputs in C (`double`, `float`, `int`, etc.) must be scalars in MATLAB, or scalar (i.e., single-element) `gpuArray` variables.
- All `const` pointer inputs in C (`const double *`, etc.) can be scalars or matrices in MATLAB. They are cast to the correct type, copied onto the device, and a pointer to the first element is passed to the kernel. No information about the original size is passed to the kernel. It is as though the kernel has directly received the result of `mxGetData` on an `mxArray`.
- All nonconstant pointer inputs in C are transferred to the kernel exactly as nonconstant pointers. However, because a nonconstant pointer could be changed by the kernel, this will be considered as an output from the kernel.
• Inputs from MATLAB workspace scalars and arrays are cast into the requested type and then passed to the kernel. However, gpuArray inputs are not automatically cast, so their type and complexity must exactly match those expected.

These rules have some implications. The most notable is that every output from a kernel must necessarily also be an input to the kernel, since the input allows the user to define the size of the output (which follows from being unable to allocate memory on the GPU).

**CUDAKernel Object Properties**

When you create a kernel object without a terminating semicolon, or when you type the object variable at the command line, MATLAB displays the kernel object properties. For example:

```matlab
k = parallel.gpu.CUDAKernel('conv.ptx','conv.cu')
```

```
k =
    parallel.gpu.CUDAKernel handle
    Package: parallel.gpu

    Properties:
      ThreadBlockSize: [1 1 1]
      MaxThreadsPerBlock: 512
      GridSize: [1 1 1]
      SharedMemorySize: 0
      EntryPoint: '_Z8theEntryPf'
      MaxNumLHSArguments: 1
      NumRHSArguments: 2
      ArgumentTypes: {'in single vector'  'inout single vector'}
```

The properties of a kernel object control some of its execution behavior. Use dot notation to alter those properties that can be changed.

For a descriptions of the object properties, see the `CUDAKernel` object reference page. A typical reason for modifying the settable properties is to specify the number of threads, as described below.

**Specify Entry Points**

If your PTX file contains multiple entry points, you can identify the particular kernel in `myfun.ptx` that you want the kernel object `k` to refer to:

```matlab
k = parallel.gpu.CUDAKernel('myfun.ptx','myfun.cu','myKernel1');
```
A single PTX file can contain multiple entry points to different kernels. Each of these entry points has a unique name. These names are generally mangled (as in C++ mangling). However, when generated by *nvcc* the PTX name always contains the original function name from the CU file. For example, if the CU file defines the kernel function as

```c
__global__ void simplestKernelEver(float * x, float val)
```

then the PTX code contains an entry that might be called

```c
_Z18simplestKernelEverPff.
```

When you have multiple entry points, specify the entry name for the particular kernel when calling *CUDAKernel* to generate your kernel.

**Note** The *CUDAKernel* function searches for your entry name in the PTX file, and matches on any substring occurrences. Therefore, you should not name any of your entries as substrings of any others.

You might not have control over the original entry names, in which case you must be aware of the unique mangled derived for each. For example, consider the following function template.

```c
template<typename T>
__global__ void add4(T * v1, const T * v2)
{
    int idx = threadIdx.x;
    v1[idx] += v2[idx];
}
```

When the template is expanded out for float and double, it results in two entry points, both of which contain the substring *add4*.

```c
template __global__ void add4<float>(float *, const float *);
template __global__ void add4<double>(double *, const double *);
```

The PTX has corresponding entries:

```c
_Z4add4IfEvPT_PKSO_
_Z4add4IdEvPT_PKSO_
```

Use entry point *add4If* for the float version, and *add4Id* for the double version.
Specify Number of Threads

You specify the number of computational threads for your CUDAKernel by setting two of its object properties:

- **GridSize** — A vector of three elements, the product of which determines the number of blocks.
- **ThreadBlockSize** — A vector of three elements, the product of which determines the number of threads per block. (Note that the product cannot exceed the value of the property `MaxThreadsPerBlock`.)

The default value for both of these properties is `[1 1 1]`, but suppose you want to use 500 threads to run element-wise operations on vectors of 500 elements in parallel. A simple way to achieve this is to create your CUDAKernel and set its properties accordingly:

```matlab
k = parallel.gpu.CUDAKernel('myfun.ptx','myfun.cu');
k.ThreadBlockSize = [500,1,1];
```

Generally, you set the grid and thread block sizes based on the sizes of your inputs. For information on thread hierarchy, and multiple-dimension grids and blocks, see the NVIDIA CUDA C Programming Guide.

Run a CUDAKernel

- “Use Workspace Variables” on page 9-28
- “Use gpuArray Variables” on page 9-29
- “Determine Input and Output Correspondence” on page 9-29

Use the `feval` function to evaluate a CUDAKernel on the GPU. The following examples show how to execute a kernel using MATLAB workspace variables and gpuArray variables.

Use Workspace Variables

Assume that you have already written some kernels in a native language and want to use them in MATLAB to execute on the GPU. You have a kernel that does a convolution on two vectors; load and run it with two random input vectors:
k = parallel.gpu.CUDAKernel('conv.ptx','conv.cu');

result = feval(k,rand(100,1),rand(100,1));

Even if the inputs are constants or variables for MATLAB workspace data, the output is gpuArray.

Use gpuArray Variables

It might be more efficient to use gpuArray objects as input when running a kernel:

k = parallel.gpu.CUDAKernel('conv.ptx','conv.cu');

i1 = gpuArray(rand(100,1,'single'));
i2 = gpuArray(rand(100,1,'single'));

result1 = feval(k,i1,i2);

Because the output is a gpuArray, you can now perform other operations using this input or output data without further transfers between the MATLAB workspace and the GPU. When all your GPU computations are complete, gather your final result data into the MATLAB workspace:

result2 = feval(k,i1,i2);

r1 = gather(result1);
r2 = gather(result2);

Determine Input and Output Correspondence

When calling \([\text{out1, out2}] = \text{feval(kernel, in1, in2, in3)}, \text{the inputs in1, in2, and in3 correspond to each of the input arguments to the C function within your CU file. The outputs out1 and out2 store the values of the first and second non-const pointer input arguments to the C function after the C kernel has been executed.}

For example, if the C kernel within a CU file has the following signature:

```c
void reallySimple( float * pInOut, float c )
```

the corresponding kernel object (k) in MATLAB has the following properties:

MaxNumLHSArguments: 1
NumRHSArguments: 2
ArgumentTypes: {'inout single vector' 'in single scalar'}
Therefore, to use the kernel object from this code with `feval`, you need to provide `feval` two input arguments (in addition to the kernel object), and you can use one output argument:

\[ y = \text{feval}(k,x1,x2) \]

The input values `x1` and `x2` correspond to `pInOut` and `c` in the C function prototype. The output argument `y` corresponds to the value of `pInOut` in the C function prototype after the C kernel has executed.

The following is a slightly more complicated example that shows a combination of const and non-const pointers:

```c
void moreComplicated( const float * pIn, float * pInOut1, float * pInOut2 )
```

The corresponding kernel object in MATLAB then has the properties:

```plaintext
MaxNumLHSArguments: 2
NumRHSArguments: 3
ArgumentTypes: {'in single vector' 'inout single vector' 'inout single vector'}
```

You can use `feval` on this code’s kernel (`k`) with the syntax:

\[ [y1,y2] = \text{feval}(k,x1,x2,x3) \]

The three input arguments `x1`, `x2`, and `x3`, correspond to the three arguments that are passed into the C function. The output arguments `y1` and `y2`, correspond to the values of `pInOut1` and `pInOut2` after the C kernel has executed.

**Complete Kernel Workflow**

- “Add Two Numbers” on page 9-30
- “Add Two Vectors” on page 9-31
- “Example with CU and PTX Files” on page 9-32

**Add Two Numbers**

This example adds two doubles together in the GPU. You should have the NVIDIA CUDA Toolkit installed, and have CUDA-capable drivers for your device.

1. The CU code to do this is as follows.

   ```c
   __global__ void add1( double * pi, double c )
   ```
*\text{pi} += c;\)

The directive \texttt{__global__} indicates that this is an entry point to a kernel. The code uses a pointer to send out the result in \texttt{pi}, which is both an input and an output. Put this code in a file called \texttt{test.cu} in the current directory.

2 Compile the CU code at the shell command line to generate a PTX file called \texttt{test.ptx}.

\texttt{nvcc -ptx test.cu}

3 Create the kernel in MATLAB. Currently this PTX file only has one entry so you do not need to specify it. If you were to put more kernels in, you would specify \texttt{add1} as the entry.

\texttt{k = parallel.gpu.CUDAKernel('test.ptx','test.cu');}

4 Run the kernel with two numeric inputs. By default, a kernel runs on one thread.

\texttt{result = feval(k,2,3)}

\texttt{result = 5}

\textbf{Add Two Vectors}

This example extends the previous one to add two vectors together. For simplicity, assume that there are exactly the same number of threads as elements in the vectors and that there is only one thread block.

1 The CU code is slightly different from the last example. Both inputs are pointers, and one is constant because you are not changing it. Each thread will simply add the elements at its thread index. The thread index must work out which element this thread should add. (Getting these thread- and block-specific values is a very common pattern in CUDA programming.)

\texttt{__global__ void add2( double * v1, const double * v2 )\}
\texttt{\{\}
\texttt{int idx = threadIdx.x;\}
\texttt{v1[idx] += v2[idx];\}
\texttt{\}}

Save this code in the file \texttt{test.cu}.
2 Compile as before using `nvcc`.

    nvcc -ptx test.cu

3 If this code was put in the same CU file along with the code of the first example, you need to specify the entry point name this time to distinguish it.

    k = parallel.gpu.CUDAKernel('test.ptx','test.cu','add2');

4 Before you run the kernel, set the number of threads correctly for the vectors you want to add.

    N = 128;
    k.ThreadBlockSize = N;
    in1 = ones(N,1,'gpuArray');
    in2 = ones(N,1,'gpuArray');
    result = feval(k,in1,in2);

Example with CU and PTX Files

For an example that shows how to work with CUDA, and provides CU and PTX files for you to experiment with, see Illustrating Three Approaches to GPU Computing: The Mandelbrot Set.
Run MEX-Functions Containing CUDA Code

Write a MEX-File Containing CUDA Code

As with any MEX-files, those containing CUDA code have a single entry point, known as \texttt{mexFunction}. The MEX-function contains the host-side code that interacts with \texttt{gpuArray} objects from MATLAB and launches the CUDA code. The CUDA code in the MEX-file must conform to the CUDA runtime API.

You should call the function \texttt{mxInitGPU} at the entry to your MEX-file. This ensures that the GPU device is properly initialized and known to MATLAB.

The interface you use to write a MEX-file for \texttt{gpuArray} objects is different from the MEX interface for standard MATLAB arrays.

You can see an example of a MEX-file containing CUDA code at:

\texttt{matlabroot/toolbox/distcomp/gpu/extern/src/mex/mexGPUExample.cu}

This file contains the following CUDA device function:

\begin{verbatim}
void __global__ TimesTwo(double const * const A, double * const B, int const N)
{
    int i = blockDim.x * blockIdx.x + threadIdx.x;
    if (i < N)
        B[i] = 2.0 * A[i];
}
\end{verbatim}

It contains the following lines to determine the array size and launch a grid of the proper size:
N = (int)(mxGPUGetNumberOfElements(A));
blocksPerGrid = (N + threadsPerBlock - 1) / threadsPerBlock;
TimesTwo<<<blocksPerGrid, threadsPerBlock>>>(d_A, d_B, N);

Run the Resulting MEX-Functions

The MEX-function in this example multiplies every element in the input array by 2 to get the values in the output array. To test it, start with a gpuArray in which every element is 1:

```matlab
x = ones(4,4,'gpuArray');
y = mexGPUExample(x)
```

```
y =
 2 2 2 2
 2 2 2 2
 2 2 2 2
 2 2 2 2
```

Both the input and output arrays are gpuArray objects:

```matlab
disp(['class(x) = ',class(x),', class(y) = ',class(y)])
```

```
class(x) = gpuArray, class(y) = gpuArray
```

Comparison to a CUDA Kernel

Parallel Computing Toolbox also supports CUDAKernel objects that can be used to integrate CUDA code with MATLAB. Consider the following when choosing the MEX-file approach versus the CUDAKernel approach:

- MEX-files can interact with host-side libraries, such as the NVIDIA Performance Primitives (NPP) or CUFFT libraries, and can also contain calls from the host to functions in the CUDA runtime library.
- MEX-files can analyze the size of the input and allocate memory of a different size, or launch grids of a different size, from C or C++ code. In comparison, MATLAB code that calls CUDAKernel objects must preallocate output memory and determine the grid size.
Access Complex Data

Complex data on a GPU device is stored in interleaved complex format. That is, for a complex gpuArray \( A \), the real and imaginary parts of element \( i \) are stored in consecutive addresses. MATLAB uses CUDA built-in vector types to store complex data on the device (see the NVIDIA CUDA C Programming Guide).

Depending on the needs of your kernel, you can cast the pointer to complex data either as the real type or as the built-in vector type. For example, in MATLAB, suppose you create a matrix:

\[
a = \text{complex}(\text{ones}(4,'gpuArray'),\text{ones}(4,'gpuArray'));
\]

If you pass a gpuArray to a MEX-function as the first argument (prhs[0]), then you can get a pointer to the complex data by using the calls:

\[
\text{mxGPUArray const * A} = \text{mxGPUCreateFromMxArray(prhs[0]);}
\text{mwSize numel_complex} = \text{mxGPUGetNumberOfElements(A);}
\text{double2 * d_A} = (\text{double2 const *})(\text{mxGPUGetDataReadOnly(A)}); 
\]

To treat the array as a real double-precision array of twice the length, you could do it this way:

\[
\text{mxGPUArray const * A} = \text{mxGPUCreateFromMxArray(prhs[0]);}
\text{mwSize numel_real} = 2*\text{mxGPUGetNumberOfElements(A);}
\text{double * d_A} = (\text{double const *})(\text{mxGPUGetDataReadOnly(A)}); 
\]

Various functions exist to convert data between complex and real formats on the GPU. These operations require a copy to interleave the data. The function \text{mxGPUCreateComplexGPUArray} takes two real \text{mxGPUArrays} and interleaves their elements to produce a single complex \text{mxGPUArray} of the same length. The functions \text{mxGPUCopyReal} and \text{mxGPUCopyImag} each copy either the real or the imaginary elements into a new real \text{mxGPUArray}. (There is no equivalent of the \text{mxGetImagData} function for \text{mxGPUArray} objects.)

Compile a GPU MEX-File

To compile CUDA code you must have installed the CUDA toolkit version consistent with the \text{ToolkitVersion} property of the \text{GPUDevice} object.

Use the \text{mexcuda} command in MATLAB to compile a MEX-file containing the CUDA code. You can compile the example file using the command:
mexcuda mexGPUExample.cu

If `mexcuda` has trouble locating the NVIDIA compiler (`nvcc`), it might be installed in a non-default location. You can specify the location of `nvcc` on your system by storing it in the environment variable `MW_NVCC_PATH`. You can set this variable using the MATLAB `setenv` command. For example,

```matlab
setenv('MW_NVCC_PATH','/usr/local/CUDA/bin')
```

Only a subset of Visual Studio® compilers is supported for `mexcuda`. For details, consult the NVIDIA toolkit documentation.
Measure and Improve GPU Performance

Getting Started with GPU Benchmarking

You can use various benchmark tests in MATLAB to measure the performance of your GPU:

- Use `gpuBench` in MATLAB Central File Exchange to do various tests, including both memory and compute intensive card tasks in both single and double precision. Compare the performance of a display card with a compute card. For more information, see http://www.mathworks.com/matlabcentral/fileexchange/34080-gpubench.

- Use the `paralleldemo_gpu_bench` script in “Measuring GPU Performance” to obtain information on your PCI bus speed, GPU memory read/write and peak calculation performances for double precision matrix calculations.

Improve Performance Using Single Precision Calculations

You can improve the performance of your GPU by doing your calculations in single precision instead of double precision. In CPU computations, on the other hand, you do not get this improvement when switching from double to single precision. The reason is that most GPU cards are designed for graphic display, demanding high single precision performance.

Typical examples of calculations suitable for single-precision computation on the GPU include image processing and machine learning, see e.g. https://www.mathworks.com/deep-learning-in-the-cloud-with-matlab-white-paper. However, other types of calculations, such as linear algebra problems, typically require double precision processing.

You can get a performance improvement of up to a factor of 50 for single compared to double precision calculations, depending on the GPU card and total number of cores. High end compute cards typically show a smaller improvement. You can determine the performance improvement of your particular GPU by using `gpuBench`, see http://www.mathworks.com/matlabcentral/fileexchange/34080-gpubench.

For a comprehensive performance overview of NVIDIA GPU cards, see https://en.wikipedia.org/wiki/List_of_Nvidia_graphics_processing_units. You can calculate the performance improvement factor between single precision and double precision as follows:
• Find the GPU on the wiki page above.
• Get the stated single and double precision performance values from the table. If there is no double precision GFLOPS value, assume the ratio is 24-32x slower for double precision.
• Divide the stated single precision GFLOPS value by the double precision GFLOPS value.

**Note** If you have a mobile graphics card in your laptop, you can use this card for GPU computing. However, the laptop GPU is likely to be much less powerful than the desktop machine equivalent and so performance is reduced.

**Basic Workflow for Improving Performance**

The purpose of GPU computing in MATLAB is to speed up your applications. This topic discusses fundamental concepts and practices that can help you achieve better performance on the GPU, such as the configuration of the GPU hardware and best practices within your code. It discusses the trade-off between implementation difficulty and performance, and describes the criteria you might use to choose between using gpuArray functions, `arrayfun`, MEX-files, or CUDA kernels. Finally, it describes how to accurately measure performance on the GPU.

When converting MATLAB code to run on the GPU, it is best to start with MATLAB code that already performs well. While the GPU and CPU have different performance characteristics, the general guidelines for writing good MATLAB code also help you write good MATLAB code for the GPU. The first step is almost always to profile your CPU code. The lines of code that the profiler shows taking the most time on the CPU will likely be ones that you must concentrate on when you code for the GPU.

It is easiest to start converting your code using MATLAB built-in functions that support gpuArray data. These functions take gpuArray inputs, perform calculations on the GPU, and return gpuArray outputs. A list of the MATLAB functions that support gpuArray data is found in “Run Built-In Functions on a GPU” on page 9-8. In general these functions support the same arguments and data types as standard MATLAB functions that are calculated in the CPU. Any limitations in these functions for gpuArrays are described in their command-line help (e.g., `help gpuArray/qr`).

If all the functions that you want to use are supported on the GPU, running code on the GPU may be as simple as calling `gpuArray` to transfer input data to the GPU, and
calling \texttt{gather} to retrieve the output data from the GPU when finished. In many cases, you might need to vectorize your code, replacing looped scalar operations with MATLAB matrix and vector operations. While vectorizing is generally a good practice on the CPU, it is usually critical for achieving high performance on the GPU. For more information, see “Vectorize for Improved GPU Performance” on page 9-42.

**Advanced Tools for Improving Performance**

It is possible that even after converting inputs to \texttt{gpuArrays} and vectorizing your code, there are operations in your algorithm that are either not built-in functions, or that are not fast enough to meet your application’s requirements. In such situations you have three main options: use \texttt{arrayfun} to precompile element-wise parts of your application, make use of GPU library functions, or write a custom CUDA kernel.

If you have a purely element-wise function, you can improve its performance by calling it with \texttt{arrayfun}. The \texttt{arrayfun} function on the GPU turns an element-wise MATLAB function into a custom CUDA kernel, thus reducing the overhead of performing the operation. Often, there is a subset of your application that can be used with \texttt{arrayfun} even if the entire application cannot be. The example Improve Performance of Element-wise MATLAB Functions on the GPU using \texttt{ARRAYFUN} shows the basic concepts of this approach; and the example Using \texttt{ARRAYFUN} for Monte-Carlo Simulations shows how this can be done in simulations for a finance application.

MATLAB provides an extensive library of GPU-enabled functions in Parallel Computing Toolbox, Image Processing Toolbox™, Signal Processing Toolbox™, and other products. However, there are many libraries of additional functions that do not have direct built-in analogs in MATLAB’s GPU support. Examples include the NVIDIA Performance Primitives library and the CURAND library, which are included in the CUDA toolkit that ships with MATLAB. If you need to call a function in one of these libraries, you can do so using the GPU MEX interface. This interface allows you to extract the pointers to the device data from MATLAB \texttt{gpuArrays} so that you can pass these pointers to GPU functions. You can convert the returned values into \texttt{gpuArrays} for return to MATLAB. For more information see “Run MEX-Functions Containing CUDA Code” on page 9-33.

Finally, you have the option of writing a custom CUDA kernel for the operation that you need. Such kernels can be directly integrated into MATLAB using the CUDAKernel object.

The example Illustrating Three Approaches to GPU Computing: The Mandelbrot Set shows how to implement a simple calculation using three of the approaches mentioned in
this section. This example begins with MATLAB code that is easily converted to run on the GPU, rewrites the code to use `arrayfun` for element-wise operations, and finally shows how to integrate a custom CUDA kernel for the same operation.

Alternately, you can write a CUDA kernel as part of a MEX-file and call it using the CUDA Runtime API inside the MEX-file. Either of these approaches might let you work with low-level features of the GPU, such as shared memory and texture memory, that are not directly available in MATLAB code. For more details, see the example Accessing Advanced CUDA Features Using MEX.

**Best Practices for Improving Performance**

**Hardware Configuration**

In general you can achieve the best performance when your GPU is dedicated to computing. It is usually not practical to use the same GPU device for both computations and graphics, because of the amount of memory taken up for problems of reasonable size and the constant use of the device by the system for graphics. If possible, obtain a separate device for graphics. Details of configuring your device for compute or graphics depend on the operating system and driver version.

On Windows systems, a GPU device can be in one of two modes: Windows Display Driver Model (WDDM) or Tesla Compute Cluster (TCC) mode. For best performance, any devices used for computing should be in TCC mode. Consult NVIDIA documentation for more details.

NVIDIA’s highest-performance compute devices, the Tesla line, support error correcting codes (ECC) when reading and writing GPU memory. The purpose of ECC is to correct for occasional bit-errors that occur normally when reading or writing dynamic memory. One technique to improve performance is to turn off ECC to increase the achievable memory bandwidth. While the hardware can be configured this way, MathWorks does not recommend this practice. The potential loss of accuracy due to silent errors can be more harmful than the performance benefit.

**MATLAB Coding Practices**

This topic describes general techniques that help you achieve better performance on the GPU. Some of these tips apply when writing MATLAB code for the CPU as well.

Data in MATLAB arrays is stored in column-major order. Therefore, it is beneficial to operate along the first or column dimension of your array. If one dimension of your data
is significantly longer than others, you might achieve better performance if you make that the first dimension. Similarly, if you frequently operate along a particular dimension, it is usually best to have it as the first dimension. In some cases, if consecutive operations target different dimensions of an array, it might be beneficial to transpose or permute the array between these operations.

GPUs achieve high performance by calculating many results in parallel. Thus, matrix and higher-dimensional array operations typically perform much better than operations on vectors or scalars. You can achieve better performance by rewriting your loops to make use of higher-dimensional operations. The process of revising loop-based, scalar-oriented code to use MATLAB matrix and vector operations is called vectorization. For more details, see “Using Vectorization” (MATLAB).

By default, all operations in MATLAB are performed in double-precision floating-point arithmetic. However, most operations support a variety of data types, including integer and single-precision floating-point. Today’s GPUs and CPUs typically have much higher throughput when performing single-precision operations, and single-precision floating-point data occupies less memory. If your application’s accuracy requirements allow the use of single-precision floating-point, it can greatly improve the performance of your MATLAB code.

The GPU sits at the end of a data transfer mechanism known as the PCI bus. While this bus is an efficient, high-bandwidth way to transfer data from the PC host memory to various extension cards, it is still much slower than the overall bandwidth to the global memory of the GPU device or of the CPU (for more details, see the example Measuring GPU Performance). In addition, transfers from the GPU device to MATLAB host memory cause MATLAB to wait for all pending operations on the device to complete before executing any other statements. This can significantly hurt the performance of your application. In general, you should limit the number of times you transfer data between the MATLAB workspace and the GPU. If you can transfer data to the GPU once at the start of your application, perform all the calculations you can on the GPU, and then transfer the results back into MATLAB at the end, that generally results in the best performance. Similarly, when possible it helps to create arrays directly on the GPU, using either the 'gpuArray' or the 'like' option for functions such as zeros (e.g., \( Z = \text{zeros}(__, \text{'gpuArray'}) \) or \( Z = \text{zeros}(N, \text{'like'}, g) \) for existing gpuArray \( g \)).

**Measure Performance on the GPU**

The best way to measure performance on the GPU is to use gputimeit. This function takes as input a function handle with no input arguments, and returns the measured
execution time of that function. It takes care of such benchmarking considerations as repeating the timed operation to get better resolution, executing the function before measurement to avoid initialization overhead, and subtracting out the overhead of the timing function. Also, \texttt{gputimeit} ensures that all operations on the GPU have completed before the final timing.

For example, consider measuring the time taken to compute the \texttt{lu} factorization of a random matrix \( A \) of size \( N \)-by-\( N \). You can do this by defining a function that does the \texttt{lu} factorization and passing the function handle to \texttt{gputimeit}:

\begin{verbatim}
A = rand(N,'gpuArray');
fh = @() lu(A);
gputimeit(fh,2);  % 2nd arg indicates number of outputs
\end{verbatim}

You can also measure performance with \texttt{tic} and \texttt{toc}. However, to get accurate timing on the GPU, you must wait for operations to complete before calling \texttt{toc}. There are two ways to do this. You can call \texttt{gather} on the final GPU output before calling \texttt{toc}: this forces all computations to complete before the time measurement is taken. Alternately, you can use the \texttt{wait} function with a \texttt{GPUDevice} object as its input. For example, if you wanted to measure the time taken to compute the \texttt{lu} factorization of matrix \( A \) using \texttt{tic}, \texttt{toc}, and \texttt{wait}, you can do it as follows:

\begin{verbatim}
gd = gpuDevice();
tic();
[l,u] = lu(A);
wait(gd);
tLU = toc();
\end{verbatim}

You can also use the MATLAB profiler to show how computation time is distributed in your GPU code. Note, that to accomplish timing measurements, the profiler runs each line of code independently, so it cannot account for overlapping (asynchronous) execution such as might occur during normal operation. For timing whole algorithms, you should use \texttt{tic} and \texttt{toc}, or \texttt{gputimeit}, as described above. Also, the profile might not yield correct results for user-defined MEX functions if they run asynchronously.

\section*{Vectorize for Improved GPU Performance}

This example shows you how to improve performance by running a function on the GPU instead of the CPU, and by vectorizing the calculations.

Consider a function that performs fast convolution on the columns of a matrix. Fast convolution, which is a common operation in signal processing applications, transforms
each column of data from the time domain to the frequency domain, multiplies it by the transform of a filter vector, transforms back to the time domain, and stores the result in an output matrix.

```matlab
function y = fastConvolution(data,filter)
    [m,n] = size(data);
    % Zero-pad filter to the column length of data, and transform
    filter_f = fft(filter,m);

    % Create an array of zeros of the same size and class as data
    y = zeros(m,n,'like',data);

    % Transform each column of data
    for ix = 1:n
        af = fft(data(:,ix));
        y(:,ix) = ifft(af .* filter_f);
    end
end
```

Execute this function in the CPU on data of a particular size, and measure the execution time using the MATLAB `timeit` function. The `timeit` function takes care of common benchmarking considerations, such as accounting for startup and overhead.

```matlab
a = complex(randn(4096,100),randn(4096,100));  % Data input
b = randn(16,1);                               % Filter input
c = fastConvolution(a,b);                      % Calculate output
ctime = timeit(@()fastConvolution(a,b));       % Measure CPU time
disp(['Execution time on CPU = ',num2str(ctime)]);
```

On a sample machine, this code displays the output:

```
Execution time on CPU = 0.019335
```

Now execute this function on the GPU. You can do this easily by changing the input data to be gpuArrays rather than normal MATLAB arrays. The 'like' syntax used when creating the output inside the function ensures that `y` will be a gpuArray if `data` is a gpuArray.

```matlab
ga = gpuArray(a);                              % Move array to GPU
gb = gpuArray(b);                              % Move filter to GPU
c = fastConvolution(ga,gb);                    % Calculate output
gtime = gputimeit(@()fastConvolution(ga,gb));  % Measure GPU time
gerr = max(max(abs(gather(gc)-c)));            % Calculate error
disp(['Execution time on GPU = ',num2str(gtime)]);
disp(['Maximum absolute error = ',num2str(gerr)]);
```

Measure and Improve GPU Performance
On the same machine, this code displays the output:

```matlab
Execution time on CPU = 0.019335
Execution time on GPU = 0.027235
Maximum absolute error = 1.1374e-14
```

Unfortunately, the GPU is slower than the CPU for this problem. The reason is that the for-loop is executing the FFT, multiplication, and inverse FFT operations on individual columns of length 4096. The best way to increase the performance is to vectorize the code, so that a single MATLAB function call performs more calculation. The FFT and IFFT operations are easy to vectorize: `fft(A)` computes the FFT of each column of a matrix `A`. You can perform a multiply of the filter with every column in a matrix at once using the MATLAB binary scalar expansion function `bsxfun`. The vectorized function looks like this:

```matlab
function y = fastConvolution_v2(data,filter)
m = size(data,1);
% Zero-pad filter to the length of data, and transform
filter_f = fft(filter,m);

% Transform each column of the input
af = fft(data);

% Multiply each column by filter and compute inverse transform
y = ifft(bsxfun(@times,af,filter_f));
end
```

Perform the same experiment using the vectorized function:

```matlab
a = complex(randn(4096,100),randn(4096,100));   % Data input
b = randn(16,1);                                % Filter input
c = fastConvolution_v2(a,b);                    % Calculate output
cctime = timeit(@()fastConvolution_v2(a,b));   % Measure CPU time
disp(['Execution time on CPU = ',num2str(ctime)]);

ga = gpuArray(a);                               % Move data to GPU
gb = gpuArray(b);                                % Move filter to GPU
gc = fastConvolution_v2(ga, gb);                % Calculate on GPU
gctime = gputimeit(@()fastConvolution_v2(ga,gb));% Measure GPU time
gerr = max(max(abs(gather(gc)-c)));             % Calculate error
disp(['Execution time on GPU = ',num2str(gctime)]);
disp(['Maximum absolute error = ',num2str(gerr)]);
```
Execution time on CPU = 0.010393
Execution time on GPU = 0.0020537
Maximum absolute error = 1.1374e-14

In conclusion, vectorizing the code helps both the CPU and GPU versions to run faster. However, vectorization helps the GPU version much more than the CPU. The improved CPU version is nearly twice as fast as the original; the improved GPU version is 13 times faster than the original. The GPU code went from being 40% slower than the CPU in the original version, to about five times faster in the revised version.

Troubleshooting GPUs

If you only have one GPU in your machine, then it is likely that your graphics card is also acting as your display card. In this case, your GPU is probably subject to timeout imposed by the operating system (OS). You can examine this for your GPU as follows:

gpuDevice

ans =
...

KernelExecutionTimeout: 1

If KernelExecutionTimeout = 1, then your GPU is subject to timeout imposed by the OS, ensuring that the OS is always able to print updates to the screen. If your GPU calculation takes too much time, then the operation is killed. In this case, you must restart MATLAB to resume GPU calculations successfully.

See Also

“GPU Capabilities and Performance” on page 9-2 | “Establish Arrays on a GPU” on page 9-3 | “Run Built-In Functions on a GPU” on page 9-8 | “Identify and Select a GPU Device” on page 9-19 | gpuDevice
Objects — Alphabetical List
codistributed

Access elements of arrays distributed among workers in parallel pool

Constructor

codistributed, codistributed.build

You can also create a codistributed array explicitly from spmd code or a communicating job task with any of several MATLAB functions.

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>eye(___,'codistributed')</td>
<td>Generates a codistributed identity matrix</td>
</tr>
<tr>
<td>rand(___,'codistributed')</td>
<td>Generates a codistributed uniformly distributed array</td>
</tr>
<tr>
<td>false(___,'codistributed')</td>
<td>Generates a codistributed logical false array</td>
</tr>
<tr>
<td>randi(___,'codistributed')</td>
<td>Generates a codistributed uniformly distributed integer array</td>
</tr>
<tr>
<td>Inf(___,'codistributed')</td>
<td>Generates a codistributed positive infinity array</td>
</tr>
<tr>
<td>randn(___,'codistributed')</td>
<td>Generates a codistributed normally distributed array</td>
</tr>
<tr>
<td>NaN(___,'codistributed')</td>
<td>Generates a codistributed NaN array</td>
</tr>
<tr>
<td>ones(___,'codistributed')</td>
<td>Generates a codistributed one array</td>
</tr>
<tr>
<td>true(___,'codistributed')</td>
<td>Generates a codistributed logical true array</td>
</tr>
<tr>
<td>zeros(___,'codistributed')</td>
<td>Generates a codistributed zero array</td>
</tr>
<tr>
<td>codistributed.cell</td>
<td>Creates a codistributed cell array</td>
</tr>
<tr>
<td>codistributed.spalloc</td>
<td>Allocates codistributed array space</td>
</tr>
<tr>
<td>codistributed.speye</td>
<td>Creates a codistributed identity matrix</td>
</tr>
<tr>
<td>codistributed.sprand</td>
<td>Creates a codistributed sparse random array</td>
</tr>
<tr>
<td>codistributed.sprandn</td>
<td>Creates a codistributed sparse normally distributed array</td>
</tr>
</tbody>
</table>

Description

Arrays partitioned among the workers in a pool, are accessible from the workers as codistributed array objects.

Codistributed arrays on workers that you create inside spmd statements or from within task functions of communicating jobs can be accessed as distributed arrays on the client.

Methods

The methods for codistributed arrays are too numerous to list here. Most resemble and behave the same as built-in MATLAB functions. See “Using MATLAB Functions on Distributed Arrays” on page 5-24.
Also among the methods there are several for examining the characteristics of the array itself. Most behave like the MATLAB functions of the same name:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>classUnderlying</td>
<td>Class (data type) of the elements in the array</td>
</tr>
<tr>
<td>iscodistributed</td>
<td>Indication if array is codistributed</td>
</tr>
<tr>
<td>isreal</td>
<td>Indication if array elements are real</td>
</tr>
<tr>
<td>length</td>
<td>Length of vector or largest array dimension</td>
</tr>
<tr>
<td>ndims</td>
<td>Number of dimensions in the array</td>
</tr>
<tr>
<td>size</td>
<td>Size of array dimensions</td>
</tr>
</tbody>
</table>

*Introduced in R2008b*
**codistributor1d**

1-D distribution scheme for codistributed array

**Constructor**

codistributor1d

**Description**

A codistributor1d object defines the 1-D distribution scheme for a codistributed array. The 1-D codistributor distributes arrays along a single specified dimension, the distribution dimension, in a noncyclic, partitioned manner.

For help on codistributor1d, including a list of links to individual help for its methods and properties, type

help codistributor1d

**Methods**

**Properties**

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dimension</td>
<td>Distributed dimension of codistributor1d object</td>
</tr>
<tr>
<td>Partition</td>
<td>Partition scheme of codistributor1d object</td>
</tr>
</tbody>
</table>

Introduced in R2009b
codistributor2dbc

2-D block-cyclic distribution scheme for codistributed array

Constructor

codistributor2dbc

Description

A codistributor2dbc object defines the 2-D block-cyclic distribution scheme for a codistributed array. The 2-D block-cyclic codistributor can only distribute two-dimensional matrices. It distributes matrices along two subscripts over a rectangular computational grid of labs in a blocked, cyclic manner. The parallel matrix computation software library called ScaLAPACK uses the 2-D block-cyclic codistributor.

For help on codistributor2dbc, including a list of links to individual help for its methods and properties, type

help codistributor2dbc

Methods

Properties

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BlockSize</td>
<td>Block size of codistributor2dbc object</td>
</tr>
<tr>
<td>LabGrid</td>
<td>Lab grid of codistributor2dbc object</td>
</tr>
<tr>
<td>Orientation</td>
<td>Orientation of codistributor2dbc object</td>
</tr>
</tbody>
</table>

Introduced in R2009b
Composite

Access nondistributed variables on multiple workers from client

Constructor

Composite

Description

Variables that exist on the workers running an `spmd` statement are accessible on the client as a Composite object. A Composite resembles a cell array with one element for each worker. So for Composite `C`:

\[
C\{1\} \text{ represents value of } C \text{ on worker1} \\
C\{2\} \text{ represents value of } C \text{ on worker2} \\
etc.
\]

`spmd` statements create Composites automatically, which you can access after the statement completes. You can also create a Composite explicitly with the `Composite` function.

Methods

Other methods of a Composite object behave similarly to these MATLAB array functions:

- `disp`, `display` - Display Composite
- `end` - Indicate last Composite index
- `isempty` - Determine whether Composite is empty
- `length` - Length of Composite
- `ndims` - Number of Composite dimensions
- `numel` - Number of elements in Composite
size

Composite dimensions

Introduced in R2008b
**CUDAKernel**

Kernel executable on GPU

**Constructor**

parallel.gpu.CUDAKernel

**Description**

A CUDAKernel object represents a CUDA kernel, that can execute on a GPU. You create the kernel when you compile PTX or CU code, as described in “Run CUDA or PTX Code on GPU” on page 9-22.

**Methods**

**Properties**

A CUDAKernel object has the following properties:

<table>
<thead>
<tr>
<th>Property Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ThreadBlockSize</td>
<td>Size of block of threads on the kernel. This can be an integer vector of length 1, 2, or 3 (since thread blocks can be up to 3-dimensional). The product of the elements of ThreadBlockSize must not exceed the MaxThreadsPerBlock for this kernel, and no element of ThreadBlockSize can exceed the corresponding element of the GPUDevice property MaxThreadBlockSize.</td>
</tr>
<tr>
<td>MaxThreadsPerBlock</td>
<td>Maximum number of threads permissible in a single block for this CUDA kernel. The product of the elements of ThreadBlockSize must not exceed this value.</td>
</tr>
<tr>
<td>Property Name</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------</td>
<td>---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>GridSize</td>
<td>Size of grid (effectively the number of thread blocks that will be launched independently by the GPU). This is an integer vector of length 3. None of the elements of this vector can exceed the corresponding element in the vector of the MaxGridSize property of the GPUDevice object.</td>
</tr>
<tr>
<td>SharedMemorySize</td>
<td>The amount of dynamic shared memory (in bytes) that each thread block can use. Each thread block has an available shared memory region. The size of this region is limited in current cards to ~16 kB, and is shared with registers on the multiprocessors. As with all memory, this needs to be allocated before the kernel is launched. It is also common for the size of this shared memory region to be tied to the size of the thread block. Setting this value on the kernel ensures that each thread in a block can access this available shared memory region.</td>
</tr>
<tr>
<td>EntryPoint</td>
<td>(read-only) A character vector containing the actual entry point name in the PTX code that this kernel is going to call. An example might look like '_Z13returnPointerPKfPy'.</td>
</tr>
<tr>
<td>MaxNumLHSArguments</td>
<td>(read-only) The maximum number of left hand side arguments that this kernel supports. It cannot be greater than the number of right hand side arguments, and if any inputs are constant or scalar it will be less.</td>
</tr>
<tr>
<td>NumRHSArguments</td>
<td>(read-only) The required number of right hand side arguments needed to call this kernel. All inputs need to define either the scalar value of an input, the elements for a vector input/output, or the size of an output argument.</td>
</tr>
<tr>
<td>ArgumentTypes</td>
<td>(read-only) Cell array of character vectors, the same length as NumRHSArguments. Each of the character vectors indicates what the expected MATLAB type for that input is (a numeric type such as uint8, single, or double followed by the word scalar or vector to indicate if we are passing by reference or value). In addition, if that argument is only an input to the kernel, it is prefixed by in; and if it is an input/output, it is prefixed by inout. This allows you to decide how to efficiently call the kernel with both MATLAB arrays and gpuArray, and to see which of the kernel inputs are being treated as outputs.</td>
</tr>
</tbody>
</table>
See Also

gpuArray, GPUDevice

Introduced in R2011b
distributed

Access elements of distributed arrays from client

Constructor

distributed

You can also create a distributed array explicitly from the client with any of several MATLAB functions, shown in the table.

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>eye(___,'distributed')</code></td>
<td>true(___,'distributed')</td>
</tr>
<tr>
<td><code>false(___,'distributed')</code></td>
<td>zeros(___,'distributed')</td>
</tr>
<tr>
<td><code>Inf(___,'distributed')</code></td>
<td>distributed.cell</td>
</tr>
<tr>
<td><code>NaN(___,'distributed')</code></td>
<td>distributed.spalloc</td>
</tr>
<tr>
<td><code>ones(___,'distributed')</code></td>
<td>distributed.speye</td>
</tr>
<tr>
<td><code>rand(___,'distributed')</code></td>
<td>distributed.sprand</td>
</tr>
<tr>
<td><code>randi(___,'distributed')</code></td>
<td>distributed.sprandn</td>
</tr>
<tr>
<td><code>randn(___,'distributed')</code></td>
<td></td>
</tr>
</tbody>
</table>

Description

Distributed arrays represent those arrays which are partitioned out among the workers in a parallel pool. A distributed array resembles a normal MATLAB array in the way you index and manipulate its elements, but none of its elements exists on the client.

Codistributed arrays that you create inside `spmd` statements are accessible as distributed arrays from the client.

Use the `gather` function to retrieve distributed arrays into the client work space.
Methods

The methods for distributed arrays are too numerous to list here. Most resemble and behave the same as built-in MATLAB functions. See “Using MATLAB Functions on Distributed Arrays” on page 5-24.

Also among the methods are several for examining the characteristics of the array itself. Most behave like the MATLAB functions of the same name:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>classUnderlying</td>
<td>Class (data type) of the elements in the array</td>
</tr>
<tr>
<td>isdistributed</td>
<td>Indication if array is distributed</td>
</tr>
<tr>
<td>isreal</td>
<td>Indication if array elements are real</td>
</tr>
<tr>
<td>length</td>
<td>Length of vector or largest array dimension</td>
</tr>
<tr>
<td>ndims</td>
<td>Number of dimensions in the array</td>
</tr>
<tr>
<td>size</td>
<td>Size of array dimensions</td>
</tr>
</tbody>
</table>

Introduced in R2008a
gpuArray

Array stored on GPU

Constructor

gpuArray converts an array in the MATLAB workspace into a gpuArray with elements stored on the GPU device.

Also, the following create gpuArrays:

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>eye(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>false(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>Inf(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>NaN(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>ones(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>true(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>zeros(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>rand(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>randi(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>randn(_, 'gpuArray')</td>
<td></td>
</tr>
<tr>
<td>gpuArray.colon</td>
<td></td>
</tr>
<tr>
<td>gpuArray.freqspace</td>
<td></td>
</tr>
<tr>
<td>gpuArray.linspace</td>
<td></td>
</tr>
<tr>
<td>gpuArray.logspace</td>
<td></td>
</tr>
<tr>
<td>gpuArray.speye</td>
<td></td>
</tr>
</tbody>
</table>

For class specific help on the three methods with the `gpuArray` prefix, type

help gpuArray.methodname

where methodname is the name of the method. For example, to get help on colon, type

help gpuArray.colon

The following methods control the random number stream on the GPU:

<table>
<thead>
<tr>
<th>Method</th>
</tr>
</thead>
<tbody>
<tr>
<td>parallel.gpu.RandStream</td>
</tr>
<tr>
<td>parallel.gpu.rng</td>
</tr>
</tbody>
</table>
Description

A gpuArray object represents an array stored on the GPU. You can use the array for direct calculations, or in CUDA kernels that execute on the GPU. You can return the array to the MATLAB workspace with the `gather` function.

Methods

Other methods for a gpuArray object are too numerous to list here. Most resemble and behave the same as built-in MATLAB functions. See “Run Built-In Functions on a GPU” on page 9-8.

Among the gpuArray methods there are several for examining the characteristics of a gpuArray object. Most behave like the MATLAB functions of the same name:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>classUnderlying</code></td>
<td>Class (data type) of the elements in the array</td>
</tr>
<tr>
<td><code>existsOnGPU</code></td>
<td>Indication if array exists on the GPU and is accessible</td>
</tr>
<tr>
<td><code>isreal</code></td>
<td>Indication if array elements are real</td>
</tr>
<tr>
<td><code>length</code></td>
<td>Length of vector or largest array dimension</td>
</tr>
<tr>
<td><code>ndims</code></td>
<td>Number of dimensions in the array</td>
</tr>
<tr>
<td><code>size</code></td>
<td>Size of array dimensions</td>
</tr>
</tbody>
</table>

See Also

CUDAKernel, GPUDevice

Introduced in R2012b
GPUDevice

Graphics processing unit (GPU)

Constructor

gpuDevice

Description

A GPUDevice object represents a graphic processing unit (GPU) in your computer. You can use the GPU to execute CUDA kernels or MATLAB code.

Methods

The following functions let you identify, select, reset, or wait for a GPU device:

Methods of the class include the following:

<table>
<thead>
<tr>
<th>Method Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>parallel.gpu.GPUDevice.isAvailable(idx)</td>
<td>True if the GPU specified by index idx is supported and capable of being selected. idx can be an integer or a vector of integers; the default index is the current device.</td>
</tr>
<tr>
<td>parallel.gpu.GPUDevice.getDevice(idx)</td>
<td>Returns a GPUDevice object without selecting it.</td>
</tr>
</tbody>
</table>

For the complete list, use the methods function on the GPUDevice class:

methods('parallel.gpu.GPUDevice')

You can get help on any of the class methods with the command

help parallel.gpu.GPUDevice.methodname
where `methodname` is the name of the method. For example, to get help on `isAvailable`, type

```
help parallel.gpu.GPUDevice.isAvailable
```

### Properties

A `GPUDevice` object has the following read-only properties:

<table>
<thead>
<tr>
<th>Property Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Name</td>
<td>Name of the CUDA device.</td>
</tr>
<tr>
<td>Index</td>
<td>Index by which you can select the device.</td>
</tr>
<tr>
<td>ComputeCapability</td>
<td>Computational capability of the CUDA device. Must meet required specification.</td>
</tr>
<tr>
<td>SupportsDouble</td>
<td>Indicates if this device can support double precision operations.</td>
</tr>
<tr>
<td>DriverVersion</td>
<td>The CUDA device driver version currently in use. Must meet required specification.</td>
</tr>
<tr>
<td>ToolkitVersion</td>
<td>Version of the CUDA toolkit used by the current release of MATLAB.</td>
</tr>
<tr>
<td>MaxThreadsPerBlock</td>
<td>Maximum supported number of threads per block during CUDAKernel execution.</td>
</tr>
<tr>
<td>MaxShmemPerBlock</td>
<td>Maximum supported amount of shared memory that can be used by a thread block during CUDAKernel execution.</td>
</tr>
<tr>
<td>MaxThreadBlockSize</td>
<td>Maximum size in each dimension for thread block. Each dimension of a thread block must not exceed these dimensions. Also, the product of the thread block size must not exceed <code>MaxThreadsPerBlock</code>.</td>
</tr>
<tr>
<td>MaxGridSize</td>
<td>Maximum size of grid of thread blocks.</td>
</tr>
<tr>
<td>SIMDWidth</td>
<td>Number of simultaneously executing threads.</td>
</tr>
<tr>
<td>TotalMemory</td>
<td>Total memory (in bytes) on the device.</td>
</tr>
<tr>
<td>AvailableMemory</td>
<td>Total amount of memory (in bytes) available for data. This property is available only for the currently selected device.</td>
</tr>
<tr>
<td>MultiprocessorCount</td>
<td>The number of vector processors present on the device.</td>
</tr>
<tr>
<td>Property Name</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>ClockRateKHz</td>
<td>Peak clock rate of the GPU in kHz.</td>
</tr>
<tr>
<td>ComputeMode</td>
<td>The compute mode of the device, according to the following values:</td>
</tr>
<tr>
<td></td>
<td>'Default' — The device is not restricted and can be used by multiple applications simultaneously. MATLAB can share the device with other applications, including other MATLAB sessions or workers.</td>
</tr>
<tr>
<td></td>
<td>'Exclusive thread' or 'Exclusive process' — The device can be used by only one application at a time. While the device is selected in MATLAB, it cannot be used by other applications, including other MATLAB sessions or workers.</td>
</tr>
<tr>
<td></td>
<td>'Prohibited' — The device cannot be used.</td>
</tr>
<tr>
<td>GPUOverlapsTransfers</td>
<td>Indicates if the device supports overlapped transfers.</td>
</tr>
<tr>
<td>KernelExecutionTimeout</td>
<td>Indicates if the device can abort long-running kernels. If true, the operating system places an upper bound on the time allowed for the CUDA kernel to execute, after which the CUDA driver times out the kernel and returns an error.</td>
</tr>
<tr>
<td>CanMapHostMemory</td>
<td>Indicates if the device supports mapping host memory into the CUDA address space.</td>
</tr>
<tr>
<td>DeviceSupported</td>
<td>Indicates if toolbox can use this device. Not all devices are supported; for example, if their ComputeCapability is insufficient, the toolbox cannot use them.</td>
</tr>
<tr>
<td>DeviceSelected</td>
<td>Indicates if this is the currently selected device.</td>
</tr>
</tbody>
</table>

See Also

CUDAKernel, gpuArray

Introduced in R2010b
GPUDeviceManager

Manager for GPU Devices

Constructor

parallel.gpu.GPUDeviceManager.instance

Description

parallel.gpu.GPUDeviceManager provides events that indicate when a GPU device has been selected or deselected. These events also fire when a GPU device is reset. There is only a single instance of the parallel.gpu.GPUDeviceManager available in a given MATLAB session, and it is obtained using the method parallel.gpu.GPUDeviceManager.instance.

Events

Events of the class include the following:

<table>
<thead>
<tr>
<th>Event Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>DeviceSelected</td>
<td>Fired after a GPU device is selected.</td>
</tr>
<tr>
<td>DeviceDeselecting</td>
<td>Fired just before a GPU device is deselected.</td>
</tr>
</tbody>
</table>

Properties

A GPUDeviceManager object has one property:

<table>
<thead>
<tr>
<th>Property Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SelectedDevice</td>
<td>Contains the currently selected GPU Device.</td>
</tr>
</tbody>
</table>
Methods

Methods of the class include the following:

<table>
<thead>
<tr>
<th>Method Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>getDeviceCount</td>
<td>Returns the number of GPU devices available.</td>
</tr>
<tr>
<td>selectDevice</td>
<td>Selects a GPU device.</td>
</tr>
</tbody>
</table>

See Also

gpuDevice, gpuDeviceCount, gpuArray

Introduced in R2016a
mxGPUArray

Type for MATLAB gpuArray

Description

mxGPUArray is an opaque C language type that allows a MEX function access to the elements in a MATLAB gpuArray. Using the mxGPU API, you can perform calculations on a MATLAB gpuArray, and return gpuArray results to MATLAB.

All MEX functions receive inputs and pass outputs as mxArrays. A gpuArray in MATLAB is a special kind of mxArray that represents an array stored on the GPU. In your MEX function, you use mxGPUArray objects to access an array stored on the GPU: these objects correspond to MATLAB gpuArrays.

The mxGPU API contains functions that manipulate mxGPUArray objects. These functions allow you to extract mxGPUArrays from input mxArrays, to wrap output mxGPUArrays as mxArrays for return to MATLAB, to determine the characteristics of the arrays, and to get pointers to the underlying elements. You can perform calculations by passing the pointers to CUDA functions that you write or that are available in external libraries.

The basic structure of a GPU MEX function is:

1. Call `mxInitGPU` to initialize MathWorks GPU library.
2. Determine which `mxArray` inputs contain GPU data.
3. Create `mxGPUArray` objects from the input `mxArray` arguments, and get pointers to the input elements on the device.
4. Create `mxGPUArray` objects to hold the outputs, and get the pointers to the output elements on the device.
5. Call a CUDA function, passing it the device pointers.
6. Wrap the output `mxGPUArray` as an `mxArray` for return to MATLAB.
7. Destroy the `mxGPUArray` objects you created.

The header file that contains this type is `mxGPUArray.h`. You include it with the line:
#include "gpu/mxGPUArray.h"

See Also

gpuArray, mxArray

Introduced in R2013a
parallel.Cluster

Access cluster properties and behaviors

Constructors

parcluster

getCurrentCluster (in the workspace of the MATLAB worker)

Container Hierarchy

Parent          None
Children        parallel.Job, parallel.Pool

Description

A parallel.Cluster object provides access to a cluster, which controls the job queue, and distributes tasks to workers for execution.

Types

The two categories of clusters are the MATLAB job scheduler (MJS) and common job scheduler (CJS). The MJS is available in the MATLAB Distributed Computer Server. The CJS clusters encompass all other types, including the local, generic, and third-party schedulers.

Use Cloud objects to interact with MATLAB Parallel Cloud clusters.

Use MJSCluster objects to interact with MATLAB Distributed Computing Server for Amazon EC2 clusters.

The following table describes the available types of cluster objects.
<table>
<thead>
<tr>
<th>Cluster Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>parallel.cluster.MJS</td>
<td>Interact with MATLAB job scheduler (MJS) cluster on-premises</td>
</tr>
<tr>
<td>parallel.cluster.Cloud</td>
<td>Interact with MATLAB Parallel Cloud cluster</td>
</tr>
<tr>
<td>parallel.cluster.MJSComputeCloud</td>
<td>Interact with MATLAB Distributed Computing Server for Amazon EC2 cluster</td>
</tr>
<tr>
<td>parallel.cluster.Local</td>
<td>Interact with CJS cluster running locally on client machine</td>
</tr>
<tr>
<td>parallel.cluster.HPCServer</td>
<td>Interact with CJS cluster running Windows Microsoft HPC Server</td>
</tr>
<tr>
<td>parallel.cluster.LSF</td>
<td>Interact with CJS cluster running Platform LSF</td>
</tr>
<tr>
<td>parallel.cluster.PBSPro</td>
<td>Interact with CJS cluster running Altair PBS Pro</td>
</tr>
<tr>
<td>parallel.cluster.Torque</td>
<td>Interact with CJS cluster running TORQUE</td>
</tr>
<tr>
<td>parallel.cluster.Generic</td>
<td>Interact with CJS cluster using the generic interface</td>
</tr>
</tbody>
</table>
Methods

Common to All Cluster Types

MJS

Cloud

MJSClusterComputeCloud

HPC Server, PBS Pro, LSF, TORQUE, and Local Clusters

Generic

Properties

Common to All Cluster Types

The following properties are common to all cluster object types.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ClusterMatlabRoot</td>
<td>Specifies path to MATLAB for workers to use</td>
</tr>
<tr>
<td>Host</td>
<td>Host name of the cluster head node</td>
</tr>
<tr>
<td>JobStorageLocation</td>
<td>Location where cluster stores job and task information</td>
</tr>
<tr>
<td>Jobs</td>
<td>List of jobs contained in this cluster</td>
</tr>
<tr>
<td>LicenseNumber</td>
<td>License number to use when running jobs with this cluster</td>
</tr>
<tr>
<td>Modified</td>
<td>True if any properties in this cluster have been modified</td>
</tr>
</tbody>
</table>
### Property Description

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>NumThreads</td>
<td>Number of computational threads for workers</td>
</tr>
<tr>
<td>NumWorkers</td>
<td>Number of workers available for this cluster</td>
</tr>
<tr>
<td>OperatingSystem</td>
<td>Operating system of nodes used by cluster</td>
</tr>
<tr>
<td>Profile</td>
<td>Profile used to build this cluster</td>
</tr>
<tr>
<td>RequiresMathWorksHostedLicensing</td>
<td>True if the cluster is using the MathWorks Hosted License Manager</td>
</tr>
<tr>
<td>Type</td>
<td>Type of this cluster</td>
</tr>
<tr>
<td>UserData</td>
<td>Information associated with cluster object within client session</td>
</tr>
</tbody>
</table>

### MJS

MJS cluster objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AllHostAddresses</td>
<td>IP addresses of the cluster host</td>
</tr>
<tr>
<td>BusyWorkers</td>
<td>Workers currently running tasks</td>
</tr>
<tr>
<td>IdleWorkers</td>
<td>Workers currently available for running tasks</td>
</tr>
<tr>
<td>HasSecureCommunication</td>
<td>True if cluster is using secure communication</td>
</tr>
<tr>
<td>Name</td>
<td>Name of this cluster</td>
</tr>
<tr>
<td>NumBusyWorkers</td>
<td>Number of workers currently running tasks</td>
</tr>
<tr>
<td>NumIdleWorkers</td>
<td>Number of workers available for running tasks</td>
</tr>
<tr>
<td>PromptForPassword</td>
<td>True if system should prompt for password when authenticating user</td>
</tr>
</tbody>
</table>
Property | Description
--- | ---
SecurityLevel | Degree of security applied to cluster and its jobs. For descriptions of security levels, see “Set MJS Cluster Security” (MATLAB Distributed Computing Server).
State | Current state of cluster
Username | User accessing cluster

Cloud

Cloud cluster objects, `parallel.cluster.Cloud`, have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BusyWorkers</td>
<td>Workers currently running tasks</td>
</tr>
<tr>
<td>Certificate</td>
<td>Cluster SSL certificate</td>
</tr>
<tr>
<td>HasSecureCommunication</td>
<td>True if cluster is using secure communication</td>
</tr>
<tr>
<td>Identifier</td>
<td>Unique cluster identifier</td>
</tr>
<tr>
<td>IdleWorkers</td>
<td>Workers currently available for running tasks</td>
</tr>
<tr>
<td>MatlabVersion</td>
<td>Version of MATLAB running on the workers</td>
</tr>
<tr>
<td>MaxNumMachines</td>
<td>Maximum number of machines this cluster can use. When more workers are required, machines are automatically added to the cluster up to this maximum value.</td>
</tr>
<tr>
<td>Name</td>
<td>Name of this cluster</td>
</tr>
<tr>
<td>NumBusyMachines</td>
<td>Number of machines that currently have at least one busy worker</td>
</tr>
<tr>
<td>NumBusyWorkers</td>
<td>Number of workers currently running tasks</td>
</tr>
<tr>
<td>Property</td>
<td>Description</td>
</tr>
<tr>
<td>--------------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>NumIdleMachines</td>
<td>Number of machines that currently have no workers running a task</td>
</tr>
<tr>
<td>NumIdleWorkers</td>
<td>Number of workers available for running tasks</td>
</tr>
<tr>
<td>NumMachines</td>
<td>Number of machines currently in this cluster</td>
</tr>
<tr>
<td>NumWorkersPerMachine</td>
<td>Number of workers per machine in this cluster</td>
</tr>
<tr>
<td>ShutdownAt</td>
<td>Shutdown time or event</td>
</tr>
<tr>
<td>State</td>
<td>Current state of cluster</td>
</tr>
<tr>
<td>Username</td>
<td>User accessing cluster</td>
</tr>
</tbody>
</table>

**MJSComputeCloud**

MJSComputeCloud cluster objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BusyWorkers</td>
<td>Workers currently running tasks</td>
</tr>
<tr>
<td>Certificate</td>
<td>Cluster SSL certificate</td>
</tr>
<tr>
<td>HasSecureCommunication</td>
<td>True if cluster is using secure communication</td>
</tr>
<tr>
<td>Identifier</td>
<td>Unique cluster identifier</td>
</tr>
<tr>
<td>IdleWorkers</td>
<td>Workers currently available for running tasks</td>
</tr>
<tr>
<td>MatlabVersion</td>
<td>Version of MATLAB running on the workers</td>
</tr>
<tr>
<td>Name</td>
<td>Name of this cluster</td>
</tr>
<tr>
<td>NumBusyWorkers</td>
<td>Number of workers currently running tasks</td>
</tr>
<tr>
<td>NumIdleWorkers</td>
<td>Number of workers available for running tasks</td>
</tr>
<tr>
<td>Property</td>
<td>Description</td>
</tr>
<tr>
<td>----------------</td>
<td>--------------------------------------------------</td>
</tr>
<tr>
<td>ShutdownAt</td>
<td>Shutdown time or event</td>
</tr>
<tr>
<td>State</td>
<td>Current state of cluster</td>
</tr>
<tr>
<td>Username</td>
<td>User accessing cluster</td>
</tr>
</tbody>
</table>

**Local**

Local cluster objects have no editable properties beyond the properties common to all clusters.

**HPC Server**

HPC Server cluster objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ClusterVersion</td>
<td>Version of Microsoft Windows HPC Server running on the cluster</td>
</tr>
<tr>
<td>HasSharedFilesystem</td>
<td>Specify whether client and cluster nodes share JobStorageLocation</td>
</tr>
<tr>
<td>JobDescriptionFile</td>
<td>Name of XML job description file to use when creating jobs</td>
</tr>
<tr>
<td>JobTemplate</td>
<td>Name of job template to use for jobs submitted to HPC Server</td>
</tr>
<tr>
<td>Name</td>
<td>Name of this cluster</td>
</tr>
<tr>
<td>UseSOAJobSubmission</td>
<td>Allow service-oriented architecture (SOA) submission on HPC Server</td>
</tr>
</tbody>
</table>

**PBS Pro and TORQUE**

PBS Pro and TORQUE cluster objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CommunicatingJobWrapper</td>
<td>Script that cluster runs to start workers</td>
</tr>
</tbody>
</table>
**Property** | **Description**
---|---
RcpCommand | Command to copy files to and from client
ResourceTemplate | Define resources to request for communicating jobs
RshCommand | Remote execution command used on worker nodes during communicating job
HasSharedFilesystem | Specify whether client and cluster nodes share JobStorageLocation
SubmitArguments | Specify additional arguments to use when submitting jobs

**LSF**

LSF cluster objects have the following properties in addition to the common properties:

**Property** | **Description**
---|---
ClusterName | Name of Platform LSF cluster
CommunicatingJobWrapper | Script cluster runs to start workers
HasSharedFilesystem | Specify whether client and cluster nodes share JobStorageLocation
SubmitArguments | Specify additional arguments to use when submitting jobs

**Generic**

If you create a generic cluster object from an R2017a or later profile, you have the following properties in addition to the common properties:

**Property** | **Description**
---|---
AdditionalProperties | Additional properties for integration scripts
HasSharedFilesystem | Specify whether client and cluster nodes share JobStorageLocation
IntegrationScriptsLocation | Folder containing scheduler integration scripts
If you create a generic cluster object from an R2016b or earlier profile, you have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CancelJobFcn</td>
<td>Function to run when cancelling job</td>
</tr>
<tr>
<td>CancelTaskFcn</td>
<td>Function to run when cancelling task</td>
</tr>
<tr>
<td>CommunicatingSubmitFcn</td>
<td>Function to run when submitting communicating job</td>
</tr>
<tr>
<td>DeleteJobFcn</td>
<td>Function to run when deleting job</td>
</tr>
<tr>
<td>DeleteTaskFcn</td>
<td>Function to run when deleting task</td>
</tr>
<tr>
<td>GetJobStateFcn</td>
<td>Function to run when querying job state</td>
</tr>
<tr>
<td>HasSharedFilesystem</td>
<td>Specify whether client and cluster nodes share JobStorageLocation</td>
</tr>
<tr>
<td>IndependentSubmitFcn</td>
<td>Function to run when submitting independent job</td>
</tr>
</tbody>
</table>

**Help**

For further help on cluster objects, including links to help for specific cluster types and object properties, type:

```
help parallel.Cluster
```

**See Also**


**Introduced in R2012a**
**parallel.cluster.Hadoop**

Hadoop cluster for mapreducer, mapreduce and tall arrays

**Constructors**

`parallel.cluster.Hadoop`

**Description**

A `parallel.cluster.Hadoop` object provides access to a cluster for configuring mapreducer, mapreduce, and tall arrays.

**Properties**

A `parallel.cluster.Hadoop` object has the following properties.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AdditionalPaths</td>
<td>Paths to be added to MATLAB command search path on workers</td>
</tr>
<tr>
<td>AttachedFiles</td>
<td>Files transferred to the workers during a mapreduce call</td>
</tr>
<tr>
<td>AutoAttachFiles</td>
<td>Specifies whether automatically attach files</td>
</tr>
<tr>
<td>ClusterMatlabRoot</td>
<td>Specifies path to MATLAB for workers to use</td>
</tr>
<tr>
<td>HadoopConfigurationFile</td>
<td>Application configuration file to be given to Hadoop</td>
</tr>
<tr>
<td>HadoopInstallFolder</td>
<td>Installation location of Hadoop on the local machine</td>
</tr>
<tr>
<td>HadoopProperties</td>
<td>Map of name-value property pairs to be given to Hadoop</td>
</tr>
<tr>
<td>Property</td>
<td>Description</td>
</tr>
<tr>
<td>----------------------------------</td>
<td>--------------------------------------------------------------------</td>
</tr>
<tr>
<td>LicenseNumber</td>
<td>License number to use with MathWorks hosted licensing</td>
</tr>
<tr>
<td>RequiresMathWorksHostedLicensing</td>
<td>Specify whether cluster uses MathWorks hosted licensing</td>
</tr>
<tr>
<td>SparkInstallFolder</td>
<td>Installation location of Spark on the local machine</td>
</tr>
<tr>
<td>SparkProperties</td>
<td>Map of name-value property pairs to be given to Spark</td>
</tr>
</tbody>
</table>

**HadoopProperties** allows you to override configuration properties for Hadoop. See the list of properties in the Hadoop documentation.

The **SparkInstallFolder** is by default set to the `SPARK_HOME` environment variable. This is required for tall array evaluation on Hadoop (but not for mapreduce). For a correctly configured cluster, you only need to set the installation folder.

**SparkProperties** allows you to override configuration properties for Spark. See the list of properties in the Spark documentation.

**Help**

For further help, type:

`help parallel.cluster.Hadoop`

**Specify Memory Properties**

Spark enabled Hadoop clusters place limits on how much memory is available. You must adjust these limits to support your workflow.

**Size of Data to Gather**

The amount of data gathered to the client is limited by the Spark properties:

- `spark.driver.memory`
• `spark.executor.memory`

The amount of data to gather from a single Spark task must fit in these properties. A single Spark task processes one block of data from HDFS, which is 128 MB of data by default. If you gather a tall array containing most of the original data, you must ensure these properties are set to fit.

If these properties are set too small, you see an error like the following.

Error using tall/gather (line 50)
Out of memory; unable to gather a partition of size 300m from Spark.
Adjust the values of the Spark properties `spark.driver.memory` and `spark.executor.memory` to fit this partition.

The error message also specifies the property settings you need.

Adjust the properties either in the default settings of the cluster or directly in MATLAB. To adjust the properties in MATLAB, add name-value pairs to the `SparkProperties` property of the cluster. For example:

```matlab
cluster = parallel.cluster.Hadoop;
cluster.SparkProperties('spark.driver.memory') = '2048m';
cluster.SparkProperties('spark.executor.memory') = '2048m';
mapreducer(cluster);
```

**Specify Working Memory Size for a MATLAB Worker**

The amount of working memory for a MATLAB Worker is limited by the Spark property:

• `spark.yarn.executor.memoryOverhead`

By default, this is set to 2.5 GB. You typically need to increase this if you use `arrayfun`, `cellfun`, or custom datastores to generate large amounts of data in one go. It is advisable to increase this if you come across lost or crashed Spark Executor processes.

You can adjust these properties either in the default settings of the cluster or directly in MATLAB. To adjust the properties in MATLAB, add name-value pairs to the `SparkProperties` property of the cluster. For example:

```matlab
cluster = parallel.cluster.Hadoop;
cluster.SparkProperties('spark.yarn.executor.memoryOverhead') = '4096m';
mapreducer(cluster);
```
See Also

`parallel.Cluster, parallel.Pool`

See Also

Topics

“Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
“Run mapreduce on a Hadoop Cluster” on page 6-82

Introduced in R2014b
parallel.Future

Request function execution on parallel pool workers

Constructors

parfeval, parfevalOnAll

Container Hierarchy

Parent parallel.Pool.FevalQueue

Types

The following table describes the available types of future objects.

<table>
<thead>
<tr>
<th>Future Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>parallel.FevalFuture</td>
<td>Single parfeval future instance</td>
</tr>
<tr>
<td>parallel.FevalOnAllFuture</td>
<td>parfevalOnAll future instance</td>
</tr>
</tbody>
</table>

Description

A parallel.FevalFuture represents a single instance of a function to be executed on a worker in a parallel pool. It is created when you call the parfeval function. To create multiple FevalFutures, call parfeval multiple times; for example, you can create a vector of FevalFutures in a for-loop.

An FevalOnAllFuture represents a function to be executed on every worker in a parallel pool. It is created when you call the parfevalOnAll function.

Either type of parallel.Future object is a local object and can be accessed only in the MATLAB session that created it.
Methods

Future objects have the following methods. Note that some exist only for parallel.FevalFuture objects, not parallel.FevalOnAllFuture objects.

<table>
<thead>
<tr>
<th>Method</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>cancel</td>
<td>Cancel queued or running future</td>
</tr>
<tr>
<td>fetchNext</td>
<td>Retrieve next available unread future outputs</td>
</tr>
<tr>
<td></td>
<td>(FevalFuture only)</td>
</tr>
<tr>
<td>fetchOutputs</td>
<td>Retrieve all outputs of future</td>
</tr>
<tr>
<td>isequal</td>
<td>True if futures have same ID</td>
</tr>
<tr>
<td></td>
<td>(FevalFuture only)</td>
</tr>
<tr>
<td>wait</td>
<td>Wait for futures to complete</td>
</tr>
</tbody>
</table>

Properties

Future objects have the following properties. Note that some exist only for parallel.FevalFuture objects, not parallel.FevalOnAllFuture objects.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Diary</td>
<td>Text produced by execution of function</td>
</tr>
<tr>
<td>Error</td>
<td>Error information</td>
</tr>
<tr>
<td>Function</td>
<td>Function to evaluate</td>
</tr>
<tr>
<td>ID</td>
<td>Numeric identifier for this future</td>
</tr>
<tr>
<td>InputArguments</td>
<td>Input arguments to function</td>
</tr>
<tr>
<td>NumOutputArguments</td>
<td>Number of arguments returned by function</td>
</tr>
<tr>
<td>OutputArguments</td>
<td>Output arguments from running function</td>
</tr>
<tr>
<td>Parent</td>
<td>FevalQueue containing this future</td>
</tr>
<tr>
<td>Read</td>
<td>Indication if outputs have been read by fetchNext or fetchOutputs (FevalFuture only)</td>
</tr>
<tr>
<td>State</td>
<td>Current state of future</td>
</tr>
</tbody>
</table>
Help

To get further help on either type of parallel.Future object, including a list of links to help for its properties, type:

```matlab
help parallel.FevalFuture
help parallel.FevalOnAllFuture
```

See Also

parallel.Pool

Introduced in R2013b
**parallel.Job**

Access job properties and behaviors

**Constructors**

createCommunicatingJob, createJob, findJob, recreate

gGetCurrentJob (in the workspace of the MATLAB worker)

**Container Hierarchy**

Parent: parallel.Cluster
Children: parallel.Task

**Description**

A parallel.Job object provides access to a job, which you create, define, and submit for execution.

**Types**

The following table describes the available types of job objects. The job type is determined by the type of cluster, and whether the tasks must communicate with each other during execution.

<table>
<thead>
<tr>
<th>Job Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>parallel.job.MJSIndependentJob</td>
<td>Job of independent tasks on MJS cluster</td>
</tr>
<tr>
<td>parallel.job.MJSCommunicatingJob</td>
<td>Job of communicating tasks on MJS cluster</td>
</tr>
<tr>
<td>parallel.job.CJSIndependentJob</td>
<td>Job of independent tasks on CJS cluster</td>
</tr>
<tr>
<td>parallel.job.CJSCommunicatingJob</td>
<td>Job of communicating tasks on CJS cluster</td>
</tr>
</tbody>
</table>
Methods

All job type objects have the same methods, described in the following table.

Properties

Common to All Job Types

The following properties are common to all job object types.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AdditionalPaths</td>
<td>Folders to add to MATLAB search path of workers</td>
</tr>
<tr>
<td>AttachedFiles</td>
<td>Files and folders that are sent to workers</td>
</tr>
<tr>
<td>AutoAddClientPath</td>
<td>Specifies whether user-added-entries on the client’s path are automatically added to each worker’s path</td>
</tr>
<tr>
<td>AutoAttachFiles</td>
<td>Specifies if dependent code files are automatically sent to workers</td>
</tr>
<tr>
<td>CreateDateTime</td>
<td>Date and time when the job is created</td>
</tr>
<tr>
<td>EnvironmentVariables</td>
<td>Names of environment variables that are sent to the workers</td>
</tr>
<tr>
<td>FinishDateTime</td>
<td>Date and time when the job finishes running</td>
</tr>
<tr>
<td>ID</td>
<td>Job’s numeric identifier</td>
</tr>
<tr>
<td>JobData</td>
<td>Information made available to all workers for job’s tasks</td>
</tr>
<tr>
<td>Name</td>
<td>Name of job</td>
</tr>
<tr>
<td>Parent</td>
<td>Cluster object containing this job</td>
</tr>
<tr>
<td>StartDateTime</td>
<td>Date and time when the job starts running</td>
</tr>
<tr>
<td>State</td>
<td>State of job: 'pending', 'queued', 'running', 'finished', or 'failed'</td>
</tr>
</tbody>
</table>
### Property Description

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubmitDateTime</td>
<td>Date and time when the job is submitted to the queue</td>
</tr>
<tr>
<td>Tag</td>
<td>Label associated with job</td>
</tr>
<tr>
<td>Tasks</td>
<td>Array of task objects contained in job</td>
</tr>
<tr>
<td>Type</td>
<td>Job type: 'independent', 'pool', or 'spmd'</td>
</tr>
<tr>
<td>UserData</td>
<td>Information associated with job object</td>
</tr>
<tr>
<td>Username</td>
<td>Name of user who owns job</td>
</tr>
</tbody>
</table>

### MJS Jobs

MJS independent job objects and MJS communicating job objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AuthorizedUsers</td>
<td>Users authorized to access job</td>
</tr>
<tr>
<td>FinishedFcn</td>
<td>Callback function executed on client when this job finishes</td>
</tr>
<tr>
<td>NumWorkersRange</td>
<td>Minimum and maximum limits for number of workers to run job</td>
</tr>
<tr>
<td>QueuedFcn</td>
<td>Callback function executed on client when this job is submitted to queue</td>
</tr>
<tr>
<td>RestartWorker</td>
<td>True if workers are restarted before evaluating first task for this job</td>
</tr>
<tr>
<td>RunningFcn</td>
<td>Callback function executed on client when this job starts running</td>
</tr>
<tr>
<td>Timeout</td>
<td>Time limit, in seconds, to complete job</td>
</tr>
</tbody>
</table>

### CJS Jobs

CJS independent job objects do not have any properties beyond the properties common to all job types.
CJS communicating job objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>NumWorkersRange</td>
<td>Minimum and maximum limits for number of workers to run job</td>
</tr>
</tbody>
</table>

**Help**

To get further help on a particular type of parallel.Job object, including a list of links to help for its properties, type `help parallel.job.<job-type>`. For example:

```
help parallel.job.MJSIndependentJob
```

**See Also**

parallel.Cluster, parallel.Task, parallel.Worker

*Introduced in R2012a*
**parallel.Pool**

Access parallel pool

**Constructors**

parpool, gcp

**Description**

A parallel.Pool object provides access to a parallel pool running on a cluster.

**Methods**

A parallel pool object has the following methods.

**Properties**

A parallel pool object has the following properties.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AttachedFiles</td>
<td>Files and folders that are sent to workers</td>
</tr>
<tr>
<td>Cluster</td>
<td>Cluster on which the parallel pool is running</td>
</tr>
<tr>
<td>Connected</td>
<td>False if the parallel pool has shut down</td>
</tr>
<tr>
<td>FevalQueue</td>
<td>Queue of FevalFutures to run on the parallel pool</td>
</tr>
<tr>
<td>IdleTimeout</td>
<td>Time duration in minutes before idle parallel pool will shut down</td>
</tr>
<tr>
<td>NumWorkers</td>
<td>Number of workers comprising the parallel pool</td>
</tr>
<tr>
<td>Property</td>
<td>Description</td>
</tr>
<tr>
<td>--------------</td>
<td>--------------------------------------------------</td>
</tr>
<tr>
<td>SpmdEnabled</td>
<td>Indication if pool can run SPMD code</td>
</tr>
</tbody>
</table>

**Help**

To get further help on `parallel.Pool` objects, including a list of links to help for specific properties, type:

```
help parallel.Pool
```

**See Also**

`parallel.Cluster`, `parallel.Future`

**See Also**

**Topics**

“Run Code on Parallel Pools” on page 2-65

**Introduced in R2013b**
parallel.pool.DataQueue

Class that enables sending and listening for data between client and workers

Description

parallel.pool.DataQueue enables sending data or messages from workers back to the client in a parallel pool while a computation is carried out. For example, you can get intermediate values and an indication of the progress of the computation.

To send data from a parallel pool worker back to the client, first construct a DataQueue in the client. Pass this DataQueue into a parfor-loop or other parallel language construct, such as spmd. From the workers, call send to send data back to the client. At the client, register a function to be called each time data is received by using afterEach.

• You can call send from the process that calls the constructor, if required.
• You can construct the queue on the workers and send it back to the client to enable communication in the reverse direction. However, you cannot send a queue from one worker to another. Use spmd, labSend, or labReceive instead.
• Unlike all other handle objects, DataQueue instances do remain connected when they are sent to workers.

Construction

q = parallel.pool.DataQueue

The constructor for a DataQueue takes no arguments and returns an object that can be used to send or listen for messages (or data) from different workers. You call the constructor only in the process where you want to receive the data. In the usual workflow, the workers should not be calling the constructor, but should be handed an existing DataQueue instance instead.
Properties

QueueLength — Number of items currently held on the queue
zero or positive integer

Dependent property on the queue that indicates how many items of data are waiting to be removed from the queue.

q = parallel.pool.DataQueue;
% No messages in queue because nothing has been sent.
q.QueueLength

ans =

0

q.send('sending a message')
% Now QueueLength = 1 because one message has been sent.
q.QueueLength

ans =

1

% Add a callback to process the queue.
listener = q.afterEach(@disp);

sending a message

% Now QueueLength = 0 because there are no more pending messages.
q.QueueLength

ans =

0

% Data sent now is immediately processed by the callback so that QueueLength remains 0.
q.send('sending message 2')
q.QueueLength

sending message 2

ans =

0
% Deleting all callback listeners causes messages to build up in the queue again.
delete(listener)
q.send('sending message 3')
q.QueueLength
ans =
    1

Methods

A parallel.pool.DataQueue object has the following methods.

Copy Semantics

Handle. To learn how handle classes affect copy operations, see Copying Objects (MATLAB).

Examples

Send a Message in a parfor-Loop, and Dispatch the Message on the Queue

Construct a DataQueue, and call afterEach.

q = parallel.pool.DataQueue;
afterEach(q, @disp);

Start a parfor-loop, and send a message. The pending message is passed to the afterEach function, in this example @disp.

parfor i = 1:3
    send(q, i);
end;

    1
    2
    3
For more details on listening for data using a `DataQueue`, see `afterEach`.

**Construct a Simple `parfor` Wait Bar Using a Data Queue**

Create a `DataQueue`, and use `afterEach` to specify the function to execute each time the queue receives data. This example calls a subfunction that updates the wait bar.

Create a `parfor`-loop to carry out a computationally demanding task in MATLAB. Use `send` to send some dummy data on each iteration of the `parfor`-loop. When the queue receives the data, `afterEach` calls `nUpdateWaitbar` in the client MATLAB, and you can observe the wait bar progress.

```matlab
function a = parforWaitbar

D = parallel.pool.DataQueue;
h = waitbar(0, 'Please wait ...');
afterEach(D, @nUpdateWaitbar);

N = 200;
p = 1;

parfor i = 1:N
    a(i) = max(abs(eig(rand(400))));
    send(D, i);
end

function nUpdateWaitbar(~)
    waitbar(p/N, h);
    p = p + 1;
end
end
```

![Wait bar progress](image)
Call `afterEach` to Dispatch Data on a Queue

If you call `afterEach` and there are items on the queue waiting to be dispatched, these items are immediately dispatched to the function handle specified by `afterEach`. Call `afterEach` before sending data to the queue, to ensure that on `send`, the function handle `@disp` is called.

Construct a `DataQueue` and call `afterEach`.

```matlab
q = parallel.pool.DataQueue;
afterEach(q, @disp);
```

If you then send messages to the queue, each message is passed to the function handle specified by `afterEach` immediately.

```matlab
parfor i = 1:3
    send(q, i);
end
send(q, 0);
```

If you send the data to the queue and then call `afterEach`, each of the pending messages are passed to the function handle specified by `afterEach`.

```matlab
q = parallel.pool.DataQueue;
parfor i = 1:3
    send(q, i);
end
afterEach(q, @disp);
```
See Also
afterEach | gcp | labReceive | labSend | parallel.pool.PollableDataQueue
| parfor | poll | send | spmd

Topics
Class Attributes (MATLAB)
Property Attributes (MATLAB)

Introduced in R2017a
parallel.pool.PollableDataQueue

Class that enables sending and polling for data between client and workers

Description

parallel.pool.PollableDataQueue enables sending and polling for data or messages between workers and client in a parallel pool while a computation is being carried out. You can get intermediate values and progress of the computation.

To send data from a parallel pool worker back to the client, first construct a PollableDataQueue in the client. Pass this PollableDataQueue into a parfor-loop or other parallel language construct, such as parfeval. From the workers, call send to send data back to the client. At the client, use poll to retrieve the result of a message or data sent from a worker.

• You can call send from the process that calls the constructor, if required.
• You can construct the queue on the workers and send it back to the client to enable communication in the reverse direction. However, you cannot send a queue from one worker to another. Use spmd, labSend, or labReceive instead.
• Unlike all other handle objects, PollableDataQueue instances do remain connected when they are sent to workers.

Construction

p = parallel.pool.PollableDataQueue

The constructor for a PollableDataQueue takes no arguments and returns an object that can be used to send and poll for messages (or data) from different workers. You call the constructor only in the process where you want to receive the data. In the usual workflow, the workers should not be calling the constructor, but should be handed an existing PollableDataQueue instance instead.
Properties

QueueLength — Number of items currently held on the queue
zero or positive integer

Read-only property that indicates how many items of data are waiting to be removed from the queue.

Example:

```matlab
pollableQ = parallel.pool.PollableDataQueue;
% No messages in queue because nothing has been sent yet.
pollableQ.QueueLength

ans =

   0

pollableQ.send('A message')
% Now QueueLength = 1 because one message is sent and not yet polled.
pollableQ.QueueLength

ans =

   1

msg = pollableQ.poll();
disp(msg)
A message

pollableQ.QueueLength
% Now QueueLength = 0 because there are no more pending messages.

ans =

   0
```

Methods

A parallel.pool.PollableDataQueue object has the following methods.
Copy Semantics

Handle. To learn how handle classes affect copy operations, see Copying Objects (MATLAB).

Examples

Send a Message in a \texttt{parfor}-loop, and Poll for the Result

Construct a \texttt{PollableDataQueue}.

\begin{verbatim}
p = parallel.pool.PollableDataQueue;
\end{verbatim}

Start a \texttt{parfor}-loop, and send a message, such as data with the value 1.

\begin{verbatim}
parfor i = 1
    send(p, i);
end
\end{verbatim}

Poll for the result.

\begin{verbatim}
poll(p)
\end{verbatim}

1

For more details on polling for data using a \texttt{PollableDataQueue}, see \texttt{poll}.

See Also
afterEach | gcp | labReceive | labSend | parallel.pool.DataQueue | parfeval | parfevalOnAll | parfor | poll | send

Topics
Class Attributes (MATLAB)
Property Attributes (MATLAB)

Introduced in R2017a
**parallel.Task**

Access task properties and behaviors

**Constructors**

`createTask`, `findTask`

`getCurrentTask` *(in the workspace of the MATLAB worker)*

**Container Hierarchy**

Parent: `parallel.Job`

Children: none

**Description**

A `parallel.Task` object provides access to a task, which executes on a worker as part of a job.

**Types**

The following table describes the available types of task objects, determined by the type of cluster.

<table>
<thead>
<tr>
<th>Task Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>parallel.task.MJSTask</code></td>
<td>Task on MJS cluster</td>
</tr>
<tr>
<td><code>parallel.task.CJSTask</code></td>
<td>Task on CJS cluster</td>
</tr>
</tbody>
</table>

**Methods**

All task type objects have the same methods, described in the following table.
# Properties

## Common to All Task Types

The following properties are common to all task object types.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CaptureDiary</td>
<td>Specify whether to return diary output</td>
</tr>
<tr>
<td>CreateDateTime</td>
<td>Date and time when the task is created</td>
</tr>
<tr>
<td>Diary</td>
<td>Text produced by execution of task object’s function</td>
</tr>
<tr>
<td>Error</td>
<td>Task error information</td>
</tr>
<tr>
<td>ErrorIdentifier</td>
<td>Task error identifier</td>
</tr>
<tr>
<td>ErrorMessage</td>
<td>Message from task error</td>
</tr>
<tr>
<td>FinishDateTime</td>
<td>Date and time when the task is finished</td>
</tr>
<tr>
<td>Function</td>
<td>Function called when evaluating task</td>
</tr>
<tr>
<td>ID</td>
<td>Task’s numeric identifier</td>
</tr>
<tr>
<td>InputArguments</td>
<td>Input arguments to task function</td>
</tr>
<tr>
<td>Name</td>
<td>Name of this task</td>
</tr>
<tr>
<td>NumOutputArguments</td>
<td>Number of arguments returned by task function</td>
</tr>
<tr>
<td>OutputArguments</td>
<td>Output arguments from running task function on worker</td>
</tr>
<tr>
<td>Parent</td>
<td>Job object containing this task</td>
</tr>
<tr>
<td>StartDateTime</td>
<td>Date and time when the task is started</td>
</tr>
<tr>
<td>State</td>
<td>Current state of task</td>
</tr>
<tr>
<td>UserData</td>
<td>Information associated with this task object</td>
</tr>
<tr>
<td>Warnings</td>
<td>Warning information issued during execution of the task, captured in a struct array with the fields message, identifier, and stack</td>
</tr>
<tr>
<td>Property</td>
<td>Description</td>
</tr>
<tr>
<td>------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Worker</td>
<td>Object representing worker that ran this task</td>
</tr>
</tbody>
</table>

### MJS Tasks

MJS task objects have the following properties in addition to the common properties:

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>FailureInfo</td>
<td>Information returned from failed task</td>
</tr>
<tr>
<td>FinishedFcn</td>
<td>Callback executed in client when task finishes</td>
</tr>
<tr>
<td>MaximumRetries</td>
<td>Maximum number of times to rerun failed task</td>
</tr>
<tr>
<td>NumFailures</td>
<td>Number of times tasked failed</td>
</tr>
<tr>
<td>RunningFcn</td>
<td>Callback executed in client when task starts running</td>
</tr>
<tr>
<td>Timeout</td>
<td>Time limit, in seconds, to complete task</td>
</tr>
</tbody>
</table>

### CJS Tasks

CJS task objects have no properties beyond the properties common to all clusters.

### Help

To get further help on either type of parallel.Task object, including a list of links to help for its properties, type:

```matlab
help parallel.task.MJSTask
help parallel.task.CJSTask
```

### See Also

Introduced in R2012a
**parallel.Worker**

Access worker that ran task

**Constructors**

`getCurrentWorker` in the workspace of the MATLAB worker.

In the client workspace, a parallel.Worker object is available from the `Worker` property of a parallel.Task object.

**Container Hierarchy**

Parent: `parallel.cluster.MJS`

Children: none

**Description**

A parallel.Worker object provides access to the MATLAB worker session that executed a task as part of a job.

**Types**

<table>
<thead>
<tr>
<th>Worker Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>parallel.cluster.MJSWorker</code></td>
<td>MATLAB worker on MJS cluster</td>
</tr>
<tr>
<td><code>parallel.cluster.CJSWorker</code></td>
<td>MATLAB worker on CJS cluster</td>
</tr>
</tbody>
</table>

**Methods**

There are no methods for a parallel.Worker object other than generic methods for any objects in the workspace, such as `delete`, etc.
Properties

MJS Worker

The following table describes the properties of an MJS worker.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AllHostAddresses</td>
<td>IP addresses of worker host</td>
</tr>
<tr>
<td>Name</td>
<td>Name of worker, set when worker session started</td>
</tr>
<tr>
<td>Parent</td>
<td>MJS cluster to which this worker belongs</td>
</tr>
</tbody>
</table>

CJS Worker

The following table describes the properties of an CJS worker.

<table>
<thead>
<tr>
<th>Property</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ComputerType</td>
<td>Type of computer on which worker ran; the value of the MATLAB function computer executed on the worker</td>
</tr>
<tr>
<td>Host</td>
<td>Host name where worker executed task</td>
</tr>
<tr>
<td>ProcessId</td>
<td>Process identifier for worker</td>
</tr>
</tbody>
</table>

Help

To get further help on either type of parallel.Worker object, including a list of links to help for its properties, type:

```
help parallel.cluster.MJSWorker
help parallel.cluster.CJSWorker
```

See Also

```
```

10-58
Introduced in R2012a
RemoteClusterAccess

Connect to schedulers when client utilities are not available locally

Constructor

<generatedlist role="syntaxlist"></generatedlist>

Description

parallel.cluster.RemoteClusterAccess allows you to establish a connection and run commands on a remote host. This class is intended for use with the generic scheduler interface when using remote submission of jobs or on nonshared file systems.

\[
r = \text{parallel.cluster.RemoteClusterAccess}(\text{username})\]

uses the supplied username when connecting to the remote host, and returns a RemoteClusterAccess object \(r\). You will be prompted for a password when establishing the connection.

\[
r = \text{parallel.cluster.RemoteClusterAccess}(\text{username}, P1, V1, \ldots, Pn, Vn)\]

allows additional parameter-value pairs that modify the behavior of the connection. The accepted parameters are:

- 'IdentityFilename' — A character vector containing the full path to the identity file to use when connecting to a remote host. If 'IdentityFilename' is not specified, you are prompted for a password when establishing the connection.

- 'IdentityFileHasPassphrase' — A logical indicating whether or not the identity file requires a passphrase. If true, you are prompted for a password when establishing a connection. If an identity file is not supplied, this property is ignored. This value is false by default.

For more information and detailed examples, see the integration scripts provided in \(\text{matlabroot/toolbox/distcomp/examples/integration}\). For example, the scripts for PBS in a nonshared file system are in

\(\text{matlabroot/toolbox/distcomp/examples/integration/pbs/nonshared}\)
## Methods

<table>
<thead>
<tr>
<th>Method Name</th>
<th>Description</th>
</tr>
</thead>
</table>
| connect                | connect(r,clusterHost) establishes a connection to the specified host using the user credential options supplied in the constructor. File mirroring is not supported.  
connect(r,clusterHost,remoteDataLocation) establishes a connection to the specified host using the user credential options supplied in the constructor.  
remoteDataLocation identifies a folder on the clusterHost that is used for file mirroring. The user credentials supplied in the constructor must have write access to this folder. |
| disconnect             | disconnect(r) disconnects the existing remote connection. The connect method must have already been called.                                      |
| doLastMirrorForJob     | doLastMirrorForJob(r,job) performs a final copy of changed files from the remote DataLocation to the local DataLocation for the supplied job. Any running mirrors for the job also stop and the job files are removed from the remote DataLocation. The startMirrorForJob or resumeMirrorForJob method must have already been called. |
| getRemoteJobLocation   | getRemoteJobLocation(r,jobID,remoteOS) returns the full path to the remote job location for the supplied jobID. Valid values for remoteOS are 'pc' and 'unix'. |
| isJobUsingConnection   | isJobUsingConnection(r,jobID) returns true if the job is currently being mirrored.                                                        |
| resumeMirrorForJob     | resumeMirrorForJob(r,job) resumes the mirroring of files from the remote DataLocation to the local DataLocation for the supplied job. This is similar to the startMirrorForJob method, but does not first copy the files from the local DataLocation to the remote DataLocation. The connect method must have already been called. This is useful if the original client MATLAB session has ended, and you are accessing the same files from a new client session. |
## Method Name

<table>
<thead>
<tr>
<th>Method Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>runCommand</td>
<td><code>[status, result] = runCommand(r, command)</code> runs the supplied command on the remote host and returns the resulting status and standard output. The <code>connect</code> method must have already been called.</td>
</tr>
<tr>
<td>startMirrorForJob</td>
<td><code>startMirrorForJob(r, job)</code> copies all the job files from the local <code>DataLocation</code> to the remote <code>DataLocation</code>, and starts mirroring files so that any changes to the files in the remote <code>DataLocation</code> are copied back to the local <code>DataLocation</code>. The <code>connect</code> method must have already been called.</td>
</tr>
<tr>
<td>stopMirrorForJob</td>
<td><code>stopMirrorForJob(r, job)</code> immediately stops the mirroring of files from the remote <code>DataLocation</code> to the local <code>DataLocation</code> for the specified job. The <code>startMirrorForJob</code> or <code>resumeMirrorForJob</code> method must have already been called. This cancels the running mirror and removes the files for the job from the remote location. This is similar to <code>doLastMirrorForJob</code>, except that <code>stopMirrorForJob</code> makes no attempt to ensure that the local job files are up to date. For normal mirror stoppage, use <code>doLastMirrorForJob</code>.</td>
</tr>
</tbody>
</table>

## Properties

A `RemoteClusterAccess` object has the following read-only properties. Their values are set when you construct the object or call its `connect` method.

<table>
<thead>
<tr>
<th>Property Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hostname</td>
<td>Name of the remote host to access.</td>
</tr>
<tr>
<td>IdentityFileHasPassphrase</td>
<td>Indicates if the identity file requires a passphrase.</td>
</tr>
<tr>
<td>IdentityFilename</td>
<td>Full path to the identity file used when connecting to the remote host.</td>
</tr>
<tr>
<td>IsConnected</td>
<td>Indicates if there is an active connection to the remote host.</td>
</tr>
<tr>
<td>IsFileMirrorSupported</td>
<td>Indicates if file mirroring is supported for this connection. This is false if no remote <code>DataLocation</code> is supplied to the <code>connect()</code> method.</td>
</tr>
<tr>
<td>Property Name</td>
<td>Description</td>
</tr>
<tr>
<td>------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>JobStorageLocation</td>
<td>Location on the remote host for files that are being mirrored.</td>
</tr>
<tr>
<td>UseIdentityFile</td>
<td>Indicates if an identity file should be used when connecting to the remote host.</td>
</tr>
<tr>
<td>Username</td>
<td>User name for connecting to the remote host.</td>
</tr>
</tbody>
</table>

### Examples

Mirror files from the remote data location. Assume the object `job` represents a job on your generic scheduler.

```matlab
code = parallel.cluster.RemoteClusterAccess('testname');
connect(code, 'headnode1', '/tmp/filemirror');
startMirrorForJob(code, job);
submit(job);
% Wait for the job to finish
wait(job);

% Ensure that all the local files are up to date, and remove the % remote files
doLastMirrorForJob(code, job);

% Get the output arguments for the job
results = fetchOutputs(job)
```

For more detailed examples, see the integration scripts provided in `matlabroot/toolbox/distcomp/examples/integration`. For example, the scripts for PBS in a nonshared file system are in

```matlab
matlabroot/toolbox/distcomp/examples/integration/pbs/nonshared
```

**Introduced in R2011a**
Functions — Alphabetical List
addAttachedFiles

Attach files or folders to parallel pool

Syntax

addAttachedFiles(poolobj,files)

Description

addAttachedFiles(poolobj,files) adds extra attached files to the specified parallel pool. These files are transferred to each worker and are treated exactly the same as if they had been set at the time the pool was opened — specified by the parallel profile or the 'AttachedFiles' argument of the parpool function.

Examples

Add Attached Files to Current Parallel Pool

Add two attached files to the current parallel pool.

poolobj = gcp;
addAttachedFiles(poolobj,{'myFun1.m','myFun2.m'})

Input Arguments

poolobj — Pool to which files attach
pool object

Pool to which files attach, specified as a pool object.

Example: poolobj = gcp;
files — Files or folders to attach
character vector | cell array

Files or folders to attach, specified as a character vector or cell array of character vectors. Each character vector can specify either an absolute or relative path to a file or folder.

Example: {'myFun1.m','myFun2.m'}

See Also
gcp | getAttachedFilesFolder | listAutoAttachedFiles | parpool | updateAttachedFiles

Topics
“Create and Modify Cluster Profiles” on page 6-24

Introduced in R2013b
**afterEach**

Define a function to call when new data is received.

**Syntax**

```matlab
listener = afterEach(queue, funtocall)
```

**Description**

`listener = afterEach(queue, funtocall)` specifies a function `funtocall` to execute each time the queue receives new data. You can specify multiple different functions to call, because each call to `afterEach` creates a new listener on the queue. If you want to specify another function, call `afterEach` again. To remove the registration of the function with the queue, delete the returned `listener` object.

You must call `afterEach` in the same process where you created the data queue, otherwise an error occurs. After calling `afterEach`, any current data in the queue is dispatched immediately to the supplied function.

**Examples**

**Call afterEach to Dispatch Data on a Queue**

If you call `afterEach` and there are items on the queue waiting to be dispatched, these items are immediately dispatched to the `afterEach` function. Call `afterEach` before sending data to the queue, to ensure that on `send`, the function handle specified by `afterEach` is called.

Construct a `DataQueue` and call `afterEach`.

```matlab
q = parallel.pool.DataQueue;
afterEach(q, @disp);
```
If you then send messages to the queue, each message is passed to the function handle specified by `afterEach` immediately.

```matlab
parfor i = 1
    send(q, 2);
end

send(q, 3)
```

You can also first send various messages to the queue. When you call `afterEach`, the pending messages are passed to the `afterEach` function, in this example to the function handle `@disp`.

```matlab
q = parallel.pool.DataQueue;
parfor i = 1
    send(q, 2);
end
send(q, 3)

afterEach(q, @disp);
```

### Remove a Callback by Deleting the Listener

Construct a `DataQueue` and create a listener.

```matlab
D = parallel.pool.DataQueue;
listener = D.afterEach(@disp);
```

Send some data with the value 1.

```matlab
D.send(1)
```

Delete the listener.
delete(listener)
D.send(1)

No data is returned because you have removed the callback by deleting the listener.

### Input Arguments

- **queue** — Data queue
  parallel.pool.DataQueue

  Data queue, specified as a parallel.pool.DataQueue object.

  Example: `q = parallel.pool.DataQueue;`

- **funtocall** — Function handle
  function handle

  Function handle, specifying the function added to the list of functions to call when a piece of new data is received from `queue`.

  Example: `listener = afterEach(queue, funtocall)`

  All callback functions must accept `data` as single argument.

  `afterEach(queue, @foo)` expects a function handle `@foo` to a function of the form

  ```
  function foo(data)
  end
  ```

  When `send(queue, someData)` is called on the worker, `someData` is serialized and sent back to the client. `someData` is deserialized on the client and passed as the input to `foo(data)`.

### Output Arguments

- **listener** — listener
  event.listener

  Listener object created by `afterEach`, returned as the handle to an event.listener object.
See Also
afterEach | event.listener | parallel.pool.DataQueue | parallel.pool.PollableDataQueue | parfor | poll | send

Introduced in R2017a
arrayfun

Apply function to each element of array on GPU

Syntax

A = arrayfun(FUN, B)
A = arrayfun(FUN,B,C,...)
[A,B,...] = arrayfun(FUN,C,...)

Description

This method of a gpuArray object is very similar in behavior to the MATLAB function arrayfun, except that the actual evaluation of the function happens on the GPU, not on the CPU. Thus, any required data not already on the GPU is moved to GPU memory, the MATLAB function passed in for evaluation is compiled for the GPU, and then executed on the GPU. All the output arguments return as gpuArray objects, whose data you can retrieve with the gather method.

A = arrayfun(FUN, B) applies the function specified by FUN to each element of the gpuArray B, and returns the results in gpuArray A. A is the same size as B, and A(i,j,...) is equal to FUN(B(i,j,...)). FUN is a function handle to a function that takes one input argument and returns a scalar value. FUN must return values of the same class each time it is called. The input data must be an array of one of the following types: numeric, logical, or gpuArray. The order in which arrayfun computes elements of A is not specified and should not be relied on.

FUN must be a handle to a function that is written in the MATLAB language (i.e., not a MEX-function).

For more detailed information, see “Run Element-wise MATLAB Code on GPU” on page 9-14. For the subset of the MATLAB language that is currently supported by arrayfun on the GPU, see “Supported MATLAB Code” on page 9-15.

A = arrayfun(FUN,B,C,...) evaluates FUN using elements of arrays B, C, ... as input arguments with singleton expansion enabled. The resulting gpuArray element
\( A(i,j,...) \) is equal to \( \text{FUN}(B(i,j,...),C(i,j,...),...) \). The inputs \( B, C, ... \) must all have the same size or be scalar. Any scalar inputs are scalar expanded before being input to the function \( \text{FUN} \).

One or more of the inputs \( B, C, ... \) must be a gpuArray; any of the others can reside in CPU memory. Each array that is held in CPU memory is converted to a gpuArray before calling the function on the GPU. If you plan to use an array in several different \( \text{arrayfun} \) calls, it is more efficient to convert that array to a gpuArray before making the series of calls to \( \text{arrayfun} \).

\[ [A,B,...] = \text{arrayfun}(\text{FUN},C,...), \] where \( \text{FUN} \) is a function handle to a function that returns multiple outputs, returns gpuArrays \( A, B, ... \), each corresponding to one of the output arguments of \( \text{FUN} \). \( \text{arrayfun} \) calls \( \text{FUN} \) each time with as many outputs as there are in the call to \( \text{arrayfun} \). \( \text{FUN} \) can return output arguments having different classes, but the class of each output must be the same each time \( \text{FUN} \) is called. This means that all elements of \( A \) must be the same class; \( B \) can be a different class from \( A \), but all elements of \( B \) must be of the same class, etc.

Although the MATLAB \( \text{arrayfun} \) function allows you to specify optional parameter name/value pairs, the \( \text{gpuArray} \) \( \text{arrayfun} \) method does not support these options.

**Tips**

- The first time you call \( \text{arrayfun} \) to run a particular function on the GPU, there is some overhead time to set up the function for GPU execution. Subsequent calls of \( \text{arrayfun} \) with the same function can run significantly faster.

- Nonsingleton dimensions of input arrays must match each other. In other words, the corresponding dimensions of arguments \( B, C, \) etc., must be equal to each other, or equal to one. Whenever a dimension of an input array is singleton (equal to 1), \( \text{arrayfun} \) uses singleton expansion to virtually replicate the array along that dimension to match the largest of the other arrays in that dimension. In the case where a dimension of an input array is singleton and the corresponding dimension in another argument array is zero, \( \text{arrayfun} \) virtually diminishes the singleton dimension to 0.

The size of the output array \( A \) is such that each dimension is the largest of the input arrays in that dimension for nonzero size, or zero otherwise. Notice in the following code how dimensions of size 1 are scaled up or down to match the size of the corresponding dimension in the other argument:
R1 = rand(2,5,4,'gpuArray');
R2 = rand(2,1,4,3,'gpuArray');
R3 = rand(1,5,4,3,'gpuArray');
R = arrayfun(@(x,y,z)(x+y.*z),R1,R2,R3);
size(R)
   2     5     4     3

R1 = rand(2,2,0,4,'gpuArray');
R2 = rand(2,1,1,4,'gpuArray');
R = arrayfun(@plus,R1,R2);
size(R)
   2     2     0     4

• Because the operations supported by arrayfun are strictly element-wise, and each element’s computation is performed independently of the others, certain restrictions are imposed:
  • Input and output arrays cannot change shape or size.
  • Functions like rand do not support size specifications. Arrays of random numbers have independent streams for each element.

For more limitations and details, see “Tips and Restrictions” on page 9-18.

---

Examples

If you define a MATLAB function as follows:

```matlab
function [o1,o2] = aGpuFunction(a,b,c)
o1 = a + b;
o2 = o1 .* c + 2;
```

You can evaluate this on the GPU.

```matlab
s1 = gpuArray(rand(400));
s2 = gpuArray(rand(400));
s3 = gpuArray(rand(400));
[o1,o2] = arrayfun(@aGpuFunction,s1,s2,s3);
whos
```

<table>
<thead>
<tr>
<th>Name</th>
<th>Size</th>
<th>Bytes</th>
<th>Class</th>
</tr>
</thead>
<tbody>
<tr>
<td>s1</td>
<td>400</td>
<td>3200</td>
<td></td>
</tr>
<tr>
<td>s2</td>
<td>400</td>
<td>3200</td>
<td></td>
</tr>
<tr>
<td>s3</td>
<td>400</td>
<td>3200</td>
<td></td>
</tr>
<tr>
<td>o1</td>
<td>400</td>
<td>3200</td>
<td></td>
</tr>
<tr>
<td>o2</td>
<td>400</td>
<td>3200</td>
<td></td>
</tr>
</tbody>
</table>
Use `gather` to retrieve the data from the GPU to the MATLAB workspace.

```matlab
d = gather(o2);
```

**See Also**

`bsxfun` | `gather` | `gpuArray` | `pagefun`

*Introduced in R2010b*
**batch**

Run MATLAB script or function on worker

**Syntax**

```plaintext
j = batch('aScript')
j = batch(myCluster,'aScript')
j = batch(fcn,N,{x1, ..., xn})
j = batch(myCluster,fcn,N,{x1,...,xn})
j = batch(...,'p1',v1,'p2',v2,...)
```

**Arguments**

- `j`: The batch job object.
- `'aScript'`: The script of MATLAB code to be evaluated by the worker.
- `myCluster`: Cluster object representing cluster compute resources.
- `fcn`: Function handle or function name to be evaluated by the worker.
- `N`: The number of output arguments from the evaluated function.
- `{x1, ..., xn}`: Cell array of input arguments to the function.
- `p1`, `p2`: Object properties or other arguments to control job behavior.
- `v1`, `v2`: Initial values for corresponding object properties or arguments.

**Description**

`j = batch('aScript')` runs the script code of the file `aScript.m` on a worker in the cluster specified by the default cluster profile. (Note: Do not include the `.m` file extension with the script name argument.) The function returns `j`, a handle to the job object that runs the script. The script file `aScript.m` is copied to the worker.

`j = batch(myCluster,'aScript')` is identical to `batch('aScript')` except that the script runs on a worker according to the cluster identified by the cluster object `myCluster`.
\[ j = \text{batch}(\text{fcn},N,\{x_1, \ldots, x_n\}) \] runs the function specified by a function handle or function name, \text{fcn}, on a worker in the cluster identified by the default cluster profile. The function returns \( j \), a handle to the job object that runs the function. The function is evaluated with the given arguments, \( x_1, \ldots, x_n \), returning \( N \) output arguments. The function file for \text{fcn} is copied to the worker. (Do not include the \text{.m} file extension with the function name argument.)

\[ j = \text{batch}(\text{myCluster},\text{fcn},N,\{x_1, \ldots, x_n\}) \] is identical to \( \text{batch}(\text{fcn},N,\{x_1, \ldots, x_n\}) \) except that the function runs on a worker in the cluster identified by the cluster object \text{myCluster}.

\[ j = \text{batch}(\ldots,'p1',v1,'p2',v2,\ldots) \] allows additional parameter-value pairs that modify the behavior of the job. These parameters support \text{batch} for functions and scripts, unless otherwise indicated. The supported parameters are:

- **'Workspace'** — A 1-by-1 struct to define the workspace on the worker just before the script is called. The field names of the struct define the names of the variables, and the field values are assigned to the workspace variables. By default this parameter has a field for every variable in the current workspace where \text{batch} is executed. This parameter supports only the running of scripts.

- **'Profile'** — The name of a cluster profile used to identify the cluster. If this option is omitted, the default profile is used to identify the cluster and is applied to the job and task properties.

- **'AdditionalPaths'** — A character vector or cell array of character vectors that defines paths to be added to the MATLAB search path of the workers before the script or function executes. The default search path might not be the same on the workers as it is on the client; the path difference could be the result of different current working folders (\text{pwd}), platforms, or network file system access. The 'AdditionalPaths' property can assure that workers are looking in the correct locations for necessary code files, data files, model files, etc.

- **'AttachedFiles'** — A character vector or cell array of character vectors. Each character vector in the list identifies either a file or a folder, which gets transferred to the worker.

- **'AutoAddClientPath'** — A logical value (\text{true} or \text{false}) that controls whether user-added-entries on the client's path are added to each worker's path. The default is \text{true}.

- **'AutoAttachFiles'** — A logical value to specify whether code files should be automatically attached to the job. If \text{true}, the batch script or function is analyzed and
the code files that it depends on are automatically transferred to the worker. The default is true.

- 'CurrentFolder' — A character vector indicating in what folder the script executes. There is no guarantee that this folder exists on the worker. The default value for this property is the cwd of MATLAB when the batch command is executed. If the argument is '.', there is no change in folder before batch execution.

- 'CaptureDiary' — A logical flag to indicate that the toolbox should collect the diary from the function call. See the diary function for information about the collected data. The default is true.

- 'EnvironmentVariables' — A character vector, or cell array of character vectors that specifies the names of environment variables which are copied from the client session to the workers. The names specified here are appended to the 'EnvironmentVariables' property specified in the applicable parallel profile to form the complete list of environment variables. Any variables listed which are not set are not copied to the workers. These environment variables will be set on the workers for the duration of the batch job.

- 'Pool' — An integer specifying the number of workers to make into a parallel pool for the job in addition to the worker running the batch job itself. The script or function uses this pool for execution of statements such as parfor and spmd that are inside the batch code. Because the pool requires \( N \) workers in addition to the worker running the batch, there must be at least \( N+1 \) workers available on the cluster. You do not need a parallel pool already running to execute batch; and the new pool that batch creates is not related to a pool you might already have open. (See “Run a Batch Parallel Loop” on page 1-7.) The default value is 0, which causes the script or function to run on only a single worker without a parallel pool.

**Examples**

Run a batch script on a worker, without using a parallel pool:

```matlab
j = batch('script1');
```

Run a batch script that requires two additional files for execution:

```matlab
j = batch('myScript','AttachedFiles',{'mscr1.m','mscr2.m'});
wait(j);
load(j);
```
Run a batch pool job on a remote cluster, using eight workers for the parallel pool in addition to the worker running the batch script. Capture the diary, and load the results of the job into the workspace. This job requires a total of nine workers:

```matlab
j = batch('script1','Pool',8,'CaptureDiary',true);
wait(j);   % Wait for the job to finish
diary(j)   % Display the diary
load(j)    % Load job workspace data into client workspace
```

Run a batch pool job on a local worker, which employs two other local workers for the pool. Note, this requires a total of three workers in addition to the client, all on the local machine:

```matlab
j = batch('script1','Profile','local','Pool',2);
```

Clean up a batch job’s data after you are finished with it:

```matlab
delete(j)
```

Run a batch function on a cluster that generates a 10-by-10 random matrix:

```matlab
c = parcluster();
j = batch(c,@rand,1,{10,10});
```

```matlab
wait(j)   % Wait for the job to finish
diary(j)   % Display the diary
```

```matlab
r = fetchOutputs(j); % Get results into a cell array
r{1}                 % Display result
```

### Tips

To see your batch job’s status or to track its progress, use the Job Monitor, as described in “Job Monitor” on page 6-38. You can also use the Job Monitor to retrieve a job object for a batch job that was created in a different session, or for a batch job that was created without returning a job object from the `batch` call.

As a matter of good programming practice, when you no longer need it, you should delete the job created by the batch function so that it does not continue to consume cluster storage resources.
See Also
delete | diary | findJob | load | wait

Introduced in R2008a
bsxfun

Binary singleton expansion function for gpuArray

Syntax

\[ C = \text{bsxfun}(\text{FUN}, A, B) \]

Description

bsxfun with gpuArray input is similar in behavior to the MATLAB function bsxfun, except that the actual evaluation of the function, \text{FUN}, happens on the GPU, not on the CPU.

\[ C = \text{bsxfun}(\text{FUN}, A, B) \]
applies the element-by-element binary operation specified by the function handle \text{FUN} to arrays \( A \) and \( B \), with singleton expansion enabled. If \( A \) or \( B \) is a gpuArray, bsxfun moves all other required data to the GPU and performs its calculation on the GPU. The output array \( C \) is a gpuArray, which you can copy to the MATLAB workspace with \text{gather}.

For more detailed information, see “Run Element-wise MATLAB Code on GPU” on page 9-14. For the subset of the MATLAB language that is currently supported by bsxfun on the GPU, see “Supported MATLAB Code” on page 9-15.

The corresponding dimensions of \( A \) and \( B \) must be equal to each other, or equal to one. Whenever a dimension of \( A \) or \( B \) is singleton (equal to 1), bsxfun virtually replicates the array along that dimension to match the other array. In the case where a dimension of \( A \) or \( B \) is singleton and the corresponding dimension in the other array is zero, bsxfun virtually diminishes the singleton dimension to 0.

The size of the output array \( C \) is such that each dimension is the larger of the two input arrays in that dimension for nonzero size, or zero otherwise. Notice in the following code how dimensions of size 1 are scaled up or down to match the size of the corresponding dimension in the other argument:

\[
\begin{align*}
R1 & = \text{rand}(2, 5, 4, 'gpuArray'); \\
R2 & = \text{rand}(2, 1, 4, 3, 'gpuArray');
\end{align*}
\]
R = bsxfun(@plus,R1,R2);
size(R)

2 5 4 3

R1 = rand(2,2,0,4,'gpuArray');
R2 = rand(2,1,1,4,'gpuArray');
R = bsxfun(@plus,R1,R2);
size(R)

2 2 0 4

Examples

Subtract the mean of each column from all elements in that column:

A = rand(8,'gpuArray');
M = bsxfun(@minus,A,mean(A));

See Also

arrayfun | gather | gpuArray | pagefun

Introduced in R2012a
cancel

Cancel job or task

Syntax

cancel(t)
cancel(j)

Arguments

<table>
<thead>
<tr>
<th>t</th>
<th>Pending or running task to cancel.</th>
</tr>
</thead>
<tbody>
<tr>
<td>j</td>
<td>Pending, running, or queued job to cancel.</td>
</tr>
</tbody>
</table>

Description

cancel(t) stops the task object, t, that is currently in the pending or running state. The task’s State property is set to finished, and no output arguments are returned. An error message stating that the task was canceled is placed in the task object’s ErrorMessage property, and the worker session running the task is restarted.

cancel(j) stops the job object, j, that is pending, queued, or running. The job’s State property is set to finished, and a cancel is executed on all tasks in the job that are not in the finished state. A job object that has been canceled cannot be started again.

If the job is running from an MJS, any worker sessions that are evaluating tasks belonging to the job object are restarted.

If the specified job or task is already in the finished state, no action is taken.

Examples

Cancel a task. Note afterward the task’s State, ErrorIdentifier, and ErrorMessage properties.
c = parcluster();
job1 = createJob(c);
t = createTask(job1, @rand, 1, {3,3});
cancel(t)
t
Task with properties:
  ID: 1
  State: finished
  Function: @rand
  Parent: Job 1
  StartTime: 
  Running Duration: 0 days 0h 0m 0s
  ErrorIdentifier: parallel:task:UserCancellation
  ErrorMessage: The task was cancelled by user "mylogin" on machine "myhost.mydomain.com".

See Also
delete | submit

Introduced before R2006a
cancel (FevalFuture)

Cancel queued or running future

Syntax

cancel(F)

Description

cancel(F) stops the queued and running futures contained in F. No action is taken for finished futures. Each element of F that is not already in state 'finished' has its State property set to 'finished', and its Error property is set to contain an MException indicating that execution was cancelled.

Examples

Run a function several times until a satisfactory result is found. In this case, the array of futures F is cancelled when a result is greater than 0.95.

N = 100;
for idx = N:-1:1
    F(idx) = parfeval(@rand,1); % Create a random scalar
end
result = NaN; % No result yet.
for idx = 1:N
    [~, thisResult] = fetchNext(F);
    if thisResult > 0.95
        result = thisResult;
        % Have all the results needed, so break
        break;
    end
end
% With required result, cancel any remaining futures
cancel(F)
result
See Also
fetchNext | fetchOutputs | isEqual | parfeval | parfevalOnAll

Introduced in R2013b
changePassword

Prompt user to change MJS password

Syntax

changePassword(mjs)
changePassword(mjs,username)

Arguments

mjs MJS cluster object on which password is changing
username Character vector identifying the user whose password is changing

Description

changePassword(mjs) prompts you to change your password as the current user on the MATLAB job scheduler (MJS) cluster represented by cluster object mjs. (Use the parcluster function to create a cluster object.) In the dialog box that opens, you must enter your current password as well as the new password.

changePassword(mjs,username) prompts you as the MJS cluster admin user to change the password for another specified user. In the dialog box that opens, you must enter the cluster admin password in addition to the user’s new password. This allows the cluster admin to reset a password for a user who is not available or has forgotten the password. (Note: The cluster admin account was created when the MJS cluster was started with a security level of 1, 2, or 3.)
Examples

Change Password with a Cluster Profile

Change your password for the MJS cluster identified by an MJS cluster profile called MyMjsProfile.

```matlab
mjs = parcluster('MyMjsProfile');
changePassword(mjs)
```

Change Password on a Parallel Pool

Change your password for the MJS cluster on which the parallel pool is running.

```matlab
p = gcp;
mjs = p.Cluster;
changePassword(mjs)
```

Change Password of Another User

Change the password for another user named john. The admin user can access the MJS from a different session of MATLAB to do this, or change the Username property of the cluster object within john’s MATLAB client session.

```matlab
mjs = parcluster('MyMjsProfile');
mjs.Username = 'admin'     % Generates prompt for admin user password.
changePassword(mjs,'john') % Generates prompt for both passwords.
```
At this point, the admin user might want to set the session user back to john.

```matlab
mjs.Username = 'john'  % Prompted again for password.
```

See Also

`logout` | `parcluster` | `startjobmanager`

Topics

“Set MJS Cluster Security” (MATLAB Distributed Computing Server)

Introduced in R2010b
classUnderlying

Class of elements within gpuArray or distributed array

Syntax

C = classUnderlying(D)

Description

C = classUnderlying(D) returns the name of the class of the elements contained within the gpuArray or distributed array D. Similar to the MATLAB class function, this returns a character vector indicating the class of the data.

Examples

Examine the class of the elements of a gpuArray.

N = 1000;
G8 = ones(1,N,'uint8','gpuArray');
G1 = NaN(1,N,'single','gpuArray');
c8 = classUnderlying(G8)
c1 = classUnderlying(G1)

c8 =
uint8

c1 =
single

Examine the class of the elements of a distributed array.

N = 1000;
D8 = ones(1,N,'uint8','distributed');
D1 = NaN(1,N,'single','distributed');
c8 = classUnderlying(D8)
c1 = classUnderlying(D1)

c8 =
uint8

c1 =
single

See Also
codistributed | distributed | gpuArray

Introduced in R2013b
clear

Remove objects from MATLAB workspace

Syntax

clear obj

Arguments

obj                   An object or an array of objects.

Description

clear obj removes obj from the MATLAB workspace.

Note Use parfevalOnAll instead of parfor or spmd if you want to use clear. This preserves workspace “Ensure Transparency in parfor-Loops” on page 2-56.

Examples

This example creates two job objects on the MATLAB job scheduler jm. The variables for these job objects in the MATLAB workspace are job1 and job2. job1 is copied to a new variable, job1copy; then job1 and job2 are cleared from the MATLAB workspace. The job objects are then restored to the workspace from the job object's Jobs property as j1 and j2, and the first job in the MJS is shown to be identical to job1copy, while the second job is not.

c = parcluster();
delete(c.Jobs) % Assure there are no jobs
job1 = createJob(c);
job2 = createJob(c);
job1copy = job1;
clear job1 job2;
j1 = c.Jobs(1);
j2 = c.Jobs(2);
isequal (job1copy,j1)

ans =
    1

isequal (job1copy,j2)

ans =
    0

**Tips**

If `obj` references an object in the cluster, it is cleared from the workspace, but it remains in the cluster. You can restore `obj` to the workspace with the `parcluster`, `findJob`, or `findTask` function; or with the `Jobs` or `Tasks` property.

**See Also**

`createJob` | `createTask` | `findJob` | `findTask` | `parcluster`

*Introduced before R2006a*
codistributed

Create codistributed array from replicated local data

Syntax

\[ C = \text{codistributed}(X) \]
\[ C = \text{codistributed}(X,\text{codist}) \]
\[ C = \text{codistributed}(X,\text{lab},\text{codist}) \]
\[ C = \text{codistributed}(C1,\text{codist}) \]

Description

\( C = \text{codistributed}(X) \) distributes a replicated array \( X \) using the default codistributor, creating a codistributed array \( C \) as a result. \( X \) must be a replicated array, that is, it must have the same value on all workers. \( \text{size}(C) \) is the same as \( \text{size}(X) \).

\( C = \text{codistributed}(X,\text{codist}) \) distributes a replicated array \( X \) using the distribution scheme defined by codistributor \( \text{codist} \). \( X \) must be a replicated array, namely it must have the same value on all workers. \( \text{size}(C) \) is the same as \( \text{size}(X) \). For information on constructing codistributor objects, see the reference pages for \( \text{codistributor1d} \) and \( \text{codistributor2dbc} \).

\( C = \text{codistributed}(X,\text{lab},\text{codist}) \) distributes a local array \( X \) that resides on the worker identified by \( \text{lab} \), using the codistributor \( \text{codist} \). Local array \( X \) must be defined on all workers, but only the value from \( \text{lab} \) is used to construct \( C \). \( \text{size}(C) \) is the same as \( \text{size}(X) \).

\( C = \text{codistributed}(C1,\text{codist}) \) accepts an array \( C1 \) that is already codistributed, and redistributes it into \( C \) according to the distribution scheme defined by the codistributor \( \text{codist} \). This is the same as calling \( C = \text{redistribute}(C1,\text{codist}) \). If the existing distribution scheme for \( C1 \) is the same as that specified in \( \text{codist} \), then the result \( C \) is the same as the input \( C1 \).
Examples

Create a 1000-by-1000 codistributed array \( C_1 \) using the default distribution scheme.

```matlab
spmd
    N = 1000;
    X = magic(N);       % Replicated on every worker
    C1 = codistributed(X); % Partitioned among the workers
end
```

Create a 1000-by-1000 codistributed array \( C_2 \), distributed by rows (over its first dimension).

```matlab
spmd
    N = 1000;
    X = magic(N);
    C2 = codistributed(X,codistributor1d(1));
end
```

Tips

gather essentially performs the inverse of codistributed.

See Also

“What Is a Datastore?” (MATLAB) | codistributor1d | codistributor2dbc | distributed | gather | getLocalPart | globalIndices | redistribute | size | subsasgn | subsref
codistributed.build

Create codistributed array from distributed data

**Syntax**

\[ D = \text{codistributed.build}(L,\text{codist}) \]
\[ D = \text{codistributed.build}(L,\text{codist},'\text{noCommunication}') \]

**Description**

\( D = \text{codistributed.build}(L,\text{codist}) \) forms a codistributed array with
\( \text{getLocalPart}(D) = L \). The codistributed array \( D \) is created as if you had combined all copies of the local array \( L \). The distribution scheme is specified by \( \text{codist} \). Global error checking ensures that the local parts conform with the specified distribution scheme. For information on constructing codistributor objects, see the reference pages for \( \text{codistributor1d} \) and \( \text{codistributor2dbc} \).

\( D = \text{codistributed.build}(L,\text{codist},'\text{noCommunication}') \) builds a codistributed array, without performing any interworker communications for error checking.

\( \text{codist} \) must be complete, which you can check by calling \( \text{codist}.\text{isComplete}() \). The requirements on the size and structure of the local part \( L \) depend on the class of \( \text{codist} \). For the 1-D and 2-D block-cyclic codistributors, \( L \) must have the same class and sparsity on all workers. Furthermore, the local part \( L \) must represent the region described by the \( \text{globalIndices} \) method on \( \text{codist} \).

**Examples**

Create a codistributed array of size 1001-by-1001 such that column \( ii \) contains the value \( ii \).

```
spmd
    N = 1001;
    globalSize = [N,N];
```
% Distribute the matrix over the second dimension (columns),
% and let the codistributor derive the partition from the
% global size.
codistr = codistributor1d(2, ...
    codistributor1d.unsetPartition,globalSize)

% On 4 workers, codistr.Partition equals [251,250,250,250].
% Allocate storage for the local part.
localSize = [N, codistr.Partition(labindex)];
L = zeros(localSize);

% Use globalIndices to map the indices of the columns
% of the local part into the global column indices.
globalInd = codistr.globalIndices(2);
% On 4 workers, globalInd has the values:
% 1:251    on worker 1
% 252:501  on worker 2
% 502:751  on worker 3
% 752:1001 on worker 4

% Initialize the columns of the local part to
% the correct value.
for localCol = 1:length(globalInd)
    globalCol = globalInd(localCol);
    L(:,localCol) = globalCol;
end
D = codistributed.build(L,codistr)
end

See Also
codistributor1d | codistributor2dbc | gather | getLocalPart |
globalIndices | redistribute | size | subsasgn | subsref

Introduced in R2009b
codistributed.cell

Create codistributed cell array

Syntax

C = codistributed.cell(n)
C = codistributed.cell(m,n,p,...)
C = codistributed.cell([m,n,p,...])
C = cell(n,codist)
C = cell(m,n,p,...,codist)
C = cell([m,n,p,...],codist)

Description

C = codistributed.cell(n) creates an n-by-n codistributed array of underlying class cell, distributing along columns.
C = codistributed.cell(m,n,p,...) or C = codistributed.cell([m,n,p,...]) creates an m-by-n-by-p-by-... codistributed array of underlying class cell, using a default scheme of distributing along the last nonsingleton dimension.

Optional arguments to codistributed.cell must be specified after the required arguments, and in the following order:

- codist — A codistributor object specifying the distribution scheme of the resulting array. If omitted, the array is distributed using the default distribution scheme. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc.
- 'noCommunication' — Specifies that no communication is to be performed when constructing the array, skipping some error checking steps.

C = cell(n,codist) is the same as C = codistributed.cell(n, codist). You can also use the 'noCommunication' object with this syntax. To use the default distribution scheme, specify a codistributor constructor without arguments. For example:
spmd
    C = cell(8,codistributor1d());
end

C = cell(m,n,p,...,codist) and C = cell([m,n,p,...],codist) are the same as C = codistributed.cell(m,n,p,...) and C = codistributed.cell([m,n,p,...]), respectively. You can also use the optional 'noCommunication' argument with this syntax.

Examples

With four workers,

```matlab
spmd(4)
    C = codistributed.cell(1000);
end
```

creates a 1000-by-1000 distributed cell array C, distributed by its second dimension (columns). Each worker contains a 1000-by-250 local piece of C.

```matlab
spmd(4)
    codist = codistributor1d(2, 1:numlabs);
    C = cell(10, 10, codist);
end
```

creates a 10-by-10 codistributed cell array C, distributed by its columns. Each worker contains a 10-by-labindex local piece of C.

See Also

cell | distributed.cell

Introduced in R2009b
codistributed.colon

Distributed colon operation

Syntax

codistributed.colon(a,d,b)
codistributed.colon(a,b)
codistributed.colon(___,'noCommunication')
codistributed.colon(___,'noCommunication')

description

codistributed.colon(a,d,b) partitions the vector a:d:b into numlabs contiguous subvectors of equal, or nearly equal length, and creates a codistributed array whose local portion on each worker is the labindex-th subvector.

codistributed.colon(a,b) uses d = 1.

Optional arguments to codistributed.colon must be specified after the required arguments, and in the following order:

codistributed.colon(___,'noCommunication') or codistributed.colon(___,'noCommunication') specifies that no communication is to be performed when constructing the vector, skipping some error checking steps.

Examples

Partition the vector 1:10 into four subvectors among four workers.


```matlab
spmd(4); C = codistributed.colon(1,10), end

Lab 1:
   This worker stores C(1:3).
   LocalPart: [1 2 3]
   Codistributor: [1x1 codistributor1d]
Lab 2:
   This worker stores C(4:6).
   LocalPart: [4 5 6]
   Codistributor: [1x1 codistributor1d]
Lab 3:
   This worker stores C(7:8).
   LocalPart: [7 8]
   Codistributor: [1x1 codistributor1d]
Lab 4:
   This worker stores C(9:10).
   LocalPart: [9 10]
   Codistributor: [1x1 codistributor1d]
```

**See Also**

codistributor1d | codistributor2dbc | colon | for

**Introduced in R2009b**
**codistributed.spalloc**

Allocate space for sparse codistributed matrix

**Syntax**

```matlab
SD = codistributed.spalloc(M,N,nzmax)
SD = spalloc(M,N,nzmax,codist)
```

**Description**

```matlab
SD = codistributed.spalloc(M,N,nzmax) creates an M-by-N all-zero sparse
codistributed matrix with room to hold nzmax nonzeros.
```

Optional arguments to `codistributed.spalloc` must be specified after the required arguments, and in the following order:

- `codist` — A codistributor object specifying the distribution scheme of the resulting array. If omitted, the array is distributed using the default distribution scheme. The allocated space for nonzero elements is consistent with the distribution of the matrix among the workers according to the `Partition` of the codistributor.
- `'noCommunication'` — Specifies that no communication is to be performed when constructing the array, skipping some error checking steps. You can also use this argument with `SD = spalloc(M, N, nzmax, codistr)`.

```matlab
SD = spalloc(M,N,nzmax,codist) is the same as SD =
codistributed.spalloc(M,N,nzmax,codist). You can also use the optional arguments with this syntax.
```

**Examples**

Allocate space for a 1000-by-1000 sparse codistributed matrix with room for up to 2000 nonzero elements. Use the default codistributor. Define several elements of the matrix.

```matlab
spmd  % codistributed array created inside spmd statement
    N = 1000;
```
SD = codistributed.spalloc(N, N, 2*N);
for ii=1:N-1
    SD(ii,ii:ii+1) = [ii ii];
end
end

See Also
distributed.spalloc | spalloc | sparse

Introduced in R2009b
codistributed.speye

Create codistributed sparse identity matrix

Syntax

CS = codistributed.speye(n)
CS = codistributed.speye(m,n)
CS = codistributed.speye([m,n])
CS = speye(n,codist)
CS = speye(m,n,codist)
CS = speye([m,n],codist)

Description

CS = codistributed.speye(n) creates an n-by-n sparse codistributed array of underlying class double.

CS = codistributed.speye(m,n) or CS = codistributed.speye([m,n]) creates an m-by-n sparse codistributed array of underlying class double.

Optional arguments to codistributed.speye must be specified after the required arguments, and in the following order:

- **codist** — A codistributor object specifying the distribution scheme of the resulting array. If omitted, the array is distributed using the default distribution scheme. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc.
- **'noCommunication'** — Specifies that no interworker communication is to be performed when constructing the array, skipping some error checking steps.

CS = speye(n,codist) is the same as CS = codistributed.speye(n,codist).

You can also use the optional arguments with this syntax. To use the default distribution scheme, specify a codistributor constructor without arguments. For example:
spmd
  CS = codistributed.speye(8,codistributor1d());
end

CS = speye(m,n,codist) and CS = speye([m,n],codist) are the same as CS =
codistributed.speye(m,n) and CS = codistributed.speye([m,n]),
respectively. You can also use the optional arguments with this syntax.

Note To create a sparse codistributed array of underlying class logical, first create an
array of underlying class double and then cast it using the logical function:

CLS = logical(speye(m,n,codistributor1d()))

Examples

With four workers,

spmd(4)
  CS = speye(1000,codistributor())
end

creates a 1000-by-1000 sparse codistributed double array CS, distributed by its second
dimension (columns). Each worker contains a 1000-by-250 local piece of CS.

spmd(4)
  codist = codistributor1d(2,1:numlabs);
  CS = speye(10,10,codist);
end

creates a 10-by-10 sparse codistributed double array CS, distributed by its columns. Each
worker contains a 10-by-labindex local piece of CS.

See Also
distributed.speye | sparse | speye

Introduced in R2009b
**codistributed.sprand**

Create codistributed sparse array of uniformly distributed pseudo-random values

**Syntax**

```matlab
CS = codistributed.sprand(m,n,density)
CS = sprand(n,codist)
```

**Description**

`CS = codistributed.sprand(m,n,density)` creates an `m`-by-`n` sparse codistributed array with approximately `density*m*n` uniformly distributed nonzero double entries.

Optional arguments to `codistributed.sprand` must be specified after the required arguments, and in the following order:

- `codist` — A codistributor object specifying the distribution scheme of the resulting array. If omitted, the array is distributed using the default distribution scheme. For information on constructing codistributor objects, see the reference pages for `codistributor1d` and `codistributor2dbc`.
- `'noCommunication'` — Specifies that no interworker communication is to be performed when constructing the array, skipping some error checking steps.

`CS = sprand(n,codist)` is the same as `CS = codistributed.sprand(n, codist)`. You can also use the optional arguments with this syntax. To use the default distribution scheme, specify a codistributor constructor without arguments. For example:

```matlab
spmd
    CS = codistributed.sprand(8,8,0.2,codistributor1d());
end
```

**Examples**

With four workers,
spmd(4)
    CS = codistributed.sprand(1000,1000,0.001);
end

creates a 1000-by-1000 sparse codistributed double array CS with approximately 1000 nonzeros. CS is distributed by its second dimension (columns), and each worker contains a 1000-by-250 local piece of CS.

spmd(4)
    codist = codistributor1d(2,1:numlabs);
    CS = sprand(10,10,0.1,codist);
end

creates a 10-by-10 codistributed double array CS with approximately 10 nonzeros. CS is distributed by its columns, and each worker contains a 10-by-labindex local piece of CS.

Tips

When you use sprand on the workers in the parallel pool, or in an independent or communicating job (including pmode), each worker sets its random generator seed to a value that depends only on the labindex or task ID. Therefore, the array on each worker is unique for that job. However, if you repeat the job, you get the same random data.

See Also
distributed.sprandn | rand | sprand

Introduced in R2009b
codistributed.sprandn

Create codistributed sparse array of uniformly distributed pseudo-random values

Syntax

CS = codistributed.sprandn(m,n,density)
CS = sprandn(n,codist)

Description

CS = codistributed.sprandn(m,n,density) creates an m-by-n sparse codistributed array with approximately density*m*n normally distributed nonzero double entries.

Optional arguments to codistributed.sprandn must be specified after the required arguments, and in the following order:

• codist — A codistributor object specifying the distribution scheme of the resulting array. If omitted, the array is distributed using the default distribution scheme. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc.

• 'noCommunication' — Specifies that no interworker communication is to be performed when constructing the array, skipping some error checking steps.

CS = sprandn(n,codist) is the same as CS = codistributed.sprandn(n, codist). You can also use the optional arguments with this syntax. To use the default distribution scheme, specify a codistributor constructor without arguments. For example:

```matlab
spmd
    CS = codistributed.sprandn(8,8,0.2,codistributor1d());
end
```

Examples

With four workers,
spmd(4)
    CS = codistributed.sprandn(1000,1000,0.001);
end

creates a 1000-by-1000 sparse codistributed double array CS with approximately 1000 nonzeros. CS is distributed by its second dimension (columns), and each worker contains a 1000-by-250 local piece of CS.

spmd(4)
    codist = codistributor1d(2,1:numlabs);
    CS = sprandn(10,10,0.1,codist);
end

creates a 10-by-10 codistributed double array CS with approximately 10 nonzeros. CS is distributed by its columns, and each worker contains a 10-by-labindex local piece of CS.

Tips

When you use sprandn on the workers in the parallel pool, or in an independent or communicating job (including pmode), each worker sets its random generator seed to a value that depends only on the labindex or task ID. Therefore, the array on each worker is unique for that job. However, if you repeat the job, you get the same random data.

See Also
codistributed.speye | codistributed.sprand | distributed.sprandn | rand | randn | sparse | sprandn

Introduced in R2009b
**codistributor**

Create codistributor object for codistributed arrays

**Syntax**

```matlab
codist = codistributor()
codist = codistributor('1d')
codist = codistributor('1d',dim)
codist = codistributor('1d',dim,part)
codist = codistributor('2dbc')
codist = codistributor('2dbc',lbgrid)
codist = codistributor('2dbc',lbgrid,blksize)
```

**Description**

There are two schemes for distributing arrays. The scheme denoted by the character vector '1d' distributes an array along a single specified subscript, the distribution dimension, in a noncyclic, partitioned manner. The scheme denoted by '2dbc', employed by the parallel matrix computation software ScaLAPACK, applies only to two-dimensional arrays, and varies both subscripts over a rectangular computational grid of labs (workers) in a blocked, cyclic manner.

`codist = codistributor()`, with no arguments, returns a default codistributor object with zero-valued or empty parameters, which can then be used as an argument to other functions to indicate that the function is to create a codistributed array if possible with default distribution. For example,

```matlab
Z = zeros(..., codistributor())
R = randn(..., codistributor())
```

`codist = codistributor('1d')` is the same as `codist = codistributor()`.

`codist = codistributor('1d',dim)` also forms a codistributor object with `codist.Dimension = dim` and default partition.
codist = codistributor('1d',dim,part) also forms a codistributor object with codist.Dimension = dim and codist.Particle = part.

codist = codistributor('2dbc') forms a 2-D block-cyclic codistributor object. For more information about '2dbc' distribution, see “2-Dimensional Distribution” on page 5-16.

codist = codistributor('2dbc',lbgrid) forms a 2-D block-cyclic codistributor object with the lab grid defined by lbgrid and with default block size.

codist = codistributor('2dbc',lbgrid,blksize) forms a 2-D block-cyclic codistributor object with the lab grid defined by lbgrid and with a block size defined by blksize.

codist = getCodistributor(D) returns the codistributor object of codistributed array D.

Examples

On four workers, create a 3-dimensional, 2-by-6-by-4 array with distribution along the second dimension, and partition scheme [1 2 1 2]. In other words, worker 1 contains a 2-by-1-by-4 segment, worker 2 a 2-by-2-by-4 segment, etc.

spmd
    dim = 2; % distribution dimension
    codist = codistributor('1d',dim,[1 2 1 2],[2 6 4]);
    if mod(labindex,2)
        L = rand(2,1,4);
    else
        L = rand(2,2,4);
    end
    A = codistributed.build(L,codist)
end
A

On four workers, create a 20-by-5 codistributed array A, distributed by rows (over its first dimension) with a uniform partition scheme.

spmd
    dim = 1; % distribution dimension
    partn = codistributor1d.defaultPartition(20);
codist = codistributor('1d',dim,partn,[20 5]);
L = magic(5) + labindex;
A = codistributed.build(L,codist)
end
A

See Also

codistributed | codistributor1d | codistributor2dbc | getCodistributor |
getLocalPart | redistribute

Introduced in R2008b
codistributor1d

Create 1-D codistributor object for codistributed arrays

Syntax

codist = codistributor1d()
codist = codistributor1d(dim)
codist = codistributor1d(dim,part)
codist = codistributor1d(dim,part,gsize)

Description

The 1-D codistributor distributes arrays along a single, specified distribution dimension, in a noncyclic, partitioned manner.

codist = codistributor1d() forms a codistributor1d object using default dimension and partition. The default dimension is the last nonsingleton dimension of the codistributed array. The default partition distributes the array along the default dimension as evenly as possible.

codist = codistributor1d(dim) forms a 1-D codistributor object for distribution along the specified dimension: 1 distributes along rows, 2 along columns, etc.

codist = codistributor1d(dim,part) forms a 1-D codistributor object for distribution according to the partition vector part. For example C1 =
codistributor1d(1, [1, 2, 3, 4]) describes the distribution scheme for an array of ten rows to be codistributed by its first dimension (rows), to four workers, with 1 row to the first, 2 rows to the second, etc.

The resulting codistributor of any of the above syntax is incomplete because its global size is not specified. A codistributor constructed in this manner can be used as an argument to other functions as a template codistributor when creating codistributed arrays.

codist = codistributor1d(dim,part,gsize) forms a codistributor object with distribution dimension dim, distribution partition part, and global size of its
codistributed arrays \texttt{gsize}. The resulting codistributor object is complete and can be used to build a codistributed array from its local parts with \texttt{codistributed.build}. To use a default dimension, specify \texttt{codistributor1d.unsetDimension} for that argument; the distribution dimension is derived from \texttt{gsize} and is set to the last non-singleton dimension. Similarly, to use a default partition, specify \texttt{codistributor1d.unsetPartition} for that argument; the partition is then derived from the default for that global size and distribution dimension.

The local part on worker \texttt{labidx} of a codistributed array using such a codistributor is of size \texttt{gsize} in all dimensions except \texttt{dim}, where the size is \texttt{part(labidx)}. The local part has the same class and attributes as the overall codistributed array. Conceptually, the overall global array could be reconstructed by concatenating the various local parts along dimension \texttt{dim}.

**Examples**

Use a \texttt{codistributor1d} object to create an \texttt{N-by-N} matrix of ones, distributed by rows.

\begin{verbatim}
N = 1000;
spmd
codistr = codistributor1d(1); % 1st dimension (rows)
C = ones(N,codistr);
end
\end{verbatim}

Use a fully specified \texttt{codistributor1d} object to create a trivial \texttt{N-by-N} codistributed matrix from its local parts. Then visualize which elements are stored on worker 2.

\begin{verbatim}
N = 1000;
spmd
codistr = codistributor1d( ... 
codistributor1d.unsetDimension, ... 
codistributor1d.unsetPartition, ... 
[N,N]);
myLocalSize = [N,N]; % start with full size on each lab
% then set myLocalSize to default part of whole array:
myLocalSize(codistr.Dimension) = codistr.Partition(labindex);
myLocalPart = labindex*ones(myLocalSize); % arbitrary values
D = codistributed.build(myLocalPart,codistr);
end
spy(D==2);
\end{verbatim}
See Also

codistributed | codistributor2dbc | redistribute
codistributor1d.defaultPartition

Default partition for codistributed array

Syntax

P = codistributor1d.defaultPartition(n)

Description

P = codistributor1d.defaultPartition(n) is a vector with sum(P) = n and length(P) = numlabs. The first rem(n,numlabs) elements of P are equal to ceil(n/numlabs) and the remaining elements are equal to floor(n/numlabs). This function is the basis for the default distribution of codistributed arrays.

Examples

If numlabs = 4, the following code returns the vector [3 3 2 2] on all workers:

spmd
    P = codistributor1d.defaultPartition(10)
end

See Also

codistributed | codistributed.colon | codistributor1d

Introduced in R2009b
codistributor2dbc

Create 2-D block-cyclic codistributor object for codistributed arrays

Syntax

codist = codistributor2dbc()
codist = codistributor2dbc(lbgrid)
codist = codistributor2dbc(lbgrid,blksize)
codist = codistributor2dbc(lbgrid,blksize,orient)
codist = codistributor2dbc(lbgrid,blksize,orient,gsize)

Description

The 2-D block-cyclic codistributor can be used only for two-dimensional arrays. It distributes arrays along two subscripts over a rectangular computational grid of labs (workers) in a block-cyclic manner. For a complete description of 2-D block-cyclic distribution, default parameters, and the relationship between block size and lab grid, see “2-Dimensional Distribution” on page 5-16. The 2-D block-cyclic codistributor is used by the ScaLAPACK parallel matrix computation software library.

codist = codistributor2dbc() forms a 2-D block-cyclic codistributor2dbc codistributor object using default lab grid and block size.

codist = codistributor2dbc(lbgrid) forms a 2-D block-cyclic codistributor object using the specified lab grid and default block size. lbgrid must be a two-element vector defining the rows and columns of the lab grid, and the rows times columns must equal the number of workers for the codistributed array.

codist = codistributor2dbc(lbgrid,blksize) forms a 2-D block-cyclic codistributor object using the specified lab grid and block size.

codist = codistributor2dbc(lbgrid,blksize,orient) allows an orientation argument. Valid values for the orientation argument are 'row' for row orientation, and 'col' for column orientation of the lab grid. The default is row orientation.
The resulting codistributor of any of the above syntax is incomplete because its global size is not specified. A codistributor constructed this way can be used as an argument to other functions as a template codistributor when creating codistributed arrays.

\[
\text{codist} = \text{codistributor2dbc(lbgrid,blksize,orient,gsize)}
\]
forms a codistributor object that distributes arrays with the global size \( \text{gsizes} \). The resulting codistributor object is complete and can therefore be used to build a codistributed array from its local parts with \( \text{codistributed.build} \). To use the default values for lab grid, block size, and orientation, specify them using \( \text{codistributor2dbc.defaultLabGrid} \), \( \text{codistributor2dbc.defaultBlockSize} \), and \( \text{codistributor2dbc.defaultOrientation} \), respectively.

**Examples**

Use a codistributor2dbc object to create an \( N \)-by-\( N \) matrix of ones.

\[
N = 1000;
\text{spmd}
\begin{align*}
\text{codistr} &= \text{codistributor2dbc}(); \\
D &= \text{ones}(N,\text{codistr});
\end{align*}
\text{end}
\]

Use a fully specified codistributor2dbc object to create a trivial \( N \)-by-\( N \) codistributed matrix from its local parts. Then visualize which elements are stored on worker 2.

\[
N = 1000;
\text{spmd}
\begin{align*}
\text{codistr} &= \text{codistributor2dbc}(... \\
& \quad \text{codistributor2dbc.defaultLabGrid}, ... \\
& \quad \text{codistributor2dbc.defaultBlockSize}, ... \\
& \quad 'row',[N,N]); \\
\text{myLocalSize} &= [\text{length}(\text{codistr.globalIndices}(1)), ... \\
& \quad \text{length}(\text{codistr.globalIndices}(2))]; \\
\text{myLocalPart} &= \text{labindex}\cdot\text{ones}(\text{myLocalSize}); \\
D &= \text{codistributed.build}(\text{myLocalPart},\text{codistr});
\end{align*}
\text{end}
\text{spy}(D==2);
See Also

codistributed | codistributor1d | getLocalPart | redistribute
codistributor2dbc.defaultLabGrid

Default computational grid for 2-D block-cyclic distributed arrays

Syntax

grid = codistributor2dbc.defaultLabGrid()

Description

grid = codistributor2dbc.defaultLabGrid() returns a vector, grid = [nrow ncol], defining a computational grid of nrow-by-ncol workers in the open parallel pool, such that numlabs = nrow x ncol.

The grid defined by codistributor2dbc.defaultLabGrid is as close to a square as possible. The following rules define nrow and ncol:

• If numlabs is a perfect square, nrow = ncol = sqrt(numlabs).
• If numlabs is an odd power of 2, then nrow = ncol/2 = sqrt(numlabs/2).
• nrow <= ncol.
• If numlabs is a prime, nrow = 1, ncol = numlabs.
• nrow is the greatest integer less than or equal to sqrt(numlabs) for which ncol = numlabs/nrow is also an integer.

Examples

View the computational grid layout of the default distribution scheme for the open parallel pool.

spmd
grid = codistributor2dbc.defaultLabGrid
end
See Also

codistributed | codistributor2dbc | numlabs
Composite

Create Composite object

Syntax

C = Composite()
C = Composite(nlabs)

Description

C = Composite() creates a Composite object on the client using workers from the parallel pool. The actual number of workers referenced by this Composite object depends on the size of the pool and any existing Composite objects. Generally, you should construct Composite objects outside any spmd statement.

C = Composite(nlabs) creates a Composite object on the parallel pool set that matches the specified constraint. nlabs must be a vector of length 1 or 2, containing integers or Inf. If nlabs is of length 1, it specifies the exact number of workers to use. If nlabs is of size 2, it specifies the minimum and maximum number of workers to use. The actual number of workers used is the maximum number of workers compatible with the size of the parallel pool, and with other existing Composite objects. An error is thrown if the constraints on the number of workers cannot be met.

A Composite object has one entry for each lab; initially each entry contains no data. Use either indexing or an spmd block to define values for the entries.

Examples

The following examples all use a local parallel pool of four workers, opened with the statement:

```matlab
p = parpool('local',4);
```

This example shows how to create a Composite object with no defined elements, then assign values using a for-loop in the client.
c = Composite();  % One element per worker in the pool
for w = 1:length(c)
    c{w} = 0;    % Value stored on each worker
end

This example shows how to assign Composite elements in an `spmd` block.

```matlab
c = Composite();
spmd
    c = 0;    % Value stored on each worker
end
```

This example shows how to assign the elements of a Composite with a value from each worker.

```matlab
c = Composite();
spmd
    c = labindex;
end
c{:}
```

1

2

3

4

This example shows how to use a distributed array vector to set the values of a Composite.

```matlab
d = distributed([3 1 4 2]);  % One integer per worker
spmd
    c = getLocalPart(d);    % Unique value on each worker
end
c{:}
```

3

1
Tips

- A Composite is created on the workers of the existing parallel pool. If no pool exists, the Composite starts a new parallel pool, unless the automatic starting of pools is disabled in your parallel preferences. If there is no parallel pool and Composite cannot start one, the result is a 1-by-1 Composite in the client workspace.

See Also

parallel.pool.Constant | parpool | spmd
createCommunicatingJob

Create communicating job on cluster

Syntax

job = createCommunicatingJob(cluster)
job = createCommunicatingJob(...,'p1',v1,'p2',v2,...)
job = createCommunicatingJob(...,'Type','pool',...)
job = createCommunicatingJob(...,'Type','spmd',...)
job = createCommunicatingJob(...,'Profile','profileName',...)

Description

job = createCommunicatingJob(cluster) creates a communicating job object for the identified cluster.

job = createCommunicatingJob(...,'p1',v1,'p2',v2,...) creates a communicating job object with the specified property values. For a listing of the valid properties of the created object, see the parallel.Job object reference page. The property name must be a character vector, with the value being the appropriate type for that property. In most cases, the values specified in these property-value pairs override the values in the profile. But when you specify AttachedFiles or AdditionalPaths at the time of creating a job, the settings are combined with those specified in the applicable profile. If an invalid property name or property value is specified, the object will not be created.

job = createCommunicatingJob(...,'Type','pool',...) creates a communicating job of type 'pool'. This is the default if 'Type' is not specified. A 'pool' job runs the specified task function with a parallel pool available to run the body of parfor loops or spmd blocks. Note that only one worker runs the task function, and the rest of the workers in the cluster form the parallel pool. So on a cluster of N workers for a 'pool' type job, only N-1 workers form the actual pool that performs the spmd and parfor code found within the task function.

job = createCommunicatingJob(...,'Type','spmd',...) creates a communicating job of type 'spmd', where the specified task function runs
simultaneously on all workers, and `lab*` functions can be used for communication between workers.

```matlab
job = createCommunicatingJob(...,'Profile','profileName',...) creates a communicating job object with the property values specified in the profile 'profileName'. If no profile is specified and the cluster object has a value specified in its 'Profile' property, the cluster’s profile is automatically applied.
```

## Examples

### Example 11.1. Pool Type Communicating Job

Consider the function `myFunction` which uses a `parfor` loop:

```matlab
function result = myFunction(N)
    result = 0;
    parfor ii=1:N
        result = result + max(eig(rand(ii)));
    end
end
```

Create a communicating job object to evaluate `myFunction` on the default cluster:

```matlab
myCluster = parcluster;
j = createCommunicatingJob(myCluster,'Type','pool');
```

Add the task to the job, supplying an input argument:

```matlab
createTask(j, @myFunction, 1, {100});
```

Set the number of workers required for parallel execution:

```matlab
j.NumWorkersRange = [5 10];
```

Run the job.

```matlab
submit(j);
```

Wait for the job to finish and retrieve its results:

```matlab
wait(j)
out = fetchOutputs(j)
```
Delete the job from the cluster.

\texttt{delete(j);}

\section*{See Also}
\texttt{createJob} | \texttt{createTask} | \texttt{findJob} | \texttt{parcluster} | \texttt{recreate} | \texttt{submit}

Introduced in R2012a
createJob

Create independent job on cluster

Syntax

\[
\begin{align*}
\text{obj} &= \text{createJob}(\text{cluster}) \\
\text{obj} &= \text{createJob}(..., 'p1', v1, 'p2', v2, ...) \\
\text{job} &= \text{createJob}(..., 'Profile', 'profileName', ...)
\end{align*}
\]

Arguments

<table>
<thead>
<tr>
<th>Argument</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>obj</td>
<td>The job object.</td>
</tr>
<tr>
<td>cluster</td>
<td>The cluster object created by \text{parcluster}.</td>
</tr>
<tr>
<td>(p1, p2)</td>
<td>Object properties configured at object creation.</td>
</tr>
<tr>
<td>(v1, v2)</td>
<td>Initial values for corresponding object properties.</td>
</tr>
</tbody>
</table>

Description

\[\text{obj} = \text{createJob}(\text{cluster})\] creates an independent job object for the identified cluster.

The job’s data is stored in the location specified by the cluster’s \text{JobStorageLocation} property.

\[\text{obj} = \text{createJob}(..., 'p1', v1, 'p2', v2, ...)\] creates a job object with the specified property values. For a listing of the valid properties of the created object, see the parallel.Job object reference page. The property name must be a character vector, with the value being the appropriate type for that property. In most cases, the values specified in these property-value pairs override the values in the profile; but when you specify \text{AttachedFiles} or \text{AdditionalPaths} at the time of creating a job, the settings are combined with those specified in the applicable profile. If an invalid property name or property value is specified, the object will not be created.
job = createJob(...,'Profile','profileName',...) creates an independent job object with the property values specified in the profile 'profileName'. If a profile is not specified and the cluster has a value specified in its 'Profile' property, the cluster's profile is automatically applied. For details about defining and applying profiles, see “Discover Clusters and Use Cluster Profiles” on page 6-18.

Examples

Example 11.2. Create and Run a Basic Job

Construct an independent job object using the default profile.

c = parcluster
j = createJob(c);

Add tasks to the job.

for i = 1:10
    createTask(j,@rand,1,{10});
end

Run the job.

submit(j);

Wait for the job to finish running, and retrieve the job results.

wait(j);
out = fetchOutputs(j);

Display the random matrix returned from the third task.

disp(out{3});

Delete the job.

delete(j);

Example 11.3. Create a Job with Attached Files

Construct an independent job with attached files in addition to those specified in the default profile.
c = parcluster
j = createJob(c,'AttachedFiles',...
     {'myapp/folderA','myapp/folderB','myapp/file1.m'});

See Also
createCommunicatingJob | createTask | findJob | parcluster | recreate | submit

Introduced before R2006a
createTask

Create new task in job

Syntax

t = createTask(j, F, N, {inputargs})
t = createTask(j, F, N, {C1,...,Cm})
t = createTask(..., 'p1',v1,'p2',v2,...)
t = createTask(...,'Profile', 'ProfileName',...)

Arguments

t Task object or vector of task objects.
j The job that the task object is created in.
F A handle to the function that is called when the task is evaluated, or an array of function handles.
N The number of output arguments to be returned from execution of the task function. This is a double or array of doubles.

{inputargs} A row cell array specifying the input arguments to be passed to the function F. Each element in the cell array will be passed as a separate input argument. If this is a cell array of cell arrays, a task is created for each cell array.

{C1,...,Cm} Cell array of cell arrays defining input arguments to each of m tasks.
p1,p2 Task object properties configured at object creation.
v1,v2 Initial values for corresponding task object properties.
Description

t = createTask(j, F, N, {inputargs}) creates a new task object in job j, and returns a reference, t, to the added task object. This task evaluates the function specified by a function handle or function name F, with the given input arguments {inputargs}, returning N output arguments.

t = createTask(j, F, N, {C1,...,Cm}) uses a cell array of m cell arrays to create m task objects in job j, and returns a vector, t, of references to the new task objects. Each task evaluates the function specified by a function handle or function name F. The cell array C1 provides the input arguments to the first task, C2 to the second task, and so on, so that there is one task per cell array. Each task returns N output arguments. If F is a cell array, each element of F specifies a function for each task in the vector; it must have m elements. If N is an array of doubles, each element specifies the number of output arguments for each task in the vector. Multidimensional matrices of inputs F, N and {C1,...,Cm} are supported; if a cell array is used for F, or a double array for N, its dimensions must match those of the input arguments cell array of cell arrays. The output t will be a vector with the same number of elements as {C1,...,Cm}. Note that because a communicating job has only one task, this form of vectorized task creation is not appropriate for such jobs.

t = createTask(..., 'p1',v1,'p2',v2,...) adds a task object with the specified property values. For a listing of the valid properties of the created object, see the parallel.Task object reference page. The property name must be a character vector, with the value being the appropriate type for that property. The values specified in these property-value pairs override the values in the profile. If an invalid property name or property value is specified, the object will not be created.

t = createTask(...,'Profile', 'ProfileName',...) creates a task object with the property values specified in the cluster profile ProfileName. For details about defining and applying cluster profiles, see “Discover Clusters and Use Cluster Profiles” on page 6-18.

Examples

Example 11.4. Create a Job with One Task

Create a job object.
```
c = parcluster(); % Use default profile
j = createJob(c);

Add a task object which generates a 10-by-10 random matrix.
t = createTask(j, @rand, 1, {10,10});

Run the job.
submit(j);

Wait for the job to finish running, and get the output from the task evaluation.
wait(j);
taskoutput = fetchOutputs(j);

Show the 10-by-10 random matrix.
disp(taskoutput{1});
```

**Example 11.5. Create a Job with Three Tasks**

This example creates a job with three tasks, each of which generates a 10-by-10 random matrix.
```
c = parcluster(); % Use default profile
j = createJob(c);
t = createTask(j, @rand, 1, {{10,10} {10,10} {10,10}});
```

**Example 11.6. Create a Task with Different Property Values**

This example creates a task that captures the worker diary, regardless of the setting in the profile.
```
c = parcluster(); % Use default profile
j = createJob(c);
t = createTask(j, @rand, 1, {10,10}, 'CaptureDiary',true);
```

**See Also**
createCommunicatingJob | createJob | findTask | recreate

**Introduced before R2006a**
delete

Remove job or task object from cluster and memory

Syntax

delete(obj)

Description

delete(obj) removes the job or task object, obj, from the local MATLAB session, and removes it from the cluster's JobStorageLocation. When the object is deleted, references to it become invalid. Invalid objects should be removed from the workspace with the clear command. If multiple references to an object exist in the workspace, deleting one reference to that object invalidates the remaining references to it. These remaining references should be cleared from the workspace with the clear command.

When you delete a job object, this also deletes all the task objects contained in that job. Any references to those task objects will also be invalid, and you should clear them from the workspace.

If obj is an array of objects and one of the objects cannot be deleted, the other objects in the array are deleted and a warning is returned.

Because its data is lost when you delete an object, delete should be used only after you have retrieved all required output data from the effected object.

Examples

Create a job object using the default profile, then delete the job:

```matlab
myCluster = parcluster;
j = createJob(myCluster,'Name','myjob');
t = createTask(j,@rand,1,{10});
delete(j);
clear j t
```
Delete all jobs on the cluster identified by the profile myProfile:

```matlab
myCluster = parcluster('myProfile');
delete(myCluster.Jobs)
```

**See Also**

batch | createJob | createTask | findJob | findTask | wait

*Introduced in R2012a*
delete (Pool)

Shut down parallel pool

Syntax

delete(poolobj)

Description

delete(poolobj) shuts down the parallel pool associated with the object poolobj, and destroys the communicating job that comprises the pool. Subsequent parallel language features will automatically start a new parallel pool, unless your parallel preferences disable this behavior.

References to the deleted pool object become invalid. Invalid objects should be removed from the workspace with the clear command. If multiple references to an object exist in the workspace, deleting one reference to that object invalidates the remaining references to it. These remaining references should be cleared from the workspace with the clear command.

Examples

Get the current pool and shut it down.

poolobj = gcp('nocreate');
delete(poolobj);

See Also

gcp | parpool

Introduced in R2013b
demote

Demote job in cluster queue

Syntax

demote(c,job)

Arguments

c              Cluster object that contains the job.
job            Job object demoted in the job queue.

Description

demote(c,job) demotes the job object job that is queued in the cluster c.

If job is not the last job in the queue, demote exchanges the position of job and the job
that follows it in the queue.

Examples

Create and submit multiple jobs to the MATLAB job scheduler (MJS) identified by the
default parallel configuration:

c = parcluster();
pause(c) % Prevent submissions from running.

j1 = createJob(c,'Name','Job A');
j2 = createJob(c,'Name','Job B');
j3 = createJob(c,'Name','Job C');
submit(j1);submit(j2);submit(j3);

Demote one of the jobs by one position in the queue:
demote(c, j2)

Examine the new queue sequence:

[pjobs, qjobs, rjobs, fjobs] = findJob(c);
get(qjobs, 'Name')

   'Job A'
   'Job C'
   'Job B'

Tips

After a call to demote or promote, there is no change in the order of job objects contained in the Jobs property of the cluster object. To see the scheduled order of execution for jobs in the queue, use the findJob function in the form [pending queued running finished] = findJob(c).

See Also

createJob | findJob | promote | submit

Introduced before R2006a
diary

Display or save Command Window text of batch job

Syntax

diary(job)
diary(job, 'filename')

Arguments

<table>
<thead>
<tr>
<th>Argument</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>job</td>
<td>Job from which to view Command Window output text.</td>
</tr>
<tr>
<td>'filename'</td>
<td>File to append with Command Window output text from batch job</td>
</tr>
</tbody>
</table>

Description

diary(job) displays the Command Window output from the batch job in the MATLAB Command Window. The Command Window output will be captured only if the batch command included the 'CaptureDiary' argument with a value of true.

diary(job, 'filename') causes the Command Window output from the batch job to be appended to the specified file.

The captured Command Window output includes only the output generated by execution of the task function. Output is not captured from code that runs asynchronously from the task.

See Also

batch | diary | load

Introduced in R2008a
distributed

Create distributed array from data in client workspace

Syntax

\[ D = \text{distributed}(X) \]

Description

\( D = \text{distributed}(X) \) creates a distributed array from \( X \). \( X \) can be an array stored on the MATLAB client workspace or a datastore. \( D \) is a distributed array stored in parts on the workers of the open parallel pool.

Constructing a distributed array from local data this way is appropriate only if the MATLAB client can store the entirety of \( X \) in its memory. To construct large distributed arrays, use one of the constructor methods such as \( \text{ones}(\_, \text{'distributed'}) \), \( \text{zeros}(\_, \text{'distributed'}) \), etc.

If the input argument is already a distributed array, the result is the same as the input.

Use \text{gather} to retrieve the distributed array elements from the pool back to an array in the MATLAB workspace.

Examples

Create a small array and distribute it:

\[ \text{Nsmall} = 50; \]
\[ D1 = \text{distributed}(	ext{magic}(\text{Nsmall})); \]

Create a large distributed array directly, using a build method:

\[ \text{Nlarge} = 1000; \]
\[ D2 = \text{rand}(\text{Nlarge}, \text{'distributed'}); \]
Retrieve elements of a distributed array, and note where the arrays are located by their Class:

\[
D3 = \text{gather}(D2);
\]

\[
\text{whos}
\]

<table>
<thead>
<tr>
<th>Name</th>
<th>Size</th>
<th>Bytes</th>
<th>Class</th>
</tr>
</thead>
<tbody>
<tr>
<td>D1</td>
<td>50x50</td>
<td>733</td>
<td>distributed</td>
</tr>
<tr>
<td>D2</td>
<td>1000x1000</td>
<td>733</td>
<td>distributed</td>
</tr>
<tr>
<td>D3</td>
<td>1000x1000</td>
<td>8000000</td>
<td>double</td>
</tr>
<tr>
<td>Nlarge</td>
<td>1x1</td>
<td>8</td>
<td>double</td>
</tr>
<tr>
<td>Nsmall</td>
<td>1x1</td>
<td>8</td>
<td>double</td>
</tr>
</tbody>
</table>

This example shows how to create and load distributed arrays using datastore. You first create a datastore using an example data set. This data set is too small to show equal partitioning of the data over the workers. To simulate a real big data set, artificially increase the size of the datastore using repmat:

\[
\text{files} = \text{repmat}({'airlinesmall.csv'}, 10, 1);
\]

\[
\text{ds} = \text{tabularTextDatastore}(	ext{files});
\]

Select the example variables:

\[
\text{ds.SelectedVariableNames} = \{'\text{DepTime}', '\text{DepDelay}'\};
\]

\[
\text{ds.TreatAsMissing} = '\text{NA}'
\]

Create a distributed table by reading the datastore in parallel. Partition the datastore with one partition per worker. Each worker then reads all data from the corresponding partition. The files must be in a shared location accessible from the workers.

\[
\text{dt} = \text{distributed}(	ext{ds});
\]

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.

Finally, display summary information about the distributed table:

\[
\text{summary(dt)}
\]

Variables:

\[
\text{DepTime: 1,235,230x1 double}
\]

Values:

\[
\begin{array}{c}
\text{min} \\
1
\end{array}
\]
max       2505
NaNs     23,510

DepDelay: 1,235,230×1 double
Values:

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>min</td>
<td>-1036</td>
</tr>
<tr>
<td>max</td>
<td>1438</td>
</tr>
<tr>
<td>NaNs</td>
<td>23,510</td>
</tr>
</tbody>
</table>

**Tips**

- A distributed array is created on the workers of the existing parallel pool. If no pool exists, `distributed` will start a new parallel pool, unless the automatic starting of pools is disabled in your parallel preferences. If there is no parallel pool and `distributed` cannot start one, the result is the full array in the client workspace.

**See Also**

codistributed | datastore | gather | ones | parpool | spmd | tall | zeros
distributed.cell

Create distributed cell array

Syntax

D = distributed.cell(n)
D = distributed.cell(m, n, p, ...)
D = distributed.cell([m, n, p, ...])

Description

D = distributed.cell(n) creates an n-by-n distributed array of underlying class cell.

D = distributed.cell(m, n, p, ...) or D = distributed.cell([m, n, p, ...]) create an m-by-n-by-p-by-... distributed array of underlying class cell.

Examples

Create a distributed 1000-by-1000 cell array:

D = distributed.cell(1000)

See Also

cell | codistributed.cell

Introduced in R2009b
distributed.spalloc

Allocate space for sparse distributed matrix

Syntax

\[
SD = \text{distributed.spalloc}(M, N, nzmax)
\]

Description

\[
SD = \text{distributed.spalloc}(M, N, nzmax)
\]
creates an \(M\)-by-\(N\) all-zero sparse distributed matrix with room to hold \(nzmax\) nonzeros.

Examples

Allocate space for a 1000-by-1000 sparse distributed matrix with room for up to 2000 nonzero elements, then define several elements:

\[
N = 1000;
SD = \text{distributed.spalloc}(N, N, 2*N);
\text{for}\ \text{ii}=1:N-1
\quad SD(ii,ii:ii+1) = [ii ii];
\text{end}
\]

See Also

codistributed.spalloc | spalloc | sparse

Introduced in R2009b
**distributed.speye**

Create distributed sparse identity matrix

**Syntax**

\[
\text{DS} = \text{distributed.speye}(n) \\
\text{DS} = \text{distributed.speye}(m,n) \\
\text{DS} = \text{distributed.speye}([m,n])
\]

**Description**

\[
\text{DS} = \text{distributed.speye}(n) \text{ creates an } n\text{-by-}n \text{ sparse distributed array of underlying class double.}
\]

\[
\text{DS} = \text{distributed.speye}(m,n) \text{ or } \text{DS} = \text{distributed.speye}([m,n]) \text{ creates an } m\text{-by-}n \text{ sparse distributed array of underlying class double.}
\]

**Examples**

Create a distributed 1000-by-1000 sparse identity matrix:

\[
N = 1000; \\
\text{DS} = \text{distributed.speye}(N);
\]

**See Also**

codistributed.speye | eye | speye

*Introduced in R2009b*
distributed.sprand

Create distributed sparse array of uniformly distributed pseudo-random values

Syntax

DS = distributed.sprand(m,n,density)

Description

DS = distributed.sprand(m,n,density) creates an m-by-n sparse distributed array
with approximately density*m*n uniformly distributed nonzero double entries.

Examples

Create a 1000-by-1000 sparse distributed double array DS with approximately 1000
nonzeros.

DS = distributed.sprand(1000,1000,0.001);

Tips

When you use sprand on the workers in the parallel pool, or in an independent or
communicating job (including pmode), each worker sets its random generator seed to a
value that depends only on the labindex or task ID. Therefore, the array on each
worker is unique for that job. However, if you repeat the job, you get the same random
data.

See Also

codistributed.sprand | distributed.speye | distributed.sprandn | rand |
randn | sparse | sprand
Introduced in R2009b
**distributed.sprandn**

Create distributed sparse array of normally distributed pseudo-random values

**Syntax**

\[ DS = \text{distributed.sprandn}(m,n,density) \]

**Description**

\[ DS = \text{distributed.sprandn}(m,n,density) \] creates an \( m \)-by-\( n \) sparse distributed array with approximately \( density \cdot m \cdot n \) normally distributed nonzero double entries.

**Examples**

Create a 1000-by-1000 sparse distributed double array \( DS \) with approximately 1000 nonzeros.

\[ DS = \text{distributed.sprandn}(1000,1000,0.001); \]

**Tips**

When you use \text{sprandn} on the workers in the parallel pool, or in an independent or communicating job (including pmode), each worker sets its random generator seed to a value that depends only on the \text{labindex} or task ID. Therefore, the array on each worker is unique for that job. However, if you repeat the job, you get the same random data.

**See Also**

codistributed.sprandn | distributed.speye | distributed.sprand | rand | randn | sparse | sprandn
Introduced in R2009b
dload

Load distributed arrays and Composite objects from disk

Syntax

dload
dload filename
dload filename X
dload filename X Y Z ...
dload -scatter ...
[X,Y,Z,...] = dload('filename','X','Y','Z',...)

Description

dload without any arguments retrieves all variables from the binary file named matlab.mat. If matlab.mat is not available, the command generates an error.

dload filename retrieves all variables from a file given a full pathname or a relative partial pathname. If filename has no extension, dload looks for filename.mat. dload loads the contents of distributed arrays and Composite objects onto parallel pool workers, other data types are loaded directly into the workspace of the MATLAB client.

dload filename X loads only variable X from the file. dload filename X Y Z ... loads only the specified variables. dload does not support wildcards, nor the -regexp option. If any requested variable is not present in the file, a warning is issued.

dload -scatter ... distributes nondistributed data if possible. If the data cannot be distributed, a warning is issued.

[X,Y,Z,...] = dload('filename','X','Y','Z',...) returns the specified variables as separate output arguments (rather than a structure, which the load function returns). If any requested variable is not present in the file, an error occurs.

When loading distributed arrays, the data is distributed over the available parallel pool workers using the default distribution scheme. It is not necessary to have the same size pool open when loading as when saving using dsave.
When loading Composite objects, the data is sent to the available parallel pool workers. If the Composite is too large to fit on the current parallel pool, the data is not loaded. If the Composite is smaller than the current parallel pool, a warning is issued.

**Examples**

Load variables \( X \), \( Y \), and \( Z \) from the file \( \text{fname.mat} \):

\[
dload \ \text{fname} \ X \ Y \ Z
\]

Use the function form of `dload` to load distributed arrays \( P \) and \( Q \) from file \( \text{fname.mat} \):

\[
[P,Q] = dload('\text{fname.mat}','P','Q');
\]

**See Also**

`Composite` | `distributed` | `dsave` | `load` | `parpool`

*Introduced in R2010a*
dsave

Save workspace distributed arrays and Composite objects to disk

Syntax

dsave

dsave filename

dsave filename X

dsave filename X Y Z

Description

dsave without any arguments creates the binary file named matlab.mat and writes to the file all workspace variables, including distributed arrays and Composite objects. You can retrieve the variable data using dload.

dsave filename saves all workspace variables to the binary file named filename.mat. If you do not specify an extension for filename, it assumes the extension .mat.

dsave filename X saves only variable X to the file.

dsave filename X Y Z saves X, Y, and Z. dsave does not support wildcards, nor the -regexp option.

dsave does not support saving sparse distributed arrays.

Examples

With a parallel pool open, create and save several variables to mydatafile.mat:

```matlab
D = rand(1000,'distributed'); % Distributed array
C = Composite(); %
C{1} = magic(20); % Data on worker 1 only
```
X = rand(40); % Client workspace only
dsave mydatafile D C X % Save all three variables

See Also
Composite | distributed | dload | parpool | save

Introduced in R2010a
exist

Check whether Composite is defined on workers

Syntax

\[
\begin{align*}
h &= \text{exist}(C, \text{labidx}) \\
h &= \text{exist}(C)
\end{align*}
\]

Description

\( h = \text{exist}(C, \text{labidx}) \) returns true if the entry in Composite \( C \) has a defined value on the worker with labindex \( \text{labidx} \), false otherwise. In the general case where \( \text{labidx} \) is an array, the output \( h \) is an array of the same size as \( \text{labidx} \), and \( h(i) \) indicates whether the Composite entry \( \text{labidx}(i) \) has a defined value.

\( h = \text{exist}(C) \) is equivalent to \( h = \text{exist}(C, 1:\text{length}(C)) \).

If \( \text{exist}(C, \text{labidx}) \) returns true, \( C(\text{labidx}) \) does not throw an error, provided that the values of \( C \) on those workers are serializable. The function throws an error if any \( \text{labidx} \) is invalid.

Examples

Define a variable on a random number of workers. Check on which workers the Composite entries are defined, and get all those values:

```matlab
spmd
    if rand() > 0.5
        c = labindex;
    end
end
ind = exist(c);
cvals = c(ind);```

See Also
Composite

Introduced in R2008b
existsOnGPU

Determine if gpuArray or CUDAKernel is available on GPU

Syntax

TF = existsOnGPU(DATA)

Description

TF = existsOnGPU(DATA) returns a logical value indicating whether the gpuArray or CUDAKernel object represented by DATA is still present on the GPU and available from your MATLAB session. The result is false if DATA is no longer valid and cannot be used. Such arrays and kernels are invalidated when the GPU device has been reset with any of the following:

reset(dev) % Where dev is the current gpuDevice
gpuDevice(ix) % Where ix is valid index of current or different device
gpuDevice([]) % With an empty argument (as opposed to no argument)

Examples

Query Existence of gpuArray

Create a gpuArray on the selected GPU device, then reset the device. Query array’s existence and content before and after resetting.

g = gpuDevice(1);
M = gpuArray(magic(4));
M_exists = existsOnGPU(M)

1

M % Display gpuArray

16 2 3 13
5 11 10 8
reset(g);
M_exists = existsOnGPU(M)

0

M  % Try to display gpuArray

Data no longer exists on the GPU.
clear M

See Also

gpuArray | gpuDevice | parallel.gpu.CUDAKernel | reset

Introduced in R2012a
eye

Identity matrix

Syntax

E = eye(sz,arraytype)
E = eye(sz,datatype,arraytype)

E = eye(sz,'like',P)
E = eye(sz,datatype,'like',P)

C = eye(sz,codist)
C = eye(sz,datatype,codist)
C = eye(sz,___,codist,'noCommunication')
C = eye(sz,___,codist,'like',P)

Description

E = eye(sz,arraytype) creates an arraytype identity matrix with underlying class of double, with ones on the main diagonal and zeros elsewhere.

E = eye(sz,datatype,arraytype) creates an arraytype identity matrix with underlying class of datatype, with ones on the main diagonal and zeros elsewhere.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>sz</td>
<td>n</td>
<td>Specifies array size as an n-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m,n</td>
<td>Specifies array size as an m-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>[m n]</td>
<td></td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
</tbody>
</table>
Argument | Values | Descriptions
---|---|---
'codistributed' | Specifies codistributed array, using the default distribution scheme.
'gpuArray' | Specifies gpuArray.
```
datatype | 'double' (default), 'single', 'int8', 'uint8', 'int16', 'uint16', 'int32', 'uint32', 'int64', or 'uint64' | Specifies underlying class of the array, i.e., the data type of its elements.
```

E = eye(sz,'like',P) creates an identity matrix of the same type and underlying class (data type) as array P.

E = eye(sz,datatype,'like',P) creates an identity matrix of the specified underlying class (datatype), and the same type as array P.

C = eye(sz,codist) or C = eye(sz,datatype,codist) creates a codistributed identity matrix of the specified size and underlying class (the default datatype is 'double'). The codistributor object, codist, specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```
spmd
    C = eye(8,codistributor1d());
end
```

C = eye(sz,___,codist,'noCommunication') specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = eye(sz,___,codist,'like',P) creates a codistributed identity matrix with the specified size, underlying class (datatype), and distribution scheme. If either the datatype or codistributor argument is omitted, the characteristic is acquired from the codistributed array P.
Examples

Create Distributed Identity Matrix

Create a 1000-by-1000 distributed identity matrix of underlying class double:

\[ D = \text{eye}(1000, 'distributed'); \]

Create Codistributed Identity Matrix

Create a 1000-by-1000 codistributed double identity matrix, distributed by its second dimension (columns).

\[
\text{spmd}(4) \\
\text{C} = \text{eye}(1000, '\text{codistributed}'); \\
\text{end}
\]

With four workers, each worker contains a 1000-by-250 local piece of \( C \).

Create a 1000-by-1000 codistributed \texttt{uint16} identity matrix, distributed by its columns.

\[
\text{spmd}(4) \\
\text{codist} = \text{codistributor('1d', 2, 100*[1:numlabs])}; \\
\text{C} = \text{eye}(1000, 1000, '\text{uint16}', \text{codist}); \\
\text{end}
\]

Each worker contains a 100-by-\texttt{labindex} local piece of \( C \).

Create gpuArray Identity Matrix

Create a 1000-by-1000 \texttt{gpuArray} identity matrix of underlying class \texttt{uint32}:

\[ G = \text{eye}(1000, '\text{uint32}', '\text{gpuArray}'); \]

See Also

\texttt{Inf} | \texttt{NaN} | \texttt{codistributed.speye} | \texttt{distributed.speye} | \texttt{eye} | \texttt{false} | \texttt{ones} | \texttt{true} | \texttt{zeros}

Introduced in R2006b
**false**

Array of logical 0 (false)

**Syntax**

\[ F = \text{false}(sz, \text{arraytype}) \]

\[ F = \text{false}(sz, 'like', P) \]

\[ C = \text{false}(sz, \text{codist}) \]
\[ C = \text{false}(sz, ___, \text{codist}, 'noCommunication') \]
\[ C = \text{false}(sz, ___, \text{codist}, 'like', P) \]

**Description**

\[ F = \text{false}(sz, \text{arraytype}) \] creates a matrix with false values in all elements.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>( sz )</td>
<td>( n )</td>
<td>Specifies size as an ( n )-by-( n ) matrix.</td>
</tr>
<tr>
<td></td>
<td>( m, n )</td>
<td>Specifies size as an ( m )-by-( n ) matrix.</td>
</tr>
<tr>
<td></td>
<td>( m, n, \ldots, k )</td>
<td>Specifies size as an ( m )-by-( n )-by-( \ldots )-by-( k ) array.</td>
</tr>
<tr>
<td>( \text{arraytype} )</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td></td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
</tbody>
</table>

\[ F = \text{false}(sz, 'like', P) \] creates an array of false values with the same type as array \( P \).
C = false(sz,codist) creates a codistributed array of false values with the specified size. The codistributor object codist specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = false(8,codistributor1d());
end
```

C = false(sz,___,codist,'noCommunication') specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = false(sz,___,codist,'like',P) creates a codistributed array of false values with the specified size and distribution scheme. If the codistributor argument is omitted, the distribution scheme is taken from the codistributed array P.

**Examples**

**Create Distributed False Matrix**

Create a 1000-by-1000 distributed array of false values with underlying class double:

```matlab
D = false(1000,'distributed');
```

**Create Codistributed False Matrix**

Create a 1000-by-1000 codistributed matrix of false values, distributed by its second dimension (columns).

```matlab
spmd(4)
    C = false(1000,'codistributed');
end
```

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed matrix of false values, distributed by its columns.
```matlab
spmd(4)
    codist = codistributor('1d',2,100*[1:numlabs]);
    C = false(1000,1000,codist);
end

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray False Matrix

Create a 1000-by-1000 gpuArray of false:

G = false(1000,'gpuArray');

See Also
Inf | NaN | eye | false | ones | true | zeros

Introduced in R2006b
fetchNext

Retrieve next available unread FevalFuture outputs

Syntax

\[ [idx,B1,B2,...,Bn] = \text{fetchNext}(F) \]
\[ [idx,B1,B2,...,Bn] = \text{fetchNext}(F,\text{TIMEOUT}) \]

Description

\[ [idx,B1,B2,...,Bn] = \text{fetchNext}(F) \] waits for an unread FevalFuture in the array of futures \( F \) to finish, and then returns the linear index of that future in array \( F \) as \( idx \), along with the future's results in \( B1,B2,...,Bn \). Before this call, the 'Read' property of the particular future is \text{false}; afterward it is \text{true}.

\[ [idx,B1,B2,...,Bn] = \text{fetchNext}(F,\text{TIMEOUT}) \] waits no longer than \( \text{TIMEOUT} \) seconds for a result to become available. If the timeout expires before any result becomes available, all output arguments are empty.

If there are no futures in \( F \) whose 'Read' property is \text{false}, then an error is reported. You can check whether there are any unread futures using \text{anyUnread} = \sim\text{all}([F.Read]).

If the element of \( F \) which has become finished encountered an error during execution, that error will be thrown by \text{fetchNext}. However, that future's 'Read' property is set \text{true}, so that any subsequent calls to \text{fetchNext} can proceed.

Examples

Request several function evaluations, and update a progress bar while waiting for completion.

\[ N = 100; \]
\[ \text{for } idx = N:-1:1 \]
% Compute the rank of N magic squares
F(idx) = parfeval(@rank,1,magic(idx));
end

% Build a waitbar to track progress
h = waitbar(0,'Waiting for FevalFutures to complete...');
results = zeros(1,N);
for idx = 1:N
    [completedIdx,thisResult] = fetchNext(F);
    % store the result
    results(completedIdx) = thisResult;
    % update waitbar
    waitbar(idx/N,h,sprintf('Latest result: %d',thisResult));
end
delete(h)

Tips

The fetchNext function returns the linear index of the future from its array. If instead, you need the subscript values of a multidimensional array, you can use the ind2sub function to convert the values.

See Also
fetchOutputs | isequal | parfeval | parfevalOnAll | parpool

Introduced in R2013b
fetchOutputs (job)

Retrieve output arguments from all tasks in job

Syntax

data = fetchOutputs(job)

Description

data = fetchOutputs(job) retrieves the output arguments contained in the tasks of a finished job. If the job has M tasks, each row of the M-by-N cell array data contains the output arguments for the corresponding task in the job. Each row has N elements, where N is the greatest number of output arguments from any one task in the job. The N elements of a row are arrays containing the output arguments from that task. If a task has less than N output arguments, the excess arrays in the row for that task are empty. The order of the rows in data is the same as the order of the tasks contained in the job’s Tasks property.

Calling fetchOutputs does not remove the output data from the location where it is stored. To remove the output data, use the delete function to remove individual tasks or entire jobs.

fetchOutputs reports an error if the job is not in the 'finished' state, or if one of its tasks encountered an error during execution. If some tasks completed successfully, you can access their output arguments directly from the OutputArguments property of the tasks.

Examples

Create a job to generate a random matrix:

myCluster = parcluster; % Use default profile
j = createJob(myCluster,'Name','myjob');
t = createTask(j,@rand,1,{10});
submit(j);
Wait for the job to finish and retrieve the random matrix:

```matlab
wait(j)
data = fetchOutputs(j);
data{1}
```

_Introduced in R2012a_
fetchOutputs (FevalFuture)

Retrieve all output arguments from Future

Syntax

\[
[B_1, B_2, \ldots, B_n] = \text{fetchOutputs}(F)
\]

\[
[B_1, B_2, \ldots, B_n] = \text{fetchOutputs}(F, 'UniformOutput', false)
\]

Description

\[ [B_1, B_2, \ldots, B_n] = \text{fetchOutputs}(F) \]
fetches all outputs of future object \( F \) after first waiting for each element of \( F \) to reach the state 'finished'. An error results if any element of \( F \) has \( \text{NumOutputArguments} \) less than the requested number of outputs.

When \( F \) is a vector of FevalFutures, each output argument is formed by concatenating the corresponding output arguments from each future in \( F \). An error results if these outputs cannot be concatenated. To avoid this error, set the 'UniformOutput' option to false.

\[ [B_1, B_2, \ldots, B_n] = \text{fetchOutputs}(F, 'UniformOutput', false) \]
requests that fetchOutputs combine the future outputs into cell arrays \( B_1, B_2, \ldots, B_n \). The outputs of \( F \) can be of any size or type.

After the call to fetchOutputs, all futures in \( F \) have their 'Read' property set to true. fetchOutputs returns outputs for all futures in \( F \) regardless of the value of each future's 'Read' property.

Examples

Create an FevalFuture, and fetch its outputs.

\[
f = \text{parfeval}(@\text{rand}, 1, 3);
R = \text{fetchOutputs}(f)
\]
Create an FevalFuture vector, and fetch all its outputs.

```matlab
for idx = 1:10
    F(idx) = parfeval(@rand,1,1,10); % One row each future
end
R = fetchOutputs(F); % 10-by-10 concatenated output
```

See Also
fetchNext | parfeval | parpool

Introduced in R2013b
feval

Evaluate kernel on GPU

Syntax

feval(KERN, x1, ..., xn)
[y1, ..., ym] = feval(KERN, x1, ..., xn)

Description

feval(KERN, x1, ..., xn) evaluates the CUDA kernel KERN with the given arguments x1, ..., xn. The number of input arguments, n, must equal the value of the NumRHSArguments property of KERN, and their types must match the description in the ArgumentTypes property of KERN. The input data can be regular MATLAB data, GPU arrays, or a mixture of the two.

[y1, ..., ym] = feval(KERN, x1, ..., xn) returns multiple output arguments from the evaluation of the kernel. Each output argument corresponds to the value of the non-const pointer inputs to the CUDA kernel after it has executed. The output from feval running a kernel on the GPU is always gpuArray type, even if all the inputs are data from the MATLAB workspace. The number of output arguments, m, must not exceed the value of the MaxNumLHSArguments property of KERN.

Examples

If the CUDA kernel within a CU file has the following signature:

void myKernel(const float * pIn, float * pInOut1, float * pInOut2)

The corresponding kernel object in MATLAB then has the properties:

MaxNumLHSArguments: 2
NumRHSArguments: 3
ArgumentTypes: {'in single vector' 'inout single vector' 'inout single vector'}
You can use `feval` on this code’s kernel (`KERN`) with the syntax:

\[ [y1, y2] = \text{feval}(KERN, x1, x2, x3) \]

The three input arguments, \( x1, x2, \) and \( x3, \) correspond to the three arguments that are passed into the CUDA function. The output arguments, \( y1 \) and \( y2, \) are `gpuArray` types, and correspond to the values of `pInOut1` and `pInOut2` after the CUDA kernel has executed.

**See Also**

`arrayfun` | `gather` | `gpuArray` | `parallel.gpu.CUDAKernel`

*Introduced in R2010b*
findJob

Find job objects stored in cluster

Syntax

out = findJob(c)
[pending queued running completed] = findJob(c)
out = findJob(c,'p1',v1,'p2',v2,...)

Arguments

c
pending
queued
running
completed
out
p1,p2
v1,v2

Cluster object in which to find the job.
Array of jobs whose State is pending in cluster c.
Array of jobs whose State is queued in cluster c.
Array of jobs whose State is running in cluster c.
Array of jobs that have completed running, i.e., whose State is finished or failed in cluster c.
Array of jobs found in cluster c.
Job object properties to match.
Values for corresponding object properties.

Description

out = findJob(c) returns an array, out, of all job objects stored in the cluster c. Jobs in the array are ordered by the ID property of the jobs, indicating the sequence in which they were created.

[pending queued running completed] = findJob(c) returns arrays of all job objects stored in the cluster c, by state. Within pending, running, and completed, the jobs are returned in sequence of creation. Jobs in the array queued are in the order in which they are queued, with the job at queued(1) being the next to execute. The
completed jobs include those that failed. Jobs that are deleted or whose status is unavailable are not returned by this function.

`out = findJob(c,'p1',v1,'p2',v2,...)` returns an array, `out`, of job objects whose property values match those passed as property-value pairs, `p1`, `v1`, `p2`, `v2`, etc. The property name must be a character vector, with the value being the appropriate type for that property. For a match, the object property value must be exactly the same as specified, including letter case. For example, if a job’s `Name` property value is `MyJob`, then `findJob` will not find that object while searching for a `Name` property value of `myjob`.

See Also
`createJob` | `findTask` | `parcluster` | `recreate` | `submit`

Introduced before R2006a
**findTask**

Task objects belonging to job object

**Syntax**

```
tasks = findTask(j)
[pending running completed] = findTask(j)
tasks = findTask(j,'p1',v1,'p2',v2,...)
```

**Arguments**

- **j**  
  Job object.
- **tasks**  
  Returned task objects.
- **pending**  
  Array of tasks in job object whose State is pending.
- **running**  
  Array of tasks in job object whose State is running.
- **completed**  
  Array of completed tasks in job object, i.e., those whose State is finished or failed.
- **p1, p2**  
  Task object properties to match.
- **v1, v2**  
  Values for corresponding object properties.

**Description**

- **tasks = findTask(j)** gets a 1-by-N array of task objects belonging to a job object j. Tasks in the array are ordered by the ID property of the tasks, indicating the sequence in which they were created.

- **[pending running completed] = findTask(j)** returns arrays of all task objects stored in the job object j, sorted by state. Within each array (pending, running, and completed), the tasks are returned in sequence of creation.

- **tasks = findTask(j,'p1',v1,'p2',v2,...)** returns an array of task objects belonging to a job object j. The returned task objects will be only those matching the
specified property-value pairs, \( p1, v1, p2, v2, \) etc. The property name must be a character vector, with the value being the appropriate type for that property. For a match, the object property value must be exactly the same as specified, including letter case. For example, if a task's Name property value is MyTask, then findTask will not find that object while searching for a Name property value of mytask.

### Examples

Create a job object.

```matlab
c = parcluster();
j = createJob(c);
```

Add a task to the job object.

```matlab
createTask(j,@rand,1,{10})
```

Find all task objects now part of job \( j \).

```matlab
t = findTask(j)
```

### Tips

If job \( j \) is contained in a remote service, findTask will result in a call to the remote service. This could result in findTask taking a long time to complete, depending on the number of tasks retrieved and the network speed. Also, if the remote service is no longer available, an error will be thrown.

### See Also

createJob | createTask | findJob

Introduced before R2006a
for

for-loop over distributed range

Syntax

for variable = drange(colonop)
    statement
    ...
    statement
end

Description

The general format is

for variable = drange(colonop)
    statement
    ...
    statement
end

The colonop is an expression of the form start:increment:finish or start:finish. The default value of increment is 1. The colonop is partitioned by codistributed.colon into numlabs contiguous segments of nearly equal length. Each segment becomes the iterator for a conventional for-loop on an individual worker.

The most important property of the loop body is that each iteration must be independent of the other iterations. Logically, the iterations can be done in any order. No communication with other workers is allowed within the loop body. The functions that perform communication are gop, gcat, gplus, codistributor, codistributed, gather, and redistribute.

It is possible to access portions of codistributed arrays that are local to each worker, but it is not possible to access other portions of codistributed arrays.

The break statement can be used to terminate the loop prematurely.
Examples

Find the rank of magic squares. Access only the local portion of a codistributed array.

```matlab
r = zeros(1, 40, codistributor());
for n = drange(1:40)
    r(n) = rank(magic(n));
end
r = gather(r);
```

Perform Monte Carlo approximation of pi. Each worker is initialized to a different random number state.

```matlab
m = 10000;
for p = drange(1:numlabs)
    z = rand(m,1) + i*rand(m,1);
    c = sum(abs(z) < 1)
end
k = gplus(c)
p = 4*k/(m*numlabs);
```

Attempt to compute Fibonacci numbers. This will not work, because the loop bodies are dependent.

```matlab
f = zeros(1, 50, codistributor());
f(1) = 1;
f(2) = 2;
for n = drange(3:50)
    f(n) = f(n-1) + f(n-2)
end
```

See Also

for | numlabs | parfor

Introduced in R2007b
**gather**

Transfer distributed array or gpuArray to local workspace

**Syntax**

\[
X = \text{gather}(A) \\
X = \text{gather}(C, \text{lab})
\]

**Description**

\(X = \text{gather}(A)\) can operate inside an \texttt{spmd} statement, \texttt{pmode}, or communicating job to gather together the elements of a codistributed array, or outside an \texttt{spmd} statement to gather the elements of a distributed array. If you execute this inside an \texttt{spmd} statement, \texttt{pmode}, or communicating job, \(X\) is a replicated array with all the elements of the array on every worker. If you execute this outside an \texttt{spmd} statement, \(X\) is an array in the local workspace, with the elements transferred from the multiple workers.

\(X = \text{gather}(	ext{distributed}(X))\) or \(X = \text{gather}(	ext{codistributed}(X))\) returns the original array \(X\).

\(X = \text{gather}(C, \text{lab})\) converts a codistributed array \(C\) to a variant array \(X\), such that all of the elements are contained on worker \(\text{lab}\), and \(X\) is a 0-by-0 empty double on all other workers.

For a gpuArray input, \(X = \text{gather}(A)\) transfers the array elements from the GPU to the local workspace.

If the input argument to \texttt{gather} is not a distributed, a codistributed, or a gpuArray, the output is the same as the input.
Examples

Distribute a magic square across your workers, then gather the whole matrix onto every worker and then onto the client. This code results in the equivalent of \( M = \text{magic}(n) \) on all workers and the client.

\[
n = 10;
spmd
    C = \text{codistributed}([\text{magic}(n)]);
    M = \text{gather}(C) \ % \text{Gather all elements to all workers}
end
S = \text{gather}(C) \ % \text{Gather elements to client}
\]

Gather all of the elements of \( C \) onto worker 1, for operations that cannot be performed across distributed arrays.

\[
n = 10;
spmd
    C = \text{codistributed}([\text{magic}(n)]);
    out = \text{gather}(C,1);
    if \text{labindex} == 1
        \ % \text{Characteristic sum for this magic square:}
        \text{characteristicSum} = \text{sum}(1:n^2)/n;
        \ % \text{Ensure that the diagonal sums are equal to the}
        \ % \text{characteristic sum:}
        \text{areDiagonalsEqual} = \text{isequal ...}
            \text{(trace(out),trace(flipud(out))),characteristicSum)}
    end
end
\]

Lab 1:
areDiagonalsEqual =
1

Gather all of the elements from a distributed array \( D \) onto the client.

\[
n = 10;
D = \text{distributed}([\text{magic}(n)]); \ % \text{Distribute array to workers}
M = \text{gather}(D) \ % \text{Return array to client}
\]

Gather the results of a GPU operation to the MATLAB workspace.

\[
G = \text{gpuArray}([\text{rand}(1024,1)]);
F = \text{sqrt}(G); \ % \text{Input and output are both gpuArray}
\]
W = gather(G); % Return array to workspace
whos

<table>
<thead>
<tr>
<th>Name</th>
<th>Size</th>
<th>Bytes</th>
<th>Class</th>
</tr>
</thead>
<tbody>
<tr>
<td>F</td>
<td>1024x1</td>
<td>108</td>
<td>gpuArray</td>
</tr>
<tr>
<td>G</td>
<td>1024x1</td>
<td>108</td>
<td>gpuArray</td>
</tr>
<tr>
<td>W</td>
<td>1024x1</td>
<td>8192</td>
<td>double</td>
</tr>
</tbody>
</table>

**Tips**

Note that `gather` assembles the codistributed or distributed array in the workspaces of all the workers on which it executes, or on the MATLAB client, respectively, but not both. If you are using `gather` within an `spmd` statement, the gathered array is accessible on the client via its corresponding `Composite` object; see “Access Worker Variables with Composites” on page 3-8. If you are running `gather` in a communicating job, you can return the gathered array to the client as an output argument from the task.

As the `gather` function requires communication between all the workers, you cannot gather data from all the workers onto a single worker by placing the function inside a conditional statement such as `if labindex == 1`.

**See Also**
arrayfun | bsxfun | codistributed | distributed | gpuArray | pagefun | pmode

*Introduced in R2006b*
**gcat**

Global concatenation

**Syntax**

\[
Xs = \text{gcat}(X) \\
Xs = \text{gcat}(X, \text{dim}) \\
Xs = \text{gcat}(X, \text{dim}, \text{targetlab})
\]

**Description**

\[Xs = \text{gcat}(X)\] concatenates the variant array \(X\) from each worker in the second dimension. The result is replicated on all workers.

\[Xs = \text{gcat}(X, \text{dim})\] concatenates the variant array \(X\) from each worker in the dimension indicated by \(\text{dim}\).

\[Xs = \text{gcat}(X, \text{dim}, \text{targetlab})\] performs the reduction, and places the result into \(\text{res}\) only on the worker indicated by \(\text{targetlab}\). \(\text{res}\) is set to [] on all other workers.

**Examples**

With four workers,

\[Xs = \text{gcat}(\text{labindex})\]

returns \(Xs = [1 2 3 4]\) on all four workers.

**See Also**

cat | gop | labindex | numlabs

*Introduced in R2006b*
gcp

Get current parallel pool

Syntax

\[
p = \text{gcp}
\]

\[
p = \text{gcp}('nocreate')
\]

Description

\( p = \text{gcp} \) returns a parallel.Pool object representing the current parallel pool. The current pool is where parallel language features execute, such as \text{parfor}, \text{spmd}, \text{distributed}, \text{Composite}, \text{parfeval} and \text{parfevalOnAll}.

If no parallel pool exists, \text{gcp} starts a new parallel pool and returns a pool object for that, unless automatic pool starts are disabled in your parallel preferences. If no parallel pool exists and automatic pool starts are disabled, \text{gcp} returns an empty pool object.

\( p = \text{gcp}('nocreate') \) returns the current pool if one exists. If no pool exists, the 'nocreate' option causes \text{gcp} not to create a pool, regardless of your parallel preferences settings.

Examples

Find Size of Current Pool

Find the number of workers in the current parallel pool.

\[
p = \text{gcp}('nocreate'); \quad \% \text{If no pool, do not create new one.}
\text{if empty}(p)
\quad \text{poolsize} = 0;
\text{else}
\]
poolsize = p.NumWorkers
end

Delete Current Pool

Use the parallel pool object to delete the current pool.

delete(gcp('nocreate'))

See Also

Composite | delete | distributed | parfeval | parfevalOnAll | parfor | parpool | spmd

Introduced in R2013b
getAttachedFilesFolder

Folder into which AttachedFiles are written

Syntax

folder = getAttachedFilesFolder
folder = getAttachedFilesFolder(FileName)

Arguments

folder       Character vector indicating location where files from job’s AttachedFiles property are placed
FileName     Character vector specifying all or part of the attached file or folder name

Description

folder = getAttachedFilesFolder returns the path to the local folder into which AttachedFiles are written on the worker. This function returns an empty array if it is not called on a MATLAB worker.

folder = getAttachedFilesFolder(FileName) returns the path name to the specified attached folder on the worker, or the folder containing the specified attached file. FileName can match either the full name of the attached file or folder, or on the ending part of the name. Multiple match results return a cell array.

If you have attached a folder, this does not match on file names within that folder.

Suppose you attach the folder 'C:\monday\tuesday\wednesday\thursday', which on the workers is stored in /tmp/MDCS/tp12345. The following table displays the results of various match attempts.
<table>
<thead>
<tr>
<th>Specified Matching Character Vector Argument</th>
<th>Result</th>
</tr>
</thead>
<tbody>
<tr>
<td>getAttachedFilesFolder('C:\monday')</td>
<td>Empty result, because 'C:\monday' is only the start of the path, and does not include 'thursday'</td>
</tr>
<tr>
<td>getAttachedFilesFolder('wednesday')</td>
<td>Empty result, because 'wednesday' is in the middle of the path and does not include 'thursday'</td>
</tr>
<tr>
<td>getAttachedFilesFolder('thurs')</td>
<td>Empty result, because 'thurs' is not the ending of the folder name.</td>
</tr>
<tr>
<td>getAttachedFilesFolder('thursday')</td>
<td>'/tmp/MDCS(tp12345'</td>
</tr>
<tr>
<td>getAttachedFilesFolder('wednesday \thursday')</td>
<td>'/tmp/MDCS(tp12345'</td>
</tr>
</tbody>
</table>

**Examples**

Attach a folder to a parallel pool, then find its location on the worker to execute one of its files.

```matlab
myPool = parpool;
addAttachedFiles(myPool,'mydir');
spmd
    folder = getAttachedFilesFolder('mydir');
    oldFolder = cd(folder);  % Change to that folder
    [OK,output] = system('myExecutable');
    cd(oldFolder);          % Change to original folder
end
```

Attach an executable file to a parallel pool, then change to its folder for accessing and processing some data.

```matlab
myPool = parpool;
addAttachedFiles(myPool,'myExecutable');
spmd
    system('myExecutable');  % Now on MATLAB path
    folder = getAttachedFilesFolder('myExecutable');
    oldFolder = cd(folder);
    fid = open('myData.txt');  % Access data file
end
```
% Process fid
    close(fid)
    cd(oldFolder);
% Change back to the original folder
end

See Also

Functions
addAttachedFiles | getCurrentCluster | getCurrentJob | getCurrentTask | getCurrentWorker

Introduced in R2012a
getCodistributor

Codistributor object for existing codistributed array

Syntax

codist = getCodistributor(D)

Description

codist = getCodistributor(D) returns the codistributor object of codistributed array D. Properties of the object are Dimension and Partition for 1-D distribution; and BlockSize, LabGrid, and Orientation for 2-D block cyclic distribution. For any one codistributed array, getCodistributor returns the same values on all workers. The returned codistributor object is complete, and therefore suitable as an input argument for codistributed.build.

Examples

Get the codistributor object for a 1-D codistributed array that uses default distribution on 4 workers:

```matlab
spmd (4)
    I1 = eye(64,codistributor1d());
    codist1 = get Codistributor(I1)
    dim    = codist1.Dimension
    partn  = codist1.Partition
end
```

Get the codistributor object for a 2-D block cyclic codistributed array that uses default distribution on 4 workers:

```matlab
spmd (4)
    I2 = eye(128,codistributor2dbc());
    codist2 = get Codistributor(I2)
    blocksz = codist2.BlockSize
```
Demonstrate that these codistributor objects are complete:

```matlab
spmd (4)
    isComplete(codist1)
    isComplete(codist2)
end
```

**See Also**

codistributed | codistributed.build | getLocalPart | redistribute

*Introduced in R2009b*
getCurrentCluster

Cluster object that submitted current task

Syntax

c = getCurrentCluster

Arguments

c The cluster object that scheduled the task currently being evaluated by the worker session.

Description

c = getCurrentCluster returns the parallel.Cluster object that has sent the task currently being evaluated by the worker session. Cluster object c is the Parent of the task’s parent job.

Examples

Find the current cluster.

myCluster = getCurrentCluster;

Get the host on which the cluster is running.

host = myCluster.Host;

Tips

If this function is executed in a MATLAB session that is not a worker, you get an empty result.
See Also

getAttachedFilesFolder | getCurrentJob | getCurrentTask | getCurrentWorker

Introduced in R2012a
**getCurrentJob**

Job object whose task is currently being evaluated

**Syntax**

```matlab
job = getCurrentJob
```

**Arguments**

<table>
<thead>
<tr>
<th>Argument</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>job</code></td>
<td>The job object that contains the task currently being evaluated by the worker session.</td>
</tr>
</tbody>
</table>

**Description**

`job = getCurrentJob` returns the `Parallel.Job` object that is the Parent of the task currently being evaluated by the worker session.

**Tips**

If the function is executed in a MATLAB session that is not a worker, you get an empty result.

**See Also**

`getAttachedFilesFolder` | `getCurrentCluster` | `getCurrentTask` | `getCurrentWorker`

**Introduced before R2006a**
getCurrentTask

Task object currently being evaluated in this worker session

Syntax

task = getCurrentTask

Arguments

task  The task object that the worker session is currently evaluating.

Description

task = getCurrentTask returns the Parallel.Task object whose function is currently being evaluated by the MATLAB worker session on the cluster.

Tips

If the function is executed in a MATLAB session that is not a worker, you get an empty result.

See Also

getAttachedFilesFolder | getCurrentCluster | getCurrentJob | getCurrentWorker

Introduced before R2006a
getCurrentWorker

Worker object currently running this session

Syntax

worker = getCurrentWorker

Arguments

worker  The worker object that is currently evaluating the task that contains this function.

Description

worker = getCurrentWorker returns the Parallel.Worker object representing the MATLAB worker session that is currently evaluating the task function that contains this call.

If the function runs in a MATLAB session that is not a worker, it returns an empty result.

Examples

Find the Host property of a worker that runs a task. The file identifyWorkerHost.m contains the following function code.

```
function localHost = identifyWorkerHost()
    thisworker = getCurrentWorker;  % Worker object
    localHost = thisworker.Host;    % Host property
end
```

Create a job with a task to execute this function on a worker and return the worker's host name. This example manually attaches the necessary code file.
c = parcluster();
j = createJob(c);
j.AttachedFiles = {'identifyWorkerHost.m'};
t = createTask(j,@identifyWorkerHost,1,{});
submit(j)
wait(j)
workerhost = fetchOutputs(j)

See Also
getAttachedFilesFolder | getCurrentCluster | getCurrentJob | getCurrentTask

Introduced before R2006a
getDebugLog

Read output messages from job run in CJS cluster

Syntax

str = getDebugLog(cluster,job_or_task)

Arguments

str
Variable to which messages are returned as a character vector expression.

cluster
Cluster object referring to Microsoft Windows HPC Server (or CCS), Platform LSF, PBS Pro, or TORQUE cluster, created by parcluster.

job_or_task
Object identifying job or task whose messages you want.

Description

str = getDebugLog(cluster,job_or_task) returns any output written to the standard output or standard error stream by the job or task identified by job_or_task, being run in the cluster identified by cluster.

Examples

This example shows how to create and submit a communicating job, and how to retrieve the job's debug log. Assume that you already have a cluster profile called My3pCluster that defines the properties of the cluster.

c = parcluster('My3pCluster');

j = createCommunicatingJob(c);
createTask(j,@labindex,1,{});
submit(j);
getDebugLog(c,j);

See Also
createCommunicatingJob | createJob | createTask | parcluster

Introduced before R2006a
getJobClusterData

Get specific user data for job on generic cluster

Syntax

userdata = getJobClusterData(cluster, job)

Arguments

userdata  Information that was previously stored for this job
cluster    Cluster object identifying the generic third-party cluster running the job
job        Job object identifying the job for which to retrieve data

Description

userdata = getJobClusterData(cluster, job) returns data stored for the job job that was derived from the generic cluster cluster. The information was originally stored with the function setJobClusterData. For example, it might be useful to store the third-party scheduler’s external ID for this job, so that the function specified in GetJobStateFcn can later query the scheduler about the state of the job.

To use this feature, you should call the function setJobClusterData in the submit function (identified by the IndependentSubmitFcn or CommunicatingSubmitFcn property) and call getJobClusterData in any of the functions identified by the properties GetJobStateFcn, DeleteJobFcn, DeleteTaskFcn, CancelJobFcn, or CancelTaskFcn.

For more information and examples on using these functions and properties, see “Manage Jobs with Generic Scheduler” on page 7-35.

See Also

setJobClusterData
Introduced in R2012a
getJobFolder

Folder on client where jobs are stored

Syntax

joblocation = getJobFolder(cluster, job)

Description

joblocation = getJobFolder(cluster, job) returns the path to the folder on disk where files are stored for the specified job and cluster. This folder is valid only the client MATLAB session, not necessarily the workers. This method exists only on clusters using the generic interface.

See Also

getJobFolderOnCluster | parcluster

Introduced in R2012a
getJobFolderOnCluster

Folder on cluster where jobs are stored

Syntax

joblocation = getJobFolderOnCluster(cluster, job)

Description

joblocation = getJobFolderOnCluster(cluster, job) returns the path to the folder on disk where files are stored for the specified job and cluster. This folder is valid only in worker MATLAB sessions. An error results if the HasSharedFilesystem property of the cluster is false. This method exists only on clusters using the generic interface.

See Also

getJobFolder | parcluster

Introduced in R2012a
getLocalPart

Local portion of codistributed array

Syntax

L = getLocalPart(A)

Description

L = getLocalPart(A) returns the local portion of a codistributed array.

Examples

With four workers,

A = magic(4);  \%replicated on all workers
D = codistributed(A, codistributor1d(1));
L = getLocalPart(D)

returns

Lab 1: L = [16 2 3 13]
Lab 2: L = [ 5 11 10  8]
Lab 3: L = [ 9  7  6 12]
Lab 4: L = [ 4 14 15  1]

See Also

codistributed | codistributor

Introduced in R2009b
getLogLocation

Log location for job or task

Syntax

logfile = getLogLocation(cluster,cj)
logfile = getLogLocation(cluster,it)

Description

logfile = getLogLocation(cluster,cj) for a generic cluster cluster and communicating job cj, returns the location where the log data should be stored for the whole job cj.

logfile = getLogLocation(cluster,it) for a generic cluster cluster and task it of an independent job returns the location where the log data should be stored for the task it.

This function can be useful during submission, to instruct the third-party cluster to put worker output logs in the correct location.

See Also
parcluster

Introduced in R2012a
**globalIndices**

Global indices for local part of codistributed array

**Syntax**

\[
K = \text{globalIndices}(C, \text{dim}) \\
K = \text{globalIndices}(C, \text{dim, lab}) \\
[E,F] = \text{globalIndices}(C, \text{dim}) \\
[E,F] = \text{globalIndices}(C, \text{dim, lab}) \\
K = \text{globalIndices}(\text{codist, dim, lab}) \\
[E,F] = \text{globalIndices}(\text{codist, dim, lab})
\]

**Description**

globalIndices tells you the relationship between indices on a local part and the corresponding index range in a given dimension on the codistributed array. The globalIndices method on a codistributor object allows you to get this relationship without actually creating the array.

\[
K = \text{globalIndices}(C, \text{dim}) \text{ or } K = \text{globalIndices}(C, \text{dim, lab}) \text{ returns a vector } K \text{ so that } \text{getLocalPart}(C) = C(...,K,...) \text{ in the specified dimension dim of codistributed array } C \text{ on the specified worker. If the lab argument is omitted, the default is labindex.}
\]

\[
[E,F] = \text{globalIndices}(C, \text{dim}) \text{ or } [E,F] = \text{globalIndices}(C, \text{dim, lab}) \text{ returns two integers } E \text{ and } F \text{ so that } \text{getLocalPart}(C) = C(...,E:F,...) \text{ of codistributed array } C \text{ in the specified dimension dim on the specified worker. If the lab argument is omitted, the default is labindex.}
\]

\[
K = \text{globalIndices}(\text{codist, dim, lab}) \text{ is the same as } K = \text{globalIndices}(C, \text{dim, lab}), \text{ where codist is the codistributor to be used for } C, \text{ or } \text{codist} = \text{getCodistributor}(C). \text{ This allows you to get the global indices for a codistributed array without having to create the array itself.}
\]

\[
[E,F] = \text{globalIndices}(\text{codist, dim, lab}) \text{ is the same as } [E,F] = \text{globalIndices}(C, \text{dim, lab}), \text{ where codist is the codistributor to be used for } C, \text{ or}
\]
codist = getCodistributor(C). This allows you to get the global indices for a codistributed array without having to create the array itself.

Examples

Create a 2-by-22 codistributed array among four workers, and view the global indices on each lab:

```matlab
spmd
    C = zeros(2,22,codistributor1d(2,[6 6 5 5]));
    if labindex == 1
        K = globalIndices(C,2)  \% returns K = 1:6.
    elseif labindex == 2
        [E,F] = globalIndices(C,2) \% returns E = 7, F = 12.
    end
    K = globalIndices(C,2,3) \% returns K = 13:17.
    [E,F] = globalIndices(C,2,4) \% returns E = 18, F = 22.
end
```

Use `globalIndices` to load data from a file and construct a codistributed array distributed along its columns, i.e., dimension 2. Notice how `globalIndices` makes the code not specific to the number of workers and alleviates you from calculating offsets or partitions.

```matlab
spmd
    siz = [1000,1000];
    codistr = codistributor1d(2,[],siz);

    % Use globalIndices to figure out which columns
    % each worker should load.
    [firstCol,lastCol] = globalIndices(codistr,2);

    % Call user-defined function readRectangleFromFile to
    % load all the values that should go into
    % the local part for this worker.
    labLocalPart = readRectangleFromFile(fileName, ...
                   1,siz(1),firstCol,lastCol);

    % With the local part and codistributor,
    % construct the corresponding codistributed array.
    C = codistributed.build(labLocalPart,codistr);
end
```
See Also
getLocalPart | labindex

Introduced in R2008a
gop

Global operation across all workers

Syntax

\[ \text{res} = \text{gop}(\text{FUN}, x) \]
\[ \text{res} = \text{gop}(\text{FUN}, x, \text{targetlab}) \]

Arguments

- **FUN**: Function to operate across workers.
- **x**: Argument to function \( F \), should be the same variable on all workers, but can have different values.
- **res**: Variable to hold reduction result.
- **targetlab**: Lab to which reduction results are returned. This value is returned by that worker’s labindex.

Description

\[ \text{res} = \text{gop}(\text{FUN}, x) \] is the reduction via the function \( \text{FUN} \) of the quantities \( x \) from each worker. The result is duplicated on all workers.

\( \text{FUN} \) can be a handle to any function, including user-written functions and user-defined anonymous functions. It should accept two arguments of the same type, and return one result of that same type, so it can be used iteratively in the form:

\[ \text{FUN}(\text{FUN}(x_1, x_2), \text{FUN}(x_3, x_4)) \]

The function \( \text{FUN} \) should be associative, that is,

\[ \text{FUN}(\text{FUN}(x_1, x_2), x_3) = \text{FUN}(x_1, \text{FUN}(x_2, x_3)) \]

\[ \text{res} = \text{gop}(\text{FUN}, x, \text{targetlab}) \] performs the reduction, and places the result into \( \text{res} \) only on the worker indicated by \( \text{targetlab} \). \( \text{res} \) is set to \( [ ] \) on all other workers.
Examples

This example shows how to calculate the sum and maximum values for $x$ among all workers.

```matlab
p = parpool('local',4);
x = Composite();
x{1} = 3;
x{2} = 1;
x{3} = 4;
x{4} = 2;
spmd
    xsum = gop(@plus,x);
    xmax = gop(@max,x);
end
xsum{1}
10
xmax{1}
4
```

This example shows how to horizontally concatenate the column vectors of $x$ from all workers into a matrix. It uses the same 4-worker parallel pool opened by the previous example.

```matlab
x{1} = [3;30];
x{2} = [1;10];
x{3} = [4;40];
x{4} = [2;20];
spmd
    res = gop(@horzcat,x);
end
res{1}
```

This example shows how to use an anonymous function with `gop` to join character vectors with spaces between them. In this case, the character vectors are created from each worker's `labindex` value.

```matlab
afun = @(a,b)[a,' ',b]
spmd
```
res = gop(afun,num2str(labindex));
end
res{1}
1 2 3 4

See Also
labBarrier | labindex | numlabs

Topics
Using GOP to Achieve MPI_Allreduce Functionality

Introduced before R2006a
gplus
Global addition

Syntax

S = gplus(X)
S = gplus(X,targetlab)

Description

S = gplus(X) returns the addition of the variant array X from each worker. The result S is replicated on all workers.

S = gplus(X,targetlab) performs the addition, and places the result into S only on the worker indicated by targetlab. S is set to [] on all other workers.

Examples

With four workers,

S = gplus(labindex)

calculates S = 1 + 2 + 3 + 4, and returns 10 on all four workers.

See Also

gop | labindex

Introduced in R2006b
gpuArray

Create array on GPU

Syntax

G = gpuArray(X)

Description

G = gpuArray(X) copies the numeric array X to the GPU, and returns a gpuArray object. You can operate on this array by passing its gpuArray to the feval method of a CUDA kernel object, or by using one of the methods defined for gpuArray objects in “Establish Arrays on a GPU” on page 9-3.

The MATLAB array X must be numeric (for example: single, double, int8, etc.) or logical, and the GPU device must have sufficient free memory to store the data.

If the input argument is already a gpuArray, the output is the same as the input.

Use gather to retrieve the array from the GPU to the MATLAB workspace.

Examples

Transfer a 10-by-10 matrix of random single-precision values to the GPU, then use the GPU to square each element.

X = rand(10,'single');
G = gpuArray(X);
classUnderlying(G)

single

G2 = G .* G; % Performed on GPU
whos G2 % Result on GPU
Copy the array back to the MATLAB workspace.

G1 = gather(G2);
whos G1

See Also
arrayfun | bsxfun | existsOnGPU | feval | gather | parallel.gpu.CUDAKernel | reset

Topics
“Establish Arrays on a GPU” on page 9-3
“Run Built-In Functions on a GPU” on page 9-8
“Identify and Select a GPU Device” on page 9-19

Introduced in R2010b
gpuDevice

Query or select GPU device

Syntax

D = gpuDevice
D = gpuDevice()  
D = gpuDevice(IDX)
gpuDevice([])

Description

D = gpuDevice or D = gpuDevice(), if no device is already selected, selects the default GPU device and returns a GPUDevice object representing that device. If a GPU device is already selected, this returns an object representing that device without clearing it.

D = gpuDevice(IDX) selects the GPU device specified by index IDX. IDX must be in the range of 1 to gpuDeviceCount. A warning or error might occur if the specified GPU device is not supported. This form of the command with a specified index resets the device and clears its memory (even if this device is already currently selected, equivalent to reset); so all workspace variables representing gpuArray or CUDAKernel variables are now invalid, and you should clear them from the workspace or redefine them.

gpuDevice([]), with an empty argument (as opposed to no argument), deselects the GPU device and clears its memory of gpuArray and CUDAKernel variables. This leaves no GPU device selected as the current device.

Examples

Create an object representing the default GPU device.

g = gpuDevice;

Query the compute capabilities of all available GPU devices.
for ii = 1:gpuDeviceCount
    g = gpuDevice(ii);
    fprintf(1,'Device %i has ComputeCapability %s \n', ... 
        g.Index, g.ComputeCapability)
end

Device 1 has ComputeCapability 3.5
Device 2 has ComputeCapability 2.0

See Also
arrayfun | feval | gpuDeviceCount | parallel.gpu.CUDAKernel | reset | wait (GPUDevice)

Introduced in R2010b
gpuDeviceCount

Number of GPU devices present

Syntax

\( n = \text{gpuDeviceCount} \)

Description

\( n = \text{gpuDeviceCount} \) returns the number of GPU devices present in your computer.

Examples

Determine how many GPU devices you have available in your computer and examine the properties of each.

\( n = \text{gpuDeviceCount}; \)
\( \text{for } ii = 1:n \)
\( \quad \text{gpuDevice}(ii) \)
\( \text{end} \)

See Also

arrayfun | feval | gpuDevice | parallel.gpu.CUDAKernel

Introduced in R2010b
**gputimeit**

Time required to run function on GPU

**Syntax**

\[
t = \text{gputimeit}(F)
\]

\[
t = \text{gputimeit}(F,N)
\]

**Description**

\[
t = \text{gputimeit}(F)
\] measures the typical time (in seconds) required to run the function specified by the function handle \( F \). The function handle accepts no external input arguments, but can be defined with input arguments to its internal function call.

\[
t = \text{gputimeit}(F,N)
\] calls \( F \) to return \( N \) output arguments. By default, \text{gputimeit} calls the function \( F \) with one output argument, or no output arguments if \( F \) does not return any output.

**Examples**

Measure the time to calculate \( \text{sum}(A.' \ .* \ B, 1) \) on a GPU, where \( A \) is a 12000-by-400 matrix and \( B \) is 400-by-12000.

\[
A = \text{rand}(12000,400,\text{'gpuArray'});
B = \text{rand}(400,12000,\text{'gpuArray'});
f = @(A) \text{sum}(A.' \ .* \ B, 1);
t = \text{gputimeit}(f)
\]

0.0026

Compare the time to run \( \text{svd} \) on a GPU, with one versus three output arguments.

\[
X = \text{rand}(1000,\text{'gpuArray'});
f = @(X) \text{svd}(X);
t3 = \text{gputimeit}(f,3)
\]
1.0622

t1 = gputimeit(f,1)

0.2933

**Tips**

gputimeit is preferable to timeit for functions that use the GPU, because it ensures that all operations on the GPU have finished before recording the time and compensates for the overhead. For operations that do not use a GPU, timeit offers greater precision.

Note the following limitations:

- The function \( F \) should not call tic or toc.
- You cannot use tic and toc to measure the execution time of gputimeit itself.

**See Also**
gpuArray | wait

*Introduced in R2013b*
help

Help for toolbox functions in Command Window

Syntax

help class/function

Arguments

class
A Parallel Computing Toolbox object class, for example,
parallel.cluster, parallel.job, or parallel.task.

function
A function or property of the specified class. To see what functions or
properties are available for a class, see the methods or properties
reference page.

Description

help class/function returns command-line help for the specified function of the
given class.

If you do not know the class for the function, use class(obj), where function is of the
same class as the object obj.

Examples

Get help on functions or properties from Parallel Computing Toolbox object classes.

help parallel.cluster/createJob
help parallel.job/cancel
help parallel.task/wait

c = parcluster();
j1 = createJob(c);
class(j1)
See Also

methods

Introduced before R2006a
Inf

Array of infinity

Syntax

\[
A = \text{Inf}(sz, \text{arraytype})
\]
\[
A = \text{Inf}(sz, \text{datatype}, \text{arraytype})
\]
\[
A = \text{Inf}(sz, \text{'like'}, P)
\]
\[
A = \text{Inf}(sz, \text{datatype}, \text{'like'}, P)
\]
\[
C = \text{Inf}(sz, \text{codist})
\]
\[
C = \text{Inf}(sz, \text{datatype}, \text{codist})
\]
\[
C = \text{Inf}(sz, \text{'like'}, P)
\]
\[
C = \text{Inf}(sz, \text{'like'}, P)
\]

Description

\[
A = \text{Inf}(sz, \text{arraytype})
\]
creates a matrix with underlying class of double, with Inf values in all elements.

\[
A = \text{Inf}(sz, \text{datatype}, \text{arraytype})
\]
creates a matrix with underlying class of datatype, with Inf values in all elements.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>sz</td>
<td>n</td>
<td>Specifies size as an n-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m, n or [m n]</td>
<td>Specifies size as an m-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m, n, ..., k or [m n ... k]</td>
<td>Specifies size as an m-by-n-by-....-by-k array.</td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td>Argument</td>
<td>Values</td>
<td>Descriptions</td>
</tr>
<tr>
<td>----------</td>
<td>--------</td>
<td>--------------</td>
</tr>
<tr>
<td></td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
<tr>
<td>datatype</td>
<td>'double' (default), 'single'</td>
<td>Specifies underlying class of the array, i.e., the data type of its elements.</td>
</tr>
</tbody>
</table>

A = Inf(sz, 'like', P) creates an array of Inf values with the same type and underlying class (data type) as array P.

A = Inf(sz, datatype, 'like', P) creates an array of Inf values with the specified underlying class (datatype), and the same type as array P.

C = Inf(sz, codist) or C = Inf(sz, datatype, codist) creates a codistributed array of Inf values with the specified size and underlying class (the default datatype is 'double'). The codistributor object codist specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = Inf(8, codistributor1d());
end
```

C = Inf(sz, ____, codist, 'noCommunication') specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = Inf(sz, ____, codist, 'like', P) creates a codistributed array of Inf values with the specified size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array P.
Examples

Create Distributed Inf Matrix

Create a 1000-by-1000 distributed array of Inf's with underlying class double:

```matlab
D = Inf(1000,'distributed');
```

Create Codistributed Inf Matrix

Create a 1000-by-1000 codistributed double matrix of Inf's, distributed by its second dimension (columns).

```matlab
spmd(4)
    C = Inf(1000,'codistributed');
end
```

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed single matrix of Inf's, distributed by its columns.

```matlab
spmd(4)
    codist = codistributor('1d',2,100*[1:numlabs]);
    C = Inf(1000,1000,'single',codist);
end
```

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray Inf Matrix

Create a 1000-by-1000 gpuArray of Inf's with underlying class double:

```matlab
G = Inf(1000,'double','gpuArray');
```

See Also
Inf | NaN | eye | false | ones | true | zeros
isaUnderlying

True if distributed array's underlying elements are of specified class

Syntax

TF = isaUnderlying(D, 'classname')

Description

TF = isaUnderlying(D, 'classname') returns true if the elements of distributed or codistributed array D are either an instance of classname or an instance of a class derived from classname. isaUnderlying supports the same values for classname as the MATLAB isa function does.

Examples

N = 1000;
D_uint8 = ones(1,N,'uint8','distributed');
D_cell = distributed.cell(1,N);
isUint8 = isaUnderlying(D_uint8,'uint8') % returns true
isDouble = isaUnderlying(D_cell,'double') % returns false

See Also

isa

Introduced in R2010a
iscodistributed

True for codistributed array

Syntax

tf = iscodistributed(X)

Description

tf = iscodistributed(X) returns true for a codistributed array, or false otherwise. For a description of codistributed arrays, see “Nondistributed Versus Distributed Arrays” on page 5-2.

Examples

With a running parallel pool,

```matlab
spmd
    L = ones(100,1);
    D = ones(100,1,'codistributed');
    iscodistributed(L)    % returns false
    iscodistributed(D)    % returns true
end
```

See Also

isdistributed

Introduced in R2009b
isComplete

True if codistributor object is complete

Syntax

tf = isComplete(codist)

Description

tf = isComplete(codist) returns true if codist is a completely defined codistributor, or false otherwise. For a description of codistributed arrays, see “Nondistributed Versus Distributed Arrays” on page 5-2.

See Also

codistributed | codistributor

Introduced in R2009b
isdistributed

True for distributed array

Syntax

tf = isdistributed(X)

Description

tf = isdistributed(X) returns true for a distributed array, or false otherwise. For a description of a distributed array, see “Nondistributed Versus Distributed Arrays” on page 5-2.

Examples

With a running parallel pool,

L = ones(100,1);
D = ones(100,1,'distributed');
isdistributed(L) % returns false
isdistributed(D) % returns true

See Also

iscodistributed

Introduced in R2006b
isequal

True if clusters have same property values

Syntax

isequal(C1,C2)
isequal(C1,C2,C3,...)

Description

isequal(C1,C2) returns logical 1 (true) if clusters C1 and C2 have the same property values, or logical 0 (false) otherwise.

isequal(C1,C2,C3,...) returns true if all clusters are equal. isequal can operate on arrays of clusters. In this case, the arrays are compared element by element.

When comparing clusters, isequal does not compare the contents of the clusters’ Jobs property.

Examples

Compare clusters after some properties are modified.

```matlab
c1 = parcluster('local');
c1.NumWorkers = 2;       % Modify cluster
c1.saveAsProfile('local2') % Create new profile
c2 = parcluster('local2'); % Make cluster from new profile
isequal(c1,c2)

1

c0 = parcluster('local')   % Use original profile
isequal(c0,c1)

0
```
See Also
parcluster

Introduced in R2012a
isequal (FevalFuture)

True if futures have same ID

Syntax

eq = isequal(F1,F2)

Description

eq = isequal(F1,F2) returns logical 1 (true) if futures F1 and F2 have the same ID property value, or logical 0 (false) otherwise.

Examples

Compare future object in workspace to queued future object.

p = parpool('local',2);
q = p.FevalQueue;
Fp = parfevalOnAll(p,@pause,0,30);
F1 = parfeval(p,@magic,1,10);
F2 = q.QueueedFutures;
isequal(F1,F2)

1

See Also

cancel | fetchNext | fetchOutputs | parfeval | wait

Introduced in R2014a
isreplicated

True for replicated array

Syntax

tf = isreplicated(X)

Description

tf = isreplicated(X) returns true for a replicated array, or false otherwise. For a description of a replicated array, see “Nondistributed Versus Distributed Arrays” on page 5-2. isreplicated also returns true for a Composite X if all its elements are identical.

Examples

With an open parallel pool,

spmd
    A = magic(3);
    t = isreplicated(A) % returns t = true
    B = magic(labindex);
    f = isreplicated(B) % returns f = false
end

Tips

isreplicated(X) requires checking for equality of the array X across all workers. This might require extensive communication and time. isreplicated is most useful for debugging or error checking small arrays. A codistributed array is not replicated.

See Also

iscodistributed |isdistributed
Introduced in R2006b
jobStartup

File for user-defined options to run when job starts

Syntax

jobStartup(job)

Arguments

job The job for which this startup is being executed.

Description

jobStartup(job) runs automatically on a worker the first time that worker evaluates a task for a particular job. You do not call this function from the client session, nor explicitly as part of a task function.

You add MATLAB code to the jobStartup.m file to define job initialization actions on the worker. The worker looks for jobStartup.m in the following order, executing the one it finds first:

1  Included in the job’s AttachedFiles property.
2  In a folder included in the job’s AdditionalPaths property.
3  In the worker’s MATLAB installation at the location

matlabroot/toolbox/distcomp/user/jobStartup.m

To create a version of jobStartup.m for AttachedFiles or AdditionalPaths, copy the provided file and modify it as required. For further details on jobStartup and its implementation, see the text in the installed jobStartup.m file.

See Also

poolStartup | taskFinish | taskStartup
Introduced before R2006a
labBarrier

Block execution until all workers reach this call

Syntax

labBarrier

Description

labBarrier blocks execution of a parallel algorithm until all workers have reached the call to labBarrier. This is useful for coordinating access to shared resources such as file I/O.

Examples

Synchronize Workers for Timing

When timing code execution on the workers, use labBarrier to ensure all workers are synchronized and start their timed work together.

labBarrier;

tic
    A = rand(1,1e7,'codistributed');
distTime = toc;

See Also

labBroadcast | labReceive | labSend | labSendReceive

Introduced before R2006a
**labBroadcast**

Send data to all workers or receive data sent to all workers

**Syntax**

```plaintext
shared_data = labBroadcast(srcWkrIdx, data)
shared_data = labBroadcast(srcWkrIdx)
```

**Arguments**

- `srcWkrIdx`: The labindex of the worker sending the broadcast.
- `data`: The data being broadcast. This argument is required only for the worker that is broadcasting. The absence of this argument indicates that a worker is receiving.
- `shared_data`: The broadcast data as it is received on all other workers.

**Description**

`shared_data = labBroadcast(srcWkrIdx, data)` sends the specified data to all executing workers. The data is broadcast from the worker with `labindex == srcWkrIdx`, and is received by all other workers.

`shared_data = labBroadcast(srcWkrIdx)` receives on each executing worker the specified `shared_data` that was sent from the worker whose `labindex` is `srcWkrIdx`.

If `labindex` is not `srcWkrIdx`, then you do not include the `data` argument. This indicates that the function is to receive data, not broadcast it. The received data, `shared_data`, is identical on all workers.

This function blocks execution until the worker’s involvement in the collective broadcast operation is complete. Because some workers may complete their call to `labBroadcast` before others have started, use `labBarrier` if you need to guarantee that all workers are at the same point in a program.
Examples

In this case, the broadcaster is the worker whose labindex is 1.

```matlab
srcWkrIdx = 1;
if labindex == srcWkrIdx
    data = randn(10);
    shared_data = labBroadcast(srcWkrIdx,data);
else
    shared_data = labBroadcast(srcWkrIdx);
end
```

See Also

labBarrier | labSendReceive | labindex

Introduced before R2006a
**labindex**

Index of this worker

**Syntax**

$id = \text{labindex}$

**Description**

$id = \text{labindex}$ returns the index of the worker currently executing the function. \text{labindex} is assigned to each worker when a job begins execution, and applies only for the duration of that job. The value of \text{labindex} spans from 1 to \(n\), where \(n\) is the number of workers running the current job, defined by \text{numlabs}.

**Examples**

View \text{labindex} in \text{spmd} blocks and \text{parfor-loops}.

```matlab
p = parpool('local',2);
spmd
    labindex
end

Lab 1:
    1

Lab 2:
    2

Using the same two-worker pool, p:

```matlab
parfor a=1:4
    [a,labindex]
end

ans =
    3 1```
ans =
   2  1
ans =
   1  1
ans =
   1
   4  1

Tips

In an `spmd` block, because you have access to all workers individually and control what gets executed on them, each worker has a unique `labindex`.

However, inside a `parfor`-loop, `labindex` always returns a value of 1 on all workers in all iterations.

See Also

`labSendReceive` | `numlabs`

Introduced before R2006a
labProbe

Test to see if messages are ready to be received from other worker.

Syntax

```matlab
isDataAvail = labProbe
isDataAvail = labProbe(srcWkrIdx)
isDataAvail = labProbe('any',tag)
isDataAvail = labProbe(srcWkrIdx,tag)
[isDataAvail,srcWkrIdx,tag] = labProbe
```

Arguments

- `srcWkrIdx`  
  Labindex of a particular worker from which to test for a message.

- `tag`  
  Tag defined by the sending worker’s `labSend` function to identify particular data.

- `'any'`  
  Character vector to indicate that all workers should be tested for a message.

- `isDataAvail`  
  Logical indicating if a message is ready to be received.

Description

`isDataAvail = labProbe` returns a logical value indicating whether any data is available for this worker to receive with the `labReceive` function.

`isDataAvail = labProbe(srcWkrIdx)` tests for a message only from the specified worker.

`isDataAvail = labProbe('any',tag)` tests only for a message with the specified tag, from any worker.

`isDataAvail = labProbe(srcWkrIdx,tag)` tests for a message from the specified worker and tag.
[isDataAvail, srcWkrIdx, tag] = labProbe returns labindex of the workers and tags of ready messages. If no data is available, srcWkrIdx and tag are returned as [].

See Also
labReceive | labSend | labSendReceive | labindex

Introduced before R2006a
labReceive

Receive data from another worker

Syntax

data = labReceive
data = labReceive(srcWkrIdx)
data = labReceive('any',tag)
data = labReceive(srcWkrIdx,tag)
[data,srcWkrIdx,tag] = labReceive

Arguments

srcWkrIdx labindex of a particular worker from which to receive data.
tag Tag defined by the sending worker’s labSend function to identify particular data.
'any' Character vector to indicate that data can come from any worker.
data Data sent by the sending worker’s labSend function.

Description

data = labReceive receives data from any worker with any tag.
data = labReceive(srcWkrIdx) receives data from the specified worker with any tag.
data = labReceive('any',tag) receives data from any worker with the specified tag.
data = labReceive(srcWkrIdx,tag) receives data from only the specified worker with the specified tag.
[data,srcWkrIdx,tag] = labReceive returns the source worker labindex and tag with the data.
Tips

This function blocks execution in the worker until the corresponding call to `labSend` occurs in the sending worker.

See Also

`labBarrier` | `labProbe` | `labSend` | `labSendReceive` | `labindex`

Introduced before R2006a
**labSend**

Send data to another worker

**Syntax**

labSend(data,rcvWkrIdx)
labSend(data,rcvWkrIdx,tag)

**Arguments**

data
rcvWkrIdx
tag

Data sent to the other workers; any MATLAB data type.
labindex of receiving worker or workers.
Nonnegative integer to identify data.

**Description**

labSend(data,rcvWkrIdx) sends the data to the specified destination. data can be any MATLAB data type. rcvWkrIdx identifies the labindex of the receiving worker, and must be either a scalar or a vector of integers between 1 and numlabs; it cannot be labindex of the current (sending) worker.

labSend(data,rcvWkrIdx,tag) sends the data to the specified destination with the specified tag value. tag can be any integer from 0 to 32767, with a default of 0.

**Tips**

This function might or might not return before the corresponding labReceive completes in the receiving worker.

**See Also**

labBarrier | labProbe | labReceive | labSendReceive | labindex | numlabs
Introduced before R2006a
**labSendReceive**

Simultaneously send data to and receive data from another worker

**Syntax**

\[
\text{dataReceived} = \text{labSendReceive}(\text{rcvWkrIdx}, \text{srcWkrIdx}, \text{dataSent}) \\
\text{dataReceived} = \text{labSendReceive}(\text{rcvWkrIdx}, \text{srcWkrIdx}, \text{dataSent}, \text{tag})
\]

**Arguments**

- **dataSent**
  Data on the sending worker that is sent to the receiving worker; any MATLAB data type.

- **dataReceived**
  Data accepted on the receiving worker.

- **rcvWkrIdx**
  labindex of the receiving worker to which data is sent.

- **srcWkrIdx**
  labindex of the source worker from which data is sent.

- **tag**
  Nonnegative integer to identify data.

**Description**

\[
\text{dataReceived} = \text{labSendReceive}(\text{rcvWkrIdx}, \text{srcWkrIdx}, \text{dataSent}) \text{ sends dataSent to the worker whose labindex is rcvWkrIdx, and receives dataReceived from the worker whose labindex is srcWkrIdx. The values for arguments rcvWkrIdx and srcWkrIdx must be scalars. This function is conceptually equivalent to the following sequence of calls:}
\]

\[
\text{labSend(dataSent,rcvWkrIdx);} \\
\text{dataReceived = labReceive(srcWkrIdx)};
\]

with the important exception that both the sending and receiving of data happens concurrently. This can eliminate deadlocks that might otherwise occur if the equivalent call to labSend would block.

If **rcvWkrIdx** is an empty array, **labSendReceive** does not send data, but only receives. If **srcWkrIdx** is an empty array, **labSendReceive** does not receive data, but only sends.
dataReceived = labSendReceive(rcvWkrIdx, srcWkrIdx, dataSent, tag) uses the specified tag for the communication. \( \text{tag} \) can be any integer from 0 to 32767.

**Examples**

Create a unique set of data on each worker, and transfer each worker’s data one worker to the right (to the next higher labindex).

First use the `magic` function to create a unique value for the variant array `mydata` on each worker.

\[
\text{mydata} = \text{magic}((\text{labindex})
\]

Lab 1:
\[
\begin{align*}
\text{mydata} &= 1 \\
\end{align*}
\]
Lab 2:
\[
\begin{align*}
\text{mydata} &= 1 & 3 \\
& & 4 & 2 \\
\end{align*}
\]
Lab 3:
\[
\begin{align*}
\text{mydata} &= 8 & 1 & 6 \\
& & 3 & 5 & 7 \\
& & 4 & 9 & 2 \\
\end{align*}
\]

Define the worker on either side, so that each worker will receive data from the worker on its “left,” while sending data to the worker on its “right,” cycling data from the end worker back to the beginning worker.

\[
\begin{align*}
\text{rcvWkrIdx} &= \text{mod}(\text{labindex}, \text{nulabs}) + 1; \quad \% \text{one worker to the right} \\
\text{srcWkrIdx} &= \text{mod}(\text{labindex} - 2, \text{nulabs}) + 1; \quad \% \text{one worker to the left} \\
\end{align*}
\]

Transfer the data, sending each worker’s `mydata` into the next worker’s `otherdata` variable, wrapping the third worker’s data back to the first worker.

\[
\text{otherdata} = \text{labSendReceive}(\text{rcvWkrIdx}, \text{srcWkrIdx}, \text{mydata})
\]

Lab 1:
\[
\begin{align*}
\text{otherdata} &= 8 & 1 & 6 \\
& & 3 & 5 & 7 \\
& & 4 & 9 & 2 \\
\end{align*}
\]
Lab 2:
  otherdata =
    1
Lab 3:
  otherdata =
    1 3
    4 2

Transfer data to the next worker without wrapping data from the last worker to the first worker.

if labindex < numlabs; rcvWkrIdx = labindex + 1; else rcvWkrIdx = []; end;
if labindex > 1; srcWkrIdx = labindex - 1; else srcWkrIdx = []; end;
otherdata = labSendReceive(rcvWkrIdx,srcWkrIdx,mydata)

Lab 1:
  otherdata =
    []
Lab 2:
  otherdata =
    1
Lab 3:
  otherdata =
    1 3
    4 2

See Also
labBarrier | labProbe | labReceive | labSend | labindex | numlabs

Introduced in R2006b
length

Length of object array

Syntax

length(obj)

Arguments

obj An object or an array of objects.

Description

length(obj) returns the length of obj. It is equivalent to the command max(size(obj)).

Examples

Examine how many tasks are in the job j1.

length(j1.Tasks)

ans =
   9

See Also

size

Introduced before R2006a
listAutoAttachedFiles

List of files automatically attached to job, task, or parallel pool

Syntax

listAutoAttachedFiles(obj)

Description

listAutoAttachedFiles(obj) performs a dependency analysis on all the task functions, or on the batch job script or function. Then it displays a list of the code files that are already or going to be automatically attached to the job or task object obj.

If obj is a parallel pool, the output lists the files that have already been attached to the parallel pool following an earlier dependency analysis. The dependency analysis runs if a parfor or spmd block errors due to an undefined function. At that point any files, functions, or scripts needed by the parfor or spmd block are attached if possible.

Examples

Automatically Attach Files via Cluster Profile

Employ a cluster profile to automatically attach code files to a job. Set the AutoAttachFiles property for a job in the cluster’s profile. If this property value is true, then all jobs you create on that cluster with this profile will have the necessary code files automatically attached. This example assumes that the cluster profile myAutoCluster has that setting.

Create batch job, applying your cluster.

obj = batch(myScript,'profile','myAutoCluster');

Verify attached files by viewing list.
listAutoAttachedFiles(obj)

Automatically Attach Files Programmatically

Programmatically set a job to automatically attach code files, and then view a list of those files for one of the tasks in the job.

```matlab
c = parcluster(); % Use default profile
j = createJob(c);
j.AutoAttachFiles = true;
obj = createTask(j,myFun,OutNum,ArgCell);
listAutoAttachedFiles(obj) % View attached list
```

The files returned in the output listing are those that analysis has determined to be required for the workers to evaluate the function `myFun`, and which automatically attach to the job.

Input Arguments

- **obj** — Job, task, or pool to which files automatically attach
  - **job object** | **task object** | **parallel pool object**

  Job, task, or pool to which code files are automatically attached, specified as a `parallel.Job`, `parallel.Task`, or `parallel.Pool` object. The `AutoAttachFiles` property of the job object must be `true`; if the input is a task object, then this applies to its parent job object.

  Example: `obj = createJob(cluster);`

  Example: `obj = gcp`

See Also

- `batch`
- `createCommunicatingJob`
- `createJob`
- `createTask`
- `parcluster`
- `parpool`

Topics

- “Create and Modify Cluster Profiles” on page 6-24
Introduced in R2013a
load

Load workspace variables from batch job

Syntax

load(job)
load(job,'X')
load(job,'X','Y','Z*')
load(job,'-regexp','PAT1','PAT2')
S = load(job ...)

Arguments

job          Job from which to load workspace variables.
'X', 'Y', 'Z*' Variables to load from the job. Wildcards allow pattern matching
                in MAT-file style.
'-regexp'     Indication to use regular expression pattern matching.
S            Struct containing the variables after loading.

Description

load(job) retrieves all variables from a batch job and assigns them into the current
workspace. load throws an error if the batch runs a function (instead of a script), the job
is not finished, or the job encountered an error while running.

load(job,'X') loads only the variable named X from the job.

load(job,'X','Y','Z*') loads only the specified variables. The wildcard '*' loads
variables that match a pattern (MAT-file only).

load(job,'-regexp','PAT1','PAT2') can be used to load all variables matching the
specified patterns using regular expressions. For more information on using regular
expressions, type doc regexp at the command prompt.
S = load(job ...) returns the contents of job into variable S, which is a struct containing fields matching the variables retrieved.

Examples

Run a batch job and load its results into your client workspace.

j = batch('myScript');
wait(j)
load(j)

Load only variables whose names start with 'a'.

load(job,'a*')

Load only variables whose names contain any digits.

load(job,'-regexp','\d')

See Also

batch | fetchOutputs

Introduced in R2008a
logout

Log out of MJS cluster

Syntax

logout(c)

Description

logout(c) logs you out of the MJS cluster specified by cluster object c. Any subsequent call to a privileged action requires you to re-authenticate with a valid password. Logging out might be useful when you are finished working on a shared machine.

See Also

changePassword

Introduced in R2012a
mapreducer

Define parallel execution environment for mapreduce and tall arrays

Syntax

mapreducer
mapreducer(0)
mapreducer(poolobj)
mapreducer(hadoopCluster)
mapreducer(mr)
mr = mapreducer(__)
mr = mapreducer(__,'ObjectVisibility','Off')

Description

mapreducer defines the execution environment for mapreduce or tall arrays. Use the mapreducer function to change the execution environment to use a different cluster or to switch between serial and parallel development.

The default execution environment uses either the local MATLAB session, or a parallel pool if you have Parallel Computing Toolbox. If you have Parallel Computing Toolbox installed, when you use the tall or mapreduce functions, MATLAB automatically starts a parallel pool of workers, unless you have changed the default preferences. By default, a parallel pool uses local workers, typically one worker for each core in your machine. If you turn off the Automatically create a parallel pool option, then you must explicitly start a pool if you want to use parallel resources. See “Specify Your Parallel Preferences” on page 6-12.

When working with tall arrays, use mapreducer to set the execution environment prior to creating the tall array. Tall arrays are bound to the current global execution environment when they are constructed. If you subsequently change the global execution environment, then the tall array is invalid, and you must recreate it.
mapreducer with no input arguments creates a new mapreducer execution environment with all the defaults and sets this to be the current mapreduce or tall array execution environment. You can use gcmr to get the current mapreducer configuration.

- If you have default preferences (**Automatically create a parallel pool** is enabled), and you have not opened a parallel pool, then mapreducer opens a pool using the default cluster profile, sets gcmr to a mapreducer based on this pool and returns this mapreducer.
- If you have opened a parallel pool, then mapreducer sets gcmr to a mapreducer based on the current pool and returns this mapreducer.
- If you have disabled **Automatically create a parallel pool**, and you have not opened a parallel pool, then mapreducer sets gcmr to a mapreducer based on the local MATLAB session, and mapreducer returns this mapreducer.

mapreducer(0) specifies that mapreduce or tall array calculations run in the MATLAB client session without using any parallel resources.

mapreducer(poolobj) specifies a parallel pool for parallel execution of mapreduce or tall arrays. poolobj is a parallel.Pool object. The default pool is the current pool that is returned or opened by gcp.

mapreducer(hadoopCluster) specifies a Hadoop cluster for parallel execution of mapreduce or tall arrays. hadoopCluster is a parallel.cluster.Hadoop object.

mapreducer(mr) sets the global execution environment for mapreduce or tall arrays, using a previously created MapReducer object, mr, if its ObjectVisibility property is 'On'.

See: mapreducer in the MATLAB documentation, or mapreducer in the MATLAB Compiler documentation.
mr = mapreducer(__) returns a MapReducer object to specify the execution environment. You can define several MapReducer objects, which enables you to swap execution environments by passing one as an input argument to mapreduce or mapreducer.

mr = mapreducer(__,'ObjectVisibility','Off') hides the visibility of the MapReducer object, mr, using any of the previous syntaxes. Use this syntax to create new MapReducer objects without affecting the global execution environment of mapreduce.

Examples

Develop in Serial and Then Use Local Workers or Cluster

If you want to develop in serial and not use local workers or your specified cluster, enter:

mapreducer(0);

If you use mapreducer to change the execution environment after creating a tall array, then the tall array is invalid and you must recreate it. To use local workers or your specified cluster again, enter:

mapreducer(gcp);

mapreducer with Automatically Create a Parallel Pool Switched Off

If you have turned off the Automatically create a parallel pool option, then you must explicitly start a pool if you want to use parallel resources. See “Specify Your Parallel Preferences” on page 6-12 for details.

The following code shows how you can use mapreducer without input arguments to set the execution environment to your local MATLAB session and then specify a local parallel pool:

>> mapreducer
>> parpool('local',1);

Starting parallel pool (parpool) using the 'local' profile ... connected to 1 workers.

>> gather(min(tall(rand(1000,1))))
Evaluating tall expression using the Local MATLAB Session:
Evaluation completed in 0 sec
ans =
5.2238e-04

**Input Arguments**

- **poolobj** — Pool for parallel execution
  - `gcp` (default) | `parallel.Pool` object
  
  Pool for parallel execution, specified as a `parallel.Pool` object.
  
  Example: `poolobj = gcp`

- **hadoopCluster** — Hadoop cluster for parallel execution
  - `parallel.cluster.Hadoop` object

  Hadoop cluster for parallel execution, specified as a `parallel.cluster.Hadoop` object.
  
  Example: `hadoopCluster = parallel.cluster.Hadoop`

**Output Arguments**

- **mr** — Execution environment for `mapreduce` and tall arrays
  - `MapReducer` object

  Execution environment for `mapreduce` and tall arrays, returned as a `MapReducer` object.

  If the `ObjectVisibility` property of `mr` is set to 'On', then `mr` defines the default execution environment for all `mapreduce` algorithms and tall array calculations. If the `ObjectVisibility` property is 'Off', you can pass `mr` as an input argument to `mapreduce` to explicitly specify the execution environment for that particular call.

  You can define several `MapReducer` objects, which enables you to swap execution environments by passing one as an input argument to `mapreduce` or `mapreducer`. 
Tips

One of the benefits of developing your algorithms with tall arrays is that you only need to write the code once. You can develop your code locally, then use mapreduce to scale up and take advantage of the capabilities offered by Parallel Computing Toolbox, MATLAB Distributed Computing Server, or MATLAB Compiler, without needing to rewrite your algorithm.

See Also

gcmr | gcp | mapreduce | parallel.cluster.Hadoop | tall

Topics

“Big Data Workflow Using Tall Arrays and Datastores” on page 6-67
“Use Tall Arrays on a Parallel Pool” on page 6-70
“Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
“Run mapreduce on a Parallel Pool” on page 6-78
“Run mapreduce on a Hadoop Cluster” on page 6-82
“Specify Your Parallel Preferences” on page 6-12

Introduced in R2014b
methods

List functions of object class

Syntax

methods(obj)
out = methods(obj)

Arguments

obj    An object or an array of objects.
out    Cell array of vectors.

Description

methods(obj) returns the names of all methods for the class of which obj is an instance.

out = methods(obj) returns the names of the methods as a cell array of vectors.

Examples

Create cluster, job, and task objects, and examine what methods are available for each.

c = parcluster();
methods(c)

j1 = createJob(c);
methods(j1)

t1 = createTask(j1,@rand,1,{3});
methods(t1)
See Also

help

Introduced before R2006a
mexcuda

Compile MEX-function for GPU computation

Syntax

mexcuda filenames
mexcuda
mexcuda option1 ... optionN filenames

Description

mexcuda filenames compiles and links source files into a shared library called a MEX-file, executable from within MATLAB. mexcuda is an extension of the MATLAB mex function. It compiles MEX-files written using the CUDA C++ framework with NVIDIA’s nvcc compiler, allowing the files to define and launch GPU kernels. Only a subset of Visual Studio compilers is supported for mexcuda. For details, consult the NVIDIA toolkit documentation. In addition, the mexcuda function exposes the GPU MEX API to allow the MEX-file to read and write gpuArrays.

mexcuda option1 ... optionN filenames builds with the specified build options. The option1 ... optionN arguments supplement or override the default mexcuda build configuration.

Examples

Compile Simple MEX-Function

Compile a simple MEX-function to create the function myMexFunction from a CUDA C++ source file.

mexcuda myMexFunction.cu
An example source file is available at `matlabroot/toolbox/distcomp/gpu/extern/src/mex/mexGPUExample.cu`.

**Display Detailed Build and Troubleshooting Information**

Use verbose mode to display the compile and link commands and other information useful for troubleshooting.

```bash
mexcuda -v myMexFunction.cu
```

**Compile and Link Multiple Source Files**

Compile and link multiple source files with one command.

```bash
mexcuda myMexFunction.cu otherSource1.cpp otherSource2.cpp
```

**Compile and Link in Two Stages**

First compile, then link to create a function.

```bash
mexcuda -c myMexFunction.cu
mexcuda myMexFunction.obj
```

The first line compiles to `myMexFunction.obj` (Windows) or `myMexFunction.o` (UNIX), and the second links to create the function `myMexFunction`.

**Compile with Dynamic Parallelism**

Compile code that uses dynamic parallelism, defining kernels that launch other kernels.

```bash
mexcuda -dynamic myMexFunction.cu
```
**Link to Third-Party Library**

Compile a MEX-function that makes use of the CUDA image primitives library, npp, which is installed at `C:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v7.5\lib\x64\nppi.lib`.

```
mexcuda '-LC:\Program Files\NVIDIA GPU Computing Toolkit\CUDA\v7.5\lib\x64' -lnppi myMexFunction.cu
```

- Accessing Advanced CUDA Features Using MEX

**Input Arguments**

`filenames` — One or more file names  
character vector

One or more file names, including name and file extension, specified as a character vector. If the file is not in the current folder, specify the full path to the file. File names can be any combination of:

- C or C++ language source files
- object files
- library files

The first source code file listed in `filenames` is the name of the binary MEX-file. To override this naming convention, use the `-output` option.

Data Types: `char`

`option1 ... optionN` — One or more build options  
character vectors corresponding to valid option flags

One or more build options, specified as one of these values. Options can appear in any order on any platform, except where indicated.

In addition to most options available for the `mex` function, these options are supported:

<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>-dynamic</code></td>
<td>Dynamic parallelism: compiles MEX-files that define kernels that launch other kernels.</td>
</tr>
<tr>
<td>Option</td>
<td>Description</td>
</tr>
<tr>
<td>---------------</td>
<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>-G</td>
<td>Generate debug information for device code. This makes it possible to step through kernel code line by line in one of NVIDIA’s debugging applications (NSight or cuda-gdb). To enable debugging of host code use -g.</td>
</tr>
</tbody>
</table>

All other `mex` function options are supported, except for the following:

<table>
<thead>
<tr>
<th>Option</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>-compatibleArrayDims</td>
<td>Use of <code>-largeArrayDims</code> is implicit, and cannot be overridden.</td>
</tr>
</tbody>
</table>

**See Also**

`mex`

**Topics**

- Accessing Advanced CUDA Features Using MEX
- “Run MEX-Functions Containing CUDA Code” on page 9-33

**Introduced in R2015b**
mpiLibConf

Location of MPI implementation

Syntax

[primaryLib,extras] = mpiLibConf

Arguments

primaryLib

MPI implementation library used by a communicating job.

extras

Cell array of other required library names.

Description

[primaryLib,extras] = mpiLibConf returns the MPI implementation library to be used by a communicating job. primaryLib is the name of the shared library file containing the MPI entry points. extras is a cell array of other library names required by the MPI library.

To supply an alternative MPI implementation, create a file named mpiLibConf.m, and place it on the MATLAB path. The recommended location is matlabroot/toolbox/distcomp/user. Your mpiLibConf.m file must be higher on the cluster workers' path than matlabroot/toolbox/distcomp/mpi. (Sending mpiLibConf.m as a file dependency for this purpose does not work.) After your mpiLibConf.m file is in place, update the toolbox path caching with the following command in MATLAB:

rehash toolboxcache

Examples

Use the mpiLibConf function to view the current MPI implementation library:

mpiLibConf
**Tips**

Under all circumstances, the MPI library must support all MPI-1 functions. Additionally, the MPI library must support null arguments to `MPI_Init` as defined in section 4.2 of the MPI-2 standard. The library must also use an `mpi.h` header file that is fully compatible with MPICH2.

When used with the MATLAB job scheduler or the local cluster, the MPI library must support the following additional MPI-2 functions:

- `MPI_Open_port`
- `MPI_Comm_accept`
- `MPI_Comm_connect`

When used with any third-party scheduler, it is important to launch the workers using the version of `mpiexec` corresponding to the MPI library being used. Also, you might need to launch the corresponding process management daemons on the cluster before invoking `mpiexec`.

**See Also**

`rehash`

**Topics**

“Use Different MPI Builds on UNIX Systems” (MATLAB Distributed Computing Server)

“Toolbox Path Caching in MATLAB” (MATLAB)

**Introduced before R2006a**
**mpiprofile**

Profile parallel communication and execution times

**Syntax**

```
mpiprofile
mpiprofile on <options>
mpiprofile off
mpiprofile resume
mpiprofile clear
mpiprofile status
mpiprofile reset
mpiprofile info
mpiprofile viewer
mpiprofile('viewer',<profinfoarray>)
```

**Description**

`mpiprofile` enables or disables the parallel profiler data collection on a MATLAB worker running a communicating job. `mpiprofile` aggregates statistics on execution time and communication times. The statistics are collected in a manner similar to running the `profile` command on each MATLAB worker. By default, the parallel profiling extensions include array fields that collect information on communication with each of the other workers. This command in general should be executed in pmode or as part of a task in a communicating job.

`mpiprofile on <options>` starts the parallel profiler and clears previously recorded profile statistics.

`mpiprofile` takes the following options.
<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>-detail mmex</td>
<td>This option specifies the set of functions for which profiling statistics are gathered. -detail mmex (the default) records information about functions, local functions, and MEX-functions. -detail builtin additionally records information about built-in functions such as eig or labReceive.</td>
</tr>
<tr>
<td>-detail builtin</td>
<td></td>
</tr>
<tr>
<td>-messagedetail default</td>
<td>This option specifies the detail at which communication information is stored. -messagedetail default collects information on a per-lab instance.</td>
</tr>
<tr>
<td>-messagedetail simplified</td>
<td>-messagedetail simplified turns off collection for *PerLab data fields, which reduces the profiling overhead. If you have a very large cluster, you might want to use this option; however, you will not get all the detailed inter-lab communication plots in the viewer.</td>
</tr>
<tr>
<td></td>
<td>For information about the structure of returned data, see mpiprofile info below.</td>
</tr>
<tr>
<td>-history</td>
<td>mpiprofile supports these options in the same way as the standard profile.</td>
</tr>
<tr>
<td>-nohistory</td>
<td>No other profile options are supported by mpiprofile. These three options have no effect on the data displayed by mpiprofile viewer.</td>
</tr>
<tr>
<td>-historysize &lt;size&gt;</td>
<td></td>
</tr>
</tbody>
</table>

`mpiprofile off` stops the parallel profiler. To reset the state of the profiler and disable collecting communication information, you should also call `mpiprofile reset`.

`mpiprofile resume` restarts the profiler without clearing previously recorded function statistics. This works only in pmode or in the same MATLAB worker session.

`mpiprofile clear` clears the profile information.
mpiprofile status returns a valid status when it runs on the worker.

mpiprofile reset turns off the parallel profiler and resets the data collection back to the standard profiler. If you do not call reset, subsequent profile commands will collect MPI information.

mpiprofile info returns a profiling data structure with additional fields to the one provided by the standard profile info in the FunctionTable entry. All these fields are recorded on a per-function and per-line basis, except for the *PerLab fields.

<table>
<thead>
<tr>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BytesSent</td>
<td>Records the quantity of data sent</td>
</tr>
<tr>
<td>BytesReceived</td>
<td>Records the quantity of data received</td>
</tr>
<tr>
<td>TimeWasted</td>
<td>Records communication waiting time</td>
</tr>
<tr>
<td>CommTime</td>
<td>Records the communication time</td>
</tr>
<tr>
<td>CommTimePerLab</td>
<td>Vector of communication receive time for each lab</td>
</tr>
<tr>
<td>TimeWastedPerLab</td>
<td>Vector of communication waiting time for each lab</td>
</tr>
<tr>
<td>BytesReceivedPerLab</td>
<td>Vector of data received from each lab</td>
</tr>
</tbody>
</table>

The three *PerLab fields are collected only on a per-function basis, and can be turned off by typing the following command in pmode:

mpiprofile on -messagedetail simplified

mpiprofile viewer is used in pmode after running user code with mpiprofile on. Calling the viewer stops the profiler and opens the graphical profile browser with parallel options. The output is an HTML report displayed in the profiler window. The file listing at the bottom of the function profile page shows several columns to the left of each line of code. In the summary page:

- Column 1 indicates the number of calls to that line.
- Column 2 indicates total time spent on the line in seconds.
- Columns 3–6 contain the communication information specific to the parallel profiler

mpiprofile('viewer',<profinfoarray>) in function form can be used from the client. A structure <profinfoarray> needs be passed in as the second argument, which is an array of mpiprofile info structures. See pInfoVector in the Examples section below.
mpiprofile does not accept -timer clock options, because the communication timer clock must be real.

For more information and examples on using the parallel profiler, see “Profiling Parallel Code” on page 6-51.

Examples

In pmode, turn on the parallel profiler, run your function in parallel, and call the viewer:

```matlab
mpiprofile on;
% call your function;
mpiprofile viewer;
```

If you want to obtain the profiler information from a communicating job outside of pmode (i.e., in the MATLAB client), you need to return output arguments of `mpiprofile info` by using the functional form of the command. Define your function `foo()`, and make it the task function in a communicating job:

```matlab
function [pInfo,yourResults] = foo
mpiprofile on
initData = (rand(100, codistributor()) ...
* rand(100,codistributor()));
pInfo = mpiprofile('info');
yourResults = gather(initData,1)
```

After the job runs and `foo()` is evaluated on your cluster, get the data on the client:

```matlab
A = fetchOutputs(yourJob);
```

Then view parallel profile information:

```matlab
pInfoVector = [A(:,1)];
mpiprofile('viewer',pInfoVector);
```

See Also

`mpiSettings` | `pmode` | `profile`

Introduced in R2007b
mpiSettings

Configure options for MPI communication

Syntax

mpiSettings('DeadlockDetection','on')
mpiSettings('MessageLogging','on')
mpiSettings('MessageLoggingDestination','CommandWindow')
mpiSettings('MessageLoggingDestination','stdout')
mpiSettings('MessageLoggingDestination','File','filename')

Description

mpiSettings('DeadlockDetection','on') turns on deadlock detection during calls to labSend and labReceive. If deadlock is detected, a call to labReceive might cause an error. Although it is not necessary to enable deadlock detection on all workers, this is the most useful option. The default value is 'off' for communicating jobs, and 'on' inside pmode sessions or spmd statements. Once the setting has been changed within a pmode session or an spmd statement, the setting stays in effect until either the pmode session ends or the parallel pool is closed.

mpiSettings('MessageLogging','on') turns on MPI message logging. The default is 'off'. The default destination is the MATLAB Command Window.

mpiSettings('MessageLoggingDestination','CommandWindow') sends MPI logging information to the MATLAB Command Window. If the task within a communicating job is set to capture Command Window output, the MPI logging information will be present in the task's CommandWindowOutput property.

mpiSettings('MessageLoggingDestination','stdout') sends MPI logging information to the standard output for the MATLAB process. If you are using a MATLAB job scheduler (MJS), this is the mdce service log file.

mpiSettings('MessageLoggingDestination','File','filename') sends MPI logging information to the specified file.
Examples

Set deadlock detection for a communicating job inside the `jobStartup.m` file for that job:

```matlab
% Inside jobStartup.m for the communicating job
mpiSettings('DeadlockDetection','on');
myLogFname = sprintf('%s_%d.log',tempname,labindex);
mpiSettings('MessageLoggingDestination','File',myLogFname);
mpiSettings('MessageLogging','on');
```

Turn off deadlock detection for all subsequent `spmd` statements that use the same parallel pool:

```matlab
spmd;mpiSettings('DeadlockDetection','off');end
```

Tips

Setting the `MessageLoggingDestination` does not automatically enable message logging. A separate call is required to enable message logging.

`mpiSettings` has to be called on the worker, not the client. That is, it should be called within the task function, within `jobStartup.m`, or within `taskStartup.m`.

Introduced before R2006a
mxGPUCopyFromMxArray (C)

Copy mxArray to mxGPUArray

C Syntax

```c
#include "gpu/mxGPUArray.h"
mxGPUArray* mxGPUCopyFromMxArray(mxArray const * const mp)
```

Arguments

mp

Pointer to an mxArray that contains either GPU or CPU data.

Returns

Pointer to an mxGPUArray.

Description

mxGPUCopyFromMxArray produces a new mxGPUArray object with the same characteristics as the input mxArray.

- If the input mxArray contains a gpuArray, the output is a new copy of the data on the GPU.
- If the input mxArray contains numeric or logical CPU data, the output is copied to the GPU.

Either way, this function always allocates memory on the GPU and allocates a new mxGPUArray object on the CPU. Use mxGPUDestroyGPUArray to delete the result when you are done with it.
See Also
mxGPUCopyGPUArray | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUCopyGPUArray (C)

Duplicate (deep copy) mxGPUArray object

C Syntax

#include "gpu/mxGPUArray.h"
mxGPUArray* mxGPUCopyGPUArray(mxGPUArray const * const mgp)

Arguments

mgp

   Pointer to an mxGPUArray.

Returns

Pointer to an mxGPUArray.

Description

mxGPUCopyGPUArray produces a new array on the GPU and copies the data, and then returns a new mxGPUArray that refers to the copy. Use mxGPUDestroyGPUArray to delete the result when you are done with it.

See Also

mxGPUCopyFromMxArray | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUCopyImag (C)

Copy imaginary part of mxGPUArray

C Syntax

```c
#include "gpu/mxGPUArray.h"
mxGPUArray* mxGPUCopyImag(mxGPUArray const * const mgp)
```

Arguments

mgp

Pointer to an mxGPUArray. The target gpuArray must be full, not sparse.

Returns

Pointer to an mxGPUArray.

Description

mxGPUCopyImag copies the imaginary part of GPU data, and returns a new mxGPUArray object that refers to the copy. The returned array is real, with element values equal to the imaginary values of the input, similar to how the MATLAB `imag` function behaves. If the input is real rather than complex, the function returns an array of zeros.

Use `mxGPUDestroyGPUArray` to delete the result when you are done with it.

See Also

mxGPUCopyReal | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUCopyReal (C)

Copy real part of mxGPUArray

C Syntax

```c
#include "gpu/mxGPUArray.h"
mxGPUArray* mxGPUCopyReal(mxGPUArray const * const mgp)
```

Arguments

`mgp`

Pointer to an `mxGPUArray`. The target gpuArray must be full, not sparse.

Returns

Pointer to an `mxGPUArray`.

Description

`mxGPUCopyReal` copies the real part of GPU data, and returns a new `mxGPUArray` object that refers to the copy. If the input is real rather than complex, the function returns a copy of the input.

Use `mxGPUDestroyGPUArray` to delete the result when you are done with it.

See Also

`mxGPUCopyImag` | `mxGPUDestroyGPUArray`

Introduced in R2013a
mxGPUCreateComplexGPUArray (C)

Create complex GPU array from two real gpuArrays

C Syntax

```c
#include "gpu/mxGPUArray.h"
mxGPUArray* mxGPUCreateComplexGPUArray(mxGPUArray const * const mgpR,
                                      mxGPUArray const * const mgpI)
```

Arguments

`mgpR` `mgpI`
Pointers to `mxGPUArray` data containing real and imaginary coefficients. The target gpuArrays must be full, not sparse.

Returns

Pointer to an `mxGPUArray`.

Description

`mxGPUCreateComplexGPUArray` creates a new complex `mxGPUArray` from two real `mxGPUArray` objects. The function allocates memory on the GPU and copies the data. The inputs must both be real, and have matching sizes and classes. Use `mxGPUDestroyGPUArray` to delete the result when you are done with it.

See Also

`mxGPUDestroyGPUArray`

Introduced in R2013a
mxGPUCreateFromMxArray (C)

Create read-only mxGPUArray object from input mxArray

C Syntax

```c
#include "gpu/mxGPUArray.h"
mxGPUArray const * mxGPUCreateFromMxArray(mxArray const * const mp)
```

Arguments

mp

Pointer to an mxArray that contains either GPU or CPU data.

Returns

Pointer to a read-only mxGPUArray object.

Description

mxGPUCreateFromMxArray produces a read-only mxGPUArray object from an mxArray.

- If the input mxArray contains a gpuArray, this function extracts a reference to the GPU data from an mxArray passed as an input to the function.
- If the input mxArray contains CPU data, the data is copied to the GPU, but the returned object is still read-only.

If you need a writable copy of the array, use mxGPUCopyFromMxArray instead.

This function allocates a new mxGPUArray object on the CPU. Use mxGPUDestroyGPUArray to delete the result when you are done with it.
See Also
mxGPUCopyFromMxArray | mxGPUCreateGPUArray | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUCreateGPUArray (C)

Create mxGPUArray object, allocating memory on GPU

C Syntax

#include "gpu/mxGPUArray.h"
mxGPUArray* mxGPUCreateGPUArray(mwSize const ndims,
        mwSize const * const dims,
        mxClassID const cid,
        mxComplexity const ccx,
        mxGPUInitialize const init0)

Arguments

ndims
        mwSize type specifying the number of dimensions in the created mxGPUArray.
dims
        Pointer to an mwSize vector specifying the sizes of each dimension in the created
        mxGPUArray.
cid
        mxClassID type specifying the element class of the created mxGPUArray.
ccx
        mxComplexity type specifying the complexity of the created mxGPUArray.
init0
        mxGPUInitialize type specifying whether to initialize elements values to 0 in the
        created mxGPUArray.

        • A value of MX_GPU_INITIALIZATE_VALUES specifies that elements are to be
          initialized to 0.
        • A value of MX_GPU_DO_NOT_INITIALIZATE specifies that elements are not to be
          initialized.
Returns

Pointer to an mxGPUArray.

Description

mxGPUCreateGPUArray creates a new mxGPUArray object with the specified size, type, and complexity. It also allocates the required memory on the GPU, and initializes the memory if requested.

This function allocates a new mxGPUArray object on the CPU. Use mxGPUDestroyGPUArray to delete the object when you are done with it.

See Also

mxGPUCreateFromMxArray | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUCreateMxArrayOnCPU (C)

Create mxArray for returning CPU data to MATLAB with data from GPU

C Syntax

```
#include "gpu/mxGPUArray.h"
mxArray* mxGPUCreateMxArrayOnCPU(mxGPUArray const * const mgp)
```

Arguments

mgp

Pointer to an mxGPUArray.

Returns

Pointer to an mxArray object containing CPU data that is a copy of the GPU data.

Description

mxGPUCreateMxArrayOnCPU copies the GPU data from the specified mxGPUArray into an mxArray on the CPU for return to MATLAB. This is similar to the gather function. After calling this function, the input mxGPUArray object is no longer needed and you can delete it with mxGPUDestroyGPUArray.

See Also

mxGPUCreateMxArrayOnGPU | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUCreateMxArrayOnGPU (C)

Create mxArray for returning GPU data to MATLAB

C Syntax

#include "gpu/mxGPUArray.h"
mxArray* mxGPUCreateMxArrayOnGPU(mxGPUArray const * const mgp)

Arguments

mgp

Pointer to an mxGPUArray.

Returns

Pointer to an mxArray object containing GPU data.

Description

mxGPUCreateMxArrayOnGPU puts the mxGPUArray into an mxArray for return to MATLAB. The data remains on the GPU and the returned class in MATLAB is gpuArray. After this call, the mxGPUArray object is no longer needed and can be destroyed.

See Also

mxGPUCreateMxArrayOnCPU | mxGPUDestroyGPUArray

Introduced in R2013a
mxGPUDestroyGPUArray (C)

Delete mxGPUArray object

C Syntax

#include "gpu/mxGPUArray.h"
mxGPUDestroyGPUArray(mxGPUArray const * const mgp)

Arguments

mgp

   Pointer to an mxGPUArray.

Description

mxGPUDestroyGPUArray deletes an mxGPUArray object on the CPU. Use this function to delete an mxGPUArray object you created with:

• mxGPUCreateGPUArray
• mxGPUCreateFromMxArray
• mxGPUCopyFromMxArray
• mxGPUCopyReal
• mxGPUCopyImag, or
• mxGPUCreateComplexGPUArray.

This function clears memory on the GPU, unless some other mxArray holds a reference to the same data. For example, if the mxGPUArray was extracted from an input mxArray, or wrapped in an mxArray for an output, then the data remains on the GPU.
See Also
mxGPUCopyFromMxArray | mxGPUCopyImag | mxGPUCopyReal |
mxGPUCreateComplexGPUArray | mxGPUCreateFromMxArray |
mxGPUCreateGPUArray

Introduced in R2013a
mxGPUGetClassID (C)

mxClassID associated with data on GPU

C Syntax

```
#include "gpu/mxGPUArray.h"
mxClassID mxGPUGetClassID(mxGPUArray const * const mgp)
```

Arguments

- `mgp`
  
  Pointer to an `mxGPUArray`.

Returns

- `mxClassID` type.

Description

`mxGPUGetClassID` returns an `mxClassID` type indicating the underlying class of the input data.

See Also

- `mxGPUGetComplexity`

Introduced in R2013a
mxGPUGetComplexity (C)

Complexity of data on GPU

C Syntax

```c
#include "gpu/mxGPUArray.h"
mxComplexity mxGPUGetComplexity(mxGPUArray const * const mgp)
```

Arguments

mgp

Pointer to an mxGPUArray.

Returns

mxComplexity type.

Description

mxGPUGetComplexity returns an mxComplexity type indicating the complexity of the GPU data.

See Also

mxGPUGetClassID

Introduced in R2013a
mxGPUGetData (C)

Raw pointer to underlying data

C Syntax

```c
#include "gpu/mxGPUArray.h"
void* mxGPUGetData(mxGPUArray const * const mgp)
```

Arguments

*mgp*

Pointer to an `mxGPUArray` on the GPU. The target gpuArray must be full, not sparse.

Returns

Pointer to data.

Description

`mxGPUGetData` returns a raw pointer to the underlying data. Cast this pointer to the type of data that you want to use on the device. It is your responsibility to check that the data inside the array has the appropriate type, for which you can use `mxGPUGetClassID`.

See Also

`mxGPUGetClassID` | `mxGPUGetDataReadOnly`

Introduced in R2013a
mxGPUGetDataReadOnly (C)

Read-only raw pointer to underlying data

C Syntax

```c
#include "gpu/mxGPUArray.h"
void const* mxGPUGetDataReadOnly(mxGPUArray const * const mgp)
```

Arguments

mgp

Pointer to an mxGPUArray on the GPU. The target gpuArray must be full, not sparse.

Returns

Read-only pointer to data.

Description

mxGPUGetDataReadOnly returns a read-only raw pointer to the underlying data. Cast it to the type of data that you want to use on the device. It is your responsibility to check that the data inside the array has the appropriate type, for which you can use mxGPUGetClassID.

See Also

mxGPUGetClassID | mxGPUGetData

Introduced in R2013a
mxGPUGetDimensions (C)

mxGPUArray dimensions

C Syntax

#include "gpu/mxGPUArray.h"
mwSize const * mxGPUGetDimensions(mxGPUArray const * const mgp)

Arguments

mgp

Pointer to an mxGPUArray.

Returns

Pointer to a read-only array of mwSize type.

Description

mxGPUGetDimensions returns a pointer to an array of mwSize indicating the dimensions of the input argument. Use mxFree to delete the output.

See Also

mxGPUGetComplexity | mxGPUGetNumberOfDimensions

Introduced in R2013a
mxGPUGetNumberOfDimensions (C)

Size of dimension array for mxGPUArray

C Syntax

```
#include "gpu/mxGPUArray.h"
mwSize mxGPUGetNumberOfDimensions(mxGPUArray const * const mgp)
```

Arguments

mgp

Pointer to an mxGPUArray.

Returns

mwSize type.

Description

mxGPUGetNumberOfDimensions returns the size of the dimension array for the mxGPUArray input argument, indicating the number of its dimensions.

See Also

mxGPUGetComplexity | mxGPUGetDimensions

Introduced in R2013a
mxGPUGetNumberOfElements (C)

Number of elements on GPU for array

C Syntax

```
#include "gpu/mxGPUArray.h"
mwSize mxGPUGetNumberOfElements(mxGPUArray const * const mgp)
```

Arguments

mgp

Pointer to an mxGPUArray.

Returns

mwSize type.

Description

mxGPUGetNumberOfElements returns the total number of elements on the GPU for this array.

See Also

mxGPUGetComplexity | mxGPUGetDimensions | mxGPUGetNumberOfDimensions

Introduced in R2013a
mxGPUIsSame (C)

Determine if two mxGPUArrays refer to same GPU data

C Syntax

```c
#include "gpu/mxGPUArray.h"
int mxGPUIsSame(mxGPUArray const * const mgp1,
                mxGPUArray const * const mgp2)
```

Arguments

- `mgp1` - Pointer to `mxGPUArray`.
- `mgp2` - Pointer to `mxGPUArray`.

Returns

- `int` type.

Description

`mxGPUIsSame` returns an integer indicating if two `mxGPUArray` pointers refer to the same GPU data:

- 1 (true) indicates that the inputs refer to the same data.
- 0 (false) indicates that the inputs do not refer to the same data.

See Also

- `mxGPUIsValidGPUData`

Introduced in R2013a
mxGPUIsSparse (C)

Determine if mxGPUArray contains sparse GPU data

C Syntax

```c
#include "gpu/mxGPUArray.h"
int mxGPUIsSparse(mxGPUArray const * mp);
```

Arguments

mp

Pointer to an mxGPUArray to be queried for sparse data.

Returns

Integer indicating true result:

- 1 indicates the input is a sparse gpuArray.
- 0 indicates the input is not a sparse gpuArray.

See Also

mxGPUIsValidGPUData | mxIsGPUArray

Introduced in R2015a
mxGPUIsValidGPUData (C)

Determine if mxArray is pointer to valid GPU data

C Syntax

#include "gpu/mxGPUArray.h"
int mxGPUIsValidGPUData(mxArray const * const mp)

Arguments

mp
  Pointer to an mxArray.

Returns

int type.

Description

mxGPUIsValidGPUData indicates if the mxArray is a pointer to valid GPU data

If the GPU device is reinitialized in MATLAB with gpuDevice, all data on the device
becomes invalid, but the CPU data structures that refer to the GPU data still exist. This
function checks whether the mxArray is a container of valid GPU data, and returns one
of the following values:

- 0 (false) for CPU data or for invalid GPU data.
- 1 (true) for valid GPU data.

See Also

mxIsGPUArray
Introduced in R2013a
**mxInitGPU (C)**

Initialize MATLAB GPU library on currently selected device

**C Syntax**

```c
#include "gpu/mxGPUArray.h"
int mxInitGPU()
```

**Returns**

`int` type with one of the following values:

- `MX_GPU_SUCCESS` if the MATLAB GPU library is successfully initialized.
- `MX_GPU_FAILURE` if not successfully initialized.

**Description**

Before using any CUDA code in your MEX file, initialize the MATLAB GPU library if you intend to use any `mxGPUArray` functionality in MEX or any GPU calls in MATLAB. There are many ways to initialize the MATLAB GPU API, including:

- Call `mxInitGPU` at the beginning of your MEX file before any CUDA code.
- Call `gpuDevice(deviceIndex)` in MATLAB before running any MEX code.
- Create a `gpuArray` in MATLAB before running any MEX code.

You should call `mxInitGPU` at the beginning of your MEX file, unless you have an alternate way of guaranteeing that the MATLAB GPU library is initialized at the start of your MEX file.

If the library is initialized, this function returns without doing any work. If the library is not initialized, the function initializes the default device. Note: At present, a MATLAB MEX file can work with only one GPU device at a time.
See Also

gpuArray | gpuDevice

Introduced in R2013a
**mxIsGPUArray (C)**

Determine if mxArray contains GPU data

**C Syntax**

```c
#include "gpu/mxGPUArray.h"
int mxIsGPUArray(mxArray const * const mp);
```

**Arguments**

*mp*

Pointer to an mxArray that might contain gpuArray data.

**Returns**

Integer indicating true result:

- 1 indicates the input is a gpuArray.
- 0 indicates the input is not a gpuArray.

**See Also**

mxGPUIsSparse | mxGPUIsValidGPUData

**Introduced in R2013a**
**NaN**

Array of Not-a-Numbers

**Syntax**

\[ A = \text{NaN}(sz, \text{arraytype}) \]
\[ A = \text{NaN}(sz, \text{datatype}, \text{arraytype}) \]

\[ A = \text{NaN}(sz, \text{'like'}, P) \]
\[ A = \text{NaN}(sz, \text{datatype}, \text{'like'}, P) \]

\[ C = \text{NaN}(sz, \text{codist}) \]
\[ C = \text{NaN}(sz, \text{datatype}, \text{codist}) \]
\[ C = \text{NaN}(sz, \text{___}, \text{codist}, \text{'noCommunication'}) \]
\[ C = \text{NaN}(sz, \text{___}, \text{codist}, \text{'like'}, P) \]

**Description**

\[ A = \text{NaN}(sz, \text{arraytype}) \] creates a matrix with underlying class of double, with NaN values in all elements.

\[ A = \text{NaN}(sz, \text{datatype}, \text{arraytype}) \] creates a matrix with underlying class of datatype, with NaN values in all elements.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>sz</td>
<td>n</td>
<td>Specifies size as an n-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m, n or [m n]</td>
<td>Specifies size as an m-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m, n, ..., k or [m n ... k]</td>
<td>Specifies size as an m-by-n-by-...-by-k array.</td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td>Argument</td>
<td>Values</td>
<td>Descriptions</td>
</tr>
<tr>
<td>-----------</td>
<td>-------------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td></td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
<tr>
<td>datatype</td>
<td>'double' (default),</td>
<td>Specifies underlying class of the array, i.e., the data type of its elements.</td>
</tr>
<tr>
<td></td>
<td>'single'</td>
<td></td>
</tr>
</tbody>
</table>

A = NaN(sz,'like',P) creates an array of NaN values with the same type and underlying class (data type) as array P.

A = NaN(sz,datatype,'like',P) creates an array of NaN values with the specified underlying class (datatype), and the same type as array P.

C = NaN(sz,codist) or C = NaN(sz,datatype,codist) creates a codistributed array of NaN values with the specified size and underlying class (the default datatype is 'double'). The codistributor object codist specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = NaN(8,codistributor1d());
end
```

C = NaN(sz,___,codist,'noCommunication') specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = NaN(sz,___,codist,'like',P) creates a codistributed array of NaN values with the specified size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array P.
Examples

Create Distributed NaN Matrix

Create a 1000-by-1000 distributed matrix of NaNs with underlying class double:

\[
D = \text{NaN}(1000,'\text{distributed}');
\]

Create Codistributed NaN Matrix

Create a 1000-by-1000 codistributed double matrix of NaNs, distributed by its second dimension (columns).

\[
\text{spmd}(4) \\
\quad C = \text{NaN}(1000,'\text{codistributed}'); \\
\text{end}
\]

With four workers, each worker contains a 1000-by-250 local piece of \( C \).

Create a 1000-by-1000 codistributed single matrix of NaNs, distributed by its columns.

\[
\text{spmd}(4) \\
\quad \text{codist} = \text{codistributor}(\text{1d'},2,100*[1:\text{numlabs}]); \\
\quad C = \text{NaN}(1000,1000,'\text{single}',\text{codist}); \\
\text{end}
\]

Each worker contains a 100-by-\text{labindex} local piece of \( C \).

Create gpuArray NaN Matrix

Create a 1000-by-1000 gpuArray of NaNs with underlying class double:

\[
G = \text{NaN}(1000,'\text{double}','\text{gpuArray}');
\]

See Also
Inf | NaN | eye | false | ones | true | zeros

Introduced in R2006b
numlabs

Total number of workers operating in parallel on current job

Syntax

\[ n = \text{numlabs} \]

Description

\( n = \text{numlabs} \) returns the total number of workers currently operating on the current job. This value is the maximum value that can be used with \texttt{labSend} and \texttt{labReceive}.

Tips

In an \texttt{spmd} block, \texttt{numlabs} on each worker returns the parallel pool size.

However, inside a \texttt{parfor}-loop, \texttt{numlabs} always returns a value of 1.

See Also

\texttt{labSendReceive} | \texttt{labindex}

Introduced before R2006a
ones

Array of ones

Syntax

N = ones(sz,arraytype)
N = ones(sz,datatype,arraytype)

N = ones(sz,'like',P)
N = ones(sz,datatype,'like',P)

C = ones(sz,codist)
C = ones(sz,datatype,codist)
C = ones(sz,___,codist,'noCommunication')
C = ones(sz,___,codist,'like',P)

Description

N = ones(sz,arraytype) creates a matrix with underlying class of double, with ones in all elements.

N = ones(sz,datatype,arraytype) creates a matrix with underlying class of datatype, with ones in all elements.

The size and type of array are specified by the argument options according to the following table.

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<td>m,n,...,k or [m n ... k]</td>
<td>Specifies size as an m-by-n-by-....-by-k array.</td>
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<td>Specifies codistributed array, using the default distribution scheme.</td>
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<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
<tr>
<td><em>datatype</em></td>
<td>'double' (default), 'single', 'int8', 'uint8', 'int16', 'uint16', 'int32', 'uint32', 'int64', or 'uint64'</td>
<td>Specifies underlying class of the array, i.e., the data type of its elements.</td>
</tr>
</tbody>
</table>

N = ones(sz, 'like', P) creates an array of ones with the same type and underlying class (data type) as array P.

N = ones(sz, *datatype*, 'like', P) creates an array of ones with the specified underlying class (*datatype*), and the same type as array P.

C = ones(sz, codist) or C = ones(sz, *datatype*, codist) creates a codistributed array of ones with the specified size and underlying class (the default *datatype* is 'double'). The codistributor object codist specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```plaintext
spmd
    C = ones(8, codistributor1d());
end
```

C = ones(sz, ___, codist, 'noCommunication') specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = ones(sz, ___, codist, 'like', P) creates a codistributed array of ones with the specified size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array P.
Examples

Create Distributed Ones Matrix

Create a 1000-by-1000 distributed array of ones with underlying class double:

\[
D = \text{ones}(1000,'\text{distributed}')
\]

Create Codistributed Ones Matrix

Create a 1000-by-1000 codistributed double matrix of ones, distributed by its second dimension (columns).

\[
\text{spmd}(4)
\]
\[
C = \text{ones}(1000,'\text{codistributed}')
\]
\[
\text{end}
\]

With four workers, each worker contains a 1000-by-250 local piece of \(C\).

Create a 1000-by-1000 codistributed uint16 matrix of ones, distributed by its columns.

\[
\text{spmd}(4)
\]
\[
\text{codist} = \text{codistributor}(\text{1d},2,100*[1:\text{numlabs}]);
\]
\[
C = \text{ones}(1000,1000,'\text{uint16}',\text{codist})
\]
\[
\text{end}
\]

Each worker contains a 100-by-labindex local piece of \(C\).

Create gpuArray Ones Matrix

Create a 1000-by-1000 gpuArray of ones with underlying class uint32:

\[
G = \text{ones}(1000,'\text{uint32}',\text{gpuArray}')
\]

See Also
Inf | NaN | eye | false | ones | true | zeros

Introduced in R2006b
**pagefun**

Apply function to each page of array on GPU

**Syntax**

\[
A = \text{pagefun}(\text{FUN}, B)
\]

\[
A = \text{pagefun}(\text{FUN}, B, C, \ldots)
\]

\[
[A, B, \ldots] = \text{pagefun}(\text{FUN}, C, \ldots)
\]

**Description**

`pagefun` iterates over the pages of a `gpuArray`, applying the same function to each page.

\[
A = \text{pagefun}(\text{FUN}, B)
\]

applies the function specified by `FUN` to each page of the `gpuArray` `B`, and returns the results in `gpuArray` `A`, such that:

\[
A(:,:,I,J,\ldots) = \text{FUN}(B(:,:,I,J,\ldots)).
\]

`FUN` is a handle to a function that takes a two-dimensional input argument.

You can use `gather` to retrieve the array from the GPU back to the MATLAB workspace.

\[
A = \text{pagefun}(\text{FUN}, B, C, \ldots)
\]

evaluates `FUN` using pages of the arrays `B`, `C`, etc., as input arguments with scalar expansion enabled. Any of the input page dimensions that are scalar are virtually replicated to match the size of the other arrays in that dimension so that:

\[
A(:,:,I,J,\ldots) = \text{FUN}(B(:,:,I,J,\ldots), C(:,:,I,J,\ldots), \ldots).
\]

At least one of the inputs `B`, `C`, etc. must be a `gpuArray`. Any other inputs held in CPU memory are converted to a `gpuArray` before calling the function on the GPU. If an array is to be used in several different `pagefun` calls, it is more efficient to convert that array to a `gpuArray` before your series of `pagefun` calls. The input pages `B(:,:,I, J, \ldots)`, `C(:,:,I, J, \ldots)`, etc., must satisfy all of the input and output requirements of `FUN`.

\[
[A, B, \ldots] = \text{pagefun}(\text{FUN}, C, \ldots)
\]

where `FUN` is a handle to a function that returns multiple outputs, returns `gpuArrays` `A`, `B`, etc., each corresponding to one of the output arguments of `FUN`. `pagefun` invokes `FUN` with as many outputs as there are in the call to `pagefun`. All elements of `A` must be the same class; `B` can be a different class from `A`, but all elements of `B` must be of the same class; etc.
**FUN** must return values of the same class each time it is called. The order in which **pagefun** computes pages is not specified and should not be relied on.

**FUN** must be a handle to a function that is written in the MATLAB language (i.e., not a built-in function or a MEX-function).

Currently the supported values for **FUN** are:

- Most element-wise gpuArray functions, listed in “Run Built-In Functions on a GPU” on page 9-8, and the following:
  - @ctranspose
  - @fliplr
  - @flipud
  - @inv
  - @mldivide
  - @mrdivide
  - @mtimes
  - @rot90
  - @transpose

**Examples**

```matlab
M = 3;         % output number of rows
K = 6;         % matrix multiply inner dimension
N = 2;         % output number of columns
P1 = 10;       % size of first page dimension
P2 = 17;       % size of second page dimension
P3 = 4;        % size of third page dimension
P4 = 12;       % size of fourth page dimension
A = rand(M,K,P1,1,P3,'gpuArray');
B = rand(K,N,1,P2,P3,P4,'gpuArray');
C = pagefun(@mtimes,A,B);
s = size(C)    % M-by-N-by-P1-by-P2-by-P3-by-P4
s =
    3     2    10    17     4    12

M = 300;       % output number of rows
K = 500;       % matrix multiply inner dimension
```
N = 1000;  % output number of columns
P = 200;   % number of pages
A = rand(M,K,'gpuArray');
B = rand(K,N,P,'gpuArray');
C = pagefun(@mtimes,A,B);
s = size(C)    % returns M-by-N-by-P

s =
   300  1000  200

See Also
arrayfun | bsxfun | gather | gpuArray

Introduced in R2013b
parallel.cluster.Hadoop

Create Hadoop cluster object

Syntax

hadoopCluster = parallel.cluster.Hadoop
hadoopCluster = parallel.cluster.Hadoop(Name,Value)

Description


You use the resulting object as input to the mapreduce and mapreducer functions, for specifying the Hadoop cluster as the parallel execution environment for tall arrays and mapreduce.

hadoopCluster = parallel.cluster.Hadoop(Name,Value) uses the specified names and values to set properties on the created parallel.cluster.Hadoop object.

Examples

Set Hadoop Cluster as Execution Environment for mapreduce and mapreducer

This example shows how to create and use a parallel.cluster.Hadoop object to set a Hadoop cluster as the mapreduce parallel execution environment.

hadoopCluster = parallel.cluster.Hadoop('HadoopInstallFolder','/host/hadoop-install');
mr = mapreducer(hadoopCluster);
Set Hadoop Cluster as Execution Environment for tall arrays

This example shows how to create and use a `parallel.cluster.Hadoop` object to set a Hadoop cluster as the tall array parallel execution environment.

```matlab
hadoopCluster = parallel.cluster.Hadoop(...
    'HadoopInstallFolder', '/host/hadoop-install', ...
    'SparkInstallFolder', '/host/spark-install');
mr = mapreducer(hadoopCluster);
```

- “Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
- “Run mapreduce on a Hadoop Cluster” on page 6-82
- “Read and Analyze Hadoop Sequence File” (MATLAB)

Input Arguments

Name-Value Pair Arguments

Specify optional comma-separated pairs of `Name,Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside single quotes ('). You can specify several name and value pair arguments in any order as `Name1,Value1,...,NameN,ValueN`.

Example: `'HadoopInstallFolder', '/share/hadoop/a1.2.1'`

**ClusterMatlabRoot** — Path to MATLAB for workers
character vector

Path to MATLAB for workers, specified as the comma-separated pair consisting of `'ClusterMatlabRoot'` and a character vector. This points to the installation of MATLAB Distributed Computing Server for the workers, whether local to each machine or on a network share.

**HadoopConfigurationFile** — Path to Hadoop application configuration file
character vector

Path to Hadoop application configuration file, specified as the comma-separated pair consisting of `'HadoopConfigurationFile'` and a character vector.
HadoopInstallFolder — Path to Hadoop installation on worker machines

class: character vector

Path to Hadoop installation on worker machines, specified as the comma-separated pair consisting of 'HadoopInstallFolder' and a character vector. If this property is not set, the default is the value specified by the environment variable HADOOP_PREFIX, or if that is not set, then HADOOP_HOME.

SparkInstallFolder — Path to Spark enabled Hadoop installation on worker machines

class: character vector

Path to Spark enabled Hadoop installation on worker machines, specified as the comma-separated pair consisting of 'SparkInstallFolder' and a character vector. If this property is not set, the default is the value specified by the environment variable SPARK_PREFIX, or if that is not set, then SPARK_HOME.

Output Arguments

hadoopCluster — Hadoop cluster

class: parallel.cluster.Hadoop object

Hadoop cluster, returned as a parallel.cluster.Hadoop object.

See Also

mapreduce | mapreducer

Topics

“Use Tall Arrays on a Spark Enabled Hadoop Cluster” on page 6-74
“Run mapreduce on a Hadoop Cluster” on page 6-82
“Read and Analyze Hadoop Sequence File” (MATLAB)

Introduced in R2014b
**parallel.clusterProfiles**

Names of all available cluster profiles

**Syntax**

```
ALLPROFILES = parallel.clusterProfiles
[ALLPROFILES, DEFAULTPROFILE] = parallel.clusterProfiles
```

**Description**

`ALLPROFILES = parallel.clusterProfiles` returns a cell array containing the names of all available profiles.

`[ALLPROFILES, DEFAULTPROFILE] = parallel.clusterProfiles` returns a cell array containing the names of all available profiles, and separately the name of the default profile.

The cell array `ALLPROFILES` always contains a profile called `local` for the local cluster, and always contains the default profile. If the default profile has been deleted, or if it has never been set, `parallel.clusterProfiles` returns `local` as the default profile.

You can create and change profiles using the `saveProfile` or `saveAsProfile` methods on a cluster object. Also, you can create, delete, and change profiles through the Cluster Profile Manager.

**Examples**

Display the names of all the available profiles and set the first in the list to be the default profile.

```
allNames = parallel.clusterProfiles()
parallel.defaultClusterProfile(allNames{1});
```

Display the names of all the available profiles and get the cluster identified by the last profile name in the list.
allNames = parallel.clusterProfiles()
lastCluster = parcluster(allNames(end));

See Also
parallel.defaultClusterProfile | parallel.exportProfile | parallel.importProfile

Introduced in R2012a
parallel.defaultClusterProfile

Examine or set default cluster profile

Syntax

\[
p = \text{parallel.defaultClusterProfile} \\
\text{oldprofile} = \text{parallel.defaultClusterProfile}(\text{newprofile})
\]

Description

\[ p = \text{parallel.defaultClusterProfile} \] returns the name of the default cluster profile.

\[ \text{oldprofile} = \text{parallel.defaultClusterProfile}(\text{newprofile}) \] sets the default profile to be \text{newprofile} and returns the previous default profile. It might be useful to keep the old profile so that you can reset the default later.

If the default profile has been deleted, or if it has never been set, \text{parallel.defaultClusterProfile} returns 'local' as the default profile.

You can save modified profiles with the \text{saveProfile} or \text{saveAsProfile} method on a cluster object. You can create, delete, import, and modify profiles with the Cluster Profile Manager, accessible from the MATLAB desktop \text{Home} tab \text{Environment} area by selecting \text{Parallel > Manage Cluster Profiles}.

Examples

Display the names of all available profiles and set the first in the list to be the default.

\[
\text{allProfiles} = \text{parallel.clusterProfiles} \\
\text{parallel.defaultClusterProfile}(\text{allProfiles}(1));
\]

First set the profile named 'MyProfile' to be the default, and then set the profile named 'Profile2' to be the default.
parallel.defaultClusterProfile('MyProfile');
oldDefault = parallel.defaultClusterProfile('Profile2');
str cmp(oldDefault,'MyProfile') % returns true

See Also
parallel.clusterProfiles | parallel.importProfile

Introduced in R2012a
parallel.exportProfile

Export one or more profiles to file

Syntax

parallel.exportProfile(profileName, filename)
parallel.exportProfile({'profileName1,profileName2,...,profileNameN'}, filename)

Description

parallel.exportProfile(profileName, filename) exports the profile with the name profileName to specified filename. The extension .settings is appended to the filename, unless already there.

parallel.exportProfile({'profileName1,profileName2,...,profileNameN'}, filename) exports the profiles with the specified names to filename.

To import a profile, use parallel.importProfile or the Cluster Profile Manager.

Examples

Export the profile named MyProfile to the file MyExportedProfile.settings.

parallel.exportProfile('MyProfile','MyExportedProfile')

Export the default profile to the file MyDefaultProfile.settings.

def_profile = parallel.defaultClusterProfile();
parallel.exportProfile(def_profile,'MyDefaultProfile')

Export all profiles except for local to the file AllProfiles.settings.

allProfiles = parallel.clusterProfiles();
% Remove 'local' from allProfiles
notLocal = ~strcmp(allProfiles,'local');
profilesToExport = allProfiles(notLocal);
if ~isempty(profilesToExport)
    parallel.exportProfile(profilesToExport,'AllProfiles');
end

See Also
parallel.clusterProfiles | parallel.importProfile

Introduced in R2012a
parallel.gpu.CUDAKernel

Create GPU CUDA kernel object from PTX and CU code

Syntax

KERN = parallel.gpu.CUDAKernel(PTXFILE, CPROTO)
KERN = parallel.gpu.CUDAKernel(PTXFILE, CPROTO, FUNC)
KERN = parallel.gpu.CUDAKernel(PTXFILE, CUFILE)
KERN = parallel.gpu.CUDAKernel(PTXFILE, CUFILE, FUNC)

Description

KERN = parallel.gpu.CUDAKernel(PTXFILE, CPROTO) and KERN = parallel.gpu.CUDAKernel(PTXFILE, CPROTO, FUNC) create a CUDAKernel object that you can use to call a CUDA kernel on the GPU. PTXFILE is the name of the file that contains the PTX code, or the contents of a PTX file as a character vector; and CPROTO is the C prototype for the kernel call that KERN represents. If specified, FUNC must be a character vector that unambiguously defines the appropriate kernel entry name in the PTX file. If FUNC is omitted, the PTX file must contain only a single entry point.

KERN = parallel.gpu.CUDAKernel(PTXFILE, CUFILE) and KERN = parallel.gpu.CUDAKernel(PTXFILE, CUFILE, FUNC) create a kernel object that you can use to call a CUDA kernel on the GPU. In addition, they read the CUDA source file CUFILE, and look for a kernel definition starting with '__global__' to find the function prototype for the CUDA kernel that is defined in PTXFILE.

For information on executing your kernel object, see “Run a CUDAKernel” on page 9-28.

Examples

If simpleEx.cu contains the following:

/*
 * Add a constant to a vector.
__global__ void addToVector(float * pi, float c, int vecLen) {
    int idx = blockIdx.x * blockDim.x + threadIdx.x;
    if (idx < vecLen) {
        pi[idx] += c;
    }
}

and simpleEx.ptx contains the PTX resulting from compiling simpleEx.cu into PTX, both of the following statements return a kernel object that you can use to call the addToVector CUDA kernel.

kern = parallel.gpu.CUDAKernel('simpleEx.ptx', ...
                                   'simpleEx.cu');
kern = parallel.gpu.CUDAKernel('simpleEx.ptx', ...
                                   'float *,float,int');

See Also
arrayfun | existsOnGPU | feval | gpuArray | reset

Introduced in R2010b
parallel.importProfile

Import cluster profiles from file

Syntax

prof = parallel.importProfile(filename)

Description

prof = parallel.importProfile(filename) imports the profiles stored in the specified file and returns the names of the imported profiles. If filename has no extension, .settings is assumed; configuration files must be specified with the .mat extension. Configuration .mat files contain only one profile, but profile .settings files can contain one or more profiles. If only one profile is defined in the file, then prof is a character vector reflecting the name of the profile; if multiple profiles are defined in the file, then prof is a cell array of character vectors. If a profile with the same name as an imported profile already exists, an extension is added to the name of the imported profile.

You can use the imported profile with any functions that support profiles. parallel.importProfile does not set any of the imported profiles as the default; you can set the default profile by using the parallel.defaultClusterProfile function.

Profiles that were exported in a previous release are upgraded during import. Configurations are automatically converted to cluster profiles.

Imported profiles are saved as a part of your MATLAB settings, so these profiles are available in subsequent MATLAB sessions without importing again.

Examples

Import a profile from file ProfileMaster.settings and set it as the default cluster profile.
profile_master = parallel.importProfile('ProfileMaster');
parallel.defaultClusterProfile(profile_master)

Import all the profiles from the file ManyProfiles.settings, and use the first one to open a parallel pool.

profs = parallel.importProfile('ManyProfiles');
parpool(profs{1})

Import a configuration from the file OldConfiguration.mat, and set it as the default parallel profile.

old_conf = parallel.importProfile('OldConfiguration.mat')
parallel.defaultClusterProfile(old_conf)

See Also
parallel.clusterProfiles | parallel.defaultClusterProfile | parallel.exportProfile

Introduced in R2012a
parallel.pool.Constant

Build parallel.pool.Constant from data or function handle

Syntax

C = parallel.pool.Constant(X)
C = parallel.pool.Constant(FH)
C = parallel.pool.Constant(FH,CLEANUP)
C = parallel.pool.Constant(COMP)

Description

C = parallel.pool.Constant(X) copies the value X to each worker and returns a parallel.pool.Constant object, C, which allows each worker to access the value X within a parallel language construct (parfor, spmd, parfeval) using the property C.Value. This can improve performance when you have multiple parfor-loops accessing the same constant set of data, because X is transferred only once to the workers.

C = parallel.pool.Constant(FH) evaluates function handle FH on each worker and stores the result in C.Value. This is also useful for creating and using any handle-type resources on the workers, such as file handles and database connections.

C = parallel.pool.Constant(FH,CLEANUP) evaluates function handle FH on each worker and stores the result in C.Value. When C is cleared, the function handle CLEANUP is evaluated with a single argument C.Value on each worker.

C = parallel.pool.Constant(COMP) uses the values stored in the Composite COMP, and stores them in C.Value on each worker. This is especially useful when the data that you need to use inside a parfor-loop can be constructed only on the workers, such as when the data is too large to conveniently fit in the client, or when it is being loaded from a file that only the workers can access. If COMP does not have a defined value on every worker, an error results.
**Tips**

*parallel.pool.Constant* must be called in the MATLAB client session.

*parallel.pool.Constant* automatically starts a parallel pool, if possible. If no pool is running, and one cannot be started automatically, *parallel.pool.Constant* generates an error.

**Examples**

**Make parallel.pool.Constant from array in client**

This example shows how to create a numeric *parallel.pool.Constant*, and use it in multiple *parfor*-loops on the same pool.

First, create some large data on the client, then build a *parallel.pool.Constant*, transferring the data to the pool only once.

```matlab
data = rand(1000);
c = parallel.pool.Constant(data);
for ii = 1:10
    % Run multiple PARFOR loops accessing the data.
    parfor jj = 1:10
        x(ii,jj) = c.Value(ii,jj);
    end
end
```

**Make parallel.pool.Constant from function handle**

This example shows how to create a *parallel.pool.Constant* with a function handle and a cleanup function.

Create a temporary file on each worker. By passing @fclose as the second argument, the file is automatically closed when *c* goes out of scope.

```matlab
c = parallel.pool.Constant(@() fopen(tempname(pwd),'wt'),@fclose);
spmd
    disp(fopen(c.Value)); % Displays the temporary filenames.
end
```
parfor idx = 1:1000
    fprintf(c.Value,'Iteration: %d\n',idx);
end
clear c; % Closes the temporary files.

Make parallel.pool.Constant from Composite

This example shows how to build large data sets as a Composite on pool workers inside an spmd block, and then use that data as a parallel.pool.Constant inside a parfor-loop.

spmd
    if labindex == 1
        x = labBroadcast(1,rand(5000));
    else
        x = labBroadcast(1);
    end
end
xc = parallel.pool.Constant(x);
parfor idx = 1:10
    s(idx) = sum(xc.Value(:,idx));
end
s

s =
    1.0e+03 *
    2.5108  2.5031  2.5123  2.4909  2.4957  2.5462  2.4859  2.5320  2.5076  2.5432

See Also
parcluster | parfeval | parfor | parpool | spmd

Introduced in R2015b
parcluster

Create cluster object

Syntax

c = parcluster

c = parcluster(profile)

Description

c = parcluster returns a cluster object representing the cluster identified by the default cluster profile, with the cluster object properties set to the values defined in that profile.

c = parcluster(profile) returns a cluster object representing the cluster identified by the specified cluster profile, with the cluster object properties set to the values defined in that profile.

You can save modified profiles with the saveProfile or saveAsProfile method on a cluster object. You can create, delete, import, and modify profiles with the Cluster Profile Manager, accessible from the MATLAB desktop Home tab Environment area by selecting Parallel > Manage Cluster Profiles. For more information, see “Discover Clusters and Use Cluster Profiles” on page 6-18.

Examples

Find the cluster identified by the default parallel computing cluster profile, with the cluster object properties set to the values defined in that profile.

myCluster = parcluster;

View the name of the default profile and find the cluster identified by it. Open a parallel pool on the cluster.
defaultProfile = parallel.defaultClusterProfile
myCluster = parcluster(defaultProfile);
parpool(myCluster);

Find a particular cluster using the profile named 'MyProfile', and create an
independent job on the cluster.

myCluster = parcluster('MyProfile');
j = createJob(myCluster);

See Also
createJob | parallel.clusterProfiles | parallel.defaultClusterProfile | parpool

Introduced in R2012a
parfeval

Execute function asynchronously on parallel pool worker

Syntax

\[ F = \text{parfeval}(p,\text{fcn},\text{numout},\text{in1},\text{in2},...) \]
\[ F = \text{parfeval}(\text{fcn},\text{numout},\text{in1},\text{in2},...) \]

Description

\[ F = \text{parfeval}(p,\text{fcn},\text{numout},\text{in1},\text{in2},...) \] requests asynchronous execution of the function \( \text{fcn} \) on a worker contained in the parallel pool \( p \), expecting \( \text{numout} \) output arguments and supplying as input arguments \( \text{in1},\text{in2},... \). The asynchronous evaluation of \( \text{fcn} \) does not block MATLAB. \( F \) is a parallel.FevalFuture object, from which the results can be obtained when the worker has completed evaluating \( \text{fcn} \). The evaluation of \( \text{fcn} \) always proceeds unless you explicitly cancel execution by calling \( \text{cancel}(F) \). To request multiple function evaluations, you must call parfeval multiple times. (However, parfevalOnAll can run the same function on all workers.)

\[ F = \text{parfeval}(\text{fcn},\text{numout},\text{in1},\text{in2},...) \] requests asynchronous execution on the current parallel pool. If no pool exists, it starts a new parallel pool, unless your parallel preferences disable automatic creation of pools.

Examples

Submit a single request to the parallel pool and retrieve the outputs.

\[ p = \text{gcp}(); \quad \% \text{get the current parallel pool} \]
\[ f = \text{parfeval}(p,\text{@magic},1,10); \]
\[ \text{value} = \text{fetchOutputs}(f); \quad \% \text{Blocks until complete} \]

Submit a vector of multiple future requests in a for-loop and retrieve the individual future outputs as they become available.
p = gcp();
% To request multiple evaluations, use a loop.
for idx = 1:10
    f(idx) = parfeval(p,@magic,1,idx); % Square size determined by idx
end
% Collect the results as they become available.
magicResults = cell(1,10);
for idx = 1:10
    % fetchNext blocks until next results are available.
    [completedIdx,value] = fetchNext(f);
    magicResults{completedIdx} = value;
    fprintf('Got result with index: %d.
', completedIdx);
end

See Also
afterEach | cancel | fetchNext | fetchOutputs | isequal |
parallel.pool.Constant | parfevalOnAll | parpool | poll | send | ticBytes |
tocBytes | wait

Introduced in R2013b
parfevalOnAll

Execute function asynchronously on all workers in parallel pool

Syntax

F = parfevalOnAll(p,fcn,numout,in1,in2,...)
F = parfevalOnAll(fcn,numout,in1,in2,...)

Description

F = parfevalOnAll(p,fcn,numout,in1,in2,...) requests the asynchronous execution of the function fcn on all workers in the parallel pool p, expecting numout output arguments from each worker and supplying input arguments in1,in2,... to each worker. F is a parallel.FevalOnAllFuture object, from which you can obtain the results when all workers have completed executing fcn.

F = parfevalOnAll(fcn,numout,in1,in2,...) requests asynchronous execution on all workers in the current parallel pool. If no pool exists, it starts a new parallel pool, unless your parallel preferences disable automatic creation of pools.

**Note** Use parfevalOnAll instead of parfor or spmd if you want to use clear. This preserves workspace transparency. See “Ensure Transparency in parfor-Loops” on page 2-56.

Examples

Unload a mex file before deleting temporary folders for distributing simulations:

parfevalOnAll(@clear, 0, 'mex');

Close all Simulink models on all workers:

p = gcp(); % Get the current parallel pool
f = parfevalOnAll(p,@bdclose,0,'all');
% No output arguments, but you might want to wait for completion
wait(f);

See Also
cancel | fetchNext | fetchOutputs | parallel.pool.Constant | parfeval | parpool | wait

Introduced in R2013b
parfor

Execute for-loop iterations in parallel on workers in parallel pool

Syntax

parfor loopVar = initVal:endVal; statements; end
parfor (loopVar = initVal:endVal,M); statements; end

Description

parfor loopVar = initVal:endVal; statements; end executes for-loop iterations in parallel on workers in a parallel pool.

MATLAB executes the loop body commands in statements for values of loopVar between initVal and endVal. loopVar specifies a vector of integer values increasing by 1. If you have Parallel Computing Toolbox, the iterations of statements can execute on a parallel pool of workers on your multi-core computer or cluster. As with a for-loop, you can include a single line or multiple lines in statements.

To find out how parfor can help increase your throughput, see “Decide When to Use parfor” on page 2-2.

parfor differs from a traditional for-loop in the following ways:

- Loop iterations are executed in parallel in a nondeterministic order. This means that you might need to modify your code to use parfor. For more help, see “Convert for-Loops Into parfor-Loops” on page 2-8.
- Loop iterations must be consecutive, increasing integer values.
- The body of the parfor-loop must be independent. One loop iteration cannot depend on a previous iteration, because the iterations are executed in a nondeterministic order. For more help, see “Ensure That parfor-Loop Iterations are Independent” on page 2-12.
- You cannot use a parfor-loop inside another parfor-loop. For more help, see “Nested parfor-Loops and for-Loops” on page 2-15.
parfor (loopVar = initVal:endVal,M); statements; end uses M to specify the maximum number of workers from the parallel pool to use in evaluating statements in the loop body. M must be a nonnegative integer.

By default, MATLAB uses the available workers in your parallel pool. You can change the number of workers on the Home tab in the Environment section, select Parallel > Parallel Preferences. You can override the default number of workers in a parallel pool by using parpool. When no workers are available in the pool or M is zero, MATLAB still executes the loop body in a nondeterministic order, but not in parallel. Use this syntax to switch between parallel and serial execution when testing your code.

To execute the iterations in parallel, you must have a parallel pool of workers. By default, if you execute parfor, you automatically create a parallel pool of workers on the cluster defined by your default cluster profile. The default cluster is local. You can change your cluster in Parallel Preferences. For more details, see “Specify Your Parallel Preferences” on page 6-12.

Examples

Convert a for-Loop Into a parfor-Loop

Create a parfor-loop for a computationally intensive task and measure the resulting speedup.

In the MATLAB Editor, enter the following for-loop. To measure the time elapsed, add tic and toc.

tic
n = 200;
A = 500;
a = zeros(n);
for i = 1:n
    a(i) = max(abs(eig(rand(A))));
end
toc

Run the script, and note the elapsed time.

Elapsed time is 31.935373 seconds.
In the script, replace the `for`-loop with a `parfor`-loop.

```matlab
 tic
 n = 200;
 A = 500;
 a = zeros(n);
 parfor i = 1:n
     a(i) = max(abs(eig(rand(A))));
 end
 toc
```

Run the new script, and run it again. The first run is slower than the second run, because the parallel pool has to be started, and you have to make the code available to the workers. Note the elapsed time for the second run.

By default, MATLAB automatically opens a parallel pool of workers on your local machine.

Elapsed time is 10.760068 seconds.

Observe that you speed up your calculation by converting the `for`-loop into a `parfor`-loop on four workers. You might reduce the elapsed time further by increasing the number of workers in your parallel pool. For more information, see “Convert for-Loops Into parfor-Loops” on page 2-8 and “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23.

**Test parfor-Loops by Switching Between Parallel and Serial Execution**

You can specify the maximum number of workers \( M \) for a `parfor`-loop. Set \( M = 0 \) to run the body of the loop in the desktop MATLAB, without using workers, even if a pool is open. When \( M = 0 \), MATLAB still executes the loop body in a nondeterministic order, but not in parallel, so that you can check whether your `parfor`-loops are independent and suitable to run on workers. This is the simplest way to allow you to debug the contents of a `parfor`-loop. You cannot set breakpoints directly in the body of the `parfor`-loop, but you can set breakpoints in functions called from the body of the `parfor`-loop.

Specify \( M = 0 \) to run the body of a `parfor`-loop in the desktop MATLAB, even if a pool is open.

```matlab
 M = 0;          % M specifies maximum number of workers
 y = ones(1,100);
```
parfor (i = 1:100,M)
    y(i) = i;
end

To control the number of workers in your parallel pool, see “Specify Your Parallel Preferences” on page 6-12 and parpool.

**Measure Data Transferred to Workers Using a parfor-Loop**

To measure how much data is transferred to and from the workers in your current parallel pool, add ticBytes(gcp) and tocBytes(gcp) before and after the parfor-loop. Use gcp as an argument to get the current parallel pool.

Delete your current parallel pool if you still have one.

delete(gcp('nocreate'))

tic
ticBytes(gcp);
n = 200;
A = 500;
a = zeros(n);
parfor i = 1:n
    a(i) = max(abs(eig(rand(A))));
end
tocBytes(gcp)
toc

Run the new script, and run it again. The first run is slower than the second run, because the parallel pool has to be started, and you have to make the code available to the workers.

By default, MATLAB automatically opens a parallel pool of workers on your local machine.

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers. ...

| 1 | 15340 | 7024 |
| 2 | 13328 | 5712 |
You can use the ticBytes and tocBytes results to examine the amount of data transferred to and from the workers in a parallel pool. In this example, the data transfer is small. For more information about parfor-loops, see “Decide When to Use parfor” on page 2-2 and “Convert for-Loops Into parfor-Loops” on page 2-8.

- “Decide When to Use parfor” on page 2-2
- “Convert for-Loops Into parfor-Loops” on page 2-8
- “Ensure That parfor-Loop Iterations are Independent” on page 2-12
- “Nested parfor-Loops and for-Loops” on page 2-15
- “Troubleshoot Variables in parfor-Loops” on page 2-32
- “Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
- “Specify Your Parallel Preferences” on page 6-12
- “Run Parallel Simulations” (Simulink)

### Input Arguments

#### loopVar — Loop index

integer

Loop index variable with initial value initVal and final value endVal. The variable can be any numeric type and the value must be an integer.

Make sure that your parfor-loop variables are consecutive increasing integers. For more help, see “Troubleshoot Variables in parfor-Loops” on page 2-32.

Data Types: single | double | int8 | int16 | int32 | int64 | uint8 | uint16 | uint32 | uint64

#### initVal — Initial value of loop index

integer

Initial value loop index variable, loopVar. The variable can be any numeric type and the value must be an integer. With endVal, specifies the parfor range vector, which must be of the form M:N.
endVal — Final value of loop index
integer
Final value loop index variable, loopVar. The variable can be any numeric type and the value must be an integer. With initVal, specifies the parfor range vector, which must be of the form M:N.

Data Types: single | double | int8 | int16 | int32 | int64 | uint8 | uint16 | uint32 | uint64

statements — Loop body
text
Loop body, specified as text. The series of MATLAB commands to execute in the parfor loop.

You might need to modify your code to use parfor-loops. For more help, see “Convert for-Loops Into parfor-Loops” on page 2-8

Do not nest parfor-loops, see “Nested parfor-Loops and for-Loops” on page 2-15.

M — Maximum number of workers running in parallel
number of workers in the parallel pool (default) | nonnegative integer
Maximum number of workers running in parallel, specified as a nonnegative integer. If you specify an upper limit, MATLAB uses no more than this number, even if additional workers are available. If you request more workers than the number of available workers, then MATLAB uses the maximum number of workers available at the time of the call. If the loop iterations are fewer than the number of workers, some workers perform no work.

If parfor cannot run on multiple workers (for example, if only one core is available or M is 0), MATLAB executes the loop in a serial manner. In this case, MATLAB still executes the loop body in a nondeterministic order. Use this syntax to switch between parallel and serial when testing your code.
Tips

- Use a `parfor`-loop when:
  - You have many loop iterations of a simple calculation. `parfor` divides the loop iterations into groups so that each thread can execute one group of iterations.
  - You have some loop iterations that take a long time to execute.
  - Do not use a `parfor`-loop when an iteration in your loop depends on the results of other iterations.

Reductions are one exception to this rule. A reduction variable accumulates a value that depends on all the iterations together, but is independent of the iteration order. For more information, see “Reduction Variables” on page 2-46.

- When you use `parfor`, you have to wait for the loop to complete to obtain your results. Your client MATLAB is blocked and you cannot break out of the loop early. If you want to obtain intermediate results, or break out of a `for`-loop early, try `parfeval` instead.

- A `parfor`-loop runs on the existing parallel pool. If no pool exists, `parfor` starts a new parallel pool, unless the automatic starting of pools is disabled in your parallel preferences. If there is no parallel pool and `parfor` cannot start one, the loop runs serially in the client session.

- If the `AutoAttachFiles` property in the cluster profile for the parallel pool is set to `true`, MATLAB performs an analysis on a `parfor`-loop to determine what code files are necessary for its execution, see `listAutoAttachedFiles`. Then MATLAB automatically attaches those files to the parallel pool so that the code is available to the workers.

- You cannot call scripts directly in a `parfor`-loop. However, you can call functions that call scripts.

- Do not use `clear` inside a `parfor` loop because it violates workspace transparency. See “Ensure Transparency in `parfor`-Loops” on page 2-56.

- You can run Simulink models in parallel with the `parsim` command instead of using `parfor`-loops. For more information and examples of using Simulink in parallel, see “Run Multiple Simulations” (Simulink).
See Also
afterEach | for | gcp | listAutoAttachedFiles | parfeval | parpool | send | ticBytes | tocBytes

Topics
“Decide When to Use parfor” on page 2-2
“Convert for-Loops Into parfor-Loops” on page 2-8
“Ensure That parfor-Loop Iterations are Independent” on page 2-12
“Nested parfor-Loops and for-Loops” on page 2-15
“Troubleshoot Variables in parfor-Loops” on page 2-32
“Scale Up parfor-Loops to Cluster and Cloud” on page 2-23
“Specify Your Parallel Preferences” on page 6-12
“Run Parallel Simulations” (Simulink)

Introduced in R2008a
parpool

Create parallel pool on cluster

Syntax

parpool
parpool(poolsize)
parpool(profilename)
parpool(profilename,poolsize)
parpool(cluster)
parpool(cluster,poolsize)
parpool(___,Name,Value)
poolobj = parpool(__)

Description

parpool enables the full functionality of the parallel language features (parfor and spmd) in MATLAB by creating a special job on a pool of workers, and connecting the MATLAB client to the parallel pool. If possible, the working folder on the workers is set to match that of the MATLAB client session.

parpool starts a pool using the default cluster profile, with the pool size specified by your parallel preferences and the default profile.

parpool(poolsize) overrides the number of workers specified in the preferences or profile, and starts a pool of exactly that number of workers, even if it has to wait for them to be available. Most clusters have a maximum number of workers they can start. If the profile specifies a MATLAB job scheduler (MJS) cluster, parpool reserves its workers from among those already running and available under that MJS. If the profile specifies a local or third-party scheduler, parpool instructs the scheduler to start the workers for the pool.

parpool(profilename) or parpool(profilename,poolsize) starts a worker pool using the cluster profile identified by profilename.
parpool(cluster) or parpool(cluster,poolsize) starts a worker pool on the cluster specified by the cluster object cluster.

parpool(___,Name,Value) applies the specified values for certain properties when starting the pool.

poolobj = parpool(__) returns a parallel.Pool object to the client workspace representing the pool on the cluster. You can use the pool object to programmatically delete the pool or to access its properties.

Examples

Create Pool from Default Profile

Start a parallel pool using the default profile to define the number of workers.

parpool

Create Pool from Specified Profile

Start a parallel pool of 16 workers using a profile called myProf.

parpool('myProf',16)

Create Pool from Local Profile

Start a parallel pool of 2 workers using the local profile.

parpool('local',2)

Create Pool on Specified Cluster

Create an object representing the cluster identified by the default profile, and use that cluster object to start a parallel pool. The pool size is determined by the default profile.
c = parcluster
parpool(c)

Create Pool and Attach Files
Start a parallel pool with the default profile, and pass two code files to the workers.
parpool('AttachedFiles',{mod1.m','mod2.m'})

Return Pool Object and Delete Pool
Create a parallel pool with the default profile, and later delete the pool.
poolobj = parpool;
delete(poolobj)

Determine Size of Current Pool
Find the number of workers in the current parallel pool.
poolobj = gcp('nocreate'); % If no pool, do not create new one.
if isempty(poolobj)
    poolsize = 0;
else
    poolsize = poolobj.NumWorkers
end

Input Arguments

poolsize — Size of parallel pool
set in parallel preferences or parallel profile (default)

Size of the parallel pool, specified as a numeric value.

Data Types: single | double | int8 | int16 | int32 | int64 | uint8 | uint16 |
            uint32 | uint64
profilename — Profile that defines cluster and properties
character vector

Profile that defines cluster and properties, specified as a character vector.
Example:
Data Types: char

cluster — Cluster to start pool on
cluster object

Cluster to start pool on, specified as a cluster object
Example: c = parcluster();

Name-Value Pair Arguments

Specify optional comma-separated pairs of Name,Value arguments. Name is the argument name and Value is the corresponding value. Name must appear inside single quotes (' '). You can specify several name and value pair arguments in any order as Name1,Value1,...,NameN,ValueN.

Example: 'AttachedFiles', {'myFun.m'}

AttachedFiles — Files to attach to pool
character vector or cell array of character vectors

Files to attach to pool, specified as a character vector or cell array of character vectors.

With this argument pair, parpool starts a parallel pool and passes the identified files to the workers in the pool. The files specified here are appended to the AttachedFiles property specified in the applicable parallel profile to form the complete list of attached files. The 'AttachedFiles' property name is case sensitive, and must appear as shown.

Example: {'myFun.m','myFun2.m'}

Data Types: char | cell

AutoAddClientPath — Specifies if client path is added to worker path
Boolean
A logical value (true or false) that controls whether user-added-entries on the client's path are added to each worker's path at startup. By default 'AutoAddClientPath' is set to true.

Data Types: Boolean

EnvironmentVariables — Environment variables copied to workers
character vector or cell array of character vectors

Names of environment variables to be copied from the client session to the workers, specified as a character vector, or cell array of character vectors. The names specified here are appended to the 'EnvironmentVariables' property specified in the applicable parallel profile to form the complete list of environment variables. Any variables listed which are not set are not copied to the workers. These environment variables are set on the workers for the duration of the parallel pool.

Data Types: char | cell

SpmdEnabled — Indication if pool is enabled to support SPMD
ture (default) | false

Indication if pool is enabled to support SPMD, specified as a logical. You can disable support only on a local or MJS cluster. Because parfor iterations do not involve interworker communication, disabling SPMD support this way allows the parallel pool to keep evaluating a parfor-loop even if one or more workers aborts during loop execution.

Data Types: logical

Output Arguments

poolobj — Access to parallel pool from client
parallel.Pool object

Access to parallel pool from client, returned as a parallel.Pool object.

Tips

**Note** Remove any startup.m from your MATLAB path if you want to run any parallel code including parpool. If you have trouble starting the parallel pool, see this MATLAB
The pool status indicator in the lower-left corner of the desktop shows the client session connection to the pool and the pool status. Click the icon for a menu of supported pool actions.

With a pool running:  
With no pool running:  

If you set your parallel preferences to automatically create a parallel pool when necessary, you do not need to explicitly call the `parpool` command. You might explicitly create a pool to control when you incur the overhead time of setting it up, so the pool is ready for subsequent parallel language constructs.

`delete(poolobj)` shuts down the parallel pool. Without a parallel pool, `spmd` and `parfor` run as a single thread in the client, unless your parallel preferences are set to automatically start a parallel pool for them.

When you use the MATLAB editor to update files on the client that are attached to a parallel pool, those updates automatically propagate to the workers in the pool. (This automatic updating does not apply to Simulink model files. To propagate updated model files to the workers, use the `updateAttachedFiles` function.)

If possible, the working folder on the workers is initially set to match that of the MATLAB client session. Subsequently, the following commands entered in the client Command Window also execute on all the workers in the pool:

- `cd`
- `addpath`
- `rmpath`

This behavior allows you to set the working folder and the command search path on all the workers, so that subsequent pool activities such as `parfor`-loops execute in the proper context.

When changing folders or adding a path with `cd` or `addpath` on clients with Windows operating systems, the value sent to the workers is the UNC path for the folder if possible. For clients with Linux® operating systems, it is the absolute folder location.

If any of these commands does not work on the client, it is not executed on the workers either. For example, if `addpath` specifies a folder that the client cannot
access, the addpath command is not executed on the workers. However, if the working folder can be set on the client, but cannot be set as specified on any of the workers, you do not get an error message returned to the client Command Window.

Be careful of this slight difference in behavior in a mixed-platform environment where the client is not the same platform as the workers, where folders local to or mapped from the client are not available in the same way to the workers, or where folders are in a nonshared file system. For example, if you have a MATLAB client running on a Microsoft Windows operating system while the MATLAB workers are all running on Linux operating systems, the same argument to addpath cannot work on both. In this situation, you can use the function pctRunOnAll to assure that a command runs on all the workers.

Another difference between client and workers is that any addpath arguments that are part of the matlabroot folder are not set on the workers. The assumption is that the MATLAB install base is already included in the workers’ paths. The rules for addpath regarding workers in the pool are:

- Subfolders of the matlabroot folder are not sent to the workers.
- Any folders that appear before the first occurrence of a matlabroot folder are added to the top of the path on the workers.
- Any folders that appear after the first occurrence of a matlabroot folder are added after the matlabroot group of folders on the workers’ paths.

For example, suppose that matlabroot on the client is C:\Applications\matlab\. With an open parallel pool, execute the following to set the path on the client and all workers:

```matlab
addpath('P1',
        'P2',
        'C:\Applications\matlab\T3',
        'C:\Applications\matlab\T4',
        'P5',
        'C:\Applications\matlab\T6',
        'P7',
        'P8');
```

Because T3, T4, and T6 are subfolders of matlabroot, they are not set on the workers’ paths. So on the workers, the pertinent part of the path resulting from this command is:
See Also
Composite | delete | distributed | gcp | parallel.defaultClusterProfile | parallel.pool.Constant | parfeval | parfevalOnAll | parfor | pctRunOnAll | spmd

Topics
“Specify Your Parallel Preferences” on page 6-12
“Discover Clusters and Use Cluster Profiles” on page 6-18
“Pass Data to and from Worker Sessions” on page 7-18

Introduced in R2013b
pause

Pause MATLAB job scheduler queue

Syntax

pause(mjs)

Arguments

mjs MATLAB job scheduler object whose queue is paused.

Description

pause(mjs) pauses the MATLAB job scheduler's queue so that jobs waiting in the queued state will not run. Jobs that are already running also pause, after completion of tasks that are already running. No further jobs or tasks will run until the resume function is called for the MJS.

The pause function does nothing if the MJS is already paused.

See Also

resume | wait

Topics

“Program Independent Jobs for a Supported Scheduler” on page 7-8

Introduced before R2006a
pctconfig

Configure settings for Parallel Computing Toolbox client session

Syntax

pctconfig('p1',v1,...)
config = pctconfig('p1',v1,...)
config = pctconfig()

Arguments

p1
Property to configure. Supported properties are 'portrange', 'hostname'.

v1
Value for corresponding property.

config
Structure of configuration value.

Description

pctconfig('p1',v1,...) sets the client configuration property p1 with the value v1.

Note that the property value pairs can be in any format supported by the set function, i.e., param-value character vector pairs, structures, and param-value cell array pairs. If a structure is used, the structure field names are the property names and the field values specify the property values.

If the property is 'portrange', the specified value is used to set the range of ports to be used by the client session of Parallel Computing Toolbox software. This is useful in environments with a limited choice of ports. The value of 'portrange' should either be a 2-element vector [minport, maxport] specifying the range, or 0 to specify that the client session should use ephemeral ports. By default, the client session searches for available ports to communicate with the other sessions of MATLAB Distributed Computing Server software.

If the property is 'hostname', the specified value is used to set the hostname for the client session of Parallel Computing Toolbox software. This is useful when the client
computer is known by more than one hostname. The value you should use is the hostname by which the cluster nodes can contact the client computer. The toolbox supports both short hostnames and fully qualified domain names.

config = pctconfig('p1',v1,...) returns a structure to config. The field names of the structure reflect the property names, while the field values are set to the property values.

config = pctconfig(), without any input arguments, returns all the current values as a structure to config. If you have not set any values, these are the defaults.

**Examples**

View the current settings for hostname and ports.

config = pctconfig()

```matlab
config =
    portrange: [27370 27470]
    hostname: 'machine32'
```

Set the current client session port range to 21000–22000 with hostname fdm4.

```matlab
pctconfig('hostname','fdm4','portrange',[21000 22000]);
```

Set the client hostname to a fully qualified domain name.

```matlab
pctconfig('hostname','desktop24.subnet6.companydomain.com');
```

**Tips**

The values set by this function do not persist between MATLAB sessions. To guarantee its effect, call `pctconfig` before calling any other Parallel Computing Toolbox functions.

*Introduced in R2008a*
pctRunDeployedCleanup

Clean up after deployed parallel applications

Syntax

pctRunDeployedCleanup

Description

pctRunDeployedCleanup performs necessary cleanup so that the client JVM can properly terminate when the deployed application exits. All deployed applications that use Parallel Computing Toolbox functionality need to call pctRunDeployedCleanup after the last call to Parallel Computing Toolbox functionality.

After calling pctRunDeployedCleanup, you should not use any further Parallel Computing Toolbox functionality in the current MATLAB session.

Introduced in R2010a
pctRunOnAll

Run command on client and all workers in parallel pool

Syntax

pctRunOnAll command

Description

pctRunOnAll command runs the specified command on all the workers of the parallel pool as well as the client, and prints any command-line output back to the client Command Window. The specified command runs in the base workspace of the workers and does not have any return variables. This is useful if there are setup changes that need to be performed on all the workers and the client.

Note If you use pctRunOnAll to run a command such as addpath in a mixed-platform environment, it can generate a warning on the client while executing properly on the workers. For example, if your workers are all running on Linux operating systems and your client is running on a Microsoft Windows operating system, an addpath argument with Linux-based paths will warn on the Windows-based client.

Examples

Clear all loaded functions on all workers:

pctRunOnAll clear functions

Change the directory on all workers to the project directory:

pctRunOnAll cd /opt/projects/c1456

Add some directories to the paths of all the workers:

pctRunOnAll addpath({'/usr/share/path1' '/usr/share/path2'})
See Also
parpool

Introduced in R2008a
pload

Load file into parallel session

Syntax

pload(fileroot)

Arguments

fileroot Part of filename common to all saved files being loaded.

Description

pload(fileroot) loads the data from the files named [fileroot num2str(labindex)] into the workers running a communicating job. The files should have been created by the psave command. The number of workers should be the same as the number of files. The files should be accessible to all the workers. Any codistributed arrays are reconstructed by this function. If fileroot contains an extension, the character representation of the labindex will be inserted before the extension. Thus, pload('abc') attempts to load the file abc1.mat on worker 1, abc2.mat on worker 2, and so on.

Examples

Create three variables — one replicated, one variant, and one codistributed. Then save the data. (This example works in a communicating job or in pmode, but not in a parfor or spmd block.)

clear all;
rep = speye(numlabs);
var = magic(labindex);
D = eye(numlabs,codistributor());
psave('threeThings');
This creates three files (threeThings1.mat, threeThings2.mat, threeThings3.mat) in the current working directory.

Clear the workspace on all the workers and confirm there are no variables.

clear all
whos

Load the previously saved data into the workers. Confirm its presence.

pload('threeThings');
whos
isreplicated(rep)
iscodistributed(D)

See Also
labindex | load | numlabs | pmode | psave | save

Introduced in R2006b
pmode

Interactive Parallel Command Window

Syntax

pmode start
pmode start numworkers
pmode start prof numworkers
pmode quit
pmode exit
pmode client2lab clientvar workers workervar
pmode lab2client workervar worker clientvar
pmode cleanup prof

Description

pmode allows the interactive parallel execution of MATLAB commands. pmode achieves this by defining and submitting a communicating job, and opening a Parallel Command Window connected to the workers running the job. The workers then receive commands entered in the Parallel Command Window, process them, and send the command output back to the Parallel Command Window. Variables can be transferred between the MATLAB client and the workers. For more details about program development in pmode and its interactive features, see “Run Communicating Jobs Interactively Using pmode” on page 4-3.

pmode start starts pmode, using the default profile to define the cluster and number of workers. (The initial default profile is local; you can change it by using the function parallel.defaultClusterProfile.) You can also specify the number of workers using pmode start numworkers.

pmode start prof numworkers starts pmode using the Parallel Computing Toolbox profile prof to locate the cluster, submits a communicating job with the number of workers identified by numworkers, and connects the Parallel Command Window with the workers. If the number of workers is specified, it overrides the minimum and maximum number of workers specified in the profile.
pmode quit or pmode exit stops the pmode job, deletes it, and closes the Parallel Command Window. You can enter this command at the MATLAB prompt or the pmode prompt.

pmode client2lab clientvar workers workervar copies the variable clientvar from the MATLAB client to the variable workervar on the workers identified by workers. If workervar is omitted, the copy is named clientvar. workers can be either a single index or a vector of indices. You can enter this command at the MATLAB prompt or the pmode prompt.

pmode lab2client workervar worker clientvar copies the variable workervar from the worker identified by worker, to the variable clientvar on the MATLAB client. If clientvar is omitted, the copy is named workervar. You can enter this command at the MATLAB prompt or the pmode prompt. Note: If you use this command in an attempt to transfer a codistributed array to the client, you get a warning, and only the local portion of the array on the specified worker is transferred. To transfer an entire codistributed array, first use the gather function to assemble the whole array into the worker workspaces.

pmode cleanup prof deletes all communicating jobs created by pmode for the current user running on the cluster specified in the profile prof, including jobs that are currently running. The profile is optional; the default profile is used if none is specified. You can enter this command at the MATLAB prompt or the pmode prompt.

You can invoke pmode as either a command or a function, so the following are equivalent.

```matlab
pmode start prof 4
pmode('start','prof',4)
```

**Examples**

In the following examples, the pmode prompt (P>>) indicates commands entered in the Parallel Command Window. Other commands are entered in the MATLAB Command Window.

Start pmode using the default profile to identify the cluster and number of workers.

```matlab
pmode start
```

Start pmode using the local profile with four local workers.
pmode start local 4

Start pmode using the profile myProfile and eight workers on the cluster.

pmode start myProfile 8

Execute a command on all workers.

P>> x = 2*labindex;

Copy the variable x from worker 7 to the MATLAB client.

pmode lab2client x 7

Copy the variable y from the MATLAB client to workers 1 through 8.

pmode client2lab y 1:8

Display the current working directory of each worker.

P>> pwd

See Also
createCommunicatingJob | parallel.defaultClusterProfile | parcluster

Introduced in R2006b
**poll**

Retrieve data sent from a worker

**Syntax**

```
poll(pollablequeue)
[data, OK] = poll(pollablequeue, timeout)
```

**Description**

`poll(pollablequeue)` retrieves the result of a message or data sent from a worker to the `parallel.pool.PollableDataQueue` specified by `pollablequeue`. You can use `poll` only in the process where you created the data queue.

`[data, OK] = poll(pollablequeue, timeout)` returns `data`, and `OK` as a boolean true to indicate that data has been returned. If there is no data in the queue, then an empty array is returned with a boolean false for `OK`. Specify `timeout` in seconds as an optional second parameter. In that case, the method might block for the time specified by `timeout` before returning. If any data arrives in the queue during that period, that data is returned.

**Examples**

**Send a Message in a parfor-loop, and Poll for the Result**

Construct a `PollableDataQueue`.

```
p = parallel.pool.PollableDataQueue;
```

Start a `parfor`-loop, and send a message, such as data with the value 1.

```
parfor i = 1
    send(p, i);
end
```
Poll for the result.

```matlab
poll(p)
1
```

For more details on sending data using a `PollableDataQueue`, see `send`.

### Send and Poll for Data while Using `parfeval`

This example shows how to return intermediate results from a worker to the client and to display the result on the client.

Construct a `PollableDataQueue`. A `PollableDataQueue` is most useful for sending and polling for data during asynchronous function evaluations using `parfeval` or `parfevalOnAll`.

```matlab
q = parallel.pool.PollableDataQueue;
```

Start a timer and send the data queue as input to the function for `parfeval` execution on the pool. Display the time elapsed and the data returned.

```matlab
f = parfeval(@workerFcn, 0, q);
msgsReceived = 0;
starttime = tic;
while msgsReceived < 2
    [data, gotMsg] = poll(q, 1);
    if gotMsg
        fprintf('Got message: %s after %.3g seconds\n', ...
                data, toc(starttime));
        msgsReceived = msgsReceived + 1;
    else
        fprintf('No message available at %.3g seconds\n', ...
                toc(starttime));
    end
end
function workerFcn(q)
send(q, 'start');
pause(3);
send(q, 'stop');
end
```
The first message is returned in 0.39 s after you have executed `parfeval`. In that time the data and function for `parfeval` have been serialized, sent over to the workers, deserialized and set running. When you start the code, the worker sends some data, which is serialized, sent over the network back to the client and put on a data queue. `poll` notes this operation and returns the value to the client function. Then the time taken since `parfeval` was called is displayed. Note a delay of 3 s while the worker is computing something (in this case a long pause).

### Input Arguments

- **`pollablequeue` — Pollable data queue**
  
  `parallel.pool.PollableDataQueue`  

  Pollable data queue, specified as a `parallel.pool.PollableDataQueue` object.
  
  Example: `[data, OK] = poll(pollablequeue, optionalTimeout);`

- **`timeout` — Optional timeout**
  
  `scalar`

  Optional timeout interval (in seconds) used to block `poll` before returning, specified as a scalar.
  
  Example: `[data, OK] = poll(pollablequeue, timeout);`

### Output Arguments

- **`data` — Message or data**
  
  `scalar | vector | matrix | array | string | character vector`

  Message or data from workers to a data queue, specified as any serializable value.
  
  Example: `[data, OK] = poll(pollablequeue, timeout);`
**OK — Check if data has been returned**

Boolean

Check if data has been returned, returned as a Boolean value. If data has been returned, then OK is assigned the value of a boolean `true`. If there is no data in the queue `pollablequeue`, then an empty array is returned and a boolean `false` for OK.

Example: `[data, OK] = poll(pollablequeue, timeout);`

**See Also**

`afterEach` | `parallel.pool.DataQueue` | `parallel.pool.PollableDataQueue` | `parfeval` | `parfevalOnAll` | `parfor` | `parpool` | `send`

`Introduced in R2017a`
poolStartup

File for user-defined options to run on each worker when parallel pool starts

Syntax

poolStartup

Description

poolStartup runs automatically on a worker each time the worker forms part of a parallel pool. You do not call this function from the client session, nor explicitly as part of a task function.

You add MATLAB code to the poolStartup.m file to define pool initialization on the worker. The worker looks for poolStartup.m in the following order, executing the one it finds first:

1. Included in the job's AttachedFiles property.
2. In a folder included in the job's AdditionalPaths property.
3. In the worker's MATLAB installation at the location

\[\text{matlabroot/toolbox/distcomp/user/poolStartup.m}\]

To create a version of poolStartup.m for AttachedFiles or AdditionalPaths, copy the provided file and modify it as required.

poolStartup is the ideal location for startup code required for parallel execution on the parallel pool. For example, you might want to include code for using mpiSettings. Because jobStartup and taskStartup execute before poolStartup, they are not suited to pool-specific code. In other words, you should use taskStartup for setup code on your worker regardless of whether the task is from an independent job, communicating job, or using a parallel pool; while poolStartup is for setup code for pool usage only.
For further details on poolStartup and its implementation, see the text in the installed poolStartup.m file.

See Also
jobStartup | taskFinish | taskStartup

Introduced in R2010a
promote

Promote job in MJS cluster queue

Syntax

promote(c,job)

Arguments

c       The MJS cluster object that contains the job.
job     Job object promoted in the queue.

Description

promote(c,job) promotes the job object job, that is queued in the MJS cluster c.

If job is not the first job in the queue, promote exchanges the position of job and the previous job.

Examples

Create and submit multiple jobs to the cluster identified by the default cluster profile, assuming that the default cluster profile uses an MJS:

c = parcluster();
pause(c) % Prevent submissions from running.

j1 = createJob(c,'Name','Job A');
j2 = createJob(c,'Name','Job B');
j3 = createJob(c,'Name','Job C');
submit(j1);submit(j2);submit(j3);

Promote Job C by one position in its queue:
promote(c,j3)

Examine the new queue sequence:

[pjobs,qjobs,rjobs,fjobs] = findJob(c);
get(qjobs,'Name')

  'Job A'
  'Job C'
  'Job B'

Tips

After a call to promote or demote, there is no change in the order of job objects contained in the Jobs property of the MJS cluster object. To see the scheduled order of execution for jobs in the queue, use the findJob function in the form [pending queued running finished] = findJob(c).

See Also

createJob | demote | findJob | submit

Introduced before R2006a
**psave**

Save data from communicating job session

**Syntax**

```matlab
psave(fileroot)
```

**Arguments**

<table>
<thead>
<tr>
<th>Argument</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>fileroot</td>
<td>Part of filename common to all saved files.</td>
</tr>
</tbody>
</table>

**Description**

`psave(fileroot)` saves the data from the workers' workspace into the files named `[fileroot num2str(labindex)]`. The files can be loaded by using the `pload` command with the same `fileroot`, which should point to a folder accessible to all the workers. If `fileroot` contains an extension, the character representation of the `labindex` is inserted before the extension. Thus, `psave('abc')` creates the files `'abc1.mat', 'abc2.mat'`, etc., one for each worker.

**Examples**

Create three arrays — one replicated, one variant, and one codistributed. Then save the data. (This example works in a communicating job or in pmode, but not in a `parfor` or `spmd` block.)

```matlab
clear all;
rep = speye(numlabs);
var = magic(labindex);
D = eye(numlabs,codistributor());
psave('threeThings');
```

This creates three files (`threeThings1.mat`, `threeThings2.mat`, `threeThings3.mat`) in the current working folder.
Clear the workspace on all the workers and confirm there are no variables.

clear all
whos

Load the previously saved data into the workers. Confirm its presence.

pload('threeThings');
whos
isreplicated(rep)
iscodistributed(D)

See Also
labindex | load | numlabs | pload | pmode | save

Introduced in R2006b
rand

Array of rand values

Syntax

\[ R = \text{rand}(sz, \text{arraytype}) \]
\[ R = \text{rand}(sz, \text{datatype}, \text{arraytype}) \]
\[ R = \text{rand}(sz, 'like', P) \]
\[ R = \text{rand}(sz, \text{datatype}, 'like', P) \]
\[ C = \text{rand}(sz, \text{codist}) \]
\[ C = \text{rand}(sz, \text{datatype}, \text{codist}) \]
\[ C = \text{rand}(sz, [], \text{codist}, 'noCommunication') \]
\[ C = \text{rand}(sz, [], \text{codist}, 'like', P) \]

Description

\[ R = \text{rand}(sz, \text{arraytype}) \] creates a matrix with underlying class of double, with rand values in all elements.

\[ R = \text{rand}(sz, \text{datatype}, \text{arraytype}) \] creates a matrix with underlying class of datatype, with rand values in all elements.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>( sz )</td>
<td>( n )</td>
<td>Specifies size as an ( n )-by-( n ) matrix.</td>
</tr>
<tr>
<td></td>
<td>( m, n ) or ([m \ n])</td>
<td>Specifies size as an ( m )-by-( n ) matrix.</td>
</tr>
<tr>
<td></td>
<td>( m, n, \ldots, k ) or ([m \ n \ \ldots \ k])</td>
<td>Specifies size as an ( m )-by-( n )-by-\ldots-by-( k ) array.</td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
</tbody>
</table>
R = `rand(sz,'like',P)` creates an array of `rand` values with the same type and underlying class (data type) as array P.

R = `rand(sz,datatype,'like',P)` creates an array of `rand` values with the specified underlying class (`datatype`), and the same type as array P.

C = `rand(sz,codist)` or C = `rand(sz,datatype,codist)` creates a codistributed array of `rand` values with the specified size and underlying class (the default `datatype` is 'double'). The codistributor object `codist` specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for `codistributor1d` and `codistributor2dbc`. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = rand(8,codistributor1d());
end
```

C = `rand(sz,___,codist,'noCommunication')` specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = `rand(sz,___,codist,'like',P)` creates a codistributed array of `rand` values with the specified size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array P.
Examples

Create Distributed Rand Matrix

Create a 1000-by-1000 distributed array of randns with underlying class double:

\[ D = \text{rand}(1000,'distributed'); \]

Create Codistributed Rand Matrix

Create a 1000-by-1000 codistributed double matrix of randns, distributed by its second dimension (columns).

\[ \text{spmd}(4) \]
\[ C = \text{rand}(1000,'codistributed'); \]
\[ \text{end} \]

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed single matrix of randns, distributed by its columns.

\[ \text{spmd}(4) \]
\[ \text{codist} = \text{codistributor}('1d',2,100*[1:numlabs]); \]
\[ C = \text{rand}(1000,1000,'single',\text{codist}); \]
\[ \text{end} \]

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray Rand Matrix

Create a 1000-by-1000 gpuArray of randns with underlying class double:

\[ G = \text{rand}(1000,'double','gpuArray'); \]

See Also

codistributed.sprand | distributed.sprand | rand | randi | randn

Introduced in R2006b
randi

Array of random integers

Syntax

R = randi(valrange,sz,arraytype)
R = randi(valrange,sz,datatype,arraytype)

R = randi(valrange,sz,'like',P)
R = randi(valrange,sz,datatype,'like',P)

C = randi(valrange,sz,codist)
C = randi(valrange,sz,datatype,codist)
C = randi(valrange,sz,___,codist,'noCommunication')
C = randi(valrange,sz,___,codist,'like',P)

Description

R = randi(valrange,sz,arraytype) creates a matrix with underlying class of double, with randi integer values in all elements.

R = randi(valrange,sz,datatype,arraytype) creates a matrix with underlying class of datatype, with randi values in all elements.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>valrange</td>
<td>max or [min max]</td>
<td>Specifies integer value range from 1 to max, or from min to max..</td>
</tr>
<tr>
<td>sz</td>
<td>n</td>
<td>Specifies size as an n-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m,n or [m n]</td>
<td>Specifies size as an m-by-n matrix.</td>
</tr>
<tr>
<td>Argument</td>
<td>Values</td>
<td>Descriptions</td>
</tr>
<tr>
<td>----------</td>
<td>--------</td>
<td>--------------</td>
</tr>
<tr>
<td>m,n,...,k or [m n ... k]</td>
<td>Specifies size as an m-by-n-by-...-by-k array.</td>
<td></td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td></td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
<tr>
<td>datatype</td>
<td>'double' (default), 'single', 'int8', 'uint8', 'int16', 'uint16', 'int32', 'uint32', 'int64', or 'uint64'</td>
<td>Specifies underlying class of the array, i.e., the data type of its elements.</td>
</tr>
</tbody>
</table>

\[ R = \text{randi}(\text{valrange},sz,'like',P) \] creates an array of \text{randi} values with the same type and underlying class (data type) as array \( P \).

\[ R = \text{randi}(\text{valrange},sz,datatype,'like',P) \] creates an array of \text{randi} values with the specified underlying class (\text{datatype}), and the same type as array \( P \).

\[ C = \text{randi}(\text{valrange},sz,\text{codist}) \] or \[ C = \text{randi}(\text{valrange},sz,datatype,\text{codist}) \] creates a codistributed array of \text{randi} values with the specified size and underlying class (the default \text{datatype} is 'double'). The codistributor object \text{codist} specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```
spmd
    C = randi(8,codistributor1d());
end
```

\[ C = \text{randi}(\text{valrange},sz,\_\_,\_\_,\text{codist},'noCommunication') \] specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.
C = randi(valrange,sz,___,codist,'like',P) creates a codistributed array of randi values with the specified range, size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array P.

Examples

Create Distributed Randi Matrix

Create a 1000-by-1000 distributed array of randi values from 1 to 100, with underlying class double:

D = randi(100,1000,'distributed');

Create Codistributed Randi Matrix

Create a 1000-by-1000 codistributed double matrix of randi values from 0 to 12, distributed by its second dimension (columns).

spmd(4)
    C = randi([0 12],1000,'codistributed');
end

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed single matrix of randi values from 1 to 4, distributed by its columns.

spmd(4)
    codist = codistributor('1d',2,100*[1:numlabs]);
    C = randi(4,1000,1000,'single',codist);
end

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray Randi Matrix

Create a 1000-by-1000 gpuArray of randi values from —50 to 50, with underlying class double:
G = randi([-50 50],1000,'double','gpuArray');

See Also
rand | randi | randn

Introduced in R2014a
randn

Array of randn values

Syntax

\[
R = \text{randn}(sz, \text{arraytype}) \\
R = \text{randn}(sz, \text{datatype}, \text{arraytype})
\]

\[
R = \text{randn}(sz, 'like', P) \\
R = \text{randn}(sz, \text{datatype}, 'like', P)
\]

\[
C = \text{randn}(sz, \text{codist}) \\
C = \text{rand}(sz, \text{datatype}, \text{codist}) \\
C = \text{randn}(sz, __, \text{codist}, 'noCommunication') \\
C = \text{randn}(sz, __, \text{codist}, 'like', P)
\]

Description

\[
R = \text{randn}(sz, \text{arraytype}) \text{ creates a matrix with underlying class of double, with randn values in all elements.}
\]

\[
R = \text{randn}(sz, \text{datatype}, \text{arraytype}) \text{ creates a matrix with underlying class of datatype, with randn values in all elements.}
\]

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>(sz)</td>
<td>(n)</td>
<td>Specifies size as an (n)-by-(n) matrix.</td>
</tr>
<tr>
<td></td>
<td>(m, n) or ([m \ n])</td>
<td>Specifies size as an (m)-by-(n) matrix.</td>
</tr>
<tr>
<td></td>
<td>(m, n, \ldots, k) or ([m \ n \ \ldots \ k])</td>
<td>Specifies size as an (m)-by-(n)-by-(k) array.</td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td>Argument</td>
<td>Values</td>
<td>Descriptions</td>
</tr>
<tr>
<td>----------</td>
<td>----------------------</td>
<td>--------------------------------------------------</td>
</tr>
<tr>
<td></td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
<tr>
<td>datatype</td>
<td>'double' (default),</td>
<td>Specifies underlying class of the array, i.e., the data type of its elements.</td>
</tr>
<tr>
<td></td>
<td>'single'</td>
<td></td>
</tr>
</tbody>
</table>

\( R = \text{randn}(sz,'\text{like}',P) \) creates an array of \( \text{randn} \) values with the same type and underlying class (data type) as array \( P \).

\( R = \text{randn}(sz,\text{datatype},'\text{like}',P) \) creates an array of \( \text{randn} \) values with the specified underlying class (\( \text{datatype} \)), and the same type as array \( P \).

\( C = \text{randn}(sz,\text{codist}) \) or \( C = \text{rand}(sz,\text{datatype},\text{codist}) \) creates a codistributed array of \( \text{randn} \) values with the specified size and underlying class (the default \( \text{datatype} \) is 'double'). The codistributor object \( \text{codist} \) specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for \( \text{codistributor1d} \) and \( \text{codistributor2dbc} \). To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = \text{randn}(8,\text{codistributor1d}());
end
```

\( C = \text{randn}(sz,\_\_\_,\text{codist},'\text{noCommunication}') \) specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

\( C = \text{randn}(sz,\_\_\_,\text{codist},'\text{like}',P) \) creates a codistributed array of \( \text{randn} \) values with the specified size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array \( P \).
Examples

Create Distributed Randn Matrix

Create a 1000-by-1000 distributed array of randn values with underlying class double:

\[
D = \text{randn}(1000, 'distributed');
\]

Create Codistributed Randn Matrix

Create a 1000-by-1000 codistributed double matrix of randn values, distributed by its second dimension (columns).

\[
\text{spmd}(4)
\]
\[
C = \text{randn}(1000, 'codistributed');
\]
\[
\text{end}
\]

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed single matrix of randn values, distributed by its columns.

\[
\text{spmd}(4)
\]
\[
\text{codist} = \text{codistributor('1d',2,100*[1:numlabs]});
\]
\[
C = \text{randn}(1000,1000, 'single', \text{codist});
\]
\[
\text{end}
\]

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray Rand Matrix

Create a 1000-by-1000 gpuArray of randn values with underlying class double:

\[
G = \text{randn}(1000, 'double', 'gpuArray');
\]

See Also
codistributed.sprandn | distributed.sprandn | rand | randi | randn

Introduced in R2006b
recreate

Create new job from existing job

Syntax

newjob = recreate(oldjob)
newjob = recreate(oldjob,'TaskState', states)
newjob = recreate(oldjob,'TaskID', ids)

Arguments

<table>
<thead>
<tr>
<th>Argument</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>newjob</td>
<td>New job object.</td>
</tr>
<tr>
<td>oldjob</td>
<td>Original job object to be duplicated.</td>
</tr>
<tr>
<td>'TaskID'</td>
<td>Option to include only some tasks</td>
</tr>
<tr>
<td>ids</td>
<td>Vector of integers specifying task IDs</td>
</tr>
</tbody>
</table>

Description

newjob = recreate(oldjob) creates a new job object based on an existing job, containing the same tasks and settable properties as oldjob. The old job can be in any state; the new job state is pending.

newjob = recreate(oldjob,'TaskState', states) creates a job object with tasks that correspond to the tasks with State specified by states. states is a string or cell array of strings representing the State of the required tasks from oldjob. Because communicating jobs have only one task, this option only supports independent jobs. Valid states are 'pending', 'running', 'finished' and 'failed'.

newjob = recreate(oldjob,'TaskID', ids) creates a job object containing the tasks from oldjob that correspond to the tasks with IDs specified by ids, a vector of integers. Because communicating jobs have only one task, this option only supports independent jobs.
Examples

Example 11.7. Recreate an Entire Job

This example shows how to recreate the entire job myJob.

newJob = recreate(myJob)

Example 11.8. Recreate a Job with only pending Tasks

This example shows how to recreate an independent job, which has only pending tasks from the job oldIndependentJob.

newJob = recreate(oldIndependentJob,'TaskState','pending');

Example 11.9. Recreate a Job with Specified Tasks

This example shows how to recreate an independent job, which has only the tasks with IDs 21 to 32 from the job oldIndependentJob.

newJob = recreate(oldIndependentJob,'TaskID', [21:32]);

Example 11.10. Recreate Jobs of a Specific User

This example shows how to find and recreate all failed jobs submitted by user Mary. Assume the default cluster is the one Mary had submitted her jobs to.

c = parcluster();
failedjobs = findJob(c,'Username','Mary','State','failed');
for m = 1:length(failedjobs)
    newJob(m) = recreate(failedjobs(m));
end

See Also
createCommunicatingJob | createJob | createTask | findJob | submit

Introduced in R2014a
**redistribute**

Redistribute codistributed array with another distribution scheme

**Syntax**

\[ D2 = \text{redistribute}(D1, \text{codist}) \]

**Description**

\[ D2 = \text{redistribute}(D1, \text{codist}) \]

redistributes a codistributed array \( D1 \) and returns \( D2 \) using the distribution scheme defined by the \text{codistributor} object \( \text{codist} \).

**Examples**

Redistribute an array according to the distribution scheme of another array.

```matlab
spmd
    % First, create a magic square distributed by columns:
    M = codistributed(magic(10),codistributor1d(2,[1 2 3 4]));

    % Create a pascal matrix distributed by rows (first dimension):
    P = codistributed(pascal(10),codistributor1d(1));

    % Redistribute the pascal matrix according to the
    % distribution (partition) scheme of the magic square:
    R = redistribute(P,getCodistributor(M));
end
```

**See Also**

codistributed | codistributor | codistributor1d.defaultPartition

Introduced in R2006b
reset

Reset GPU device and clear its memory

Syntax

reset (gpudev)

Description

reset (gpudev) resets the GPU device and clears its memory of gpuArray and CUDAKernel data. The GPU device identified by gpudev remains the selected device, but all gpuArray and CUDAKernel objects in MATLAB representing data on that device are invalid.

Arguments

gpudev         GPUDevice object representing the currently selected device

Tips

After you reset a GPU device, any variables representing arrays or kernels on the device are invalid; you should clear or redefine them.

Examples

Reset GPU Device

Create a gpuArray on the selected GPU device, then reset the device.

```matlab
    g = gpuDevice(1);
    M = gpuArray(magic(4));
    M  % Display gpuArray
```
reset(g);
g  % Show that the device is still selected

g =

CUDADevice with properties:

    Name: 'Tesla K20c'
    Index: 1
    ComputeCapability: '3.5'
    SupportsDouble: 1
    DriverVersion: 7.5
    ToolkitVersion: 7.5
    MaxThreadsPerBlock: 1024
    MaxShmemPerBlock: 49152
    MaxThreadBlockSize: [1024 1024 64]
    MaxGridSize: [2.1475e+09 65535 65535]
    SIMDWidth: 32
    TotalMemory: 5.0327e+09
    AvailableMemory: 4.9190e+09
    MultiprocessorCount: 13
    ClockRateKHz: 705500
    ComputeMode: 'Default'
    GPUOverlapsTransfers: 1
    KernelExecutionTimeout: 0
    CanMapHostMemory: 1
    DeviceSupported: 1
    DeviceSelected: 1

whos  % Show that the gpuArray variable name
       % is still in the MATLAB workspace

     Name      Size      Bytes  Class          Attributes
       g         1x1         112  parallel.gpu.CUDADevice
       M         1x1         108  gpuArray

M  % Try to display gpuArray

Data no longer exists on the GPU.
clear M

See Also
gpuArray | gpuDevice | parallel.gpu.CUDAKernel

Introduced in R2012a
resume
Resume processing queue in MATLAB job scheduler

Syntax
resume(mjs)

Arguments
mjs MATLAB job scheduler object whose queue is resumed.

Description
resume(mjs) resumes processing of the specified MATLAB job scheduler's queue so that jobs waiting in the queued state will be run. This call will do nothing if the MJS is not paused.

See Also
pause | wait

Introduced before R2006a
saveAsProfile

Save cluster properties to specified profile

Description

saveAsProfile(cluster,profileName) saves the properties of the cluster object to the specified profile, and updates the cluster Profile property value to indicate the new profile name.

Examples

Create a cluster, then modify a property and save the properties to a new profile.

```plaintext
myCluster = parcluster('local');
myCluster.NumWorkers = 3;
saveAsProfile(myCluster,'local2'); New profile now specifies 3 workers
```

See Also

parcluster | saveProfile

Introduced in R2012a
saveProfile

Save modified cluster properties to its current profile

Description

saveProfile(cluster) saves the modified properties on the cluster object to the profile specified by the cluster’s Profile property, and sets the Modified property to false. If the cluster’s Profile property is empty, an error is thrown.

Examples

Create a cluster, then modify a property and save the change to the profile.

myCluster = parcluster('local')
myCluster =
Local Cluster
    Properties:
        Profile: local
        Modified: false
        Host: HOSTNAME
        NumWorkers: 4
myCluster.NumWorkers = 3
myCluster =
Local Cluster
    Properties:
        Profile: local
        Modified: true
        Host: HOSTNAME
        NumWorkers: 3

The myCluster.Modified property is now true.

saveProfile(myCluster);
myCluster
myCluster =
Local Cluster
    Properties:
        Profile: local
        Modified: false
        Host: HOSTNAME
        NumWorkers: 3

After saving, the local profile now matches the current property settings, so the myCluster.Modified property is false.

See Also
parcluster | saveAsProfile

Introduced in R2012a
**setConstantMemory**

Set some constant memory on GPU

**Syntax**

```matlab
setConstantMemory(kern, sym, val)
setConstantMemory(kern, sym1, val1, sym2, val2, ...)
```

**Description**

`setConstantMemory(kern, sym, val)` sets the constant memory in the CUDA kernel `kern` with symbol name `sym` to contain the data in `val`. `val` can be any numeric array, including a `gpuArray`. The command errors if the named symbol does not exist or if it is not big enough to contain the specified data. Partially filling a constant is allowed.

There is no automatic data-type conversion for constant memory, so it is important to make sure that the supplied data is of the correct type for the constant memory symbol being filled.

`setConstantMemory(kern, sym1, val1, sym2, val2, ...)` sets multiple constant symbols.

**Examples**

If `KERN` represents a CUDA kernel whose CU file contains the following includes and constant definitions:

```c
#include "tmwtypes.h"
__constant__ int32_t N1;
__constant__ int N2; // Assume 'int' is 32 bits
__constant__ double CONST_DATA[256];
```

you can fill these with MATLAB data as follows:

```matlab
KERN = parallel.gpu.CUDAKernel(ptxFile, cudaFile);
```
setConstantMemory(KERN,'N1',int32(10));
setConstantMemory(KERN,'N2',int32(10));
setConstantMemory(KERN,'CONST_DATA',1:10);

or

setConstantMemory(KERN,'N1',int32(10),'N2',int32(10),'CONST_DATA',1:10);

See Also
gpuArray | parallel.gpu.CUDAKernel

Introduced in R2012a
setJobClusterData

Set specific user data for job on generic cluster

Syntax

setJobClusterData(cluster,job,userdata)

Arguments

cluster Cluster object identifying the generic third-party cluster running the job
job Job object identifying the job for which to store data
userdata Information to store for this job

Description

setJobClusterData(cluster,job,userdata) stores data for the job job that is running on the generic cluster cluster. You can later retrieve the information with the function getJobClusterData. For example, it might be useful to store the third-party scheduler’s external ID for this job, so that the function specified in GetJobStateFcn can later query the scheduler about the state of the job. Or the stored data might be an array with the scheduler’s ID for each task in the job.

You should call the function setJobClusterData in the submit function (identified by the IndependentSubmitFcn or CommunicatingSubmitFcn property) and call getJobClusterData in any of the functions identified by the properties GetJobStateFcn, DeleteJobFcn, DeleteTaskFcn, CancelJobFcn, or CancelTaskFcn.

For more information and examples on using these functions and properties, see “Manage Jobs with Generic Scheduler” on page 7-35.
See Also
getJobClusterData

Introduced in R2012a
**shutdown**

Shut down cloud cluster

**Syntax**

```matlab
shutdown(cluster)
shtdown(MJScluster,'At',D)
shtdown(MJScluster,'After',event)
shtdown(MJScluster,'After',numhours)
```

**Description**

`shutdown(cluster)` shuts down the cluster immediately. You can use this syntax for both for both MATLAB Parallel Cloud and MATLAB Distributed Computing Server for Amazon EC2 clusters.

`shutdown(MJScluster,'At',D)` shuts down the cluster at the time specified by the datenum, datevec, or datetime D. D is interpreted in the local time zone unless D is a datetime with TimeZone specified. You can use the MJScluster argument syntaxes only for MATLAB Distributed Computing Server for Amazon EC2 clusters.

`shutdown(MJScluster,'After',event)` shuts down the cluster after the specified event event has occurred. event can be 'never' or 'idle'. A cluster is 'idle' immediately when there are no running jobs, queued jobs, or running pools. The cluster is eligible for shutdown if 'idle' for more than 5 minutes, and is guaranteed to shut down within 60 minutes.

`shutdown(MJScluster,'After',numhours)` shuts down the cluster after numhours hours, as measured from the time the method is called.

**Examples**
Shut Down a Cloud Cluster Immediately

```matlab
shutdown(cluster);
```

Shut Down Cluster at Date and Time Specified

Specify date and time to terminate a cluster using a `datenum`, `datevec`, or `datetime`. The `datetime` can (optionally) have a `TimeZone` specified.

```matlab
shutdown(MJSCluster,'At',datenum('2017-02-22 19:00'));
shutdown(MJSCluster,'At',datevec('2017-02-22 19:00'));
shutdown(MJSCluster,'At',datetime(2017, 2, 22, 19, 0, 0,'TimeZone','local'));
```

Enable Cluster to Run Indefinitely

```matlab
shutdown(MJSCluster,'After','never');
```

Shut Down When Cluster Is Idle

```matlab
shutdown(MJSCluster,'After','idle');
```

Shut Down Cluster After a Number of Hours

```matlab
shutdown(MJSCluster,'After',10);
```

Input Arguments

- `cluster` — MATLAB Parallel Cloud or MATLAB Distributed Computing Server for Amazon EC2 cloud cluster
  cluster object (default)

MATLAB Parallel Cloud or MATLAB Distributed Computing Server for Amazon EC2 cluster, specified as cluster object created using `parcluster`.

Example: `shutdown(cluster);`
**MJScluster** — MATLAB Distributed Computing Server for Amazon EC2 cloud cluster
cluster object (default)

MATLAB Distributed Computing Server for Amazon EC2 cluster, specified as cluster object created using `parcluster`.

Example: `shutdown(MJScluster);`

**D** — Date and time

datenum | datevec | datetime

Date and time, specified as a `datenum`, `datevec`, or `datetime`. D is interpreted in the local time zone unless D is a `datetime` with `TimeZone` specified.

Example: `shutdown(MJSCluster,'At',datenum('2017-02-22 19:00'));`
Example: `shutdown(MJSCluster,'At',datevec('2017-02-22 19:00'));`
Example: `shutdown(MJSCluster,'At',datetime(2017, 2, 22, 19, 0, 0,'TimeZone', 'local'));

**event** — Event to shut down the cluster

'never' | 'idle'

Event to shut down the cluster, specified as 'never' or 'idle'. A cluster is 'idle' immediately when there are no running jobs, queued jobs, or running pools. The cluster is eligible for shutdown if 'idle' for more than 5 minutes, and is guaranteed to shut down within 60 minutes.

Example: `shutdown(MJSCluster,'After','idle');`

**numHours** — Number of hours

scalar

Number of hours after which the cluster shuts down, specified as scalar, measured from the time you call `shutdown`.

Example: `shutdown(MJSCluster,'After',10);`

**See Also**

datenum | datetime | datevec | parallel.Cluster | parcluster | parpool | start | wait (cluster)
Introduced in R2017a
size

Size of object array

Syntax

\[
d = \text{size(obj)}
\]
\[
[m,n] = \text{size(obj)}
\]
\[
[m_1,m_2,m_3,...,m_n] = \text{size(obj)}
\]
\[
m = \text{size(obj,dim)}
\]

Arguments

- **obj**: An object or an array of objects.
- **dim**: The dimension of **obj**.
- **d**: The number of rows and columns in **obj**.
- **m**: The number of rows in **obj**, or the length of the dimension specified by **dim**.
- **n**: The number of columns in **obj**.
- **m_1, m_2, m_3, ..., m_n**: The lengths of the first n dimensions of **obj**.

Description

- \(d = \text{size(obj)}\) returns the two-element row vector \(d\) containing the number of rows and columns in **obj**.
- \([m,n] = \text{size(obj)}\) returns the number of rows and columns in separate output variables.
- \([m_1,m_2,m_3,...,m_n] = \text{size(obj)}\) returns the length of the first n dimensions of **obj**.
- \(m = \text{size(obj,dim)}\) returns the length of the dimension specified by the scalar **dim**. For example, \(\text{size(obj,1)}\) returns the number of rows.
See Also

length

Introduced before R2006a
sparse

Create sparse distributed or codistributed matrix

Syntax

SD = sparse(FD)
SC = sparse(m,n,codist)
SC = sparse(m,n,codist,'noCommunication')
SC = sparse(i,j,v,m,n,nzmax)
SC = sparse(i,j,v,m,n)
SC = sparse(i,j,v)

Description

SD = sparse(FD) converts a full distributed or codistributed array FD to a sparse distributed or codistributed (respectively) array SD.

SC = sparse(m,n,codist) creates an m-by-n sparse codistributed array of underlying class double, distributed according to the scheme defined by the codistributor codist. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. This form of the syntax is most useful inside spmd, pmode, or a communicating job.

SC = sparse(m,n,codist,'noCommunication') creates an m-by-n sparse codistributed array in the manner specified above, but does not perform any global communication for error checking when constructing the array. This form of the syntax is most useful inside spmd, pmode, or a communicating job.

SC = sparse(i,j,v,m,n,nzmax) uses vectors i and j to specify indices, and v to specify element values, for generating an m-by-n sparse matrix such that SC(i(k),j(k)) = v(k), with space allocated for nzmax nonzeros. If any of the input vectors i, j, or v is codistributed, the output sparse matrix SC is codistributed. Vectors i, j, and v must be the same length. Any elements of v that are zero are ignored, along with the corresponding values of i and j. Any elements of v that have duplicate values of i and j are added together.
To simplify this six-argument call, you can pass scalars for the argument \( v \) and one of the arguments \( i \) or \( j \), in which case they are expanded so that \( i, j, \) and \( v \) all have the same length.

\[
SC = \text{sparse}(i,j,v,m,n) \quad \text{uses} \quad \text{nzmax} = \max([\text{length}(i) \quad \text{length}(j)]).
\]

\[
SC = \text{sparse}(i,j,v) \quad \text{uses} \quad m = \max(i) \quad \text{and} \quad n = \max(j). \quad \text{The maxima are computed before any zeros in} \quad v \quad \text{are removed, so one of the rows of} \quad [i \quad j \quad v] \quad \text{might be} \quad [m \quad n \quad 0], \quad \text{assuring the matrix size satisfies the requirements of} \quad m \quad \text{and} \quad n.
\]

**Note** To create a sparse codistributed array of underlying class logical, first create an array of underlying class double and then cast it using the `logical` function:

```matlab
spmd
    SC = logical(sparse(m,n,codistributor1d()));
end
```

### Examples

With four workers,

```matlab
spmd(4)
    C = sparse(1000,1000,codistributor1d());
end
```

creates a 1000-by-1000 codistributed sparse double array \( C \). \( C \) is distributed by its second dimension (columns), and each worker contains a 1000-by-250 local piece of \( C \).

```matlab
spmd(4)
    codist = codistributor1d(2,1:numlabs)
    C = sparse(10,10,codist);
end
```

creates a 10-by-10 codistributed sparse double array \( C \), distributed by its columns. Each worker contains a 10-by-\text{labindex} local piece of \( C \).

Convert a distributed array into a sparse distributed array:
R = rand(1000,'distributed');
D = floor(2*R); % D also is distributed
SD = sparse(D); % SD is sparse distributed

Create a sparse codistributed array from vectors of indices and a distributed array of element values:

```matlab
r = [ 1 1 4 4 8];
c = [ 1 4 1 4 8];
v = [10 20 30 40 0];
V = distributed(v);
spmd
    SC = sparse(r,c,V);
end
```

In this example, even though the fifth element of the value array `v` is 0, the size of the result is an 8-by-8 matrix because of the corresponding maximum indices in `r` and `c`. Matrix `SC` is considered codistributed when viewed inside an `spmd` block, and distributed when viewed from the client workspace. To view a full version of the matrix, the `full` function converts this distributed sparse array to a full distributed array:

```matlab
S = full(SC)
```

```
10     0     0    20     0     0     0     0
 0     0     0     0     0     0     0     0
 0     0     0     0     0     0     0     0
30     0     0    40     0     0     0     0
 0     0     0     0     0     0     0     0
 0     0     0     0     0     0     0     0
 0     0     0     0     0     0     0     0
 0     0     0     0     0     0     0     0
```

See Also

codistributed.spalloc | distributed.spalloc | sparse

Introduced in R2006b
**spmd**

Execute code in parallel on workers of parallel pool

**Syntax**

```
spmd, statements, end
spmd(n), statements, end
spmd(m,n), statements, end
```

**Description**

The general form of an **spmd** (single program, multiple data) statement is:

```
spmd
    statements
end
```

**spmd**, **statements**, **end** defines an **spmd** statement on a single line. MATLAB executes the **spmd** body denoted by **statements** on several MATLAB workers simultaneously. The **spmd** statement can be used only if you have Parallel Computing Toolbox. To execute the statements in parallel, you must first open a pool of MATLAB workers using **parpool** or have your parallel preferences allow the automatic start of a pool.

Inside the body of the **spmd** statement, each MATLAB worker has a unique value of **labindex**, while **numlabs** denotes the total number of workers executing the block in parallel. Within the body of the **spmd** statement, communication functions for communicating jobs (such as **labSend** and **labReceive**) can transfer data between the workers.

Values returning from the body of an **spmd** statement are converted to **Composite** objects on the MATLAB client. A Composite object contains references to the values stored on the remote MATLAB workers, and those values can be retrieved using cell-array indexing. The actual data on the workers remains available on the workers for subsequent **spmd** execution, so long as the Composite exists on the client and the parallel pool remains open.
By default, MATLAB uses all workers in the pool. When there is no pool active, MATLAB will create a pool and use all the workers from that pool. If your preferences do not allow automatic pool creation, MATLAB executes the block body locally and creates Composite objects as necessary. You cannot execute an \texttt{spmd} block if any worker is busy executing a \texttt{parfeval} request, unless you use \texttt{spmd(0)}.

\texttt{spmd(n)}, \texttt{statements}, \texttt{end} uses \texttt{n} to specify the exact number of MATLAB workers to evaluate \texttt{statements}, provided that \texttt{n} workers are available from the parallel pool. If there are not enough workers available, an error is thrown. If \texttt{n} is zero, MATLAB executes the block body locally and creates Composite objects, the same as if there is no pool available.

\texttt{spmd(m,n)}, \texttt{statements}, \texttt{end} uses a minimum of \texttt{m} and a maximum of \texttt{n} workers to evaluate \texttt{statements}. If there are not enough workers available, an error is thrown. \texttt{m} can be zero, which allows the block to run locally if no workers are available.

For more information about \texttt{spmd} and Composite objects, see “Distribute Arrays and Run SPMD” on page 1-22.

\textbf{Note} Use \texttt{parfevalOnAll} instead of \texttt{parfor} or \texttt{spmd} if you want to use \texttt{clear}. This preserves workspace transparency. See “Ensure Transparency in parfor-Loops” on page 2-56.

\section*{Examples}

Perform a simple calculation in parallel, and plot the results:

\begin{verbatim}
parpool(3)
spmd
    q = magic(labindex + 2);
end
for ii=1:length(q)
    figure, imagesc(q{ii});
end
delete(gcp)
\end{verbatim}
**Tips**

- An `spmd` block runs on the workers of the existing parallel pool. If no pool exists, `spmd` will start a new parallel pool, unless the automatic starting of pools is disabled in your parallel preferences. If there is no parallel pool and `spmd` cannot start one, the code runs serially in the client session.

- If the `AutoAttachFiles` property in the cluster profile for the parallel pool is set to `true`, MATLAB performs an analysis on an `spmd` block to determine what code files are necessary for its execution, then automatically attaches those files to the parallel pool job so that the code is available to the workers.

- For information about restrictions and limitations when using `spmd`, see “Run Single Programs on Multiple Data Sets” on page 3-2.

**See Also**

Composite | batch | gop | labindex | numlabs | parallel.pool.Constant | parpool

*Introduced in R2008b*
start
Start cloud cluster

Syntax
start(cluster)

Description
start(cluster) starts the specified MATLAB Distributed Computing Server for Amazon EC2 cluster, if it is not already running. If the cluster is already running or in the process of shutting down, then start(cluster) returns immediately, and the state of the cluster is not changed.

Examples

Start Cloud Cluster

Obtain your cluster profile using one of the following ways:

- From the MATLAB Parallel > Discover Clusters user interface. For more information, see “Discover Clusters and Use Cluster Profiles” on page 6-18.
- By downloading it from Cloud Center. For more information, see MathWorks Cloud Center documentation.

Create a cluster using the default profile.

myCluster = parcluster;

Start the cluster.

start(myCluster);

Wait for the cluster to be ready to accept job submissions.
wait(myCluster);

Input Arguments

cluster — MATLAB Distributed Computing Server for Amazon EC2 cluster
cluster object (default)

MATLAB Distributed Computing Server for Amazon EC2 cluster, specified as cluster object created using parcluster.

Example: start(cluster)

See Also

parallel.Cluster | parcluster | parpool | shutdown | wait (cluster)

Introduced in R2017a
submit

Queue job in scheduler

Syntax

submit(j)

Arguments

j        Job object to be queued.

Description

submit(j) queues the job object j in its cluster queue. The cluster used for this job was determined when the job was created.

Examples

Find the MJS cluster identified by the cluster profile Profile1.

c1 = parcluster('Profile1');

Create a job object in this cluster.

ej1 = createJob(c1);

Add a task object to be evaluated for the job.

t1 = createTask(j1,@rand,1,{8,4});

Queue the job object in the cluster for execution.

submit(j1);
Tips

When a job is submitted to a cluster queue, the job’s State property is set to queued, and the job is added to the list of jobs waiting to be executed.

The jobs in the waiting list are executed in a first in, first out manner; that is, the order in which they were submitted, except when the sequence is altered by promote, demote, cancel, or delete.

See Also
createCommunicatingJob | createJob | findJob | parcluster | promote | recreate

Introduced before R2006a
subsasgn

Subscripted assignment for Composite

Syntax

\[
C(i) = \{B\} \\
C(1:end) = \{B\} \\
C([i1,i2]) = \{B1,B2\} \\
C(i) = B
\]

Description

subsasgn assigns remote values to Composite objects. The values reside on the workers in the current parallel pool.

\( C(i) = \{B\} \) sets the entry of \( C \) on worker \( i \) to the value \( B \).

\( C(1:end) = \{B\} \) sets all entries of \( C \) to the value \( B \).

\( C([i1,i2]) = \{B1,B2\} \) assigns different values on workers \( i1 \) and \( i2 \).

\( C(i) = B \) sets the entry of \( C \) on worker \( i \) to the value \( B \).

See Also

Composite | subsasgn | subsref

Introduced in R2008b
subsref

Subscripted reference for Composite

Syntax

B = C(i)
B = C([i1,i2,...])
B = C{i}
[B1,B2,...] = C{[i1,i2,...]}

Description

subsref retrieves remote values of a Composite object from the workers in the current parallel pool.

B = C(i) returns the entry of Composite C from worker i as a cell array.

B = C([i1,i2,...]) returns multiple entries as a cell array.

B = C{i} returns the value of Composite C from worker i as a single entry.

[B1,B2,...] = C{[i1,i2,...]} returns multiple entries.

See Also

Composite | subsasgn | subsref

Introduced in R2008b
**taskFinish**

User-defined options to run on worker when task finishes

**Syntax**

\[
\text{taskFinish}(\text{task})
\]

**Arguments**

\[
\text{task} \quad \text{The task being evaluated by the worker}
\]

**Description**

\[
\text{taskFinish}(\text{task}) \quad \text{runs automatically on a worker each time the worker finishes evaluating a task for a particular job. You do not call this function from the client session, nor explicitly as part of a task function.}
\]

You add MATLAB code to the `taskFinish.m` file to define anything you want executed on the worker when a task is finished. The worker looks for `taskFinish.m` in the following order, executing the one it finds first:

1. Included in the job’s `AttachedFiles` property.
2. In a folder included in the job’s `AdditionalPaths` property.
3. In the worker’s MATLAB installation at the location

   \[
   \text{matlabroot/toolbox/distcomp/user/taskFinish.m}
   \]

To create a version of `taskFinish.m` for `AttachedFiles` or `AdditionalPaths`, copy the provided file and modify it as required. For further details on `taskFinish` and its implementation, see the text in the installed `taskFinish.m` file.

**See Also**

`jobStartup` | `poolStartup` | `taskStartup`
Introduced before R2006a
**taskStartup**

User-defined options to run on worker when task starts

**Syntax**

taskStartup(task)

**Arguments**

task

The task being evaluated by the worker.

**Description**

taskStartup(task) runs automatically on a worker each time the worker evaluates a task for a particular job. You do not call this function from the client session, nor explicitly as part of a task function.

You add MATLAB code to the taskStartup.m file to define task initialization on the worker. The worker looks for taskStartup.m in the following order, executing the one it finds first:

1. Included in the job’s AttachedFiles property.
2. In a folder included in the job’s AdditionalPaths property.
3. In the worker’s MATLAB installation at the location

   `matlabroot/toolbox/distcomp/user/taskStartup.m`

To create a version of taskStartup.m for AttachedFiles or AdditionalPaths, copy the provided file and modify it as required. For further details on taskStartup and its implementation, see the text in the installed taskStartup.m file.

**See Also**

jobStartup | poolStartup | taskFinish
Introduced before R2006a
send

Send data from worker to client using a data queue

Syntax

send(queue, data)
send(pollablequeue, data)

Description

send(queue, data) sends a message or data with the value data to the parallel.pool.DataQueue specified by queue. Call afterEach to pass each of the pending messages to the function specified by afterEach.

send(pollablequeue, data) sends a message or data with the value data to the parallel.pool.PollableDataQueue specified by pollablequeue. Retrieve the result using poll(pollablequeue), and return data as the answer.

Use the send and poll functions together using a pollable data queue to transfer and retrieve messages or data from different workers.

Examples

Send a Message in a parfor-Loop, and Dispatch the Message on the Queue

Construct a DataQueue, and call afterEach.

q = parallel.pool.DataQueue;
afterEach(q, @disp);

Start a parfor-loop, and send a message. The pending message is passed to the afterEach function, in this example @disp.
parfor i = 1:3
    send(q, i);
end;

1
2
3

For more details on listening for data using a DataQueue, see afterEach.

Send a Message in a parfor-loop, and Poll for the Result

Construct a PollableDataQueue.

p = parallel.pool.PollableDataQueue;

Start a parfor-loop, and send a message, such as data with the value 1.

parfor i = 1
    send(p, i);
end

Poll for the result.

poll(p)

1

For more details on retrieving data using a PollableDataQueue, see poll.

Construct a Simple parfor Wait Bar Using a Data Queue

This example shows a function that creates a parfor wait bar. Create a DataQueue, and use afterEach to specify the function to execute each time the queue receives data. This example calls a subfunction that updates the wait bar.

Create a parfor-loop to carry out a computationally demanding task in MATLAB. Use send to send some dummy data on each iteration of the parfor-loop. When the queue
receives the data, afterEach calls nUpdateWaitbar in the client MATLAB, and you can observe the wait bar progress.

```matlab
function a = parforWaitbar

D = parallel.pool.DataQueue;
h = waitbar(0, 'Please wait ...');
afterEach(D, @nUpdateWaitbar);

N = 200;
p = 1;

parfor i = 1:N
    a(i) = max(abs(eig(rand(400))));
    send(D, i);
end

function nUpdateWaitbar(~)
    waitbar(p/N, h);
    p = p + 1;
end
end
```

**Input Arguments**

- `queue` — Data queue
  ```matlab
  parallel.pool.DataQueue
  ```
  Data queue, specified as a `parallel.pool.DataQueue` object.

  Example: `q = parallel.pool.DataQueue;`

- `data` — Message or data
  ```matlab
  scalar | vector | matrix | array | string | character vector | serializable object
  ```
Message or data from workers to a data queue, specified as any data type that can be serialized.

Example: `send(queue, data);`

**pollablequeue — Pollable data queue**

`parallel.pool.PollableDataQueue`

Pollable data queue, specified as a `parallel.pool.PollableDataQueue` object.

Example: `p = parallel.pool.PollableDataQueue;`

**See Also**

`afterEach` | `parallel.pool.DataQueue` | `parallel.pool.PollableDataQueue` | `parfor` | `parpool` | `poll`

Introduced in R2017a
ticBytes

Start counting bytes transferred within parallel pool

Syntax

ticBytes(pool)
startState = ticBytes(pool)

Description

ticBytes(pool) starts counting the number of bytes transferred to each worker in the pool, so that later tocBytes(pool) can measure the amount of data transferred to each worker between the two calls.

Use the ticBytes(pool) and tocBytes(pool) functions together to measure how much data is transferred to and from the workers in a parallel pool. You can use ticBytes and tocBytes while executing parallel language constructs and functions, such as parfor, spmd, or parfeval. Use ticBytes and tocBytes to pass around less data and optimize your code.

startState = ticBytes(pool) saves the state to an output argument, startState, so that you can simultaneously record the number of bytes transferred for multiple pairs of ticBytes and tocBytes calls. Use the value of startState as an input argument for a subsequent call to tocBytes.

Examples

Measure Amount of Data Transferred While Running a Simple parfor-loop

a = 0;
b = rand(100);
ticBytes(gcp);
parfor i = 1:100
a = a + sum(b(:, i));
end
tocBytes(gcp)

Starting parallel pool (parpool) using the 'local' profile ... connected to 4 workers.

<table>
<thead>
<tr>
<th>BytesSentToWorkers</th>
<th>BytesReceivedFromWorkers</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>42948</td>
</tr>
<tr>
<td>2</td>
<td>36548</td>
</tr>
<tr>
<td>3</td>
<td>27500</td>
</tr>
<tr>
<td>4</td>
<td>27500</td>
</tr>
<tr>
<td>Total</td>
<td>1.345e+05</td>
</tr>
</tbody>
</table>

Workers might transfer different numbers of bytes, because each worker might carry out different numbers of loop iterations.

**Simultaneously Measure Multiple Amounts of Data Transferred, Using Two Pairs of ticBytes and tocBytes Calls**

Measure the minimum and average number of bytes transferred while running a parfor loop nested in a for loop.

REPS = 10;
minBytes = Inf;
ticBytes(gcp);  % ticBytes, pair 1

for ii=1:REPS
a = 0;
b = rand(100);
startS = ticBytes(gcp)  % ticBytes, pair 2
parfor i = 1:100
  a = a + sum(b(:, i));
end
bytes = tocBytes(gcp, startS)  % tocBytes, pair 2
minBytes = min(bytes, minBytes)
end

averageBytes = tocBytes(gcp)/REPS  % tocBytes, pair 1
Note that nesting a parfor-loop in a for-loop can be slow due to overhead, see “Convert Nested for-Loops to parfor” on page 2-16.

**Input Arguments**

`pool` — parallel pool  
`parallel.Pool`  
Parallel pool, typically specified by `gcp`, if you want the current parallel pool. Otherwise, use `parpool` to create a new pool.  
Example: `ticBytes(gcp);`

**Output Arguments**

`startState` — Starting state  
`TicBytesResult`  
Starting state returned as an input argument for a subsequent call to `tocBytes`.  
Example: `startState = ticBytes(gcp);`

**See Also**

`gcp` | `parfeval` | `parfor` | `parpool` | `spmd` | `tocBytes`  

Introduced in R2016b
tocBytes

Read how many bytes have been transferred since calling ticBytes

Syntax

tocBytes(pool)
bytes = tocBytes(pool)
tocBytes(pool,startState)
bytes = tocBytes(pool,startState)

Description

tocBytes(pool) reads how many bytes have been transferred since calling ticBytes. The function displays the total number of bytes transferred to and from each of the workers in a parallel pool after the most recent execution of ticBytes.

Use the ticBytes (pool) and tocBytes (pool) functions together to measure how much data is transferred to and from the workers in a parallel pool. You can use ticBytes and tocBytes while executing parallel language constructs and functions, such as parfor, spmd, or parfeval. Use ticBytes and tocBytes to pass around less data and optimize your code.

bytes = tocBytes(pool) returns the number of bytes transferred to and from each of the workers in the parallel pool.

tocBytes(pool,startState) displays the total number of bytes transferred in the parallel pool after the ticBytes command that generated startState.

bytes = tocBytes(pool,startState) returns the number of bytes transferred to and from each of the workers in the parallel pool after the ticBytes command that generated startState.

Examples
Measure Amount of Data Transferred While Running a Simple `parfor`-loop

Use `tocBytes(gcp,startS)` to measure the amount of data transferred.

```matlab
a = 0;
b = rand(100);
startS = ticBytes(gcp);
parfor i = 1:100
    a = a + sum(b(:, i));
end
tocBytes(gcp,startS)
```

Starting parallel pool (parpool) using the 'local' profile ... 
connected to 4 workers.

<table>
<thead>
<tr>
<th>BytesSentToWorkers</th>
<th>BytesReceivedFromWorkers</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>42948</td>
</tr>
<tr>
<td>2</td>
<td>36548</td>
</tr>
<tr>
<td>3</td>
<td>27500</td>
</tr>
<tr>
<td>4</td>
<td>27500</td>
</tr>
<tr>
<td>Total</td>
<td>1.345e+05</td>
</tr>
</tbody>
</table>

Workers might transfer different numbers of bytes, because each worker might carry out different numbers of loop iterations.

Measure Amount of Data Transferred While Running a Simple `spmd` Block

Use `bytes = tocBytes(gcp)` to measure the amount of data transferred.

```matlab
ticBytes(gcp);
spmd
    rand(100);
end
bytes = tocBytes(gcp)
```

bytes =

```
13448  1208
13448  1208
13448  1208
13448  1208
```
Workers transfer the same number of bytes, because each worker carries out the same number of loop iterations.

**Simultaneously Measure Multiple Amounts of Data Transferred, Using Two Pairs of ticBytes and tocBytes Calls**

Measure the minimum and average number of bytes transferred while running a `parfor` loop nested in a `for` loop.

```matlab
REPS = 10;
minBytes = Inf;
ticBytes(gcp);  % ticBytes, pair 1

for ii=1:REPS
    a = 0;
    b = rand(100);
    startS = ticBytes(gcp)  % ticBytes, pair 2
    parfor i = 1:100
        a = a + sum(b(:, i));
    end
    bytes = tocBytes(gcp, startS)  % tocBytes, pair 2
    minBytes = min(bytes, minBytes)
end

averageBytes = tocBytes(gcp)/REPS  % tocBytes, pair 1
```

Note that nesting a `parfor`-loop in a `for`-loop can be slow due to overhead, see “Convert Nested for-Loops to parfor” on page 2-16.

**Input Arguments**

- **pool** — parallel pool
  ```matlab
  parallel.Pool
  ```

  Parallel pool, typically specified by `gcp`, if you want the current parallel pool. Otherwise, use `parpool` to create a new pool.

  Example: `tocBytes(gcp);`
**startState** — Starting state
TicBytesResult

Starting state returned by ticBytes(pool).
Example: `startState = ticBytes(gcp);`

**Output Arguments**

**bytes** — Bytes transferred
tocBytes(pool)

Bytes transferred, returned as a matrix of size `numWorkers` x 2. This matrix contains the number of bytes transferred to and from each of the workers in the parallel pool. `bytes` returns values in bytes without headings. Use `tocBytes(pool)` without an output argument to get Sent and Received headings, worker numbers, and values in bytes in the Command Window output.
Example: `bytes = tocBytes(pool);`

**See Also**

`gcp` | `parfeval` | `parfor` | `parpool` | `spmd` | `ticBytes`

Introduced in R2016b
true

Array of logical 1 (true)

Syntax

\[
T = \text{true}(sz, \text{arraytype})
\]

\[
T = \text{true}(sz, 'like', P)
\]

\[
C = \text{true}(sz, \text{codist})
\]

\[
C = \text{true}(sz, ___, \text{codist}, 'noCommunication')
\]

\[
C = \text{true}(sz, ___, \text{codist}, 'like', P)
\]

Description

\[
T = \text{true}(sz, \text{arraytype}) \text{ creates a matrix with true values in all elements.}
\]

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>( sz )</td>
<td>( n )</td>
<td>Specifies size as an ( n )-by-( n ) matrix.</td>
</tr>
<tr>
<td>( m, n ) or ([m \ n])</td>
<td>Specifies size as an ( m )-by-( n ) matrix.</td>
<td></td>
</tr>
<tr>
<td>( m, n, \ldots, k ) or ([m \ n \ldots k])</td>
<td>Specifies size as an ( m )-by-( n )-by-\ldots-by-( k ) array.</td>
<td></td>
</tr>
<tr>
<td>\text{arraytype}</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td></td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td></td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
</tbody>
</table>

\[
T = \text{true}(sz, 'like', P) \text{ creates an array of true values with the same type as array } P.
\]
C = true(sz,codist) creates a codistributed array of true values with the specified size. The codistributor object codist specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for codistributor1d and codistributor2dbc. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = true(8,codistributor1d());
end
```

C = true(sz,___,codist,'noCommunication') specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

C = true(sz,___,codist,'like',P) creates a codistributed array of true values with the specified size and distribution scheme. If the codistributor argument is omitted, the distribution scheme is taken from the codistributed array P.

Examples

Create Distributed True Matrix

Create a 1000-by-1000 distributed array of true values with underlying class double:

```matlab
D = true(1000,'distributed');
```

Create Codistributed True Matrix

Create a 1000-by-1000 codistributed matrix of true values, distributed by its second dimension (columns).

```matlab
spmd(4)
    C = true(1000,'codistributed');
end
```

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed matrix of true values, distributed by its columns.
```matlab
spmd(4)
    codist = codistributor('1d',2,100*[1:numlabs]);
    C = true(1000,1000,codist);
end

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray True Matrix

Create a 1000-by-1000 gpuArray of true:

G = true(1000,'gpuArray');

See Also
Inf | NaN | eye | false | ones | true | zeros

Introduced in R2006b
updateAttachedFiles

Update attached files or folders on parallel pool

Syntax

updateAttachedFiles(poolobj)

Description

updateAttachedFiles(poolobj) checks all the attached files of the specified parallel pool to see if they have changed, and replicates any changes to each of the workers in the pool. This checks files that were attached (by a profile or parpool argument) when the pool was started and those subsequently attached with the addAttachedFiles command.

Examples

Update Attached Files on Current Parallel Pool

Update all attached files on the current parallel pool.

poolobj = gcp;
updateAttachedFiles(poolobj)

Input Arguments

poolobj — Pool with attached files
pool object

Pool with attached files, specified as a pool object.

Example: poolobj = gcp;
See Also
addAttachedFiles | gcp | listAutoAttachedFiles | parpool

Topics
“Create and Modify Cluster Profiles” on page 6-24

Introduced in R2013b
**wait**

Wait for job to change state

**Syntax**

```plaintext
wait(j)
wait(j,'state')
wait(j,'state',timeout)
```

**Arguments**

- `j`  
  Job object whose change in state to wait for.

- `'state'`  
  Value of the job object’s `State` property to wait for.

- `timeout`  
  Maximum time to wait, in seconds.

**Description**

`wait(j)` blocks execution in the client session until the job identified by the object `j` reaches the 'finished' state or fails. This occurs when all the job’s tasks are finished processing on the workers.

`wait(j,'state')` blocks execution in the client session until the specified job object changes state to the value of `'state'`. The valid states to wait for are 'queued', 'running', and 'finished'.

If the object is currently or has already been in the specified state, a wait is not performed and execution returns immediately. For example, if you execute `wait(j,'queued')` for a job already in the 'finished' state, the call returns immediately.

`wait(j,'state',timeout)` blocks execution until either the job reaches the specified `'state'`, or `timeout` seconds elapse, whichever happens first.
**Note** Simulink models cannot run while a MATLAB session is blocked by `wait`. If you must run Simulink from the MATLAB client while also running jobs, you cannot use `wait`.

### Examples

Submit a job to the queue, and wait for it to finish running before retrieving its results.

```matlab
submit(j);
wait(j,'finished')
results = fetchOutputs(j)
```

Submit a batch job and wait for it to finish before retrieving its variables.

```matlab
j = batch('myScript');
wait(j)
load(j)
```

### See Also

`pause` | `resume` | `wait (FevalFuture)` | `wait (GPUDevice)`

Introduced in R2008a
wait (cluster)

Wait for cloud cluster to change state

Syntax

wait(cluster)
w\ait(cluster,state)
OK = wait(cluster,state,timeout)

Description

wait(cluster) blocks execution in the client MATLAB session until cluster reaches the 'online' state. The 'online' state indicates that the cluster is running and you can use all requested workers to run jobs.

You can use all wait syntaxes for both MATLAB Parallel Cloud and MATLAB Distributed Computing Server for Amazon EC2 clusters.

wait(cluster,state) blocks execution in the client session until cluster changes state. For a cluster object, the valid states are:

• 'online': The cluster is running and you can use all requested workers to run jobs.
• 'waitingforworkers': The cluster is running, and you can use some but not all of the requested workers to run jobs. You can still use the cluster in this state with the workers that are available.
• 'offline': The cluster is not running, but you can restart using the start() command or via https://cloudcenter.mathworks.com. If the cluster has shared persisted storage, then any previous jobs in the queue are still present when you restart the cluster.

OK = wait(cluster,state,timeout) blocks execution in the client session until cluster changes state, or until timeout seconds have elapsed, whichever happens first. OK is true if state has been reached or a terminal state such as 'error' occurs. OK is false in case of a timeout.
Examples

Wait Until the Cluster Is Running

In Cluster Profile Manager, select MATLAB Parallel Cloud or MATLAB Distributed Computing Server for Amazon EC2 as your default cluster profile.

Create and start a cloud cluster using the default profile.

```matlab
cluster = parcluster;
start(cluster);
```

Wait until the cluster is running. Use all requested workers to run jobs.

```matlab
wait(cluster,'online');
```

Wait for Specified Time for Cluster to Start

In Cluster Profile Manager, select MATLAB Parallel Cloud or MATLAB Distributed Computing Server for Amazon EC2 as your default cluster profile.

Create and start a cloud cluster using the default profile.

```matlab
cluster = parcluster;
start(cluster);
```

Wait 100 seconds for the head node and all workers to start.

```matlab
OK = wait(cluster,'online',100);
```

Input Arguments

- **cluster** — MATLAB Parallel Cloud or MATLAB Distributed Computing Server for Amazon EC2 cloud cluster
  - cluster object (default)

MATLAB Parallel Cloud or MATLAB Distributed Computing Server for Amazon EC2 cluster, specified as cluster object created using `parcluster`. 

11-371
Example: `wait(cluster);`

**state** — cloud cluster state  
`'online' | 'waitingforworkers' | 'offline'`

Cloud cluster state, specified as a cluster object, for which the valid states are `'online'`, `'waitingforworkers'`, and `'offline'`.  
Example: `wait(cluster,'online');`

**timeout** — time elapsed before cloud cluster changes state  
seconds

Time elapsed before cloud cluster changes state, specified in seconds.  
Example: `wait(cluster,'online',100);`

### Output Arguments

**OK** — check if state has been reached  
Boolean

Check if state has been reached, specified as a Boolean. OK is true if state has been reached or a terminal state such as `'error'` occurs. OK is false in case of a timeout.  
Example: `OK = wait(cluster,'waitingforworkers',10);`

### See Also

`parallel.Cluster` | `parcluster` | `parpool` | `shutdown` | `start`

Introduced in R2017a
wait (FevalFuture)

Wait for futures to complete

Syntax

OK = wait(F)
OK = wait(F,STATE)
OK = wait(F,STATE,TIMEOUT)

Description

OK = wait(F) blocks execution until each of the array of futures F has reached the 'finished' state. OK is true if the wait completed successfully, and false if any of the futures was cancelled or failed execution.

OK = wait(F,STATE) blocks execution until the array of futures F has reached the state STATE. Valid values for STATE are 'running' or 'finished'.

OK = wait(F,STATE,TIMEOUT) blocks execution for a maximum of TIMEOUT seconds. OK is set false if TIMEOUT is exceeded before STATE is reached, or if any of the futures was cancelled or failed execution.

See Also

fetchNext | fetchOutputs | isequal | parfeval | parfevalOnAll

Introduced in R2013b
wait (GPUDevice)

Wait for GPU calculation to complete

Syntax

wait(gpudev)

Description

wait(gpudev) blocks execution in MATLAB until the GPU device identified by the GPUDevice object gpudev completes its calculations. This can be used before calls to toc when timing GPU code that does not gather results back to the workspace. When gathering results from a GPU, MATLAB automatically waits until all GPU calculations are complete, so you do not need to explicitly call wait in that situation.

See Also

gather | gpuArray | gpuDevice | gputimeit

Topics

“Measure Performance on the GPU” on page 9-41

Introduced in R2014b
write

Write distributed data to an output location

Syntax

write(location, D)

Description

write(location, D) writes the values in the distributed array D to files in the folder location. The data is stored in an efficient binary format suitable for reading back using datastore(location).

Examples

Create distributed array and write it to an output folder

```matlab
d = distributed.rand(5000,1);
location = 'hdfs://myHadoopCluster/some/output/folder';
write(location, d);
```

Recreate the distributed array from the written files

```matlab
ds = datastore(location);
d1 = distributed(ds);
```
Create a tall array from the written files

\[
\text{ds} = \text{datastore(location)}; \\
\text{t1} = \text{tall(ds)};
\]

- “Distributed Arrays”

**Input Arguments**

**location** — Folder location to write data
character vector | string

Folder location to write data, specified as a character vector or string. location can specify a full or relative path. The specified folder can be either of these options:

- Existing empty folder that contains no other files
- New folder that write creates

Example: location = 'hdfs://myHadoopCluster/some/output/folder'
Example: location = '..../dir/data'
Example: location = 'C:\Users\MyName\Desktop'

Data Types: char | string

\( D \) — Input array
distributed array

Input array, specified as a distributed array.

**See Also**

datastore | distributed | tall

**Topics**

“Distributed Arrays”

Introduced in R2017a
zeros

Array of zeros

Syntax

Z = zeros(sz, arraytype)
Z = zeros(sz, datatype, arraytype)

Z = zeros(sz, 'like', P)
Z = zeros(sz, datatype, 'like', P)

C = zeros(sz, codist)
C = zeros(sz, datatype, codist)
C = zeros(sz, ___, codist, 'noCommunication')
C = zeros(sz, ___, codist, 'like', P)

Description

Z = zeros(sz, arraytype) creates a matrix with underlying class of double, with zeros in all elements.

Z = zeros(sz, datatype, arraytype) creates a matrix with underlying class of datatype, with zeros in all elements.

The size and type of array are specified by the argument options according to the following table.

<table>
<thead>
<tr>
<th>Argument</th>
<th>Values</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td>sz</td>
<td>n</td>
<td>Specifies size as an n-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m,n or [m n]</td>
<td>Specifies size as an m-by-n matrix.</td>
</tr>
<tr>
<td></td>
<td>m,n,...,k or [m n ... k]</td>
<td>Specifies size as an m-by-n-by-...-by-k array.</td>
</tr>
<tr>
<td>arraytype</td>
<td>'distributed'</td>
<td>Specifies distributed array.</td>
</tr>
<tr>
<td>Argument</td>
<td>Values</td>
<td>Descriptions</td>
</tr>
<tr>
<td>----------</td>
<td>--------</td>
<td>--------------</td>
</tr>
<tr>
<td>codistributed</td>
<td>'codistributed'</td>
<td>Specifies codistributed array, using the default distribution scheme.</td>
</tr>
<tr>
<td>gpuArray</td>
<td>'gpuArray'</td>
<td>Specifies gpuArray.</td>
</tr>
<tr>
<td>datatype</td>
<td>'double' (default), 'single', 'int8', 'uint8', 'int16', 'uint16', 'int32', 'uint32', 'int64', or 'uint64'</td>
<td>Specifies underlying class of the array, i.e., the data type of its elements.</td>
</tr>
</tbody>
</table>

`Z = zeros(sz,'like',P)` creates an array of zeros with the same type and underlying class (data type) as array `P`.

`Z = zeros(sz,datatype,'like',P)` creates an array of zeros with the specified underlying class (`datatype`), and the same type as array `P`.

`C = zeros(sz,codist)` or `C = zeros(sz,datatype,codist)` creates a codistributed array of zeros with the specified size and underlying class (the default `datatype` is 'double'). The codistributor object `codist` specifies the distribution scheme for creating the codistributed array. For information on constructing codistributor objects, see the reference pages for `codistributor1d` and `codistributor2dbc`. To use the default distribution scheme, you can specify a codistributor constructor without arguments. For example:

```matlab
spmd
    C = zeros(8,codistributor1d());
end
```

`C = zeros(sz,___,codist,'noCommunication')` specifies that no interworker communication is to be performed when constructing a codistributed array, skipping some error checking steps.

`C = zeros(sz,___,codist,'like',P)` creates a codistributed array of zeros with the specified size, underlying class, and distribution scheme. If either the class or codistributor argument is omitted, the characteristic is acquired from the codistributed array `P`. 
Examples

Create Distributed Zeros Matrix

Create a 1000-by-1000 distributed array of zeros with underlying class double:

D = zeros(1000,'distributed');

Create Codistributed Zeros Matrix

Create a 1000-by-1000 codistributed double matrix of zeros, distributed by its second dimension (columns).

spmd(4)
    C = zeros(1000,'codistributed');
end

With four workers, each worker contains a 1000-by-250 local piece of C.

Create a 1000-by-1000 codistributed uint16 matrix of zeros, distributed by its columns.

spmd(4)
    codist = codistributor('1d',2,100*[1:numlabs]);
    C = zeros(1000,1000,'uint16',codist);
end

Each worker contains a 100-by-labindex local piece of C.

Create gpuArray Zeros Matrix

Create a 1000-by-1000 gpuArray of zeros with underlying class uint32:

G = zeros(1000,'uint32','gpuArray');

See Also

Inf | NaN | eye | false | ones | true | zeros

Introduced in R2006b
Glossary

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
</table>
| asynchronous processing | execute a task without waiting for it to complete, in a non-blocking way, so that you can carry on with other tasks, using `parfeval`.
| CHECKPOINTBASE | The name of the parameter in the `mdce_def` file that defines the location of the checkpoint directories for the MATLAB job scheduler and workers. |
| checkpoint directory | See CHECKPOINTBASE. |
| client | The MATLAB session that defines and submits the job. This is the MATLAB session in which the programmer usually develops and prototypes applications. Also known as the MATLAB client. |
| client computer | The computer running the MATLAB client; often your desktop. |
| cluster | A collection of computers that are connected via a network and intended for a common purpose. |
| coarse-grained application | An application for which run time is significantly greater than the communication time needed to start and stop the program. Coarse-grained distributed applications are also called embarrassingly parallel applications. |
| codistributed array | An array partitioned into segments, with each segment residing in the workspace of a different worker. When created, viewed, accessed, or manipulated from one of the worker sessions that contains part of the array, it is referred to as a codistributed array. Compare to distributed array. |
| communicating job | Job composed of tasks that communicate with each other during evaluation. All tasks must run simultaneously. A special case of communicating job is a parallel pool, used for executing `parfor`-loops and `spmd` blocks. |
| Composite | An object in a MATLAB client session that provides access to data values stored on the workers in a parallel... |
pool, such as the values of variables that are assigned inside an `spmd` statement.

<table>
<thead>
<tr>
<th><strong>computer</strong></th>
<th>A system with one or more processors.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CPU</strong></td>
<td>Central Processing Unit, comprising multiple cores / processors</td>
</tr>
<tr>
<td><strong>distributed application</strong></td>
<td>The same application that runs independently on several nodes, possibly with different input parameters. There is no communication, shared data, or synchronization points between the nodes, so they are generally considered to be coarse-grained.</td>
</tr>
<tr>
<td><strong>distributed array</strong></td>
<td>An array partitioned into segments, with each segment residing in the workspace of a different worker. When created, viewed, accessed, or manipulated from the client session, it is referred to as a distributed array. Compare to codistributed array.</td>
</tr>
<tr>
<td><strong>DNS</strong></td>
<td>Domain Name System. A system that translates Internet domain names into IP addresses.</td>
</tr>
<tr>
<td><strong>dynamic licensing</strong></td>
<td>The ability of a MATLAB worker to employ all the functionality you are licensed for in the MATLAB client, while checking out only an engine license. When a job is created in the MATLAB client with Parallel Computing Toolbox software, the products for which the client is licensed will be available for all workers that evaluate tasks for that job. This allows you to run any code on the cluster that you are licensed for on your MATLAB client, without requiring extra licenses for the worker beyond MATLAB Distributed Computing Server software. For a list of products that are not eligible for use with Parallel Computing Toolbox software, see <a href="http://www.mathworks.com/products/ineligible_programs/">http://www.mathworks.com/products/ineligible_programs/</a>.</td>
</tr>
<tr>
<td><strong>fine-grained application</strong></td>
<td>An application for which run time is significantly less than the communication time needed to start and stop the program. Compare to coarse-grained applications.</td>
</tr>
<tr>
<td>Term</td>
<td>Definition</td>
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<tr>
<td><strong>GPU</strong></td>
<td>Graphics Processing Unit, now widely used for general purpose (GP) GPU computing</td>
</tr>
<tr>
<td><strong>head node</strong></td>
<td>Usually, the node of the cluster designated for running the job scheduler and license manager. It is often useful to run all the nonworker related processes on a single machine.</td>
</tr>
<tr>
<td><strong>heterogeneous cluster</strong></td>
<td>A cluster that is not homogeneous.</td>
</tr>
<tr>
<td><strong>homogeneous cluster</strong></td>
<td>A cluster of identical machines, in terms of both hardware and software.</td>
</tr>
<tr>
<td><strong>independent job</strong></td>
<td>A job composed of independent tasks, which do not communicate with each other during evaluation. Tasks do not need to run simultaneously.</td>
</tr>
<tr>
<td><strong>job</strong></td>
<td>The complete large-scale operation to perform in MATLAB, composed of a set of tasks.</td>
</tr>
<tr>
<td><strong>job scheduler checkpoint information</strong></td>
<td>Snapshot of information necessary for the MATLAB job scheduler to recover from a system crash or reboot.</td>
</tr>
<tr>
<td><strong>job scheduler database</strong></td>
<td>The database that the MATLAB job scheduler uses to store the information about its jobs and tasks.</td>
</tr>
<tr>
<td><strong>LOGDIR</strong></td>
<td>The name of the parameter in the <code>mdce_def</code> file that defines the directory where logs are stored.</td>
</tr>
<tr>
<td><strong>MATLAB client</strong></td>
<td>See client.</td>
</tr>
<tr>
<td><strong>MATLAB job scheduler (MJS)</strong></td>
<td>The MathWorks process that queues jobs and assigns tasks to workers. Formerly known as a job manager.</td>
</tr>
<tr>
<td><strong>MATLAB worker</strong></td>
<td>See worker.</td>
</tr>
<tr>
<td><strong>mdce</strong></td>
<td>The service that has to run on all machines before they can run a MATLAB job scheduler or worker. This is the engine foundation process, making sure that the job scheduler and worker processes that it controls are always running.</td>
</tr>
</tbody>
</table>
Note that the program and service name is all lowercase letters.

**mdce_def file**
The file that defines all the defaults for the mdce processes by allowing you to set preferences or definitions in the form of parameter values.

**MPI**
Message Passing Interface, the means by which workers communicate with each other while running tasks in the same job.

**node**
A computer that is part of a cluster.

**parallel application**
The same application that runs on several workers simultaneously, with communication, shared data, or synchronization points between the workers.

**parallel pool**
A collection of workers that is reserved by the client, created using `parpool` and runs a special communicating job for execution of `parfor`-loops, `spmd` statements, and distributed arrays.

**private array**
An array which resides in the workspaces of one or more, but perhaps not all workers. There might or might not be a relationship between the values of these arrays among the workers.

**random port**
A random unprivileged TCP port, i.e., a random TCP port above 1024.

**register a worker**
The action that happens when both worker and MATLAB job scheduler are started and the worker contacts the job scheduler.

**replicated array**
An array which resides in the workspaces of all workers, and whose size and content are identical on all workers.

**scheduler**
The process, either local, third-party, or the MATLAB job scheduler, that queues jobs and assigns tasks to workers.
<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>spmd (single program multiple data)</td>
<td>A block of code that executes simultaneously on multiple workers in a parallel pool. Each worker can operate on a different data set or different portion of distributed data, and can communicate with other participating workers while performing the parallel computations.</td>
</tr>
<tr>
<td>task</td>
<td>One segment of a job to be evaluated by a worker.</td>
</tr>
<tr>
<td>thread</td>
<td>Smallest set of instructions that can be managed independently by a scheduler. On a GPU, multiprocessor or multicore system, multiple threads can be executed simultaneously (multi-threading).</td>
</tr>
<tr>
<td>variant array</td>
<td>An array which resides in the workspaces of all workers, but whose content differs on these workers.</td>
</tr>
<tr>
<td>worker</td>
<td>The MATLAB session that performs the task computations. Also known as the MATLAB worker or worker process.</td>
</tr>
<tr>
<td>worker checkpoint information</td>
<td>Files required by the worker during the execution of tasks.</td>
</tr>
</tbody>
</table>